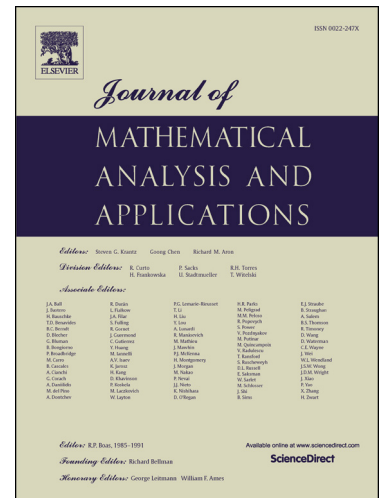


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Asymptotically autonomous multivalued Cauchy problems with spatially variable exponents

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Abstract

We study the asymptotic behavior of a non-autonomous multivalued Cauchy problem of the form

$$\frac{\partial u}{\partial t}(t) - \operatorname{div}(D(t)|\nabla u(t)|^{p(x)-2}\nabla u(t)) + |u(t)|^{p(x)-2}u(t) + F(t, u(t)) \ni 0$$

on a bounded smooth domain Ω in \mathbb{R}^n , $n \geq 1$ with a homogeneous Neumann boundary condition, where the exponent $p(\cdot) \in C(\overline{\Omega})$ satisfies $p^- := \min p(x) > 2$. We prove the existence of a pullback attractor and study the asymptotic upper semicontinuity of the elements of the pullback attractor $\mathfrak{A} = \{\mathcal{A}(t) : t \in \mathbb{R}\}$ as $t \rightarrow \infty$ for the non-autonomous evolution inclusion in a Hilbert space H under the assumptions, amongst others, that F is a measurable multifunction and $D \in L^\infty([\tau, T] \times \Omega)$ is bounded above and below and is monotonically nonincreasing in time. The global existence of solutions is obtained through results of Papageorgiou and Papalini.

Keywords: Multivalued Cauchy problem, variable exponents, pullback attractors, time-dependent operator, asymptotically autonomous inclusion

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1. Introduction

In this paper we study a multivalued Cauchy problem of the form

$$\begin{cases} \frac{\partial u}{\partial t}(t) - \operatorname{div}(D(t)|\nabla u(t)|^{p(x)-2}\nabla u(t)) + |u(t)|^{p(x)-2}u(t) + F(t, u(t)) \ni 0 \\ u(\tau) = u_0 \end{cases} \quad (1)$$

on a bounded smooth domain Ω in \mathbb{R}^n , $n \geq 1$ with a homogeneous Neumann boundary condition, where the exponent $p(\cdot) \in C(\overline{\Omega})$ satisfies

$$p^+ := \max_{x \in \overline{\Omega}} p(x) \geq p^- := \min_{x \in \overline{\Omega}} p(x) > 2,$$

and the initial condition $u(\tau) \in H := L^2(\Omega)$. The terms D and F are assumed to satisfy:

Assumption D. $D : [\tau, T] \times \Omega \rightarrow \mathbb{R}$ is a function in $L^\infty([\tau, T] \times \Omega)$ satisfying:

(D1) There are positive constants, β and M such that $0 < \beta \leq D(t, x) \leq M$ for almost all $(t, x) \in [\tau, T] \times \Omega$.

(D2) $D(t, x) \geq D(s, x)$ for each $x \in \Omega$ and $t \leq s$ in $[\tau, T]$.

Assumption F. $F : [\tau, T] \times H \rightarrow P_f(H)$, where

$$P_f(H) := \{A \subset H : A \text{ nonempty and closed}\},$$

is a multifunction satisfying:

(F1) For all $x \in H$, $t \mapsto F(t, x)$ is measurable, that is, for all $y \in H$, the function

$$[\tau, T] \ni t \mapsto d(y, F(t, x)) := \inf\{\|y - z\|_H : z \in F(t, x)\} \in \mathbb{R}$$

is measurable.

(F2) There exists $k \in L^1([\tau, T], \mathbb{R}^+)$ such that

$$h(F(t, x), F(t, y)) \leq k(t)\|x - y\|$$

a.e. on $[\tau, T]$, for all $x, y \in H$. Here h denotes the Hausdorff metric on $P_f(H)$ given by: for $A, B \in P_f(H)$,

$$h(A, B) := \max\{\operatorname{dist}(A, B), \operatorname{dist}(B, A)\},$$

where $\text{dist}(A, B) := \sup\{d(a, B) : a \in A\}$, $d(a, B) := \inf\{\|a - b\|_H : b \in B\}$ and similarly for $\text{dist}(B, A)$.

(F3) There exist $a, c \in L^2([\tau, T], \mathbb{R}^+)$:

$$\|F(t, x)\| := \sup\{\|z\|_H : z \in F(t, x)\} \leq a(t) + c(t)\|x\|_H,$$

a.e. in $[\tau, T]$, for all $x \in H$.

In [9] the authors proved the existence of a pullback attractor for the following non-autonomous evolution equation

$$\frac{\partial u}{\partial t}(t) - \text{div}(D(t)|\nabla u(t)|^{p(x)-2}\nabla u(t)) + |u(t)|^{p(x)-2}u(t) = B(t, u(t)) \quad (2)$$

on a bounded smooth domain Ω in \mathbb{R}^n , B was globally Lipschitz in its second variable and D was assumed to satisfy **Assumption D** above. Moreover, they proved upper semicontinuity of pullback attractors when the diffusion parameters vary. A similar problem was studied in [15] for a constant exponent p and stronger conditions on the diffusion coefficients D . In [10], the authors considered $B(t, u(t)) \equiv B(u)$ in the problem (2) and proved that it is asymptotically autonomous.

The paper is organized as follows. In Section 2 we prove existence of solution for inclusion (1) following Papageorgiou and Papalini [13]. In Section 3 we provide estimates on the solutions. In Section 4 we establish the existence of a pullback attractor. In Section 5 we prove the asymptotic upper semicontinuity of the elements of the pullback attractor, i.e., we prove that the inclusion (1) is, in fact, asymptotically autonomous when F does not depend explicitly on t .

2. Existence of solution

In this section we present the operator and its properties and we establish existence of solution for the multivalued Cauchy problem (1).

Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$, be a bounded smooth domain, $H := L^2(\Omega)$ and $Y := W^{1,p(\cdot)}(\Omega)$ with $p^- > 2$. Then $Y \subset H \subset Y^*$ with continuous and dense embeddings. Moreover, the inclusion $Y \subset H$ is compact (see Proposition 2.1 (ii) and Proposition 2.5 (ii) in [7]). We refer the reader to [6, 7] and references therein to see properties of the Lebesgue and Sobolev spaces with variable exponents.

In particular, with

$$L^{p(\cdot)}(\Omega) := \left\{ u : \Omega \rightarrow \mathbb{R} : u \text{ is measurable, } \int_{\Omega} |u(x)|^{p(x)} dx < \infty \right\}$$

and $L_+^\infty(\Omega) := \{q \in L^\infty(\Omega) : \text{ess inf } q \geq 1\}$, define

$$\rho(u) := \int_{\Omega} |u(x)|^{p(x)} dx, \quad \|u\|_{L^{p(\cdot)}(\Omega)} := \inf \left\{ \lambda > 0 : \rho\left(\frac{u}{\lambda}\right) \leq 1 \right\},$$

for $u \in L^{p(\cdot)}(\Omega)$ and $p \in L_+^\infty(\Omega)$.

Consider the operator $A(t)$ defined in Y such that for each $u \in Y$ associate the following element of Y^* , $A(t)u : Y \rightarrow \mathbb{R}$ given by

$$A(t)u(v) := \int_{\Omega} D(t, x) |\nabla u(x)|^{p(x)-2} \nabla u(x) \cdot \nabla v(x) dx + \int_{\Omega} |u(x)|^{p(x)-2} u(x) v(x) dx.$$

The authors in [9] proved that:

- For each $t \in [\tau, T]$ the operator $A(t) : Y \rightarrow Y^*$, with domain $Y = W^{1,p(\cdot)}(\Omega)$, is maximal monotone and $A(t)(Y) = Y^*$.
- The realization operator of $A(t)$ at $H = L^2(\Omega)$, i.e., $A_H(t)u = -\text{div}(D(t) |\nabla u(t)|^{p(x)-2} \nabla u(t)) + |u(t)|^{p(x)-2} u(t)$, is maximal monotone in H for each $t \in [\tau, T]$.
- The operator $A_H(t)$ is the subdifferential $\partial \varphi_{p(\cdot)}^t$ of the convex, proper and lower semicontinuous map $\varphi_{p(\cdot)}^t : L^2(\Omega) \rightarrow \mathbb{R} \cup \{+\infty\}$ given by

$$\varphi_{p(\cdot)}^t(u) = \begin{cases} \left[\int_{\Omega} \frac{D(t, x)}{p(x)} |\nabla u|^{p(x)} dx + \int_{\Omega} \frac{1}{p(x)} |u|^{p(x)} dx \right]; & \text{if } u \in Y \\ +\infty, & \text{otherwise.} \end{cases} \quad (3)$$

As our operator is of subdifferential type, we can obtain existence of global solution for problem (1) using results in the paper of Papageorgiou and Papalini [13].

We recall the definition of solution and a result of existence from [13]. Consider a multivalued Cauchy problem of the form

$$\begin{cases} \frac{du}{dt}(t) + \partial \varphi^t(u(t)) + F(t, u(t)) \ni 0, & \text{a.e. on } [0, T], \\ u(0) = \xi, & \xi \in H. \end{cases} \quad (4)$$

in a real Hilbert space H , where, for all $t \in [0, T]$, $\partial\varphi^t$ is the subdifferential of a lower semicontinuous proper convex function φ^t from H into $(-\infty, \infty]$.

Definition 1. A solution of (4) is a continuous function $u : [0, T] \rightarrow H$ such that $u(\cdot)$ is absolutely continuous on any closed subinterval of $(0, T)$ and with the property

- 1) $u(t) \in D(\partial\varphi^t)$, a.e. on $[0, T]$;
- 2) There exists $f \in L^2([0, T]; H)$ such that $f(t) \in F(t, u(t))$ and

$$\frac{du}{dt}(t) + \partial\varphi^t(u(t)) + f(t) \ni 0, \quad \text{a.e. on } [0, T];$$

- 3) $u(0) = \xi$.

Under the following assumption Papageorgiou and Papalini [13] established the existence of solution to problem (4) in Theorem 1 below.

Assumption A. Let $T > 0$ be fixed.

(A.1) For each $t \in [0, T]$, $\varphi^t : H \rightarrow (-\infty, \infty]$ is proper, convex and lower semicontinuous.

(A.2) For any positive integer r there exist a constant $K_r > 0$, an absolutely continuous function $g_r : [0, T] \rightarrow \mathbb{R}$ with $g'_r \in L^\beta(0, T)$ and a function of bounded variation $h_r : [0, T] \rightarrow \mathbb{R}$ such that if $t \in [0, T]$, $w \in D(\varphi^t)$ with $|w| \leq r$ and $s \in [t, T]$, then there exists an element $\tilde{w} \in D(\varphi^s)$ satisfying

$$\begin{aligned} |\tilde{w} - w| &\leq |g_r(s) - g_r(t)|(\varphi^t(w) + K_r)^\alpha, \\ \varphi^s(\tilde{w}) &\leq \varphi^t(w) + |h_r(s) - h_r(t)|(\varphi^t(w) + K_r), \end{aligned}$$

where α is some fixed constant with $0 \leq \alpha \leq 1$ and

$$\beta := \begin{cases} 2 & \text{if } 0 \leq \alpha \leq \frac{1}{2}, \\ \frac{1}{1-\alpha} & \text{if } \frac{1}{2} \leq \alpha \leq 1. \end{cases}$$

Theorem 1. [Theorem 6 in [13]] Suppose that Assumption (A) and Assumption (F) are satisfied. Then for each $\xi \in \text{cl}(D(\varphi^0))$, the multivalued problem (4) has a solution u on $[0, T]$ with $u(0) = \xi$.

Let us now return to our particular problem. We already saw that (A.1) is satisfied. To check condition (A.2) consider a positive integer r and define

$K_r := r$, $g_r(t) := t + r$ and $h_r(t) := r$. For $t \in [0, T]$, $w \in D(\varphi_{p(\cdot)}^t) = Y$ with $\|w\|_Y \leq r$ and $s \in [t, T]$, consider the element $\tilde{w} := w \in Y = D(\varphi_{p(\cdot)}^s)$. Taking $\alpha := 1/2$, condition (A.2) is then satisfied with $\beta = 2$. In particular, we need Assumption (D2) that $D(t, x) \geq D(s, x)$ for each $x \in \Omega$ and $t \leq s$ in $[0, T]$ here. Thus, we obtain the existence of a global solution for the following problem.

Theorem 2. *If Assumption (D) and Assumption (F) hold, then the multi-valued problem (1) has a solution for every $u_0 \in H$.*

3. Estimates on the solutions

In this section we provide estimates on the solutions in the spaces H and Y .

Theorem 3. *Let u be a solution of problem (1). Then there exist a constant T_1 and a function $B_1 : \mathbb{R} \rightarrow \mathbb{R}$ which does not depend on the initial data, such that*

$$\|u(t)\|_H \leq B_1(t), \quad \forall t \geq T_1 + \tau.$$

Proof: As u is a solution of (1) there exists $f \in L^2([\tau, T]; H)$ such that $f(t) \in F(t, u(t))$ and

$$\frac{du}{dt}(t) + A(t)u(t) + f(t) = 0, \quad (5)$$

a.e. on $[\tau, T]$. Multiplying the equation (5) by $u(t)$, we obtain

$$\frac{1}{2} \frac{d}{dt} \|u(t)\|_H^2 + \langle A(t)u(t), u(t) \rangle + \langle f(t), u(t) \rangle = 0.$$

We know that if $p(x) > q(x)$ then $L^{p(x)}(\Omega) \subset L^{q(x)}(\Omega)$ with $\|u\|_{L^{q(x)}(\Omega)} \leq 2(|\Omega| + 1)\|u\|_{L^{p(x)}(\Omega)}$ for all $u \in L^{p(x)}(\Omega)$ (see [6]). Thus

$$\|u(t)\|_H \leq 2(|\Omega| + 1)\|u(t)\|_{L^{p(\cdot)}(\Omega)} \leq 2(|\Omega| + 1)\|u(t)\|_Y.$$

If $\|u(t)\|_{L^{p(\cdot)}(\Omega)} \geq 1$ and $\|\nabla u(t)\|_{L^{p(\cdot)}(\Omega)} \geq 1$, then by Lemma 2.3 in [9]

$$\langle A(t)u(t), u(t) \rangle \geq \frac{\min\{1, \beta\}}{2^{(p^- - 1)}} \|u(t)\|_Y^{p^-},$$

and then

$$\frac{1}{2} \frac{d}{dt} \|u(t)\|_H^2 \leq -\frac{\min\{1, \beta\}}{2(p^- - 1)} \|u(t)\|_Y^{p^-} - \langle f(t), u(t) \rangle.$$

Using the Cauchy-Schwarz inequality and (F3), we obtain

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|u(t)\|_H^2 &\leq -\frac{\min\{1, \beta\}}{2(p^- - 1)} \|u(t)\|_Y^{p^-} + \|f(t)\|_H \|u(t)\|_H \\ &\leq -\frac{\min\{1, \beta\}}{2(p^- - 1)} \|u(t)\|_Y^{p^-} + (a(t) + c(t) \|u(t)\|_H) \|u(t)\|_H \quad (6) \\ &\leq -\frac{\min\{1, \beta\}}{2(p^- - 1)} \|u(t)\|_Y^{p^-} + C_1(t) \|u(t)\|_Y^2 + C_2(t) \|u(t)\|_Y \end{aligned}$$

where $C_1(t) := [2(|\Omega| + 1)]^2 c(t)$ and $C_2(t) := 2(|\Omega| + 1) a(t)$.

If $\theta := \frac{1}{2} p^-$, $\theta' := \frac{\theta}{\theta - 1}$ and $\epsilon > 0$, it follows from Young's inequality

$$\begin{aligned} C_1(t) \|u(t)\|_Y^2 + C_2(t) \|u(t)\|_Y &= \frac{C_1(t) \epsilon}{\epsilon} \|u(t)\|_Y^2 + \frac{C_2(t) \epsilon}{\epsilon} \|u(t)\|_Y \\ &\leq \frac{1}{\theta'} \left(\frac{C_1(t)}{\epsilon} \right)^{\theta'} + \frac{1}{\theta} \epsilon^\theta \|u(t)\|_Y^{p^-} \quad (7) \\ &\quad + \frac{1}{(p^-)'} \left(\frac{C_2(t)}{\epsilon} \right)^{(p^-)'} + \frac{1}{p^-} \epsilon^{p^-} \|u(t)\|_Y^{p^-}. \end{aligned}$$

Choose $\epsilon_0 > 0$ such that

$$\gamma := \frac{\min\{1, \beta\}}{2(p^- - 1)} - \frac{1}{\theta} \epsilon_0^\theta - \frac{1}{p^-} \epsilon_0^{p^-} > 0,$$

we have from (6) and (7),

$$\frac{1}{2} \frac{d}{dt} \|u(t)\|_H^2 + \gamma \|u(t)\|_Y^{p^-} \leq \frac{1}{\theta'} \left(\frac{C_1(t)}{\epsilon_0} \right)^{\theta'} + \frac{1}{(p^-)'} \left(\frac{C_2(t)}{\epsilon_0} \right)^{(p^-)'}$$

Let $\delta(t) := \frac{2}{\theta'} \left(\frac{C_1(t)}{\epsilon_0} \right)^{\theta'} + \frac{2}{(p^-)'} \left(\frac{C_2(t)}{\epsilon_0} \right)^{(p^-)'}$, $\tilde{\gamma} := \frac{2\gamma}{[4(|\Omega| + 1)^2]^{p^-}}$ and $y(t) := \|u(t)\|_H^2$. Then

$$y'(t) + \tilde{\gamma} y(t)^{p^-/2} \leq \delta(t), \quad \forall t \geq \tau.$$

From a slight generalization of Lemma 5.1 in [16], we obtain

$$y(t) \leq \left(\frac{\delta(t)}{\tilde{\gamma}} \right)^{2/p^-} + \left(\tilde{\gamma} \left(\frac{p^- - 2}{2} \right) (t - \tau) \right)^{-\frac{2}{p^- - 2}}.$$

Let $\tau_1 > 0$ be such that $\left[\tilde{\gamma} \left(\frac{p^- - 2}{2} \right) \tau_1 \right]^{-\frac{2}{p^- - 2}} \leq 1$. Then

$$\|u(t)\|_H \leq \left(\frac{\delta(t)}{\tilde{\gamma}} \right)^{1/p^-} + 1 =: K_1(t),$$

for all $t \geq \tau_1 + \tau$. Observe that $K_1(t)$ depends on $a(t)$ and $c(t)$ of Assumption (F3).

Similarly for each of the cases: $\|u(t)\|_{L^{p(\cdot)}(\Omega)} \geq 1$ and $\|\nabla u(t)\|_{L^{p(\cdot)}(\Omega)} \leq 1$; $\|u(t)\|_{L^{p(\cdot)}(\Omega)} \leq 1$ and $\|\nabla u(t)\|_{L^{p(\cdot)}(\Omega)} \geq 1$; $\|u(t)\|_{L^{p(\cdot)}(\Omega)} \leq 1$ and $\|\nabla u(t)\|_{L^{p(\cdot)}(\Omega)} \leq 1$, we obtain $(K_2(t), \tau_2)$, $(K_3(t), \tau_3)$ and $(K_4(t), \tau_4)$ such that

$$\|u(t)\|_H \leq K_i(t), \forall t \geq \tau_i + \tau,$$

for $i = 2, 3, 4$, respectively. Taking $B_1(t) := \max\{K_1(t), K_2(t), K_3(t), K_4(t)\}$ and $T_1 := \max\{\tau_1, \tau_2, \tau_3, \tau_4\}$ we obtain

$$\|u(t)\|_H \leq B_1(t), \forall t \geq T_1 + \tau,$$

where $B_1(t)$ depends on $a(t)$ and $c(t)$ of Assumption (F3). This completes the proof of the theorem. \square

Remark 1. Note that the function B_1 depends on the functions a and c of condition (F3) in the sense that if a and c are nondecreasing functions then $B_1(t)$ in Theorem 3 is a nondecreasing function.

Theorem 4. Let u be a solution of problem (1). Then there exist a constant T_2 and a function $B_2 : \mathbb{R} \rightarrow \mathbb{R}$, which does not depend on the initial data, such that

$$\|u(t)\|_Y \leq B_2(t), \quad \forall t \geq T_2 + \tau.$$

Proof: If u is a solution of (1) then, there exists $f \in L^2([\tau, T]; H)$ such that $f(t) \in F(t, u(t))$ and

$$\frac{du}{dt}(t) + A(t)u(t) + f(t) = 0,$$

a.e. on $[\tau, T]$. Furthermore, by Theorem 3

$$\|u(t)\|_H \leq B_1(t), \quad \forall t \geq T_1 + \tau.$$

Using the notation $\varphi_{p(\cdot)}^t(\cdot) := \varphi_{p(\cdot)}(t, \cdot)$ and $y(t) := \varphi_{p(\cdot)}^t(u(t))$ we have

$$\frac{d}{dt}y(t) = \frac{\partial}{\partial t}\varphi_{p(\cdot)}(t, u(t)) + \langle \partial\varphi_{p(\cdot)}^t(u(t)), \frac{d}{dt}u(t) \rangle.$$

Differentiating under the integral sign in (3) and using assumption (D2), we obtain $\frac{\partial}{\partial t}\varphi_{p(\cdot)}(t, u(t)) \leq 0$. Therefore

$$\frac{d}{dt}\varphi_{p(\cdot)}^t(u(t)) \leq \left\langle \partial\varphi_{p(\cdot)}^t(u(t)), \frac{du}{dt}(t) \right\rangle.$$

Then

$$\begin{aligned} \frac{d}{dt}\varphi_{p(\cdot)}^t(u(t)) &\leq \left\langle -f(t) - \frac{du}{dt}(t), \frac{du}{dt}(t) \right\rangle \\ &= -\left\|f(t) + \frac{du}{dt}(t)\right\|_H^2 + \left\langle f(t) + \frac{du}{dt}(t), f(t) \right\rangle \\ &\leq -\frac{1}{2}\left\|f(t) + \frac{du}{dt}(t)\right\|_H^2 + \frac{1}{2}\|f(t)\|_H^2. \end{aligned}$$

Thus

$$\frac{d}{dt}\varphi_{p(\cdot)}^t(u(t)) + \frac{1}{2}\left\|f(t) + \frac{du}{dt}(t)\right\|_H^2 \leq \frac{1}{2}\|f(t)\|_H^2,$$

and we obtain

$$\begin{aligned} \frac{d}{dt}\varphi_{p(\cdot)}^t(u(t)) &\leq \frac{1}{2}\|f(t)\|_H^2 \leq \frac{1}{2}(a(t) + c(t)\|u(t)\|_H)^2 \\ &\leq \frac{1}{2}(a(t) + c(t)B_1(t))^2 = \frac{1}{2}M_1(t)^2 \end{aligned}$$

for all $t \geq T_1 + \tau$, where $M_1(t) := a(t) + c(t)B_1(t)$.

From the definition of subdifferential, we have

$$\varphi_{p(\cdot)}^t(u(t)) \leq \langle \partial\varphi_{p(\cdot)}^t(u(t)), u(t) \rangle.$$

Thus,

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|u(t)\|_H^2 + \varphi_{p(\cdot)}^t(u(t)) &\leq \left\langle \frac{du}{dt}(t), u(t) \right\rangle + \langle \partial \varphi_{p(\cdot)}^t(u(t)), u(t) \rangle \\ &= \langle -f(t), u(t) \rangle \leq \|f(t)\|_H \|u(t)\|_H \\ &\leq M_1(t) B_1(t), \quad \forall t \geq T_1 + \tau. \end{aligned} \quad (8)$$

Fixing $r > 0$ and integrating both sides of (8) over $(t, t+r)$ for $t \geq T_1 + \tau$,

$$\begin{aligned} \int_t^{t+r} \varphi_{p(\cdot)}^s(u(s)) ds &\leq \frac{1}{2} \|u(t)\|_H^2 + \int_t^{t+r} M_1(s) B_1(s) ds \\ &\leq \frac{1}{2} B_1(t)^2 + \int_t^{t+r} M_1(s) B_1(s) ds =: a_3(t). \end{aligned}$$

Let $y(s) := \varphi_{p(\cdot)}^s(u(s))$, $g := 0$ and $h(s) := \frac{1}{2} M_1(s)^2$. Then

$$\int_t^{t+r} g(s) ds = 0 =: a_1(t), \quad \int_t^{t+r} h(s) ds =: a_2(t), \quad \int_t^{t+r} y(s) ds \leq a_3(t),$$

so, by a slight generalization of the Uniform Gronwall Lemma [16], we obtain

$$y(t+r) \leq \left(\frac{a_3(t)}{r} + a_2(t) \right) e^0 =: \tilde{r}_1(t), \quad \forall t \geq T_1 + \tau.$$

Therefore,

$$\int_{\Omega} \frac{D(\ell, x)}{p(x)} |\nabla u(\ell, x)|^{p(x)} dx + \int_{\Omega} \frac{1}{p(x)} |u(\ell, x)|^{p(x)} dx \leq \tilde{r}_1(\ell),$$

for all $\ell \geq T_1 + \tau + r$. Then

$$\frac{\min\{1, \beta\}}{p^+} [\rho(\nabla u(\ell)) + \rho(u(\ell))] \leq \tilde{r}_1(\ell)$$

for all $\ell \geq T_1 + \tau + r$, and hence,

$$\rho(\nabla u(\ell)) + \rho(u(\ell)) \leq \frac{p^+}{\min\{1, \beta\}} \tilde{r}_1(\ell) \quad (9)$$

for all $\ell \geq T_1 + \tau + r$.

If $\ell \geq T_1 + \tau + r$ and $\|u(\ell)\|_Y \geq 1$ there are four cases to analyze:

Case 1: If $\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)} \geq 1$ and $\|u(\ell)\|_{L^{p(\cdot)}(\Omega)} \geq 1$ we know that

$$\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-} \leq \rho(\nabla u(\ell)) \leq \|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+},$$

and

$$\|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-} \leq \rho(u(\ell)) \leq \|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+}.$$

Using (9) gives

$$\|u(t)\|_Y \leq R_1(t), \quad t \geq T_2 + \tau,$$

where $R_1(t) := 2 \left[\frac{p^+}{\min\{1, \beta\}} \tilde{r}_1(t) \right]^{1/p^-}$ and $T_2 := T_1 + r$.

Case 2: If $\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)} \geq 1$ and $\|u(\ell)\|_{L^{p(\cdot)}(\Omega)} \leq 1$ we know that

$$\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-} \leq \rho(\nabla u(\ell)) \leq \|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+},$$

and

$$\|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+} \leq \rho(u(\ell)) \leq \|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-}.$$

Using (9) we obtain

$$\|u(t)\|_Y \leq R_2(t), \quad t \geq T_2 + \tau,$$

where $R_2(t) := \left[\frac{p^+}{\min\{1, \beta\}} \tilde{r}_1(t) \right]^{1/p^-} + \left[\frac{p^-}{\min\{1, \beta\}} \tilde{r}_1(t) \right]^{1/p^+}$.

Case 3: If $\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)} \leq 1$ and $\|u(\ell)\|_{L^{p(\cdot)}(\Omega)} \geq 1$ we know that

$$\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+} \leq \rho(\nabla u(\ell)) \leq \|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-},$$

and

$$\|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-} \leq \rho(u(\ell)) \leq \|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+}.$$

By (9) it follows that

$$\|u(t)\|_Y \leq R_3(t), \quad t \geq T_2 + \tau,$$

where $R_3(t) := R_2(t)$.

Case 4: If $\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)} \leq 1$ and $\|u(\ell)\|_{L^{p(\cdot)}(\Omega)} \leq 1$ then we know that

$$\|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+} \leq \rho(\nabla u(\ell)) \leq \|\nabla u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-},$$

and

$$\|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^+} \leq \rho(u(\ell)) \leq \|u(\ell)\|_{L^{p(\cdot)}(\Omega)}^{p^-}.$$

Using (9) then gives

$$\|u(t)\|_Y \leq R_4(t), \quad t \geq T_2 + \tau,$$

where $R_4(t) := 2 \left[\frac{p^+}{\min\{1, \beta\}} \tilde{r}_1(t) \right]^{1/p^+}.$

In summary, defining

$$B_2(t) := \max \left\{ 1, 2 \left[\left(\frac{p^+}{\min\{1, \beta\}} \tilde{r}_1(t) \right)^{1/p^-} + \left(\frac{p^+}{\min\{1, \beta\}} \tilde{r}_1(t) \right)^{1/p^+} \right] \right\}$$

we have $\|u(t)\|_Y \leq B_2(t)$ for all $t \geq T_2 + \tau$. \square

Remark 2. Note that the function B_2 depends on the functions a and c of condition (F3) in the sense that if a and c are nondecreasing functions then $B_2(t)$ in Theorem 4 is a nondecreasing function.

4. Existence of a pullback attractor

We start this subsection with some definitions, see e.g., [2, 3, 12].

Definition 2. Let X be a complete metric space, $P(X)$ the set of all nonempty subsets of X and $\mathbb{R}_d := \{(t, s) \in \mathbb{R}^2 : t \geq s\}$. The map $U : \mathbb{R}_d \times X \rightarrow P(X)$ is called a multivalued evolution process on X if

- (1) $U(t, t, \cdot) = \mathbf{1}$ is the identity map;
- (2) $U(t, s, x) \subset U(t, \tau, U(\tau, s, x))$, for all $x \in X$, $s \leq \tau \leq t$, where

$$U(t, \tau, U(\tau, s, x)) = \bigcup_{y \in U(\tau, s, x)} U(t, \tau, y).$$

The multivalued evolution process U is called strict if

$$U(t, s, x) = U(t, \tau, U(\tau, s, x)), \text{ for all } x \in X, s \leq \tau \leq t.$$

Definition 3. Let U be a multivalued evolution process on X and $t \in \mathbb{R}$. The set $D(t) \subset X$ attracts (pullback) the nonempty bounded subset B of X at time t if

$$\lim_{\tau \rightarrow -\infty} \text{dist}(U(t, \tau)B, D(t)) = 0. \quad (10)$$

The set $D(t)$ is said to be (pullback) attracting at time t if (10) is satisfied for any nonempty bounded subset $B \subset X$.

For a nonempty and bounded subset $B \subset X$ and $t \in \mathbb{R}$, put $\gamma^s(t, B) = \bigcup_{\tau \leq s} U(t, \tau, B)$ and $\omega(t, B) = \bigcap \overline{\gamma^s(t, B)}$. The set $\omega(t, B)$ is called the pullback ω -limit set of B at time t with respect to the multivalued evolution process U .

Theorem 5. [Theorem 6 in [3]] Suppose that for $t \in \mathbb{R}$ and B a nonempty and bounded subset of X there exists a nonempty compact subset $D(t, B)$ of X such that

$$\lim_{s \rightarrow -\infty} \text{dist}(U(t, s)B, D(t, B)) = 0.$$

Then $\omega(t, B)$ is nonempty, compact and the minimal closed set attracting B at time t .

Definition 4. A family of sets $\{A(t) : t \in \mathbb{R}\}$ of X is called a pullback attractor for the multivalued evolution process U if

- (1) $A(t)$ is pullback attracting at time t for all $t \in \mathbb{R}$;
- (2) it is semi-invariant (or negatively invariant), that is,

$$A(t) \subset U(t, s, A(s)), \quad \text{for any } (t, s) \in \mathbb{R}_d;$$

- (3) it is minimal, that is, for any closed attracting set Y at time t , we have $A(t) \subset Y$.

Theorem 6. [Theorem 18 in [3]] Let us suppose that for all $(t, s) \in \mathbb{R}_d$ the map $x \mapsto U(t, s, x) \in P(X)$ is closed. If, moreover, for any $t \in \mathbb{R}$ there exists a nonempty compact set $D(t)$ which is attracting, then the set $\mathcal{A} = \{A(t)\}_{t \in \mathbb{R}}$, with

$$A(t) = \overline{\bigcup_{B \in \mathcal{B}(X)} \omega(t, B)}$$

where $\mathcal{B}(X) = \{B \in P(X) : B \text{ is bounded}\}$, is the pullback attractor of U . Moreover, the sets $A(t)$ are compact.

The multivalued evolution process associated with problem (1) is the map $U : \mathbb{R}_d \times H \rightarrow P(H)$ define by

$$U(t, \tau, \xi) = \{z : \text{there exists } u(\cdot) \in \mathcal{D}_\tau(\xi) \text{ such that } u(t) = z\}$$

where $\mathcal{D}_\tau(\xi)$ denotes the set of all solutions of problem (1) corresponding to the initial condition $u(\tau) = \xi$.

Theorem 7. *Let $t \in \mathbb{R}$ and let B be a nonempty and bounded subset of H . Then the ω -limit set $\omega(t, B)$ corresponding to the multivalued evolution process associated with problem (1) is nonempty, compact and the minimal closed set attracting B at time t .*

Proof: Note that Theorem 4 shows that the family $K(t) = \overline{B_Y(0, B_2(t))}^H$ of compact sets of H pullback attracts bounded sets of H at time t . Hence, by Theorem 5, $\omega(t, B)$ is nonempty, compact and the minimal closed set attracting B at time t . \square

Lemma 1. *Let $\xi \in H$ fixed. If $g_n \rightarrow g$ weakly in $L^2([\tau, T]; H)$, then the solution u_n of the problem*

$$\begin{cases} \frac{\partial u_n}{\partial t}(t) + A_H(t)u_n(t) + g_n(t) = 0 & \text{a.e. on } [\tau, T], \\ u_n(\tau) = \xi. \end{cases}$$

converges in $C([\tau, T]; H)$ to the solution u of the problem

$$\begin{cases} \frac{\partial u}{\partial t}(t) + A_H(t)u(t) + g(t) = 0 & \text{a.e. on } [\tau, T], \\ u(\tau) = \xi. \end{cases}$$

Proof: If $\xi \in Y = W^{1,p(\cdot)}(\Omega) = D(\varphi_{p(\cdot)}^\tau)$ the result follows from [8, 13].

If $\xi \in H \setminus Y$, given $n \in \mathbb{N}$ there exists $\xi_n \in Y$ with $\|\xi_n - \xi\| < \frac{1}{n}$. Let $v_{n,j}(\cdot)$ and $v_j(\cdot)$ be respectively the unique solution to

$$\begin{cases} \frac{\partial v_{n,j}}{\partial t}(t) + A_H(t)v_{n,j}(t) + g_n(t) = 0 & \text{a.e. on } [\tau, T], \\ v_{n,j}(\tau) = \xi_j, \end{cases}$$

and

$$\begin{cases} \frac{\partial v_j}{\partial t}(t) + A_H(t)v_j(t) + g(t) = 0 & \text{a.e. on } [\tau, T], \\ v_j(\tau) = \xi_j. \end{cases}$$

Since $\xi_j \in Y$ we have from [8, 13] that $v_{n,j} \rightarrow v_j$ in $C([\tau, T]; H)$ as $n \rightarrow \infty$. Moreover,

$$\|v_j(t) - u(t)\|_H \leq \|\xi_j - \xi\|_H < \frac{1}{j}, \quad \forall t \in [\tau, T],$$

and $v_j \rightarrow u$ in $C([\tau, T]; H)$ as $j \rightarrow \infty$. Hence, the subsequence $v_{n,n} \rightarrow u$ in $C([\tau, T]; H)$ as $n \rightarrow \infty$.

Since

$$\begin{aligned} \|u_n(t) - u(t)\|_H &\leq \|u_n(t) - v_{n,n}(t)\|_H + \|v_{n,n}(t) - u(t)\|_H \\ &\leq \|\xi_n - \xi\|_H + \|v_{n,n}(t) - u(t)\|_H, \end{aligned}$$

we conclude that $u_n \rightarrow u$ in $C([\tau, T]; H)$ as $n \rightarrow \infty$. \square

Theorem 8. *The multivalued evolution process associated with problem (1) has a pullback attractor $\mathfrak{A} = \{\mathcal{A}(t) : t \in \mathbb{R}\}$. Moreover, the sets $A(t)$ are compact.*

Proof: By Theorem 4 we have that the family $K(t) = \overline{B_Y(0, B_2(t))}^H$ of compact sets of H is attracting. Therefore, in order to conclude the existence of the pullback attractor using Theorem 6 we need to prove that for all $(T, \tau) \in \mathbb{R}_d$ the map $H \ni \xi \mapsto U(T, \tau, \xi) \in P(H)$ is closed. Then, for fixed $(T, \tau) \in \mathbb{R}_d$ let $y_n \in U(T, \tau, \xi_n)$ be such that

$$\xi_n \rightarrow \xi \quad \text{in } H,$$

$$y_n \rightarrow y \quad \text{in } H.$$

We have to prove that $y \in U(T, \tau, \xi)$.

There exists a sequence $u_n(\cdot) \in \mathcal{D}_\tau(\xi_n)$ such that $u_n(T) = y_n$. As $u_n(\cdot) \in \mathcal{D}_\tau(\xi_n)$ also there exists a sequence $f_n \in L^2([\tau, T]; H)$ such that $f_n(t) \in F(t, u_n(t))$ a.e. on $[\tau, T]$ and

$$\begin{cases} \frac{\partial u_n}{\partial t}(t) + A_H(t)u_n(t) + f_n(t) = 0 & \text{a.e. on } [\tau, T], \\ u_n(\tau) = \xi_n. \end{cases} \quad (11)$$

In view of (F3), we have

$$\|f_n(t)\|_H \leq a(t) + c(t)\|u_n(t)\|_H \quad \text{a.e. on } [\tau, T]. \quad (12)$$

Let $z(\cdot)$ be the unique solution to

$$\begin{cases} \frac{\partial z}{\partial t}(t) + A_H(t)z(t) = 0 & \text{a.e. on } [\tau, T], \\ z(\tau) = \xi. \end{cases} \quad (13)$$

As a particular case of Theorem 3.1 in [9] we have that $\|z(t)\|_H \leq r_0$ where the constant r_0 does not depend on t , since that we are in the case $B \equiv 0$.

Subtracting the first equation on (11) from the first equation on (13) and multiplying by $u_n(t) - z(t)$ we obtain

$$\frac{1}{2} \|u_n(t) - z(t)\|_H^2 \leq -\langle f_n(t), u_n(t) - z(t) \rangle \leq \|f_n(t)\|_H \|u_n(t) - z(t)\|_H$$

a.e. on $[\tau, T]$. Integrating the above inequality from τ to $t \leq T$ we obtain

$$\frac{1}{2} \|u_n(t) - z(t)\|_H^2 \leq \frac{1}{2} \|\xi_n - \xi\|_H^2 + \int_{\tau}^t \|f_n(s)\|_H \|u_n(s) - z(s)\|_H ds.$$

It follows by the Gronwall inequality that

$$\|u_n(t) - z(t)\|_H \leq \|\xi_n - \xi\|_H + \int_{\tau}^t \|f_n(s)\|_H ds, \quad \forall t \in [\tau, T],$$

and then by (12),

$$\begin{aligned} \|u_n(t)\|_H &\leq \|z(t)\|_H + \|\xi_n - \xi\|_H + \int_{\tau}^t (a(s) + c(s)\|u_n(s)\|_H) ds \\ &\leq r_0 + r_1 + \int_{\tau}^T a(s) ds + \int_{\tau}^t c(s)\|u_n(s)\|_H ds \end{aligned}$$

where r_1 is a constant such that $\|\xi_n - \xi\|_H \leq r_1$ for all $n \in \mathbb{N}$. So

$$\|u_n(t)\|_H \leq K(\tau, T, a) + \int_{\tau}^t c(s)\|u_n(s)\|_H ds, \quad \forall t \in [\tau, T],$$

where $K(\tau, T, a) = r_0 + r_1 + \int_{\tau}^T a(s) ds$. Hence, by the Gronwall-Bellman inequality we obtain

$$\|u_n(t)\|_H \leq K(\tau, T, a) e^{\int_{\tau}^t c(s) ds} = r(t), \quad \forall t \in [\tau, T].$$

Therefore again using (12), we obtain

$$\|f_n(t)\|_H \leq a(t) + c(t)r(t) = m(t) \quad \text{a.e. on } [\tau, T].$$

Hence, $\{f_n\}$ is a bounded sequence on the reflexive Banach space $L^2([\tau, T]; H)$, and we obtain that there exists a subsequence such that

$$f_n \rightarrow f \quad \text{weakly in } L^2([\tau, T]; H).$$

Let $v_n(\cdot)$ be the unique solution to

$$\begin{cases} \frac{\partial v_n}{\partial t}(t) + A_H(t)v_n(t) + f_n(t) = 0 & \text{a.e. on } [\tau, T], \\ v_n(\tau) = \xi. \end{cases} \quad (14)$$

By Lemma 1 we have that v_n converges in $C([\tau, T]; H)$ to the solution v of

$$\begin{cases} \frac{\partial v}{\partial t}(t) + A_H(t)v(t) + f(t) = 0 & \text{a.e. on } [\tau, T], \\ v(\tau) = \xi. \end{cases}$$

Now, using (11) and (14) we have

$$\|u_n(t) - v_n(t)\|_H \leq \|\xi_n - \xi\|_H, \quad \forall t \in [\tau, T].$$

So we conclude that $u_n \rightarrow v$ in $C([\tau, T]; H)$ and $y = v(T)$.

Now, to conclude the proof, it follows by Theorem 3.3 in [5] that $f(t) \in F(t, v(t))$ a.e. on $[\tau, T]$. \square

5. Asymptotic upper semicontinuity

In this section we assume that F does not depend explicitly in t , i.e., we consider $F(t, u) \equiv F(u)$ and $F : H \rightarrow P_f(H)$ is a multifunction such that there exists a constant $K > 0$ such that $h(F(x), F(y)) \leq K\|x - y\|$ for all $x, y \in H$.

We will prove the asymptotic upper semicontinuity of the elements of the pullback attractor, i.e., we prove that in fact the inclusion (1) is asymptotically autonomous.

5.1. Theoretical results

In this subsection motivated by problem (1), we study the asymptotic behaviour of an abstract non-autonomous multivalued problem in a Hilbert space H of the form

$$\frac{\partial u}{\partial t}(t) + A(t)u(t) + F(u(t)) \ni 0, \quad u(\tau) = \psi_\tau, \quad (15)$$

compared with that of an autonomous multivalued problem of the form

$$\frac{\partial v}{\partial t}(t) + A_\infty v(t) + F(v(t)) \ni 0, \quad v(0) = \psi_0, \quad (16)$$

where $A(t)$, A_∞ are univalued operators in H and $F : H \rightarrow P(H)$ is a multivalued map.

The autonomous problem (16) is thus the asymptotic autonomous version of the non-autonomous problem (15). In particular, we establish the convergence in the Hausdorff semi-distance of the component subsets of the pullback attractor of the non-autonomous problem (15) to the global autonomous attractor of the autonomous problem (16).

Some definitions on multivalued semigroups are recalled here, see for example [4, 11, 14] for more details.

Definition 5. Let X be a complete metric space. The map $G : \mathbb{R}^+ \times X \rightarrow P(X)$ is called a multivalued semigroup (or m -semiflow) if

- (1) $G(0, \cdot) = \mathbf{1}$ is the identity map;
- (2) $G(t_1 + t_2, x) \subset G(t_1, G(t_2, x))$, for all $x \in X$ and $t_1, t_2 \in \mathbb{R}^+$.

Definition 6. Let G be a multivalued semigroup on X . The set $A \subset X$ attracts the subset B of X if $\lim_{t \rightarrow \infty} \text{dist}(G(t, B), A) = 0$. The set M is said to be a global B -attractor for G if M attracts any nonempty bounded subset $B \subset X$ and it is negatively invariant, i.e., $M \subset G(t, M)$, $\forall t \geq 0$.

Suppose that the multivalued evolution process $\{U(t, \tau) : t \geq \tau\}$ in H associated with problem (15) has a pullback attractor $\mathfrak{A} = \{\mathcal{A}(t) : t \in \mathbb{R}\}$, with $\mathcal{A}(t)$ compact for each $t \in \mathbb{R}$, and that the multivalued semigroup $G : \mathbb{R}^+ \times H \rightarrow P(H)$ associated with problem (16) has a compact global autonomous B -attractor \mathcal{A}_∞ in the Hilbert space H . The following result will be used later to establish the convergence in the Hausdorff semi-distance of the component subsets $\mathcal{A}(t)$ of the pullback attractor \mathfrak{A} to \mathcal{A}_∞ as $t \rightarrow \infty$.

Theorem 9. Suppose that $\mathcal{C} := \overline{\cup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)}$ is a compact subset of H . In addition, suppose that for each solution u of problem (15) there exists a solution v of problem (16) such that $u(t + \tau) \rightarrow v(t)$ in H as $\tau \rightarrow +\infty$ uniformly in $t \geq 0$ whenever $\psi_\tau \in \mathcal{A}(\tau)$ and $\psi_\tau \rightarrow \psi_0$ in H as $\tau \rightarrow +\infty$. Then

$$\lim_{t \rightarrow +\infty} \text{dist}(\mathcal{A}(t), \mathcal{A}_\infty) = 0.$$

Proof: Suppose that this is not true. Then there would exist an $\epsilon_0 > 0$ and a real sequence $\{\tau_n\}_{n \in \mathbb{N}}$ with $\tau_n > n$ for $n \in \mathbb{N}$ such that $\text{dist}(\mathcal{A}(\tau_n), \mathcal{A}_\infty) \geq 3\epsilon_0$ for all $n \in \mathbb{N}$. Since the sets $\mathcal{A}(\tau_n)$ are compact, there exist $a_n \in \mathcal{A}(\tau_n)$ such that

$$\text{dist}(a_n, \mathcal{A}_\infty) = \text{dist}(\mathcal{A}(\tau_n), \mathcal{A}_\infty) \geq 3\epsilon_0, \quad (17)$$

for each $n \in \mathbb{N}$. By attraction for the multivalued semigroup we have $\text{dist}(G(\ell, \mathcal{C}), \mathcal{A}_\infty) \leq \epsilon_0$ for $\ell > 0$ large enough. Moreover, by the semi-invariance of the pullback attractor there exist $b_n \in \mathcal{A}\left(\frac{1}{2}\tau_n\right) \subset \mathcal{C}$ for $n \in \mathbb{N}$ such that $a_n \in U\left(\tau_n, \frac{1}{2}\tau_n\right)b_n$ for each $n \in \mathbb{N}$. Since \mathcal{C} is compact, there is a convergent subsequence $b_{n'} \rightarrow b \in \mathcal{C}$. Since $a_{n'} \in U\left(\tau_{n'}, \frac{1}{2}\tau_{n'}\right)b_{n'}$ there exists a solution $u_{n'}$ of

$$\frac{\partial u_{n'}}{\partial t}(t) + A(t)u_{n'}(t) + F(u_{n'}(t)) \ni 0, \quad u_{n'}\left(\frac{1}{2}\tau_{n'}\right) = b_{n'},$$

such that $a_{n'} = u_{n'}(\tau_{n'})$. From the hypotheses, there exists a solution $v_{n'}$ of

$$\frac{\partial v_{n'}}{\partial t}(t) + A_\infty v_{n'}(t) + F(v_{n'}(t)) \ni 0, \quad v_{n'}(0) = b,$$

such that

$$\left\| u_{n'}(\tau_{n'}) - v_{n'}\left(\frac{1}{2}\tau_{n'}\right) \right\|_H < \epsilon_0$$

for n' large enough (since $\frac{1}{2}\tau_{n'} > \frac{1}{2}n'$ is large enough). Hence,

$$\begin{aligned} \text{dist}(a_{n'}, \mathcal{A}_\infty) &= \text{dist}(u_{n'}(\tau_{n'}), \mathcal{A}_\infty) \\ &\leq \left\| u_{n'}(\tau_{n'}) - v_{n'}\left(\frac{1}{2}\tau_{n'}\right) \right\|_H + \text{dist}\left(v_{n'}\left(\frac{1}{2}\tau_{n'}\right), \mathcal{A}_\infty\right) \\ &\leq \left\| u_{n'}(\tau_{n'}) - v_{n'}\left(\frac{1}{2}\tau_{n'}\right) \right\|_H + \text{dist}\left(G\left(\frac{1}{2}\tau_{n'}, \mathcal{C}\right), \mathcal{A}_\infty\right) \\ &\leq 2\epsilon_0, \end{aligned}$$

which contradicts (17). \square

5.2. Application to inclusion (1)

The result in Subsection 5.1 is applied here to the nonlinear inclusion with spatially variable exponents (1) in the Hilbert space $H := L^2(\Omega)$.

We assume in this subsection that F has compact values, i.e., $F(u)$ is a compact set for each $u \in H$ and the coefficient D satisfies Assumption D and the additional Assumption D3 that follows:

Assumption D3. $D(t + \tau, \cdot) \rightarrow D^*(\cdot)$ in $L^\infty(\Omega)$ as $\tau \rightarrow +\infty$ uniformly in $t \geq 0$.

Assumptions (D1)-(D2) imply that the pointwise limit $D^*(x)$ as $t \rightarrow \infty$ exists and satisfies $0 < \beta \leq D^*(x) \leq M$ for almost all $x \in \Omega$. Then the problem (1) with $D^*(x)$ is autonomous and has a global autonomous B -attractor as a particular case of the results in Section 4.

It will be shown that the dynamics of the original non-autonomous problem is asymptotically autonomous and its pullback attractor converges upper-semi continuously to the autonomous global B -attractor \mathcal{A}_∞ of the problem

$$\begin{cases} \frac{\partial v}{\partial t}(t) - \operatorname{div} (D^* |\nabla v(t)|^{p(x)-2} \nabla v(t)) + |v(t)|^{p(x)-2} v(t) + F(v(t)) \ni 0, \\ v(0) = \psi_0. \end{cases} \quad (18)$$

In particular, we consider the operators

$$\begin{aligned} A(t)u &:= -\operatorname{div} (D(t) |\nabla u|^{p(x)-2} \nabla u) + |u|^{p(x)-2} u, \\ A_\infty v &:= -\operatorname{div} (D^* |\nabla v|^{p(x)-2} \nabla v) + |v|^{p(x)-2} v. \end{aligned}$$

Applying Theorem 3 for the particular case $F(t, u) \equiv F(u)$, there exist positive constants T_1, B_1 such that $\|u(t)\|_H \leq B_1$ for all $t \geq T_1 + \tau$. Moreover, applying Theorem 4 for the particular case $F(t, u) \equiv F(u)$ and space $Y = W^{1,p(x)}(\Omega)$, there exist positive constants T_2, B_2 such that

$$\|u(t)\|_Y \leq B_2, \quad \forall t \geq T_2 + \tau. \quad (19)$$

Since, also $\|v(t)\|_Y \leq B_2$ for all $t \geq T_2 + \tau$ and $Y \subset H$ with compact embedding, it follows that

Corollary 1. $\overline{\cup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)}$ is a compact subset of H .

Using estimate (19), the proof of the next result follows the same lines as the proof of Theorem 4.2 of [10], and therefore is omitted here.

Lemma 2. *If $\{\psi_\tau : \tau \in \mathbb{R}\}$ is a bounded set in Y and $\psi_\tau \rightarrow \psi_0$ in H as $\tau \rightarrow +\infty$, then for each $\tau \in \mathbb{R}$ there exists a function $g_\tau : [0, +\infty) \rightarrow [0, +\infty)$ given by $g_\tau(t) = K\|D(t+\tau, \cdot) - D^*(\cdot)\|_{L^\infty(\Omega)}$, where K is a positive constant, such that*

$\langle A(t+\tau)u(t+\tau) - A_\infty v(t), u(t+\tau) - v(t) \rangle \geq -g_\tau(t)$, for all $t \in \mathbb{R}^+$, $\tau \in \mathbb{R}$,
for any solution u of (15) and any uniformly bounded function v with $v(t) \in D(A_\infty)$ for all $t \geq 0$.

Observe that by Assumption D3 the function $g_\tau : [0, +\infty) \rightarrow [0, +\infty)$ given in Lemma 2 satisfies $g_\tau(t) \rightarrow 0$ as $\tau \rightarrow +\infty$ uniformly in $t \geq 0$.

In the next result we check the hypothesis of asymptotic continuity of the non-autonomous flow in the Theorem 9 for problems like (15).

Theorem 10. *If $\psi_\tau \in \mathcal{A}(\tau)$ and $\psi_\tau \rightarrow \psi_0$ in H as $\tau \rightarrow +\infty$, then for each solution u of (15) there exists a solution v of (18) such that $u(t+\tau) \rightarrow v(t)$ in H as $\tau \rightarrow +\infty$ uniformly in $t \geq 0$.*

Proof: Let u be a solution of (15) then there exists $f \in L^2([\tau, T]; H)$ such that $f(t) \in F(u(t))$ a.e. and

$$\begin{cases} \frac{\partial u}{\partial t}(t) + A(t)u(t) + f(t) = 0, & \text{a.e in } [\tau, T], \\ u(\tau) = \psi_\tau. \end{cases} \quad (20)$$

Using the semi-invariance of the pullback attractor and the estimate (19) it follows that $\{\psi_\tau : \tau \in \mathbb{R}\}$ is a bounded set in Y . From the semi-invariance of the pullback attractor, $\mathcal{A}(\tau) \subset U(\tau, s)\mathcal{A}(s)$, $\forall (\tau, s) \in \mathbb{R}_d$. So, there exists a solution w of (15) with $\psi_\tau = w(\tau)$ and $w(s) \in \mathcal{A}(s)$. Consider the concatenate solution

$$\theta_s(\ell) := \begin{cases} u(\ell), & \ell \geq \tau, \\ w(\ell), & s \leq \ell \leq \tau. \end{cases}$$

Using the pullback attracting property, we have that for each given $\epsilon > 0$ there exists $s_\epsilon \in \mathbb{R}$ such that

$$\text{dist} \left(U(t+\tau, s_\epsilon) \overline{\bigcup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)}, \mathcal{A}(t+\tau) \right) < \epsilon.$$

In particular,

$$u(t + \tau) = \theta_{s_\epsilon}(t + \tau) \in O_\epsilon(\mathcal{A}(t + \tau)) \subset O_\epsilon(\cup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)), \forall \epsilon > 0.$$

Then,

$$u(t + \tau) \in \bigcap_{\epsilon > 0} O_\epsilon(\cup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)) = \overline{\cup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)}.$$

Considering $z_\tau(t) := f(t + \tau)$, we have

$$z_\tau(t) \in F(u(t + \tau)) \subset \mathcal{K} := F\left(\overline{\cup_{\tau \in \mathbb{R}} \mathcal{A}(\tau)}\right). \quad (21)$$

Using Corollary 1 and that F is Lipschitz continuous with compact values we have from Proposition 3 p. 42 in [1] that \mathcal{K} is a compact set in H . So, for each $t \geq 0$ there exist $z(t) \in \mathcal{K}$ and a subnet of $\{z_\tau(t)\}_{\tau \in \mathbb{R}}$, which we do not relabel, such that $z_\tau(t) \rightarrow z(t)$ as $\tau \rightarrow +\infty$. Let v be the unique solution of the problem

$$\begin{cases} \frac{\partial v}{\partial t}(t) + A_\infty v(t) + z(t) = 0, \\ v(0) = \psi_0. \end{cases} \quad (22)$$

With similar computations as in Theorem 3 one can show that v is uniformly bounded. Subtracting the equation in (20) from the equation in (22) gives

$$\frac{d}{dt}(u(t + \tau) - v(t)) + A(t + \tau)u(t + \tau) - A_\infty v(t) + f(t + \tau) - z(t) = 0$$

for a.e. $t \in [0, T]$. Multiplying by $u(t + \tau) - v(t)$ and using Lemma 2, we obtain

$$\frac{1}{2} \frac{d}{dt} \|u(t + \tau) - v(t)\|_H^2 \leq g_\tau(t) + \|z_\tau(t) - z(t)\|_H \|u(t + \tau) - v(t)\|_H.$$

Integrating this last inequality from 0 to t , gives

$$\begin{aligned} \frac{1}{2} \|u(t + \tau) - v(t)\|_H^2 &\leq \frac{1}{2} \|\psi_\tau - \psi_0\|_H^2 + T \operatorname{ess\,sup}_{t \in [0, +\infty)} g_\tau(t) \\ &\quad + \int_0^t \|z_\tau(s) - z(s)\|_H \|u(s + \tau) - v(s)\|_H ds. \end{aligned}$$

Hence, by the Gronwall inequality

$$\begin{aligned} \|u(t + \tau) - v(t)\|_H &\leq \left(\|\psi_\tau - \psi_0\|_H^2 + 2T \operatorname{ess\,sup}_{t \in [0, +\infty)} g_\tau(t) \right)^{1/2} \\ &\quad + \int_0^T \|z_\tau(s) - z(s)\|_H ds. \end{aligned}$$

Using (21) and the Dominated Convergence Theorem, we have

$$\int_0^T \|z_\tau(s) - z(s)\|_H ds \rightarrow 0$$

as $\tau \rightarrow +\infty$.

Since $\psi_\tau \rightarrow \psi_0$ in H and $\text{ess sup}_{t \in [0, +\infty)} g_\tau(t) \rightarrow 0$ as $\tau \rightarrow +\infty$, we obtain $u(t + \tau) \rightarrow v(t)$ in H as $\tau \rightarrow +\infty$ uniformly in $[0, T]$.

By Theorem 4, $u(t + \tau) \in K$ for all $t \geq T_2$ where K is a compact set in H which is independent of t in this case of $F(t, u) \equiv F(u)$.

Consider $\epsilon > 0$ given. Since K is a compact set we have $K \subset \bigcup_i^n B_{\epsilon/4}(x_i)$, $x_1, \dots, x_n \in K$. Then there exists $\tau_1 = \tau_1(T_2)$ such that $u(T_2 + \tau), v(T_2) \in B_{\epsilon/4}(x_{i_0})$ for $\tau > \tau_1$ for some $1 \leq i_0 \leq n$. For $t > T_2$ and $\tau > \tau_1$ we have $t = T_2 + s$ with $s + \tau > \tau_1$ for some $s > 0$. Then

$$u(t + \tau) = u(T_2 + s + \tau) \in B_{\epsilon/4}(x_{i_0}).$$

Once $u(t + \tau) \rightarrow v(t)$ in H as $\tau \rightarrow +\infty$ we have $v(t) \in \overline{B_{\epsilon/4}(x_{i_0})}$.

We have from the previous part that there exists τ_2 such that $\tau > \tau_2$ implies $\sup_{t \in [0, T_2]} \|u(t + \tau) - v(t)\|_H < \frac{\epsilon}{2}$. Taking $\tau_0 := \max\{\tau_1, \tau_2\}$ we have that $\tau > \tau_0$ implies

$$\begin{aligned} \sup_{t \in [0, \infty)} \|u(t + \tau) - v(t)\|_H &\leq \sup_{t \in [0, T_2]} \|u(t + \tau) - v(t)\|_H \\ &\quad + \sup_{t \in [T_2, \infty)} \|u(t + \tau) - v(t)\|_H \\ &< \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon. \end{aligned}$$

Therefore, $u(t + \tau) \rightarrow v(t)$ in H as $\tau \rightarrow +\infty$ uniformly in $[0, \infty)$.

From Theorem 3.3 in [5], $z \in \text{Sel}F(v)$ and the result follows. \square

The next result gives the desired asymptotic upper semi-continuous convergence.

Theorem 11. $\lim_{t \rightarrow +\infty} \text{dist}(\mathcal{A}(t), \mathcal{A}_\infty) = 0$.

Proof: Suppose that $\psi_\tau \in \mathcal{A}(\tau)$ and $\psi_\tau \rightarrow \psi_0$ in H . From Theorem 10, for each solution u of (15) there exists a solution v of (18) such that $u(t + \tau) \rightarrow v(t)$ in H as $\tau \rightarrow +\infty$ uniformly in $t \geq 0$. Corollary 1 and Theorem 9 then yield $\lim_{t \rightarrow +\infty} \text{dist}(\mathcal{A}(t), \mathcal{A}_\infty) = 0$. \square

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