



Non-convex sparse regularisation

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ABSTRACT

We study the regularising properties of Tikhonov regularisation on the sequence space ℓ^2 with weighted, non-quadratic penalty term acting separately on the coefficients of a given sequence. We derive sufficient conditions for the penalty term that guarantee the well-posedness of the method, and investigate to which extent the same conditions are also necessary. A particular interest of this paper is the application to the solution of operator equations with sparsity constraints. Assuming a linear growth of the penalty term at zero, we prove the sparsity of all regularised solutions. Moreover, we derive a linear convergence rate under the assumptions of even faster growth at zero and a certain injectivity of the operator to be inverted. These results in particular cover non-convex ℓ^p regularisation with $0 < p < 1$.

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1. Introduction

Regularisation with sparsity constraints is an impressingly effective method for the solution of operator equations

$$Ax = y,$$

when it is known that the solution only contains a small number of significant coefficients. The idea is that, instead of minimising the classical Tikhonov functional $\mathcal{T}_\alpha(x, y) = \|Ax - y\|^2 + \alpha \|x\|_2^2$, one increases the penalisation of small coefficients of x while at the same time decreasing the penalisation of the large ones. Following [10], this can be achieved by replacing the ℓ^2 term used for the regularisation by an ℓ^p norm with $p < 2$. The corresponding regularisation functional then reads as

$$\mathcal{T}_\alpha(x, y) = \|Ax - y\|^2 + \alpha \|x\|_p^p \quad \text{with } p < 2.$$

Applications and solution algorithms for such problems can be found, for instance, in [1,3,7–10,12,14,18,22,24]. The regularising properties of this type of functionals have been analysed in [4,10,15,16,20,23,26]. In addition, the related constrained optimisation problem $\|Ax - y\|^2 \rightarrow \min$ subject to $\|x\|_p \leq \delta$ has been studied in the context of compressed sensing [6,11]. Moreover, we refer to [5], where an overview of sparse regularisation is given.

In this paper we study more general, weighted regularisation functionals of the form

$$\mathcal{T}_\alpha(x, y) = \|Ax - y\|^2 + \alpha \sum_{\lambda} w_{\lambda} \phi(x_{\lambda})$$

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with $\phi: \mathbb{R} \rightarrow [0, +\infty]$ and $w_\lambda > 0$. We derive necessary and sufficient conditions for $\mathcal{T}_\alpha$ to define a well-posed regularisation method. The main condition turns out to be the behaviour of ϕ at zero. Quadratic or faster growth implies the well-posedness of the method—though slower growth is also possible if it is compensated by the weights. Linear growth of the function ϕ at zero implies that the minimisers of $\mathcal{T}_\alpha$ are necessarily sparse. Finally, we derive a linear convergence rate in the case of superlinear growth under the additional assumption that the operator A satisfies a kind of finite basis injectivity property.

2. Overview of the results

Let $\ell^2 = \ell^2(\Lambda)$ for some countable index set Λ , and let Y be some Hilbert space. We study the stable solution of the equation $Ax = y$ by means of Tikhonov regularisation, where $A: \ell^2 \rightarrow Y$ is a bounded linear operator. To that end, we choose some non-negative function $\phi: \mathbb{R} \rightarrow [0, +\infty]$ and weights w_λ satisfying $w_\lambda > 0$ for every $\lambda \in \Lambda$. Then we define the penalty term $\mathcal{R}: \ell^2 \rightarrow [0, +\infty]$ by

$$\mathcal{R}(x) = \sum_{\lambda} w_\lambda \phi(x_\lambda) \quad (1)$$

and, for $\alpha > 0$, the Tikhonov functional $\mathcal{T}_\alpha: \ell^2 \times Y \rightarrow [0, +\infty]$,

$$\mathcal{T}_\alpha(x, y) := \|Ax - y\|_Y^2 + \alpha \mathcal{R}(x).$$

The first task is to formulate conditions on ϕ and the weights w_λ that guarantee that the functional $\mathcal{T}_\alpha(\cdot, y)$ admits a minimiser for every $\alpha > 0$ and $y \in Y$. This is the case, if the functional $\mathcal{R}$ is weakly lower semi-continuous and weakly coercive; the latter condition means that $\|x\|_{\ell^2} \rightarrow \infty$ implies $\mathcal{R}(x) \rightarrow \infty$. In this paper we prove weak lower semi-continuity and weak coercivity of $\mathcal{R}$ under the following conditions (C1)–(C3) (see Propositions 3.1 and 3.3):

- (C1) The mapping $\phi: \mathbb{R} \rightarrow [0, +\infty]$ is lower semi-continuous and $\phi(0) = 0$.
- (C2) We have $\lim_{|t| \rightarrow \infty} \phi(t) = +\infty$.
- (C3) There exist $p \geq 1$ and $q \in (0, +\infty]$ satisfying $p - 1 = 1/q$ such that $(w_\lambda^{-1})_{\lambda \in \Lambda} \in \ell^q$ and, for some $C > 0$,

$$\phi(t) \geq \frac{C|t|^{2p}}{1 + |t|^{2p}} \quad \text{for every } t \in \mathbb{R}. \quad (2)$$

In addition to the sufficiency of these conditions, we investigate to which extent they are necessary for the weak lower semi-continuity and the weak coercivity of $\mathcal{R}$. We prove the necessity of conditions (C1) and (C2) and derive some necessary properties of the weights w_λ and the function ϕ (see Propositions 3.1 and 3.5).

Moreover we consider the special case where the weights w_λ are bounded above. We show that in this situation (2) has to be satisfied with $p = 1$, and thus we obtain a complete characterisation of weakly lower semi-continuous and weakly coercive functionals of the form (1) with bounded weights. This generalises and completes the results recently derived in [4], where only the case of constant weights has been treated.

Also in [4], the question has been asked, whether the functional $\mathcal{R}$ satisfies the *Radon–Riesz property*, also known as *Kadec–Klee property* (see [21]). This property requires that every sequence $(x^{(k)})_{k \in \mathbb{N}} \subset \ell^2$ that converges weakly to some $x \in \ell^2$ in such a way that $\mathcal{R}(x^{(k)}) \rightarrow \mathcal{R}(x) < \infty$ already satisfies $\|x^{(k)} - x\|_{\ell^2} \rightarrow 0$. This is important for the derivation of convergence and stability theorems for Tikhonov regularisation, as it allows one to infer results in the norm topology instead of merely the weak topology. Generalising [4], we prove in Proposition 3.6 that the Radon–Riesz property is already a consequence of conditions (C1)–(C3) and thus naturally satisfied.

As a consequence of the considerations above, it follows that, under conditions (C1)–(C3), the proposed functional $\mathcal{T}_\alpha$ satisfies the main properties of a regularisation method. The weak lower semi-continuity and weak coercivity of $\mathcal{R}$ imply the existence of minimisers for every $y \in Y$ and $\alpha > 0$ (see Proposition 4.1). The Radon–Riesz property implies stability of the method under perturbations of y and α (see Proposition 4.2). Also, it implies the convergence of minimisers x_α^δ of $\mathcal{T}_\alpha(\cdot, y^\delta)$ to solutions of $Ax = y$ provided the noise level $\delta = \|y^\delta - y\|$ and the regularisation parameter α converge to zero in a suitable manner (see Proposition 4.3). These results provide further generalisations of similar statements that have first been derived for weighted ℓ^p regularisation with $p \geq 1$ in [20,23], for ℓ^p regularisation with $0 < p < 1$ and constant weights in [15,26], and for general symmetric ϕ but constant weights in [4].

In order to enforce the sparsity of the regularised solutions, it is necessary to introduce a stronger growth condition for ϕ at zero. This condition (C3') below replaces the quadratic or slower growth of ϕ required in condition (C3) by at least linear growth. In Proposition 4.5 we prove that this condition implies the sparsity of every minimiser of the functional $\mathcal{T}_\alpha$.

- (C3') We have $\inf_\lambda w_\lambda > 0$ and there exists $C > 0$ such that

$$\phi(t) \geq \frac{C|t|}{1 + |t|} \quad \text{for every } t \in \mathbb{R}.$$

For the derivation of linear convergence rates we propose an even stronger growth condition at zero and a weak regularity condition for the function ϕ . To that end recall that the *lower Dini derivatives* of a function $\rho: \mathbb{R} \rightarrow [0, +\infty]$ at $t \in \mathbb{R}$ are defined as (see [19, Definition 17.2])

$$D_+\rho(t) = \liminf_{h \rightarrow 0^+} \frac{\rho(t+h) - \rho(t)}{h}, \quad D_-\rho(t) = \liminf_{h \rightarrow 0^-} \frac{\rho(t+h) - \rho(t)}{h}.$$

(C4) For every $t \in \mathbb{R}$ with $\phi(t) < +\infty$ we have

$$D_+\phi(t) > -\infty \quad \text{and} \quad D_-\phi(t) < +\infty.$$

Moreover,

$$D_+\phi(0) = +\infty \quad \text{and} \quad D_-\phi(0) = -\infty.$$

In addition, we require uniqueness and sparsity of the $\mathcal{R}$ -minimising solution $x^\dagger$ of the equation $Ax = y$ to be solved, and sufficient regularity of A on the support of $x^\dagger$:

(C5) The equation $Ax = y$ has a unique $\mathcal{R}$ -minimising solution $x^\dagger$. Moreover, its support $\Omega := \text{supp}(x^\dagger) := \{\lambda \in \Lambda: x_\lambda^\dagger \neq 0\}$ is finite, and the restriction of A to $\ell^2(\Omega)$ is injective.

In Theorem 5.1 we prove that conditions (C1)–(C5) imply the linear convergence of minimisers x_α^δ of $\mathcal{T}_\alpha(\cdot, y^\delta)$ to $x^\dagger$ as $\alpha \sim \delta = \|y - y^\delta\| \rightarrow 0$. Condition (C5) has first been used in [17] for the derivation of linear convergence rates for ℓ^p regularisation with $0 < p < 1$. The injectivity condition is a relaxation of the finite basis injectivity property proposed in [2,20].

Linear convergence rates for non-convex regularisation have already been derived in [4,15], albeit with a much stronger range condition, which requires that all standard basis vectors e_λ of ℓ^2 satisfy $e_\lambda \in \text{Range } A^*$. At the same time, a rate of order $O(\sqrt{\delta})$ has been proven in [26] for ℓ^p regularisation with $0 < p < 1$. There, the less restrictive condition has been assumed that there exists some $\omega \in Y$ such that $|x_\lambda^\dagger|^{2-p}(A^*\omega)_\lambda = x_\lambda^\dagger$ for every $\lambda \in \Lambda$. It has been noted in [17,22] that this range condition is a consequence of the injectivity condition required in our convergence rates result.

Now we present some examples of functions ϕ to which our results apply. For simplicity, we always assume that the chosen weights w_λ are uniformly bounded below, that is, $\inf_\lambda w_\lambda > 0$.

Example 2.1 (ℓ^r regularisation). Here,

$$\phi(t) = |t|^r \quad \text{for some } r > 0.$$

The mapping ϕ is lower semi-continuous, $\phi(0) = 0$, and $\lim_{|t| \rightarrow \infty} \phi(t) = +\infty$, proving (C1) and (C2). Condition (C3) is satisfied, if $r \leq 2$; for $r > 2$ we require in addition that $(w_\lambda^{-1})_{\lambda \in \Lambda} \in \ell^q$ with $1/q = r/2 - 1$. If $r \leq 1$, then condition (C3') holds. Finally, condition (C4) is satisfied for $r < 1$.

Example 2.2. Assume that

$$\phi(t) = \log(|t| + 1).$$

Then conditions (C1)–(C3) and (C3') are satisfied, while (C4) does not hold.

Example 2.3 (Positivity constraints). For any $\phi: \mathbb{R} \rightarrow [0, +\infty]$ define $\phi_+: \mathbb{R} \rightarrow [0, +\infty]$ by

$$\phi_+(t) := \begin{cases} \phi(t), & \text{if } t \geq 0, \\ +\infty, & \text{if } t < 0. \end{cases}$$

Regularisation with ϕ_+ therefore forces the minimisers to stay non-negative. If ϕ satisfies any of the conditions (C1)–(C4) and (C3'), then ϕ_+ satisfies the same conditions.

Example 2.4 (Hard constraints). For any $\phi: \mathbb{R} \rightarrow [0, +\infty]$ and $b \geq 0$ define $\phi_b: \mathbb{R} \rightarrow [0, +\infty]$ by

$$\phi_b(t) := \begin{cases} \phi(t), & \text{if } |t| \leq b, \\ +\infty, & \text{if } |t| > b. \end{cases}$$

This forces the minimisers x of the regularisation functional $\mathcal{T}_\alpha$ to obey the bound $\|x\|_\infty \leq b$. If ϕ satisfies any of the conditions (C1), (C3), (C3'), and (C4), then ϕ_b satisfies the same conditions. In addition, ϕ_b satisfies condition (C2).

Example 2.5 (ℓ^0 regularisation). Define

$$\phi(t) := \begin{cases} 0, & \text{if } t = 0, \\ 1, & \text{if } t \neq 0. \end{cases}$$

Then ϕ satisfies the conditions (C1), (C3), and (C4). The condition (C2), however, is not satisfied, and thus the weak coercivity of $\mathcal{R}$ does not hold.

On the other hand, if we impose in addition a hard constraint $b > 0$, that is, we replace ϕ by the functional (see Example 2.4)

$$\phi_b(t) := \begin{cases} 0, & \text{if } t = 0, \\ 1, & \text{if } 0 < |t| \leq b, \\ +\infty, & \text{if } |t| > b, \end{cases}$$

then all conditions (C1)–(C4) are met.

3. Properties of the regularisation functional

In the following, we investigate the weak lower semi-continuity and the weak coercivity of the regularisation term defined in (1). First we prove that (C1)–(C3) are sufficient conditions. Then we turn to the question of their necessity. We show that (C1) and (C2) are indeed necessary, while we can only derive condition (C3) with $p = 1$ in case the weights w_λ are assumed to be bounded. Finally, we prove that the Radon–Riesz property of $\mathcal{R}$ is a direct consequence of the conditions (C1)–(C3).

Proposition 3.1 (Lower semi-continuity). *Assume that $\mathcal{R}$ is proper. Then the following are equivalent:*

1. The mapping ϕ is lower semi-continuous.
2. The functional $\mathcal{R}$ is lower semi-continuous.
3. The functional $\mathcal{R}$ is weakly lower semi-continuous.

Proof. First note that the implication $3 \implies 2$ is trivial.

In order to show the implication $2 \implies 1$, choose some $x \in \text{Dom}(\mathcal{R})$. Let $t \in \mathbb{R}$ and $t_k \rightarrow t$. Choose some $\mu \in \Lambda$ and define $y^{(k)} \in \ell^2$ by $y_\mu^{(k)} = t_k$ and $y_\lambda^{(k)} = x_\lambda$ for $\lambda \neq \mu$. Define moreover $y \in \ell^2$ by $y_\mu = t$ and $y_\lambda = x_\lambda$ for $\lambda \neq \mu$. Then $y^{(k)} \rightarrow y$ and therefore

$$\begin{aligned} \liminf_k w_\mu \phi(t_k) &= \liminf_k [\mathcal{R}(y^{(k)}) - \mathcal{R}(x) + w_\mu \phi(x_\mu)] \\ &\geq \mathcal{R}(y) - \mathcal{R}(x) + w_\mu \phi(x_\mu) = w_\mu \phi(t). \end{aligned}$$

Thus ϕ is lower semi-continuous.

For the implication $1 \implies 3$ note that the lower semi-continuity of the mapping ϕ implies that for every finite set $\Lambda' \subset \Lambda$ the mapping $x \mapsto \sum_{\lambda \in \Lambda'} w_\lambda \phi(x_\lambda)$ is weakly lower semi-continuous. Since ϕ is non-negative, we have

$$\mathcal{R}(x) = \sum_{\lambda \in \Lambda} w_\lambda \phi(x_\lambda) = \sup \left\{ \sum_{\lambda \in \Lambda'} w_\lambda \phi(x_\lambda) : \Lambda' \subset \Lambda \text{ is finite} \right\}.$$

Therefore the mapping $\mathcal{R}$ is the supremum of a family of weakly lower semi-continuous functions and therefore itself weakly lower semi-continuous. $\square$

Remark 3.2. The argument for the proof of the implication $2 \implies 1$ is taken from [13, Theorem 6.49], where the same basic idea is applied to the study of lower semi-continuity of integral functionals on Lebesgue spaces.

Proposition 3.3 (Sufficient conditions for coercivity). *Assume that the conditions (C2) and (C3) are satisfied. Then $\mathcal{R}$ is weakly coercive.*

Proof. Let $K > 0$. Since $(w_\lambda^{-1})_{\lambda \in \Lambda} \in \ell^q$, it follows that $\inf_\lambda w_\lambda > 0$. The condition $\lim_{|t| \rightarrow \infty} \phi(t) = +\infty$ therefore implies that there exists some $L > 0$ such that

$$|t| \leq L \quad \text{whenever} \quad \inf_\lambda w_\lambda \phi(t) \leq K.$$

Now let $x \in \ell^2$ satisfy $\mathcal{R}(x) \leq K$. Then in particular $|x_\lambda| \leq L$ for every $\lambda \in \Lambda$. In case $p = 1$ and $q = +\infty$, we therefore obtain that

$$K \geq \mathcal{R}(x) = \sum_{\lambda} w_{\lambda} \phi(x_{\lambda}) \geq \frac{C \inf_{\lambda} w_{\lambda}}{1 + L^2} \sum_{\lambda} x_{\lambda}^2 = \frac{C \inf_{\lambda} w_{\lambda}}{1 + L^2} \|x\|_{\ell^2}^2,$$

which implies the weak coercivity of $\mathcal{R}$.

In case $p > 1$ and $q < +\infty$, we apply the (reverse) Hölder inequality (see for instance [19, Theorem 13.6]) to obtain the estimate

$$K \geq \mathcal{R}(x) = \sum_{\lambda} w_{\lambda} \phi(x_{\lambda}) \geq \frac{C}{1 + L^{2p}} \sum_{\lambda} w_{\lambda} |x_{\lambda}|^{2p} \geq \frac{C}{1 + L^{2p}} \left(\sum_{\lambda} w_{\lambda}^{-q} \right)^{-1/q} \left(\sum_{\lambda} x_{\lambda}^2 \right)^p.$$

Thus

$$\|x\|_{\ell^2}^{2p} \leq \frac{K(1 + L^{2p})}{C} \left(\sum_{\lambda} w_{\lambda}^{-q} \right)^{1/q},$$

which proves the assertion. $\square$

Lemma 3.4. Let $\rho: \mathbb{R} \rightarrow [0, +\infty]$ satisfy $\liminf_{t \rightarrow 0} \rho(t)/t^2 = 0$. Then there exists a sequence $(x_{\lambda})_{\lambda \in \Lambda}$ such that $\sum_{\lambda} x_{\lambda}^2 = \infty$ and $\sum_{\lambda} \rho(x_{\lambda}) < \infty$.

Proof. Assume for simplicity of notation that $\Lambda = \mathbb{N}$. Since $\liminf_{t \rightarrow 0} \rho(t)/t^2 = 0$, there exist for every $k \in \mathbb{N}$ some $t_k \in \mathbb{R}$ with $0 < |t_k| < 1$ and $\rho(t_k) < 2^{-k} t_k^2$. Choose now an increasing sequence $1 = n_1 < n_2 < \dots$ such that $1 \leq t_k^2(n_{k+1} - n_k) \leq 2$ and define $x_{\lambda} := t_k$ if $n_k \leq \lambda < n_{k+1}$. Then

$$\sum_{\lambda} x_{\lambda}^2 = \sum_k \sum_{n_k}^{n_{k+1}-1} t_k^2 \geq \sum_k (n_{k+1} - n_k) = +\infty,$$

while

$$\sum_{\lambda} \rho(x_{\lambda}) = \sum_k \sum_{n_k}^{n_{k+1}-1} \rho(t_k) \leq \sum_k \sum_{n_k}^{n_{k+1}-1} 2^{-k} t_k^2 \leq \sum_k 2^{-k+1} = 2. \quad \square$$

Proposition 3.5 (Necessary conditions for coercivity). Assume that $\mathcal{R}$ is proper and weakly coercive and that $\phi(\hat{t}) < \infty$ for some $\hat{t} \neq 0$. Then the following hold:

1. $\inf_{\lambda} w_{\lambda} > 0$.
2. $\liminf_{|t| \rightarrow 0} \phi(t) = 0$.
3. $\lim_{|t| \rightarrow \infty} \phi(t) = +\infty$.
4. For every $\varepsilon > 0$ we have $\inf_{|t| > \varepsilon} \phi(t) > 0$.
5. If $\sup_{\lambda} w_{\lambda} < +\infty$, then there exists $C > 0$ such that

$$\phi(t) \geq \frac{Ct^2}{1 + t^2} \quad \text{for every } t \in \mathbb{R}. \quad (3)$$

Proof. Let $\hat{x} \in \ell^2$ be such that $\mathcal{R}(\hat{x}) < \infty$.

In order to prove item 1 assume to the contrary that $\inf_{\lambda} w_{\lambda} = 0$. Then there exists an infinite subset $\Lambda' \subset \Lambda$ such that $\sum_{\lambda \in \Lambda'} w_{\lambda} < \infty$. For every finite subset $\Gamma \subset \Lambda$ define now $x^{(\Gamma)} \in \ell^2$ by $x_{\lambda}^{(\Gamma)} = \hat{t}$ if $\lambda \in \Gamma$ and $x_{\lambda}^{(\Gamma)} = \hat{x}_{\lambda}$ if $\lambda \notin \Gamma$. Since $\hat{t} \neq 0$, it follows that $\sup_{\Gamma} \|x^{(\Gamma)}\|_{\ell^2} = \infty$. On the other hand,

$$\mathcal{R}(x^{(\Gamma)}) = \sum_{\lambda \in \Gamma} w_{\lambda} \phi(\hat{t}) + \sum_{\lambda \notin \Gamma} w_{\lambda} \phi(\hat{x}_{\lambda}) \leq \phi(\hat{t}) \sum_{\lambda \in \Lambda'} w_{\lambda} + \mathcal{R}(\hat{x})$$

is uniformly bounded, which contradicts the coercivity of $\mathcal{R}$.

Item 2 follows from the estimate

$$\sum_{\lambda} \phi(\hat{x}_{\lambda}) \leq \frac{\mathcal{R}(\hat{x})}{\inf_{\lambda} w_{\lambda}} < \infty$$

and the fact that $\hat{x} \in \ell^2$.

Assume now to the contrary that item 3 does not hold. Then there exists a sequence t_k with $|t_k| \rightarrow \infty$ and $\sup_k \phi(t_k) =: c < \infty$. Now choose some $\mu \in \Lambda$ and define $x^{(k)} \in \ell^2$ by $x_\mu^{(k)} = t_k$ and $x_\lambda^{(k)} = \hat{x}_\lambda$ for $\lambda \neq \mu$. Then $\|x^{(k)}\|_{\ell^2} \rightarrow \infty$ while $\sup_k \mathcal{R}(x^{(k)}) \leq \mathcal{R}(\hat{x}) + c < \infty$, which is a contradiction to the coercivity of $\mathcal{R}$.

Now assume that item 4 does not hold. Then, for some $\varepsilon > 0$, there exists for every $\lambda \in \Lambda$ some $t_\lambda \in \mathbb{R}$ satisfying $|t_\lambda| \geq \varepsilon$ such that $\sum_\lambda w_\lambda \phi(t_\lambda) < \infty$. For every finite subset $\Gamma \subset \Lambda$ we define now $x^{(\Gamma)} \in \ell^2$ by $x_\lambda^{(\Gamma)} = t_\lambda$ if $\lambda \in \Gamma$ and $x_\lambda^{(\Gamma)} = \hat{x}_\lambda$ if $\lambda \notin \Gamma$. Then $\sup_\Gamma \|x^{(\Gamma)}\|_{\ell^2} = \infty$, while $\mathcal{R}(x^{(\Gamma)}) \leq \mathcal{R}(\hat{x}) + \sum_\lambda w_\lambda \phi(t_\lambda)$, again contradicting the coercivity of $\mathcal{R}$.

Now assume that $\sup_\lambda w_\lambda < +\infty$, but (3) does not hold. Since items 3 and 4 hold, this implies that $\liminf_{|t| \rightarrow 0} \phi(t)/t^2 = 0$. From Lemma 3.4 we obtain a sequence $(x_\lambda)_{\lambda \in \Lambda}$ satisfying $\sum_\lambda x_\lambda^2 = +\infty$ and $\sum_\lambda \phi(x_\lambda) =: c < +\infty$. In particular, $\mathcal{R}(x_\lambda) = \sum_\lambda w_\lambda \phi(x_\lambda) \leq c \sup_\lambda w_\lambda$, which, as above, contradicts the coercivity of $\mathcal{R}$. $\square$

Proposition 3.6 (Radon–Riesz property). Assume that conditions (C1)–(C3) hold. Let $(x^{(k)})_{k \in \mathbb{N}} \subset \ell^2$ converge weakly to $x \in \ell^2$ such that $\mathcal{R}(x^{(k)}) \rightarrow \mathcal{R}(x) < \infty$. Then $\|x^{(k)} - x\|_{\ell^2} \rightarrow 0$.

Proof. We only consider the case $p > 1$ and $q < +\infty$. The proof for $p = 1$ and $q = +\infty$ is similar.

Let $\varepsilon > 0$. There exists a finite set $\Gamma \subset \Lambda$ such that

$$\sum_{\lambda \notin \Gamma} w_\lambda \phi(x_\lambda) \leq \varepsilon \quad \text{and} \quad \sum_{\lambda \notin \Gamma} |x_\lambda|^2 \leq \varepsilon.$$

Since $x_\lambda^{(k)} \rightarrow x_\lambda$ for every $\lambda \in \Lambda$ and Γ is finite, there exists some $k_0 \in \mathbb{N}$ such that

$$\sum_{\lambda \in \Gamma} |x_\lambda^{(k)} - x_\lambda|^2 \leq \varepsilon$$

for every $k \geq k_0$. Since ϕ is lower semi-continuous, there exists $k_1 \geq k_0$ such that

$$\sum_{\lambda \in \Gamma} w_\lambda \phi(x_\lambda^{(k)}) \geq \sum_{\lambda \in \Gamma} w_\lambda \phi(x_\lambda) - \varepsilon \geq \mathcal{R}(x) - 2\varepsilon$$

for every $k \geq k_1$. Conversely, the assumption that $\mathcal{R}(x^{(k)}) \rightarrow \mathcal{R}(x)$ implies the existence of $k_2 \geq k_1$ such that

$$\mathcal{R}(x^{(k)}) \leq \mathcal{R}(x) + \varepsilon$$

for every $k \geq k_2$. Thus

$$\sum_{\lambda \notin \Gamma} w_\lambda \phi(x_\lambda^{(k)}) = \mathcal{R}(x_\lambda^{(k)}) - \sum_{\lambda \in \Gamma} w_\lambda \phi(x_\lambda^{(k)}) \leq \mathcal{R}(x) + \varepsilon - (\mathcal{R}(x) - 2\varepsilon) = 3\varepsilon$$

for every $k \geq k_2$. In particular, we have for every $k \geq k_2$ and $\lambda \notin \Gamma$ that

$$3\varepsilon \geq w_\lambda \phi(x_\lambda^{(k)}) \geq C w_\lambda \frac{(x_\lambda^{(k)})^{2p}}{1 + (x_\lambda^{(k)})^{2p}},$$

and therefore

$$(x_\lambda^{(k)})^{2p} \leq \frac{3\varepsilon}{C \inf_\lambda w_\lambda - 3\varepsilon} =: K_\varepsilon.$$

Consequently, the reverse Hölder inequality implies that

$$3\varepsilon \geq \sum_{\lambda \notin \Gamma} w_\lambda \phi(x_\lambda^{(k)}) \geq C \sum_{\lambda \notin \Gamma} w_\lambda \frac{(x_\lambda^{(k)})^{2p}}{1 + (x_\lambda^{(k)})^{2p}} \geq \frac{C}{1 + K_\varepsilon} \sum_{\lambda \notin \Gamma} w_\lambda |x_\lambda^{(k)}|^{2p} \geq \frac{C}{1 + K_\varepsilon} \left(\sum_{\lambda \in \Lambda} w_\lambda^{-q} \right)^{-1/q} \left(\sum_{\lambda \notin \Gamma} (x_\lambda^{(k)})^2 \right)^p$$

for every $k \geq k_2$, and thus

$$\sum_{\lambda \notin \Gamma} (x_\lambda^{(k)})^2 \leq \left(\frac{3(1 + K_\varepsilon)}{C} \right)^{1/p} \left(\sum_{\lambda \in \Lambda} w_\lambda^{-q} \right)^{1/pq} \varepsilon^{1/p} =: K'_\varepsilon \varepsilon^{1/p}.$$

Summarising the above estimates, we obtain that

$$\|x^{(k)} - x\|_{\ell^2}^2 \leq \sum_{\lambda \notin \Gamma} |x_\lambda^{(k)} - x_\lambda|^2 + 2 \sum_{\lambda \notin \Gamma} |x_\lambda|^2 + 2 \sum_{\lambda \notin \Gamma} |x_\lambda^{(k)}|^2 \leq 3\varepsilon + 2K'_\varepsilon \varepsilon^{1/p}$$

for every $k \geq k_2$. Since K'_ε tends to zero as $\varepsilon \rightarrow 0$, the assertion follows. $\square$

Remark 3.7. The proofs in this section have made no use of the Hilbert space structure of ℓ^2 . Indeed, each result can be formulated analogously for functionals on ℓ^r with $1 \leq r < +\infty$ by simply replacing every occurrence of the exponent 2 by r . In particular, the inequality (2) would read as

$$\phi(t) \geq \frac{C|t|^{rp}}{1 + |t|^{rp}} \quad \text{for every } t \in \mathbb{R}.$$

The same holds true for the results in Sections 4 and 5.

4. Well-posedness

Now we consider the regularising properties of the functional $\mathcal{T}_\alpha$ with $\mathcal{R}$ satisfying the conditions (C1)–(C3). These results are a consequence of the Radon–Riesz property and the weak lower semi-continuity and weak coercivity of $\mathcal{R}$. Instead of providing complete proofs, only references to [23] are given. In addition, we show that the stronger growth condition (C3') implies the sparsity of every minimiser of $\mathcal{T}_\alpha(\cdot, y)$.

Strictly speaking, the results in [23] do not apply, as there the convexity of the regularisation term $\mathcal{R}$ is assumed. Also, the stability theorem in [23] does not consider varying regularisation parameters. An inspection of the proofs, however, shows that the assumption of convexity is only needed for the derivation of convergence rates and that the stability proof still holds if also the regularisation parameter is perturbed.

Proposition 4.1 (Existence). *Assume that the conditions (C1)–(C3) hold. For every $\alpha > 0$ and $y \in Y$ the functional $\mathcal{T}_\alpha(\cdot, y)$ has a minimiser.*

Proof. See [23, Theorem 3.22]. $\square$

Proposition 4.2 (Stability). *Assume that the conditions (C1)–(C3) hold. Let $\alpha^{(k)} \rightarrow \alpha > 0$ and $y^{(k)} \rightarrow y \in Y$. Then every sequence*

$$x^{(k)} \in \arg \min \{ \mathcal{T}_{\alpha^{(k)}}(x, y^{(k)}) : x \in \ell^2 \}$$

has a subsequence $(x^{(k_i)})_{i \in \mathbb{N}}$ converging to a minimiser x_α of $\mathcal{T}_\alpha(\cdot, y)$ such that $\mathcal{R}(x^{(k_i)}) \rightarrow \mathcal{R}(x_\alpha)$. If the minimiser x_α is unique, then $x^{(k)} \rightarrow x_\alpha$.

Proof. Following the proof of [23, Theorem 3.23], we obtain a subsequence $(x^{(k_i)})_{i \in \mathbb{N}}$ weakly converging to x_α such that $\mathcal{R}(x^{(k_i)}) \rightarrow \mathcal{R}(x_\alpha)$. The norm convergence of the sequence then follows from Proposition 3.6. $\square$

Proposition 4.3 (Convergence). *Assume that the conditions (C1)–(C3) hold. Let $\alpha^{(k)} \rightarrow 0$ and $y^{(k)} \rightarrow y \in Y$ such that*

$$\frac{\|y^{(k)} - y\|^2}{\alpha^{(k)}} \rightarrow 0.$$

Assume that there exists $x \in \text{Dom } \mathcal{R}$ with $Ax = y$. Then every sequence

$$x^{(k)} \in \arg \min \{ \mathcal{T}_{\alpha^{(k)}}(x, y^{(k)}) : x \in \ell^2 \}$$

has a subsequence $(x^{(k_i)})_{i \in \mathbb{N}}$ converging to an $\mathcal{R}$ -minimising solution $x^\dagger$ of the equation $Ax^\dagger = y$ such that $\mathcal{R}(x^{(k_i)}) \rightarrow \mathcal{R}(x^\dagger)$. If the $\mathcal{R}$ -minimising solution $x^\dagger$ is unique, then $x^{(k)} \rightarrow x^\dagger$.

Proof. The weak convergence of a subsequence $(x^{(k_i)})_{i \in \mathbb{N}}$ to $x^\dagger$ together with the convergence of $(\mathcal{R}(x^{(k_i)}))_{i \in \mathbb{N}}$ to $\mathcal{R}(x^\dagger)$ follows from [23, Theorem 3.26]. The strong convergence of this sequence then follows from Proposition 3.6. $\square$

Corollary 4.4. *Assume that the conditions (C1)–(C3) hold. Let $y \in Y$ be such that the equation $Ax = y$ admits a unique $\mathcal{R}$ -minimising solution $x^\dagger$. Define the function $H : \mathbb{R}_{>0} \times \mathbb{R}_{>0} \rightarrow \mathbb{R}_{\geq 0}$,*

$$H(\alpha, \delta) := \sup \left\{ \|x_\alpha^\delta - x^\dagger\|_{\ell^2} : x_\alpha^\delta \in \arg \min_x \mathcal{T}_\alpha(x, y^\delta), \|y^\delta - y\| \leq \delta \right\}.$$

Then for every $\varepsilon > 0$ there exists $\gamma > 0$ such that $H(\alpha, \delta) < \varepsilon$ whenever $0 < \alpha < \gamma$ and $0 < \delta^2 < \alpha\gamma$.

Proof. Assume to the contrary that there exists $\varepsilon > 0$ such that for every $k \in \mathbb{N}$ there exist $0 < \alpha^{(k)} < 1/k$ and $0 < (\delta^{(k)})^2 < \alpha^{(k)}/k$ such that $H(\alpha^{(k)}, \delta^{(k)}) \geq \varepsilon$. Then the definition of H implies that there exist sequences $(y^{(k)})_{k \in \mathbb{N}}$ with $\|y^{(k)} - y\| \leq \delta^{(k)}$, and $x^{(k)} \in \arg \min_x \mathcal{T}_{\alpha^{(k)}}(x, y^{(k)})$ such that $\|x^{(k)} - x^\dagger\|_{\ell^2} \geq \varepsilon/2$ for all $k \in \mathbb{N}$. In particular, the sequence $(x^{(k)})_{k \in \mathbb{N}}$ has no subsequence converging to $x^\dagger$, which contradicts Proposition 4.3. $\square$

Proposition 4.5 (Sparsity). Assume that the conditions (C1), (C2), and (C3') hold. Let $\alpha > 0$, $y \in Y$, and $x \in \arg \min\{\mathcal{T}_\alpha(x, y) : x \in \ell^2\}$. Then x is sparse.

Proof. Define for $\mu \in \Lambda$ the sequence $\hat{x}^{(\mu)} \in \ell^2$ by

$$\hat{x}_\lambda^{(\mu)} := \begin{cases} x_\lambda, & \text{if } \lambda \neq \mu, \\ 0, & \text{if } \lambda = \mu. \end{cases}$$

Since x minimises $\mathcal{T}_\alpha(\cdot, y)$, it follows that

$$\|Ax - y\|^2 + \alpha \sum_{\lambda} w_{\lambda} \phi(x_{\lambda}) = \mathcal{T}_\alpha(x, y) \leq \mathcal{T}_\alpha(\hat{x}^{(\mu)}, y) = \|Ax - y - x_{\mu} A e_{\mu}\|^2 + \alpha \sum_{\lambda \neq \mu} w_{\lambda} \phi(x_{\lambda}).$$

Consequently,

$$\alpha w_{\mu} \phi(x_{\mu}) \leq x_{\mu}^2 \|A e_{\mu}\|^2 - 2x_{\mu} \langle A e_{\mu}, Ax - y \rangle \leq x_{\mu}^2 \|A\|^2 - 2x_{\mu} \langle e_{\mu}, A^*(Ax - y) \rangle$$

for every $\mu \in \Lambda$. With the estimate

$$C\alpha w_{\mu} \frac{|x_{\mu}|}{1 + |x_{\mu}|} \leq \alpha w_{\mu} \phi(x_{\mu})$$

we obtain therefore that

$$|x_{\mu}| \leq \frac{(1 + \|x\|_{\ell^2})(x_{\mu} \|A\|^2 - 2\langle e_{\mu}, A^*(Ax - y) \rangle)}{C\alpha \inf_{\lambda} w_{\lambda}} x_{\mu} =: K_{\mu} x_{\mu}$$

for every $\mu \in \Lambda$. Since $x \in \ell^2$ and $A^*(Ax - y) \in \ell^2$, it follows that the set $\Lambda' := \{\mu \in \Lambda : |K_{\mu}| \geq 1\}$ is finite. Since $x_{\mu} = 0$ whenever $\mu \notin \Lambda'$, this proves that x is sparse. $\square$

5. Linear convergence

Finally, we show that the strongest growth condition at zero, (C4), together with the uniqueness of $x^{\dagger}$ and the restricted injectivity of A , (C5), implies the linear convergence of minimisers x_{α}^{δ} to $x^{\dagger}$. The proof of this result closely resembles the proof of [17, Proposition 6.11], where the same convergence rate has been derived for constrained ℓ^p regularisation with $0 < p < 1$.

Theorem 5.1 (Linear convergence). Assume that conditions (C1)–(C5) hold. Define the function $H : \mathbb{R}_{>0} \times \mathbb{R}_{>0} \rightarrow \mathbb{R}_{\geq 0}$,

$$H(\alpha, \delta) := \sup \left\{ \|x_{\alpha}^{\delta} - x^{\dagger}\|_{\ell^2} : x_{\alpha}^{\delta} \in \arg \min_x \mathcal{T}_{\alpha}(x, y^{\delta}), \|y^{\delta} - y\| \leq \delta \right\}.$$

Then there exist constants $\beta_1, \beta_2 > 0$ such that

$$H(\alpha, \delta) \leq \frac{\beta_1 \delta^2}{\alpha} + \beta_2 \delta + \frac{\beta_2^2 \alpha}{4\beta_1}$$

whenever $\alpha > 0$ and $\delta^2/\alpha > 0$ are small enough.

Proof. Denote by $\pi_{\Omega}, \pi_{\Omega}^{\perp}$ the projections

$$\pi_{\Omega} x = \sum_{\lambda \in \Omega} x_{\lambda} e_{\lambda}, \quad \pi_{\Omega}^{\perp} x = \sum_{\lambda \notin \Omega} x_{\lambda} e_{\lambda}.$$

As in the proofs of [16, Theorems 14, 15] one can prove the existence of $C_1 > 0$ such that

$$\|x - x^{\dagger}\|_{\ell^2} \leq C_1 \|A(x - x^{\dagger})\| + (1 + C_1 \|A\|) \|\pi_{\Omega}^{\perp} x\|_{\ell^2} \quad (4)$$

for every $x \in \ell^2$.

Since by assumption $D_+ \phi(t) > -\infty$ and $D_- \phi(t) < +\infty$ for every $t \in \mathbb{R}$ and ϕ is bounded below by zero, there exists for every $t \in \mathbb{R}$ some $C(t) > 0$ such that

$$\phi(s) - \phi(t) \geq -C(t)|t - s|$$

for every $s \in \mathbb{R}$. Now define for $\sigma \in \{\pm 1\}^{\Omega}$ the sequence $\zeta(\sigma) \in \ell^2(\Omega)$ by $\zeta(\sigma)_{\lambda} = \text{sgn}(\sigma_{\lambda}) w_{\lambda} C(x_{\lambda}^{\dagger})$. Then

$$w_\lambda \phi(x_\lambda^\dagger) - w_\lambda \phi(t) \leq \zeta(\sigma)_\lambda (t - x_\lambda^\dagger)$$

for every $\lambda \in \Omega$ and $t \in \mathbb{R}$ with $\sigma_\lambda = \text{sgn}(t - x_\lambda^\dagger)$. In particular,

$$\max_{\sigma \in \{\pm 1\}^\Omega} |\langle \zeta(\sigma), \pi_\Omega x - \pi_\Omega x^\dagger \rangle| \geq \mathcal{R}(x^\dagger) - \mathcal{R}(\pi_\Omega x) \quad (5)$$

for every $x \in \ell^2$.

Denote now by $i_\Omega : \ell^2(\Omega) \rightarrow \ell^2(\Lambda)$ the embedding $i_\Omega x = x = \sum_{\lambda \in \Omega} x_\lambda e_\lambda$, which is the adjoint of the projection π_Ω . Then by assumption $A \circ i_\Omega : \ell^2(\Omega) \rightarrow \ell^2(\Lambda)$ is injective. Thus $(A \circ i_\Omega)^* = \pi_\Omega \circ A^* : \ell^2(\Lambda) \rightarrow \ell^2(\Omega)$ is surjective (see [25, Corollary VII.5.2]). In particular, $\zeta(\sigma) \in \text{Range}(\pi_\Omega \circ A^*)$ for every $\sigma \in \{\pm 1\}^\Omega$. Hence there exists for every $\sigma \in \{\pm 1\}^\Omega$ some $\omega(\sigma) \in Y$ such that $\pi_\Omega \circ A^* \omega(\sigma) = \zeta(\sigma)$. Denote now

$$C_2 := \max_{\sigma \in \{\pm 1\}^\Omega} \|\omega(\sigma)\|_Y.$$

Then

$$\begin{aligned} |\langle \zeta(\sigma), \pi_\Omega x - \pi_\Omega x^\dagger \rangle| &\leq |\langle A^* \omega(\sigma), x - x^\dagger \rangle| + |\langle A^* \omega(\sigma), \pi_\Omega^\perp x \rangle| \\ &\leq C_2 \|A(x - x^\dagger)\| + C_2 \|A\| \|\pi_\Omega^\perp x\|_{\ell^2}. \end{aligned}$$

Consequently, using (5),

$$C_2 \|A(x - x^\dagger)\| \geq \mathcal{R}(x^\dagger) - \mathcal{R}(\pi_\Omega x) - C_2 \|A\| \|\pi_\Omega^\perp x\|_{\ell^2}. \quad (6)$$

Since by assumption $D_+ \phi(0) = +\infty$ and $D_- \phi(0) = -\infty$, there exists $\varepsilon > 0$ such that

$$(C_2 \|A\| + 1)|t| \leq w_\lambda \phi(t) \quad \text{whenever } |t| \leq \varepsilon.$$

Thus we have for every $x \in \ell^2$ with $\|\pi_\Omega^\perp x\|_{\ell^\infty} \leq \varepsilon$ that

$$(C_2 \|A\| + 1) \|\pi_\Omega^\perp x\|_{\ell^2} \leq (C_2 \|A\| + 1) \|\pi_\Omega^\perp x\|_{\ell^1} = \sum_{\lambda \notin \Omega} (C_2 \|A\| + 1) |x_\lambda| \leq \sum_{\lambda \notin \Omega} w_\lambda \phi(x_\lambda) = \mathcal{R}(\pi_\Omega^\perp x).$$

With (6) we therefore we obtain for every $x \in \ell^2$ with $\|\pi_\Omega^\perp x\|_{\ell^\infty} \leq \varepsilon$ the estimate

$$\|\pi_\Omega^\perp x\|_{\ell^2} \leq \mathcal{R}(\pi_\Omega^\perp x) - C_2 \|A\| \|\pi_\Omega^\perp x\|_{\ell^2} \leq \mathcal{R}(x) - \mathcal{R}(x^\dagger) + C_2 \|A(x - x^\dagger)\|,$$

and thus, using (4),

$$\|x - x^\dagger\|_{\ell^2} \leq (1 + C_1 \|A\|)(\mathcal{R}(x) - \mathcal{R}(x^\dagger)) + (C_1 + (1 + C_1 \|A\|)C_2) \|A(x - x^\dagger)\|. \quad (7)$$

Define now

$$\beta_1 := 1 + C_1 \|A\|, \quad \beta_2 := C_1 + (1 + C_1 \|A\|)C_2. \quad (8)$$

From Corollary 4.4 it follows that there exists $\gamma > 0$ such that $H(\alpha, \delta) < \varepsilon$ whenever $0 < \alpha < \gamma$ and $0 < \delta^2 < \alpha\gamma$. Let these constraints hold, let $y^\delta \in Y$ satisfy $\|y - y^\delta\| \leq \delta$, and choose some $x_\alpha^\delta \in \arg \min_x \mathcal{T}_\alpha(x, y^\delta)$. Then

$$\|Ax_\alpha^\delta - y^\delta\|^2 + \alpha \mathcal{R}(x_\alpha^\delta) \leq \|Ax^\dagger - y^\delta\|^2 + \alpha \mathcal{R}(x^\dagger) \leq \delta^2 + \alpha \mathcal{R}(x^\dagger),$$

and thus

$$\mathcal{R}(x_\alpha^\delta) - \mathcal{R}(x^\dagger) \leq \frac{\delta^2 - \|Ax_\alpha^\delta - y^\delta\|^2}{\alpha}.$$

Since $\|x_\alpha^\delta - x^\dagger\|_{\ell^2} \leq H(\alpha, \delta) < \varepsilon$, we obtain using (7) and (8) that

$$\begin{aligned} \|x_\alpha^\delta - x^\dagger\| &\leq \beta_1 (\mathcal{R}(x_\alpha^\delta) - \mathcal{R}(x^\dagger)) + \beta_2 \|Ax_\alpha^\delta - y^\delta\| \\ &\leq \frac{\beta_1 \delta^2}{\alpha} - \frac{\beta_1 \|Ax_\alpha^\delta - y^\delta\|^2}{\alpha} + \beta_2 \|Ax_\alpha^\delta - y^\delta\| + \beta_2 \delta \\ &\leq \frac{\beta_1 \delta^2}{\alpha} + \beta_2 \delta + \frac{\beta_2^2 \alpha}{4\beta_1}, \end{aligned}$$

which proves the assertion. $\square$

6. Summary

In this paper, we have studied Tikhonov regularisation on ℓ^2 with general weighted penalty terms of the form $\mathcal{R}(x) = \sum_{\lambda} w_{\lambda} \phi(x_{\lambda})$. Fairly general requirements have been given that guarantee the well-posedness of the regularisation method. Moreover, under an additional boundedness assumption for the chosen weights, these requirements have been shown to be necessary for the weak lower semi-continuity and weak coercivity of the regularisation term. In particular, these conditions encompass weighted ℓ^p regularisation with $0 < p \leq 2$, but also ℓ^0 regularisation with additional hard constraints.

A central focus of this paper lies on the possible application of the considered regularisation method to the recovery of sparse sequences. We have formulated a sufficient growth condition for ϕ at zero that enforces the minimisers of the Tikhonov functional $\mathcal{T}_{\alpha}$ to be sparse. In addition, we have treated the question of convergence rates. Here we have assumed that there exists a unique $\mathcal{R}$ -minimising solution $x^{\dagger}$ of $Ax = y$, that $x^{\dagger}$ is sparse, and that A satisfies a kind of finite basis injectivity property. Requiring that ϕ has a superlinear growth at zero, we have shown that the minimisers of $\mathcal{T}_{\alpha}(\cdot, y^{\delta})$ converge linearly to $x^{\dagger}$ as $\alpha \sim \|y^{\delta} - y\| \rightarrow 0$. At the moment, these are the weakest conditions on $x^{\dagger}$ and A , under which a linear convergence rate has been derived.

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