



Available online at www.sciencedirect.com

SCIENCE @ DIRECT®

J. Math. Anal. Appl. 299 (2004) 615–629

Journal of
MATHEMATICAL
ANALYSIS AND
APPLICATIONS

www.elsevier.com/locate/jmaa

Atkinson's super-linear oscillation theorem for matrix dynamic equations on a time scale

Liuman Ou¹

Department of Mathematics Sun Yat-Sen (Zhongshan) University, Guangzhou 510275, PR China

Received 27 November 2003

Available online 16 September 2004

Submitted by J. Henderson

Abstract

By applying the Riccati technique and operator theory, we establish on a time scale \mathbb{T} both oscillation and non-oscillation criteria for Atkinson's super-linear matrix dynamic equation $X^{\Delta^2} + [X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) = 0$. These results extend and unify earlier results for the differential and difference equation case.

© 2004 Elsevier Inc. All rights reserved.

Keywords: Time scales; Riccati technique; Operator; Oscillation; Non-oscillation

1. Introduction

In 1955, Atkinson [1] proved that the second-order super-linear scalar ordinary differential equation

$$y'' + f(t)y^{2n+1} = 0, \quad t \geq 0,$$

E-mail address: ouliuman@163.com.

¹ Supported by the NNSF of PR China (No.10371135).

with $f(t) > 0$ and continuous for each $t \geq 0$, is oscillatory if and only if

$$\int_0^{\infty} t f(t) dt = \infty.$$

In 1982, Kura [2] obtained the same result for the $n \times n$ matrix differential equation

$$Y'' + (Y^m Q(t) Y^{*m}) Y = 0. \quad (1)$$

Butler and Erbe [3], and Ahlbrandt, Ridenhour and Thompson [4] have done a similar study for (1). In [4] it is shown that when $Q(t)$ is Hermitian, positive definite and continuous for each $t \geq 0$, a necessary and sufficient condition for all prepared solution of (1) which extend to infinity to be oscillatory is that

$$\int_0^{\infty} t \lambda_{\max}[Q(t)] dt = \infty.$$

Mingarelli [5] has shown that Atkinson's super-linear oscillation theorem is valid for second-order real scalar difference equations. In 1991, Allan Peterson and Jerry Ridenhour [8] used Riccati techniques to establish the necessary and sufficient condition

$$\sum_{t=1}^{\infty} t \lambda_{\max}[Q(t)] = \infty$$

for all prepared solutions of Atkinson's super-linear matrix difference equation

$$\Delta^2 Y(t-1) + [Y^n(t) Q(t) Y^{*n}(t)] Y(t) = 0$$

to be oscillatory.

In the past ten years, theory about calculus on time scales, a unified approach to continuous and discrete calculus, has been studied by many authors [6,7,11,12], etc., and many interesting results have been obtained. For example, see Hilger [6] and Agarwal and Bohner [11]. Motivated by the ideas in [1–5], we shall establish oscillation and non-oscillation criteria for Atkinson's matrix dynamic equation on a time scale.

2. Preliminaries

In this paper we are concerned with Atkinson's super-linear matrix dynamic equation

$$X^{\Delta^2} + [X^m(t) Q(t) X^{*m}(t)]^{\sigma} X^{\sigma}(t) = 0 \quad (2)$$

on a time scale \mathbb{T} . Following [6,10], we introduce the following concepts related to the notion of time scale.

Definition. A time scale \mathbb{T} is a closed subset of the set \mathbb{R} of real numbers equipped with the forward jump operator

$$\sigma(t) := \inf\{s > t, s \in \mathbb{T}\}$$

and the backward jump operator $\rho(t)$ at t for $t \in \mathbb{T}$ by

$$\rho(t) := \sup\{s < t, s \in \mathbb{T}\}.$$

We assume throughout that \mathbb{T} has the topology that it inherits from the standard topology on the real numbers \mathbb{R} . By an interval in \mathbb{T} we mean an interval in \mathbb{R} intersected with \mathbb{T} . If $\sigma(t) > t$, we say t is right-scattered, while if $\rho(t) < t$ we say t is left-scattered. If $\sigma(t) = t$ we say t is right-dense, while if $\rho(t) = t$ we say t is left-dense. A function $f : \mathbb{T} \rightarrow \mathbb{R}$ is said to be right-dense continuous provided f is continuous at right-dense points in \mathbb{T} and at left-dense points in \mathbb{T} , left-hand limits exist and are finite. We use $C_{rd}\mathbb{T}$ to denote the set of all right-dense continuous function on \mathbb{T} . If $\sup \mathbb{T} < \infty$ and $\sup \mathbb{T}$ is left-scattered, we let $\mathbb{T}^k := \mathbb{T} \setminus \{\sup \mathbb{T}\}$. Otherwise, we let $\mathbb{T}^k := \mathbb{T}$. We shall use the notation $\mu(t) := \sigma(t) - t$ which is called the graininess function. Finally, if $f : \mathbb{T} \rightarrow \mathbb{R}$ is a function, then we define the function $f^\sigma : \mathbb{T} \rightarrow \mathbb{R}$ by

$$f^\sigma(t) = f(\sigma(t))$$

for all $t \in \mathbb{T}$, i.e., $f^\sigma = f \circ \sigma$.

Definition. Assume $x : \mathbb{T} \rightarrow \mathbb{R}$ and fix $t \in \mathbb{T}$; then we define $x^\Delta(t)$ to be the number (provided it exists) with the property that given any $\varepsilon > 0$, there is a neighborhood U of t such that

$$| [x(\sigma(t)) - x(s)] - x^\Delta(t)[\sigma(t) - s] | \leq \varepsilon |\sigma(t) - s|$$

for all $s \in U$. We call $x^\Delta(t)$ the delta derivative of $x(t)$ at t .

It follows easily that if $x : \mathbb{T} \rightarrow \mathbb{R}$ is continuous at $t \in \mathbb{T}$ and t is right-scattered, then

$$x^\Delta(t) = \frac{x(\sigma(t)) - x(t)}{\sigma(t) - t}.$$

Definition. We denote by \mathcal{D} the set of all real matrix functions $X(t)$ so that each entry of $X(t)$ is delta differentiable on \mathbb{T}^k and is in $C_{cd}(\mathbb{T}^{k^2})$. $X^{\delta^2} := X^{\delta^\delta}$.

In this paper we always assume that $X(t) \in \mathcal{D}$ and that $a \in \mathbb{T}$. We assume throughout that the coefficient matrix satisfies $Q(t) > 0$, i.e., $Q(t)$ is positive definite, for all $t \in \mathbb{T}^{k^2} := (\mathbb{T}^k)^k$ and $Q(t) = Q^*(t)$, i.e., $Q(t)$ is Hermitian, for all $t \in \mathbb{T}^k$.

Definition. A solution $X(t)$ of (2) is said to be prepared if and only if $X^*(t)X^\Delta(t) = X^{\Delta*}(t)X(t)$, $t \in \mathbb{T}^k$.

Using the formulas $(fg)^\Delta = f^\Delta g + f^\sigma g^\Delta = fg^\Delta + f^\sigma g^\Delta$, one can show that for any solution $X(t)$ of (2), we have

$$X^*(t)X^\Delta(t) - X^{\Delta*}(t)X(t) = K.$$

A solution $X(t)$ is prepared only when K is the zero matrix.

Definition. Given a solution $X(t)$ of (2), the Riccati functions $W(t)$ and $V(t)$ defined by

$$W(t) := X^\Delta(t)X^{-1}(t) \quad \text{and} \quad V(t) := X^\Delta(t)X^{-1}(\sigma(t)). \quad (3)$$

Then we have the relation

$$\begin{aligned} I + \mu(t)W(t) &= X(\sigma(t))X^{-1}(t); \\ [I + \mu(t)W(t)]^{-1} &= I - \mu(t)V(t) = X(t)X^{-1}(\sigma(t)). \end{aligned}$$

Let $X(t)$ be a solution of (2). Using

$$[A(t)B(t)]^\Delta = A^\sigma(t)B^\Delta(t) + A^\Delta(t)B(t) = A^\Delta(t)B^\sigma(t) + A(t)B^\Delta(t)$$

and

$$\begin{aligned} [A^{-1}(t)]^\Delta &= -A^{-1}(t)A^\Delta(t)A^{-1}(\sigma(t)) = -A^{-1}(\sigma(t))A^\Delta(t)A^{-1}(t), \\ &\text{for invertible } A, \end{aligned}$$

it follows that

$$\begin{aligned} W^\Delta(t) &= [X^\Delta(t)X^{-1}(t)]^\Delta = X^{\Delta^2}(t)X^{-1}(\sigma(t)) + X^\Delta(t)[X^{-1}(t)]^\Delta \\ &= X^{\Delta^2}(t)X^{-1}(\sigma(t)) + X^\Delta(t)[-X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)] \\ &= X^{\Delta^2}(t)X^{-1}(\sigma(t)) - X^\Delta(t)X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma - X^\Delta(t)X^{-1}(\sigma(t))W(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma - W(t)[I + \mu(t)W(t)]^{-1}W(t), \end{aligned}$$

i.e.,

$$W^\Delta(t) + [X^m(t)Q(t)X^{*m}(t)]^\sigma + W(t)[I + \mu(t)W(t)]^{-1}W(t) = 0. \quad (4)$$

We say that (4) is the Riccati equation associated with (2).

3. Main results

Theorem 3.1. Assume that $X(t)$ is a solution of (2) on T . Then the following are equivalent:

- (i) $X(t)$ is a prepared solution;
- (ii) $X^*(t)X^\Delta(t)$ is Hermitian for all $t \in T^k$;
- (iii) $X^*(t_0)X^\Delta(t_0)$ is Hermitian for some $t_0 \in T^k$.

Proof. Assume that $X(t)$ is a solution of (2) on T . Since

$$X^*(t)X^\Delta(t) - X^{\Delta*}(t)X(t) = K$$

for $t \in T^k$, it follows that $X(t)$ is a prepared solution of (2) if and only if $X^*(t)X^\Delta(t)$ is Hermitian for all $t \in T^k$ if and only if $X^*(t_0)X^\Delta(t_0)$ is Hermitian for some $t_0 \in T^k$. \square

Lemma 3.2. *Let $X(t)$ be a solution of (2). If $X(t)$ is prepared, then $X^*(\sigma(t))X(t)$ is Hermitian for all $t \in \mathbb{T}^k$. Conversely, if there is $t_0 \in \mathbb{T}^k$ such that $\mu(t_0) > 0$ and $X^*(\sigma(t_0))X(t_0)$ is Hermitian, then $X(t)$ is a prepared solution of (2). Also, if $X(t)$ is a nonsingular prepared solution, then $X(\sigma(t))X^{-1}(t)$, $X(t)X^{-1}(\sigma(t))$, and $W(t)$ and $V(t)$ are Hermitian for all $t \in \mathbb{T}^k$.*

Proof. Let $X(t)$ be a solution of (2). The relation

$$X^*(\sigma(t))X(t) = (X(t) + \mu(t)X^\Delta(t))^* X(t) = X^*(t)X(t) + \mu(t)X^{\Delta*}(t)X(t)$$

proves the first two statements of this lemma. Now assume that $X(t)$ is a nonsingular prepared solution of (2). Then

$$\begin{aligned} X^*(\sigma(t))X(t) &= X^*(t)X(t) + \mu(t)(X^\Delta(t))^* X(t) = X^*(t)X(t) + \mu(t)X^{\Delta*}(t)X(t) \\ &= X^*(t)(X(t) + \mu(t)X^\Delta(t)) = X^*(t)X^\sigma(t), \end{aligned} \quad (5)$$

$$X^*(t)X^\Delta(t) = X^{\Delta*}(t)X(t) \quad (6)$$

by Theorem 3.1 and what we have shown above. Now multiply Eq. (5) on the left by $X^{-1}(t)$ and on the right by $(X^{-1}(t))^*$ to obtain that $X^\sigma(t)X^{-1}(t)$ is Hermitian. Next multiply Eq. (5) on the left by $(X^{-1}(\sigma(t)))^*$ and on the right by $X^{-1}(\sigma(t))$ to obtain that $X(t)X^{-1}(\sigma(t))$ is Hermitian. Finally, multiply Eq. (6) $(X^{-1}(t))^*$ from the left and with $X^{-1}(t)$ from the right shows that $W(t)$ is Hermitian. From (3) and $X(t)X^{-1}(\sigma(t))$ being Hermitian we have $V(t)$ is Hermitian. \square

Lemma 3.3. *Assume that $X(t)$ is a prepared solution of (2) on \mathbb{T} . Then the following are equivalent:*

- (i) $X^*(\sigma(t))X(t) > 0$ on \mathbb{T}^k ;
- (ii) $X(t)$ is nonsingular and $X(\sigma(t))X^{-1}(t) > 0$ on \mathbb{T}^k ;
- (iii) $X(t)$ is nonsingular and $X(t)X^{-1}(\sigma(t))$ on \mathbb{T}^k .

Proof. First note that $X^*(\sigma(t))X(t) > 0$ for $t \in \mathbb{T}^k$ implies that $X(t)$ is nonsingular for $t \in \mathbb{T}^k$. Since $X(t)$ is prepared solution, we have by Lemma 3.2 that

$$X(\sigma(t))X^{-1}(t) = (X^{-1}(t))^* X^*(\sigma(t)), \quad (7)$$

$$X(t)X^{-1}(\sigma(t)) = (X^{-1}(\sigma(t)))^* X^*(t) \quad (8)$$

on \mathbb{T}^k . We multiply the right-hand side of (7) on the right by $X(t)X^{-1}(t)$ to obtain the equivalence of (i) and (ii). For equivalence of (i) and (iii), multiply the right-hand side of (8) on the right by $X^\sigma(t)X^{-1}(\sigma(t))$. \square

Theorem 3.4. *If (2) has a prepared solution $X(t)$ such that $X(t)$ is invertible for all $t \in \mathbb{T}$, then $W(t)$ is a Hermitian solution of the matrix Riccati equation (4) on \mathbb{T}^k . Conversely, if (4) has a Hermitian solution $W(t)$ on \mathbb{T}^k , then there exists a prepared solution $X(t)$ of (4) such that $X(t)$ is invertible for all $t \in \mathbb{T}$ and relation (3) holds.*

Proof. From Lemma 3.2 the first conclusion follows. Conversely, let $W(t)$ be a Hermitian solution of (4) on \mathbb{T}^k . Let $t_0 \in \mathbb{T}$ and put $X = e_W(\cdot, t_0)$. By Theorem 5.8 in [13], X is defined because $I + \mu W$ is invertible on \mathbb{T}^k . Then X is invertible on \mathbb{T} by Theorem 5.21 [13], and we have

$$\begin{aligned} [X^\Delta(t)]^\Delta &= (W(t)X(t))^\Delta = W^\Delta(t)X^\sigma(t) + W(t)X^\Delta(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) - W(t)[I + \mu(t)W(t)]^{-1}W(t)X^\sigma(t) \\ &\quad + W(t)W(t)X(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) \\ &\quad + W(t)[I + \mu(t)W(t)]^{-1}[(I + \mu(t)W(t))W(t)X(t) - W(t)X^\sigma(t)] \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) \\ &\quad + W(t)[I + \mu(t)W(t)]^{-1}\{W(t)X(t) + \mu(t)W(t)W(t)X(t) \\ &\quad - W(t)[X(t) + \mu(t)W(t)X(t)]\} \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) \end{aligned}$$

on \mathbb{T}^k . So that $X(t)$ is a solution of (2) and $X(t)$ is indeed a prepared solution because $X^*(t)X^\Delta(t) = W(t)$ is Hermitian. \square

From Lemma 3.3 and Theorem 3.4 we have

Theorem 3.5. Equation (2) has a prepared solution $X(t)$ on \mathbb{T} with $X^*(\sigma(t))X(t) > 0$ on \mathbb{T}^k if and only if (4) has a Hermitian solution $W(t)$ on \mathbb{T}^k satisfying $I + \mu(t)W(t) > 0$ for all $t \in \mathbb{T}^k$.

Definition. Assume $a \in \mathbb{T}$ and $\sup \mathbb{T} = \infty$. We say that (2) is non-oscillatory on $[a, \infty)$ provided there is a prepared solution $X(t)$ of (2) and a $t_0 \in [a, \infty)$ such that $X^*(\sigma(t))X(t) > 0$ on $[t_0, \infty)$. Otherwise we say (2) is oscillatory on $[a, \infty)$.

We now introduce some notation that we will use in the remainder of this paper. If A is an $n \times n$ Hermitian matrix, let $\lambda_i(A)$ denote the i th eigenvalue of A so that

$$\lambda_{\max}(A) = \lambda_1(A) \geq \dots \geq \lambda_n(A) = \lambda_{\min}(A).$$

The trace of a matrix A is denoted by $\text{tr}(A) := \sum_{i=1}^n \lambda_i(A)$. We shall frequently use Weyl's theorem [9, p. 181, Theorem 4.3.1] which says if A and B are Hermitian matrices, then

$$\lambda_i(A) + \lambda_{\max}(B) \geq \lambda_i(A + B) \geq \lambda_i(A) + \lambda_{\min}(B)$$

and Ostrowski's inequalities [9, pp. 224–225] which give

$$\lambda_i(APA^*) \geq \lambda_i(P)\lambda_{\min}(AA^*) \quad \text{and} \quad \lambda_i(APA^*) \geq \lambda_i(AA^*)\lambda_{\min}(P).$$

Lemma 3.6. Suppose $X(t)$ is a non-oscillatory prepared solution of (2). Then there exists $t_0 \in \mathbb{T}^k$ such that $W(t)$ and $V(t)$ are both positive definite and decreasing for $t \in [t_0, \infty)$ with

$$\lim_{t \rightarrow \infty, t \in T} W(t) = \lim_{t \rightarrow \infty, t \in T} V(t) = 0. \quad (9)$$

Furthermore, multiplication of $W(t)$ and $V(t)$ is commutative at point where both exist and $W(t)V(t) = V(t)W(t)$ is positive definite for $t \in [t_0, \infty)$.

Proof. Since $X(t)$ is non-oscillatory and prepared, we begin by choosing $t_0 \in T^k$ so that $I + \mu(t)W(t) > 0$ for $t \in [t_0, \infty)$. Since $Q(t)$ is positive definite, we see from the Riccati equation (4), Ostrowski's inequality, and Weyl's inequality that $W^\Delta(t) < 0$ for $t \in [t_0, \infty)$. Hence by Weyl's inequality, each eigenvalue $\lambda_i[W(t)]$ ($1 \leq i \leq n$), is a decreasing function of t for $t \in [t_0, \infty)$. Furthermore, each $\lambda_i[W(t)]$ is bounded below for $t \in [t_0, \infty)$ since $I + \mu(t)W(t) > 0$, so $\lim_{t \rightarrow \infty} \lambda_i[W(t)]$ exists for $1 \leq i \leq n$. Since the eigenvalues of $I + \mu(t)W(t)$ decrease but remain positive, the eigenvalues of $[I + \mu(t)W(t)]^{-1}$ are positive and increasing for $t \in [t_0, \infty)$. From (4) and the eigenvalue inequalities mentioned above we obtain

$$\begin{aligned} \lambda_i[-W^\Delta(t)] &> \lambda_i\{W(t)[I + \mu(t)W(t)]^{-1}W(t)\} \\ &\geq \lambda_i[W^2(t)]\lambda_{\min}([I + \mu(t)W(t)]^{-1}) \\ &\geq \{\lambda_i[W(t)]\}^2\lambda_{\min}([I + \mu(t_0)W(t_0)]^{-1}) \end{aligned} \quad (10)$$

for $1 \leq i \leq n$ and $t \in [t_0, \infty)$. Now we claim

$$\lim_{t \rightarrow \infty, t \in T} \lambda_i[W(t)] = 0 \quad (11)$$

holds for $1 \leq i \leq n$. Suppose not. We choose i_0 with $1 \leq i_0 \leq n$ such that

$$\lim_{t \rightarrow \infty, t \in T} \lambda_{i_0}[W(t)] = \lambda_0 \neq 0. \quad (12)$$

Combining (10) and (12), we can choose $t_1 \in [t_0, \infty)$ and a positive number δ such that

$$\lambda_{i_0}[-W^\Delta(t)] > \delta \quad \text{for } t \in [t_1, \infty). \quad (13)$$

But

$$\begin{aligned} \lambda_{\max}[-W(t) + W(t_1)] &= \lambda_{\max}\left[\int_{t_1}^t -W^\Delta(\tau)\Delta\tau\right] \geq \frac{1}{n}\text{tr}\left[\int_{t_1}^t -W^\Delta(\tau)\Delta\tau\right] \\ &= \frac{1}{n}\int_{t_1}^t \text{tr}[-W^\Delta(\tau)]\Delta\tau \geq \frac{1}{n}\int_{t_1}^t \lambda_{i_0}[-W^\Delta(\tau)]\Delta\tau. \end{aligned}$$

By (13), this implies that $\lambda_{\max}[-W(t) + W(t_1)] \rightarrow \infty$ and $\lambda_{\max}[W(t)] \rightarrow -\infty$ as $t \rightarrow \infty$. This contradicts the fact the eigenvalues of $W(t)$ are bounded below for $t \in [t_0, \infty)$ and proves that (11) holds. Consequently, $\lim_{t \rightarrow \infty, t \in T} W(t) = 0$. Therefore, $W(t)$ is positive for $t \in [t_0, \infty)$. From (3), $\mu(t)V(t) = I - [I + \mu(t)W(t)]^{-1}$, so the eigenvalues of $V(t)$ are also positive and decreasing for $t \in [t_0, \infty)$ with $\lim_{t \rightarrow \infty} \lambda_i[V(t)] = 0$ for $1 \leq i \leq n$ showing that (9) holds.

Finally, from (3), we see that

$$[I + \mu(t)W(t)][I - \mu(t)V(t)] = I = [I - \mu(t)V(t)][I + \mu(t)W(t)],$$

from which it follows that

$$\mu(t)W(t)V(t) = \mu(t)V(t)W(t) = W(t) - V(t)$$

at all $t \in \mathbb{T}^k$ where both $W(t)$ and $V(t)$ exist. Since

$$\begin{aligned} V(t)[I + \mu(t)W(t)]V(t) &= \mu(t)V(t)W(t)V(t) + V^2(t) \\ &= [W(t) - V(t)]V(t) + V^2(t) = W(t)V(t), \end{aligned}$$

we see that $W(t)V(t) = V(t)W(t)$ is positive for $t \in [t_0, \infty)$ completing the proof of the lemma. \square

Theorem 3.7. Suppose $Q(t)$ is Hermitian and positive definite for all $t \in \mathbb{T}^k$. Then (2) is oscillatory if and only if

$$\int_a^\infty t \lambda_{\max}[Q(t)] \Delta t = \infty \quad (14)$$

holds.

Proof. First, we assume $m = 1$ in (2), the general case will be treated later. Suppose (14) holds but (2) has a non-oscillatory prepared solution $X(t)$. Applying Lemma 3.6, we choose $t_0 \in \mathbb{T}^k$ so that $X(t)$ is invertible and matrices $W(t)$, $V(t)$ and $W(t)V(t) = V(t)W(t)$ are all positive definite for $t \in [t_0, \infty)$. Then

$$\begin{aligned} [X^{-1}(t)X^{*-1}(t)]^\Delta &= [X^{-1}(t)]^\Delta X^{*-1}(\sigma(t)) + X^{-1}(t)[X^{*-1}(t)]^\Delta \\ &= -X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)X^{*-1}(\sigma(t)) \\ &\quad - X^{-1}(t)X^{*-1}(\sigma(t))X^{\Delta}(t)X^{*-1}(t) \\ &= -X^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)) - X^{-1}(t)V(t)X^{*-1}(t). \end{aligned} \quad (15)$$

Using the product rule for Δ -derivatives we have

$$\begin{aligned} [A(t)B(t)C(t)D(t)E(t)]^\Delta &= A^\sigma(t)B^\sigma(t)C^\sigma(t)D^\sigma(t)E^\Delta(t) + A^\sigma(t)B^\Delta(t)C^\sigma(t)D^\sigma(t)E(t) \\ &\quad + A^\sigma(t)B(t)C^\Delta(t)D^\sigma(t)E(t) + A^\sigma(t)B(t)C(t)D^\Delta(t)E(t) \\ &\quad + A^\Delta(t)B(t)C(t)D(t)E(t), \end{aligned}$$

and we obtain

$$\begin{aligned} [tX^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)X^{*-1}(\sigma(t))]^\Delta &= \sigma(t)X^{-1}(\sigma^2(t))X^\Delta(\sigma(t))X^{-1}(\sigma(t))[X^{*-1}(\sigma(t))]^\Delta \\ &\quad + \sigma(t)[X^{-1}(\sigma(t))]^\Delta X^\Delta(\sigma(t))X^{-1}(\sigma(t))X^{*-1}(\sigma(t)) \end{aligned}$$

$$\begin{aligned}
& + \sigma(t)X^{-1}(\sigma(t))[X^\Delta(t)]^\Delta X^{-1}(\sigma(t))X^{*-1}(\sigma(t)) \\
& + \sigma(t)X^{-1}(\sigma(t))X^\Delta(t)[X^{-1}(t)]^\Delta X^{*-1}(\sigma(t)) \\
& + X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)X^{*-1}(\sigma(t)) \\
& = -\sigma(t)X^{-1}(\sigma^2(t))W^2(\sigma(t))X^{*-1}(\sigma^2(t)) \\
& \quad - \sigma(t)X^{-1}(\sigma(t))V(\sigma(t))W(\sigma(t))X^{*-1}(\sigma(t)) - \sigma(t)Q(\sigma(t)) \\
& \quad - \sigma(t)X^{-1}(\sigma(t))V(t)W(t)X^{*-1}(\sigma(t)) + X^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)). \quad (16)
\end{aligned}$$

Applying the product rule gives

$$\begin{aligned}
& [A(t)B(t)C(t)D(t)E(t)]^\Delta \\
& = A^\sigma(t)B^\sigma(t)C^\sigma(t)D^\Delta(t)E^\sigma(t) + A^\sigma(t)B^\sigma(t)C^\Delta(t)D(t)E^\sigma(t) \\
& \quad + A^\sigma(t)B^\Delta(t)C(t)D(t)E^\sigma(t) + A^\sigma(t)B(t)C(t)D(t)E^\Delta(t) \\
& \quad + A^\Delta(t)B(t)C(t)D(t)E(t),
\end{aligned}$$

and we find that

$$\begin{aligned}
& [tX^{-1}(t)X^\Delta(t)X^{-1}(\sigma(t))X^{*-1}(t)]^\Delta \\
& = -\sigma(t)X^{-1}(\sigma(t))W(\sigma(t))V(\sigma(t))X^{*-1}(\sigma(t)) - \sigma(t)Q(\sigma(t)) \\
& \quad - \sigma(t)X^{-1}(\sigma(t))W(t)V(t)X^{*-1}(\sigma(t)) - \sigma(t)X^{-1}(t)V^2(t)X^{*-1}(t) \\
& \quad + X^{-1}(t)V(t)X^{*-1}(t). \quad (17)
\end{aligned}$$

Combining (15)–(17), we have

$$\begin{aligned}
& [X^{-1}(t)X^{*-1}(t)]^\Delta \\
& = -X^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)) - X^{-1}(t)V(t)X^{*-1}(t) \\
& = -[tX^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t))]^\Delta - [tX^{-1}(t)V(t)X^{*-1}(t)]^\Delta \\
& \quad - 2\sigma(t)Q(\sigma(t)) - \sigma(t)H(t), \quad (18)
\end{aligned}$$

where

$$\begin{aligned}
H(t) & = X^{-1}(\sigma^2(t))W^2(\sigma(t))X^{*-1}(\sigma^2(t)) + X^{-1}(t)V^2(t)X^{*-1}(t) \\
& \quad + X^{-1}(\sigma(t))[2V(\sigma(t))W(\sigma(t)) + 2V(t)W(t)]X^{*-1}(\sigma(t)).
\end{aligned}$$

Integrating both side of (18) from t_0 to t yields

$$\begin{aligned}
& \int_{t_0}^t [X^{-1}(\tau)X^{*-1}(\tau)]^\Delta \Delta\tau \\
& = - \int_{t_0}^t [\tau X^{-1}(\sigma(\tau))W(\tau)X^{*-1}(\sigma(\tau))]^\Delta \Delta\tau - 2 \int_{t_0}^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau
\end{aligned}$$

$$-\int_{t_0}^t [\tau X^{-1}(\tau) V(\tau) X^{*-1}(\tau)]^\Delta \Delta \tau - \int_{t_0}^t \sigma(\tau) H(\tau) \Delta \tau,$$

and hence

$$\begin{aligned} 2 \int_{t_0}^t \sigma(\tau) Q(\sigma(\tau)) \Delta \tau &= - \int_{t_0}^t \sigma(\tau) H(\tau) \Delta \tau - X^{-1}(t) X^{*-1}(t) \\ &\quad - t X^{-1}(\sigma(t)) W(t) X^{*-1}(\sigma(t)) \\ &\quad - t X^{-1}(t) V(t) X^{*-1}(t) + C, \end{aligned} \quad (19)$$

where C is a constant Hermitian matrix.

Now all the terms except C on the right-hand side of (19) are negative definite for all $t \in [t_0, \infty)$, and consequently there is a real constant M_1 such that

$$\lambda_{\max} \left[\int_{t_0}^t \sigma(\tau) Q(\sigma(\tau)) \Delta \tau \right] \leq M_1 \quad \text{for } t \in [\sigma(t_0), \infty).$$

By Weyl's inequality, there is another constant M_2 so that

$$\lambda_{\max} \left[\int_a^t \sigma(\tau) Q(\sigma(\tau)) \Delta \tau \right] \leq M_2 \quad \text{for } t \in [\sigma(t_0), \infty). \quad (20)$$

However,

$$\begin{aligned} \lambda_{\max} \left[\int_a^t \sigma(\tau) Q(\sigma(\tau)) \Delta \tau \right] &\geq \frac{1}{n} \operatorname{tr} \left[\int_a^t \sigma(\tau) Q(\sigma(\tau)) \Delta \tau \right] \\ &= \frac{1}{n} \int_a^t \operatorname{tr} [\sigma(\tau) Q(\sigma(\tau))] \Delta \tau \\ &\geq \frac{1}{n} \int_a^t \lambda_{\max} [\sigma(\tau) Q(\sigma(\tau))] \Delta \tau. \end{aligned}$$

By (14), $\int_a^t \lambda_{\max} [\sigma(\tau) Q(\sigma(\tau))] \Delta \tau \rightarrow \infty$ as $t \rightarrow \infty$ contradicting (20). This proves that (14) is a sufficient condition for (2) to be oscillatory in the case $m = 1$.

Next, we will prove the general case. Suppose (14) holds but there is a positive integer m such that (2) has a prepared non-oscillatory solution $X_0(t)$. Since $X_0(t)$ is non-oscillatory, we choose $t_0 \in [a, \infty)$ such that $X_0(t)$ is invertible for $t \in [t_0, \infty)$ and $W_0(t)$ and $V_0(t)$ are positive definite for $t \in [t_0, \infty)$. Set

$$Q_0(t) = X_0^{m-1}(\sigma(t)) Q(\sigma(t)) X_0^{*-m-1}(\sigma(t)), \quad t \in [t_0, \infty).$$

It is not difficult to verify that $Q_0(t)$ is Hermitian and positive definite for $t \in [t_0, \infty)$ and $X_0(t)$ is also a non-oscillatory prepared solution of

$$X^{\Delta^2} + X(\sigma(t))Q_0(t)X^*(\sigma(t))X(\sigma(t)) = 0, \quad t \in [t_0, \infty). \quad (21)$$

So $X_0^*(t)X_0(t)$ and $X_0(t)X_0^*(t)$ have the same eigenvalues; furthermore, we have

$$\begin{aligned} [X_0^*(t)X_0(t)]^\Delta &= X_0^*(\sigma(t))X_0^\Delta(t) + X_0^{*\Delta}(t)X_0(t) \\ &= X_0^*(\sigma(t))V_0(t)X_0(\sigma(t)) + X_0^*(t)W_0(t)X_0(t). \end{aligned}$$

It follows that $[X_0^*(t)X_0(t)]^\Delta > 0$ for $t \in [t_0, \infty)$, so the eigenvalues of $X_0(t)X_0^*(t)$ are increasing. Hence we can choose a positive real number δ so that $\lambda_{\min}[X_0(t)X_0^*(t)] > \delta$ for $t \in [t_0, \infty)$. By Ostrowski's inequality

$$\lambda_{\max}[Q_0(t)] \geq \lambda_{\max}[Q(\sigma(t))]\delta^{m-1} \quad \text{for } t \in [t_0, \infty).$$

Hence $Q_0(t)$ is Hermitian and positive definite for $t \in [t_0, \infty)$ with

$$\int_a^\infty t \lambda_{\max}[Q_0(t)] \Delta t = \infty.$$

So $X_0(t)$ is oscillatory solution of (20), even though $Q_0(t)$ may only be positive semi-definite rather than positive definite for $t \in [a, t_0)$, it is clear from the first part of the proof that (21) is oscillatory. Since $X_0(t)$ is a non-oscillatory solution, we get a contradiction. This completes the proof that (2) is oscillatory if (14) holds.

Now we prove that (14) is a necessary condition if (14) is to be oscillatory. Suppose that

$$\int_a^\infty t \lambda_{\max}[Q(t)] \Delta t < \infty.$$

We need to show that there is at least one non-oscillatory prepared solution $X(t)$ of (14). Here we recall some facts from [9] that will be used in what follows. Let M_n denote the set of $n \times n$ complex matrices, $|x|$ denote the modulus of the complex number x , and let A_{ij} denote the entry in the i th row and j th column of a matrix A . Let $\|\cdot\|_\infty$, $\|\cdot\|_1$ and $\|\cdot\|_2$ be the matrix norms on M_n induced by the l_∞ , l_1 , and l_2 , respectively. Then $\|\cdot\|_\infty$ is the maximum row sum norm, $\|\cdot\|_1$ is the maximum column sum norm, and $\|\cdot\|_2$ is the spectral norm with $\|A\|_2 = [\lambda_{\max}(AA^*)]^{1/2}$ for $A \in M_n$. $\|H\|_2 = \lambda_{\max}(H)$ when H is Hermitian and positive semi-definite. The relations

$$\|A\|_\infty \leq \sqrt{n}\|A\|_2, \quad \|A\|_1 \leq \sqrt{n}\|A\|_2, \quad \|A\|_1 \leq n\|A\|_\infty$$

hold for all $A \in M_n$.

Let $t_0 \in T$ be a fixed point. We define an $n \times n$ complex matrix-valued function $X(t)$ for $t \in [t_0, \infty)$ by

$$X(t) = I - \int_{\sigma(t)}^\infty (s-t)[X^m(s)Q(s)X^{*m}(s)]X(s)\Delta s \quad (22)$$

which satisfies (2) for $t \in [a, \infty)$. In the following discussion we use operator theory to show that $X(t)$ is a prepared non-oscillatory solution of (2). From the assumption, we choose $t_0 \in [a, \infty)$ so large that

$$\int_{\sigma(t_0)}^{\infty} s \lambda_{\max}[Q(s)] \Delta s < n^{-1/2} 2^{-2m} \left(\frac{3m}{2} + 1 \right)^{-1}. \quad (23)$$

Let H_{t_0} denote the set of all $n \times n$ complex matrix-valued functions $Z(t)$ defined for $t \in [t_0, \infty)$ and such that $\lim_{t \rightarrow \infty} Z(t)$ exists as a finite matrix. For $Z \in H_{t_0}$, let

$$\|Z\| = \sup_{t \in [t_0, \infty)} \|Z(t)\|_{\infty}.$$

H_{t_0} equipped with this norm is a Banach space. Let $\mathcal{A} = \{Z \in H_{t_0} : \|Z - I\| \leq 1\}$. Then \mathcal{A} is a nonempty closed subset of H_{t_0} . Define TX by

$$TX(t) = I - \int_{\sigma(t)}^{\infty} (s-t) [X^m(s) Q(s) X^{*m}(s)] X(s) \Delta s \quad \text{for } X \in \mathcal{A}. \quad (24)$$

Then for $X \in \mathcal{A}$, and $s \geq t$,

$$\begin{aligned} & |[(s-t) X^m(s) Q(s) X^{*m}(s) X(s)]_{ij} | \\ & \leq \| (s-t) X^m(s) Q(s) X^{*m}(s) X(s) \|_{\infty} \\ & \leq s \|X(s)\|_{\infty}^{m+1} \|X^m(s)\|_{\infty} \|Q(s)\|_{\infty} \leq s \|X\|^{m+1} \|X^m(s)\|_{\infty} \sqrt{n} \|Q(s)\|_2 \\ & \leq 2^{2m+1} n^{1/2} s \lambda_{\max}[Q(s)]. \end{aligned} \quad (25)$$

From (25), we see that the integral on the right-hand side of (24) is convergent as $t \rightarrow \infty$. Moreover, from (23) and (24) we see that, for $t \in [t_0, \infty)$,

$$\|TX(t) - I\|_{\infty} \leq 2^{2m+1} n^{1/2} \int_{\sigma(t_0)}^{\infty} s \lambda_{\max}[Q(s)] \Delta s < 1,$$

so $\|TX - I\| \leq 1$, that is, $TX(t) \in \mathcal{A}$. Thus T is a mapping from \mathcal{A} into \mathcal{A} . For X and Y both in \mathcal{A} , we have

$$\begin{aligned} & |[TX(t) - TY(t)]_{ij}| \\ & \leq \int_{\sigma(t_0)}^{\infty} s \|X^m(s) Q(s) X^{*m}(s) X(s) - Y^m(s) Q(s) Y^{*m}(s) Y(s)\|_{\infty} \Delta s. \end{aligned} \quad (26)$$

Shortening the notation in a self-evident way,

$$\begin{aligned} & \|X^m Q X^{*m} X - Y^m Q Y^{*m} Y\|_{\infty} \\ & \leq \|X^m Q X^{*m} X - X^m Q X^{*m} Y\|_{\infty} + \|X^m Q X^{*m} Y - Y^m Q Y^{*m} Y\|_{\infty} \\ & \quad + \|X^m Q Y^{*m} Y - Y^m Q Y^{*m} Y\|_{\infty} \end{aligned}$$

$$\begin{aligned} &\leq \|X\|_{\infty}^m \sqrt{n} \lambda_{\max}[Q] \|X^m\|_{\infty} \|X - Y\|_{\infty} + \|X^m\|_{\infty} \sqrt{n} \lambda_{\max}[Q] \|X^m \\ &\quad - Y^m\|_{\infty} \|Y\|_{\infty} + \|X^m - Y^m\|_{\infty} \sqrt{n} \lambda_{\max}[Q] \|Y\|_{\infty}^{m+1} \end{aligned} \quad (27)$$

and

$$\begin{aligned} &\|X^m - Y^m\|_{\infty} \\ &\leq \|X^m - X^{m-1}Y\|_{\infty} + \|X^{m-1}Y - X^{m-2}Y^2\|_{\infty} + \cdots + \|XY^{m-1} - Y^m\|_{\infty} \\ &\leq \|X^{m-1}(X - Y)\|_{\infty} + \|X^{m-2}(X - Y)Y\|_{\infty} + \cdots + \|(X - Y)X^{m-1}\|_{\infty} \\ &\leq m2^{m-1} \|X - Y\|_{\infty}. \end{aligned} \quad (28)$$

Combining (27) and (28) yields

$$\|X^m Q X^{*m} X - Y^m Q Y^{*m} Y\|_{\infty} \leq \left(\frac{3m}{2} + 1\right) 2^{2m} n^{1/2} \lambda_{\max}[Q] \|X - Y\|_{\infty}. \quad (29)$$

From (26) and (29) we find

$$\|TX - TY\| \leq \left[\left(\frac{3m}{2} + 1\right) 2^{2m} n^{1/2} \int_{\sigma(t_0)}^{\infty} s \lambda_{\max}(Q(s)) \Delta s\right] \|X - Y\|.$$

Therefore, from (23) it follows that $T : \mathcal{A} \rightarrow \mathcal{A}$ is a contraction mapping. Consequently, there is a solution $X(t)$ of (24) which is also a solution of (2) for $t \in [t_0, \infty)$. Extending this solution backward to $t = a$, we obtain a solution satisfying (2) for $t \in [a, \infty)$. Since

$$\lim_{t \rightarrow \infty} X(t) = I \quad \text{and} \quad \lim_{t \rightarrow \infty} X^{\Delta}(t) = 0,$$

it follows that $X(t)$ is a prepared solution of (2). Finally,

$$\lim_{t \rightarrow \infty} W(t) = \lim_{t \rightarrow \infty} X^{\Delta}(t) X^{-1}(t) = 0.$$

So $\lim_{t \rightarrow \infty} [W(t) + I] = I$ making $X(t)$ a non-oscillatory solution of (2). This completes the proof of Theorem 3.7. \square

4. Examples

The following examples illustrate the applications of our oscillation criteria.

Example 1. Consider the second-order matrix system (2) on time scale $\mathbb{T} = h\mathbb{Z} = \{hk : k \in \mathbb{Z}\}$ ($h > 0$); where

$$Q(t) = \begin{pmatrix} t+2 & 0 \\ 0 & 3 \end{pmatrix}.$$

For $t \in \mathbb{T}$; $\sigma(t) = t+h$; $\mu(t) = h$. Let $t_0 \in \mathbb{T}$ be given and pick $k_0 \in \mathbb{Z}$ so that $a := hk_0 > t_0$. For $t \in \mathbb{T}$; consider

$$\begin{aligned}\int_a^\infty (t+h)(t+h+2)\Delta t &= \sum_{j=k_0}^\infty (hj+h)(hj+h+2) \\ &= h^2 \sum_{j=k_0}^\infty \left[(j+1)^2 + \frac{2}{h}(j+h) \right] = \infty.\end{aligned}$$

Hence from Theorem 3.7, we get that this equation is oscillatory on \mathbb{T} .

Example 2. It will show that the q -difference equation

$$X^{\Delta^2}(t) + [X^m(t)q(q-1)t^2 X^{*m}(t)]^\sigma X(\sigma(t)) = 0$$

is oscillatory on $\mathbb{T} = q^{\mathbb{N}_0}$, where $q > 1$ is a constant. In fact, $t_0 \in [1; \infty)$ is given and pick $k_0 \in \mathbb{N}$ so that $a := q^{k_0} > t_0$. For $t \in \mathbb{T}$; let

$$\bar{Q}(t) = \sigma(t)\lambda_{\max}[Q(\sigma(t))] = qt \frac{1}{q(q-1)(qt)^2} = \frac{1}{q^2(q-1)t}$$

and

$$\begin{aligned}\int_a^{n'} \bar{Q}(t)\Delta t &= \int_{q^{k_0}}^{q^n} \bar{Q}(t)\Delta t = \sum_{j=k_0}^n \bar{Q}(q^j)\mu(q^j) = \sum_{j=k_0}^n \frac{1}{(q-1)q^{j+2}}(q-1)q^j \\ &= \sum_{j=k_0}^n \frac{1}{q^2} = \frac{1}{2q^2}(n+k_0)(n-k_0+1) = \frac{n^2+n-k_0^2+k}{2q^2} = \infty.\end{aligned}$$

Since $\lim_{n \rightarrow \infty} \frac{n^2+n-k_0^2+k}{2q^2} = \infty$. That is $\int_a^\infty \sigma(t)\lambda_{\max}[Q(\sigma(t))]\Delta t = \infty$.

Remark. When $\mathbb{T} = \mathbb{R}$ and $\mathbb{T} = \mathbb{Z}$, argument in this paper is just as [4,8], respectively.

Acknowledgments

The authors are grateful to the respectable Prof. R. Mathsen and Dr. Qiru Wang for their valuable work on this paper.

References

- [1] F.V. Atkinson, On second-order non-linear oscillation, *Pacific J. Math.* 5 (1955) 643–647.
- [2] T. Kura, A matrix analogue of Atkinson's oscillation theorem, *Funkcial Ekval.* 25 (1982) 223–226.
- [3] G.J. Butler, L.H. Erbe, Oscillation theorems for second order differential systems with functionally commutative matrix coefficients, *Funkcial Ekval.* 28 (1985) 47–55.
- [4] C.D. Ahlbrandt, J. Ridenhour, R.C. Thompson, Oscillation of superlinear matrix differential equation, *Proc. Amer. Math. Soc.* 105 (1989) 141–148.
- [5] A.B. Mingarelli, Volterra–Stieltjes integral equations and generalized ordinary differential expressions, *Lecture Notes in Math.*, vol. 989, Springer-Verlag, Berlin, 1983.

- [6] S. Hilger, Analysis on measure chain—a unified approach to continuous and discrete calculus, *Results Math.* 183 (1990) 18–56.
- [7] L. Erbe, A. Peterson, Oscillation criteria for second-order matrix dynamic equations on a time scale, *J. Comput. Appl. Math.* 141 (2002) 169–186.
- [8] A. Peterson, J. Ridenhour, Atkinson’s superlinear oscillation theorem for matrix difference equations, *SIAM J. Math. Anal.* 22 (1991) 774–784.
- [9] R.A. Horn, C.R. Johnson, *Matrix Analysis*, Cambridge Univ. Press, Cambridge, 1991.
- [10] M. Bohner, A. Peterson, *Dynamic Equations on Time Scales*, Birkhäuser, Boston, 2001.
- [11] R. Agarwal, M. Bohner, Quadratic functional for second order matrix equation on time scales, *Nonlinear Anal.* 33 (1998) 675–692.
- [12] R. Agarwal, M. Bohner, P. Wong, Sturm–Liouville eigenvalue problems on time scales, *Appl. Math. Comput.* 99 (1999) 153–166.
- [13] M. Bohner, A. Peterson, *Dynamic Equations on Time Scales: An Introduction and Applications*, Birkhäuser, Boston, 2001.