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Atkinson's super-linear oscillation theorem for matrix dynamic equations on a time scale

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Abstract

By applying the Riccati technique and operator theory, we establish on a time scale \mathbb{T} both oscillation and non-oscillation criteria for Atkinson's super-linear matrix dynamic equation $X^{\Delta^2} + [X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) = 0$. These results extend and unify earlier results for the differential and difference equation case.

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1. Introduction

In 1955, Atkinson [1] proved that the second-order super-linear scalar ordinary differential equation

$$y'' + f(t)y^{2n+1} = 0, \quad t \geq 0,$$

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with $f(t) > 0$ and continuous for each $t \geq 0$, is oscillatory if and only if

$$\int_0^{\infty} t f(t) dt = \infty.$$

In 1982, Kura [2] obtained the same result for the $n \times n$ matrix differential equation

$$Y'' + (Y^m Q(t) Y^{*m}) Y = 0. \quad (1)$$

Butler and Erbe [3], and Ahlbrandt, Ridenhour and Thompson [4] have done a similar study for (1). In [4] it is shown that when $Q(t)$ is Hermitian, positive definite and continuous for each $t \geq 0$, a necessary and sufficient condition for all prepared solution of (1) which extend to infinity to be oscillatory is that

$$\int_0^{\infty} t \lambda_{\max}[Q(t)] dt = \infty.$$

Mingarelli [5] has shown that Atkinson's super-linear oscillation theorem is valid for second-order real scalar difference equations. In 1991, Allan Peterson and Jerry Ridenhour [8] used Riccati techniques to establish the necessary and sufficient condition

$$\sum_{t=1}^{\infty} t \lambda_{\max}[Q(t)] = \infty$$

for all prepared solutions of Atkinson's super-linear matrix difference equation

$$\Delta^2 Y(t-1) + [Y^n(t) Q(t) Y^{*n}(t)] Y(t) = 0$$

to be oscillatory.

In the past ten years, theory about calculus on time scales, a unified approach to continuous and discrete calculus, has been studied by many authors [6,7,11,12], etc., and many interesting results have been obtained. For example, see Hilger [6] and Agarwal and Bohner [11]. Motivated by the ideas in [1–5], we shall establish oscillation and non-oscillation criteria for Atkinson's matrix dynamic equation on a time scale.

2. Preliminaries

In this paper we are concerned with Atkinson's super-linear matrix dynamic equation

$$X^{\Delta^2} + [X^m(t) Q(t) X^{*m}(t)]^{\sigma} X^{\sigma}(t) = 0 \quad (2)$$

on a time scale \mathbb{T} . Following [6,10], we introduce the following concepts related to the notion of time scale.

Definition. A time scale \mathbb{T} is a closed subset of the set \mathbb{R} of real numbers equipped with the forward jump operator

$$\sigma(t) := \inf\{s > t, s \in \mathbb{T}\}$$

and the backward jump operator $\rho(t)$ at t for $t \in \mathbb{T}$ by

$$\rho(t) := \sup\{s < t, s \in \mathbb{T}\}.$$

We assume throughout that \mathbb{T} has the topology that it inherits from the standard topology on the real numbers \mathbb{R} . By an interval in \mathbb{T} we mean an interval in \mathbb{R} intersected with \mathbb{T} . If $\sigma(t) > t$, we say t is right-scattered, while if $\rho(t) < t$ we say t is left-scattered. If $\sigma(t) = t$ we say t is right-dense, while if $\rho(t) = t$ we say t is left-dense. A function $f : \mathbb{T} \rightarrow \mathbb{R}$ is said to be right-dense continuous provided f is continuous at right-dense points in \mathbb{T} and at left-dense points in \mathbb{T} , left-hand limits exist and are finite. We use $C_{rd}\mathbb{T}$ to denote the set of all right-dense continuous function on \mathbb{T} . If $\sup \mathbb{T} < \infty$ and $\sup \mathbb{T}$ is left-scattered, we let $\mathbb{T}^k := \mathbb{T} \setminus \{\sup \mathbb{T}\}$. Otherwise, we let $\mathbb{T}^k := \mathbb{T}$. We shall use the notation $\mu(t) := \sigma(t) - t$ which is called the graininess function. Finally, if $f : \mathbb{T} \rightarrow \mathbb{R}$ is a function, then we define the function $f^\sigma : \mathbb{T} \rightarrow \mathbb{R}$ by

$$f^\sigma(t) = f(\sigma(t))$$

for all $t \in \mathbb{T}$, i.e., $f^\sigma = f \circ \sigma$.

Definition. Assume $x : \mathbb{T} \rightarrow \mathbb{R}$ and fix $t \in \mathbb{T}$; then we define $x^\Delta(t)$ to be the number (provided it exists) with the property that given any $\varepsilon > 0$, there is a neighborhood U of t such that

$$|[x(\sigma(t)) - x(s)] - x^\Delta(t)[\sigma(t) - s]| \leq \varepsilon |\sigma(t) - s|$$

for all $s \in U$. We call $x^\Delta(t)$ the delta derivative of $x(t)$ at t .

It follows easily that if $x : \mathbb{T} \rightarrow \mathbb{R}$ is continuous at $t \in \mathbb{T}$ and t is right-scattered, then

$$x^\Delta(t) = \frac{x(\sigma(t)) - x(t)}{\sigma(t) - t}.$$

Definition. We denote by \mathcal{D} the set of all real matrix functions $X(t)$ so that each entry of $X(t)$ is delta differentiable on \mathbb{T}^k and is in $C_{cd}(\mathbb{T}^{k^2})$. $X^{\delta^2} := X^{\delta^\delta}$.

In this paper we always assume that $X(t) \in \mathcal{D}$ and that $a \in \mathbb{T}$. We assume throughout that the coefficient matrix satisfies $Q(t) > 0$, i.e., $Q(t)$ is positive definite, for all $t \in \mathbb{T}^{k^2} := (\mathbb{T}^k)^k$ and $Q(t) = Q^*(t)$, i.e., $Q(t)$ is Hermitian, for all $t \in \mathbb{T}^k$.

Definition. A solution $X(t)$ of (2) is said to be prepared if and only if $X^*(t)X^\Delta(t) = X^{\Delta^*}(t)X(t)$, $t \in \mathbb{T}^k$.

Using the formulas $(fg)^\Delta = f^\Delta g + f^\sigma g^\Delta = fg^\Delta + f^\sigma g^\Delta$, one can show that for any solution $X(t)$ of (2), we have

$$X^*(t)X^\Delta(t) - X^{\Delta^*}(t)X(t) = K.$$

A solution $X(t)$ is prepared only when K is the zero matrix.

Definition. Given a solution $X(t)$ of (2), the Riccati functions $W(t)$ and $V(t)$ defined by

$$W(t) := X^\Delta(t)X^{-1}(t) \quad \text{and} \quad V(t) := X^\Delta(t)X^{-1}(\sigma(t)). \quad (3)$$

Then we have the relation

$$\begin{aligned} I + \mu(t)W(t) &= X(\sigma(t))X^{-1}(t); \\ [I + \mu(t)W(t)]^{-1} &= I - \mu(t)V(t) = X(t)X^{-1}(\sigma(t)). \end{aligned}$$

Let $X(t)$ be a solution of (2). Using

$$[A(t)B(t)]^\Delta = A^\sigma(t)B^\Delta(t) + A^\Delta(t)B(t) = A^\Delta(t)B^\sigma(t) + A(t)B^\Delta(t)$$

and

$$[A^{-1}(t)]^\Delta = -A^{-1}(t)A^\Delta(t)A^{-1}(\sigma(t)) = -A^{-1}(\sigma(t))A^\Delta(t)A^{-1}(t),$$

for invertible A ,

it follows that

$$\begin{aligned} W^\Delta(t) &= [X^\Delta(t)X^{-1}(t)]^\Delta = X^{\Delta^2}(t)X^{-1}(\sigma(t)) + X^\Delta(t)[X^{-1}(t)]^\Delta \\ &= X^{\Delta^2}(t)X^{-1}(\sigma(t)) + X^\Delta(t)[-X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)] \\ &= X^{\Delta^2}(t)X^{-1}(\sigma(t)) - X^\Delta(t)X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma - X^\Delta(t)X^{-1}(\sigma(t))W(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma - W(t)[I + \mu(t)W(t)]^{-1}W(t), \end{aligned}$$

i.e.,

$$W^\Delta(t) + [X^m(t)Q(t)X^{*m}(t)]^\sigma + W(t)[I + \mu(t)W(t)]^{-1}W(t) = 0. \quad (4)$$

We say that (4) is the Riccati equation associated with (2).

3. Main results

Theorem 3.1. Assume that $X(t)$ is a solution of (2) on T . Then the following are equivalent:

- (i) $X(t)$ is a prepared solution;
- (ii) $X^*(t)X^\Delta(t)$ is Hermitian for all $t \in T^k$;
- (iii) $X^*(t_0)X^\Delta(t_0)$ is Hermitian for some $t_0 \in T^k$.

Proof. Assume that $X(t)$ is a solution of (2) on T . Since

$$X^*(t)X^\Delta(t) - X^{\Delta*}(t)X(t) = K$$

for $t \in T^k$, it follows that $X(t)$ is a prepared solution of (2) if and only if $X^*(t)X^\Delta(t)$ is Hermitian for all $t \in T^k$ if and only if $X^*(t_0)X^\Delta(t_0)$ is Hermitian for some $t_0 \in T^k$. \square

Lemma 3.2. *Let $X(t)$ be a solution of (2). If $X(t)$ is prepared, then $X^*(\sigma(t))X(t)$ is Hermitian for all $t \in \mathbb{T}^k$. Conversely, if there is $t_0 \in \mathbb{T}^k$ such that $\mu(t_0) > 0$ and $X^*(\sigma(t_0))X(t_0)$ is Hermitian, then $X(t)$ is a prepared solution of (2). Also, if $X(t)$ is a nonsingular prepared solution, then $X(\sigma(t))X^{-1}(t)$, $X(t)X^{-1}(\sigma(t))$, and $W(t)$ and $V(t)$ are Hermitian for all $t \in \mathbb{T}^k$.*

Proof. Let $X(t)$ be a solution of (2). The relation

$$X^*(\sigma(t))X(t) = (X(t) + \mu(t)X^\Delta(t))^* X(t) = X^*(t)X(t) + \mu(t)X^{\Delta^*}(t)X(t)$$

proves the first two statements of this lemma. Now assume that $X(t)$ is a nonsingular prepared solution of (2). Then

$$\begin{aligned} X^*(\sigma(t))X(t) &= X^*(t)X(t) + \mu(t)(X^\Delta(t))^* X(t) = X^*(t)X(t) + \mu(t)X^{\Delta^*}(t)X(t) \\ &= X^*(t)(X(t) + \mu(t)X^\Delta(t)) = X^*(t)X^\sigma(t), \end{aligned} \tag{5}$$

$$X^*(t)X^\Delta(t) = X^{\Delta^*}(t)X(t) \tag{6}$$

by Theorem 3.1 and what we have shown above. Now multiply Eq. (5) on the left by $X^{-1}(t)$ and on the right by $(X^{-1}(t))^*$ to obtain that $X^\sigma(t)X^{-1}(t)$ is Hermitian. Next multiply Eq. (5) on the left by $(X^{-1}(\sigma(t)))^*$ and on the right by $X^{-1}(\sigma(t))$ to obtain that $X(t)X^{-1}(\sigma(t))$ is Hermitian. Finally, multiply Eq. (6) $(X^{-1}(t))^*$ from the left and with $X^{-1}(t)$ from the right shows that $W(t)$ is Hermitian. From (3) and $X(t)X^{-1}(\sigma(t))$ being Hermitian we have $V(t)$ is Hermitian. \square

Lemma 3.3. *Assume that $X(t)$ is a prepared solution of (2) on \mathbb{T} . Then the following are equivalent:*

- (i) $X^*(\sigma(t))X(t) > 0$ on \mathbb{T}^k ;
- (ii) $X(t)$ is nonsingular and $X(\sigma(t))X^{-1}(t) > 0$ on \mathbb{T}^k ;
- (iii) $X(t)$ is nonsingular and $X(t)X^{-1}(\sigma(t))$ on \mathbb{T}^k .

Proof. First note that $X^*(\sigma(t))X(t) > 0$ for $t \in \mathbb{T}^k$ implies that $X(t)$ is nonsingular for $t \in \mathbb{T}^k$. Since $X(t)$ is prepared solution, we have by Lemma 3.2 that

$$X(\sigma(t))X^{-1}(t) = (X^{-1}(t))^* X^*(\sigma(t)), \tag{7}$$

$$X(t)X^{-1}(\sigma(t)) = (X^{-1}(\sigma(t)))^* X^*(t) \tag{8}$$

on \mathbb{T}^k . We multiply the right-hand side of (7) on the right by $X(t)X^{-1}(t)$ to obtain the equivalence of (i) and (ii). For equivalence of (i) and (iii), multiply the right-hand side of (8) on the right by $X^\sigma(t)X^{-1}(\sigma(t))$. \square

Theorem 3.4. *If (2) has a prepared solution $X(t)$ such that $X(t)$ is invertible for all $t \in \mathbb{T}$, then $W(t)$ is a Hermitian solution of the matrix Riccati equation (4) on \mathbb{T}^k . Conversely, if (4) has a Hermitian solution $W(t)$ on \mathbb{T}^k , then there exists a prepared solution $X(t)$ of (4) such that $X(t)$ is invertible for all $t \in \mathbb{T}$ and relation (3) holds.*

Proof. From Lemma 3.2 the first conclusion follows. Conversely, let $W(t)$ be a Hermitian solution of (4) on \mathbb{T}^k . Let $t_0 \in \mathbb{T}$ and put $X = e_W(\cdot, t_0)$. By Theorem 5.8 in [13], X is defined because $I + \mu W$ is invertible on \mathbb{T}^k . Then X is invertible on \mathbb{T} by Theorem 5.21 [13], and we have

$$\begin{aligned} [X^\Delta(t)]^\Delta &= (W(t)X(t))^\Delta = W^\Delta(t)X^\sigma(t) + W(t)X^\Delta(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) - W(t)[I + \mu(t)W(t)]^{-1}W(t)X^\sigma(t) \\ &\quad + W(t)W(t)X(t) \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) \\ &\quad + W(t)[I + \mu(t)W(t)]^{-1}[(I + \mu(t)W(t))W(t)X(t) - W(t)X^\sigma(t)] \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) \\ &\quad + W(t)[I + \mu(t)W(t)]^{-1}\{W(t)X(t) + \mu(t)W(t)W(t)X(t) \\ &\quad - W(t)[X(t) + \mu(t)W(t)X(t)]\} \\ &= -[X^m(t)Q(t)X^{*m}(t)]^\sigma X^\sigma(t) \end{aligned}$$

on \mathbb{T}^k . So that $X(t)$ is a solution of (2) and $X(t)$ is indeed a prepared solution because $X^*(t)X^\Delta(t) = W(t)$ is Hermitian. \square

From Lemma 3.3 and Theorem 3.4 we have

Theorem 3.5. Equation (2) has a prepared solution $X(t)$ on \mathbb{T} with $X^*(\sigma(t))X(t) > 0$ on \mathbb{T}^k if and only if (4) has a Hermitian solution $W(t)$ on \mathbb{T}^k satisfying $I + \mu(t)W(t) > 0$ for all $t \in \mathbb{T}^k$.

Definition. Assume $a \in \mathbb{T}$ and $\sup \mathbb{T} = \infty$. We say that (2) is non-oscillatory on $[a, \infty)$ provided there is a prepared solution $X(t)$ of (2) and a $t_0 \in [a, \infty)$ such that $X^*(\sigma(t))X(t) > 0$ on $[t_0, \infty)$. Otherwise we say (2) is oscillatory on $[a, \infty)$.

We now introduce some notation that we will use in the remainder of this paper. If A is an $n \times n$ Hermitian matrix, let $\lambda_i(A)$ denote the i th eigenvalue of A so that

$$\lambda_{\max}(A) = \lambda_1(A) \geq \dots \geq \lambda_n(A) = \lambda_{\min}(A).$$

The trace of a matrix A is denoted by $\text{tr}(A) := \sum_{i=1}^n \lambda_i(A)$. We shall frequently use Weyl's theorem [9, p. 181, Theorem 4.3.1] which says if A and B are Hermitian matrices, then

$$\lambda_i(A) + \lambda_{\max}(B) \geq \lambda_i(A + B) \geq \lambda_i(A) + \lambda_{\min}(B)$$

and Ostrowski's inequalities [9, pp. 224–225] which give

$$\lambda_i(APA^*) \geq \lambda_i(P)\lambda_{\min}(AA^*) \quad \text{and} \quad \lambda_i(APA^*) \geq \lambda_i(AA^*)\lambda_{\min}(P).$$

Lemma 3.6. Suppose $X(t)$ is a non-oscillatory prepared solution of (2). Then there exists $t_0 \in \mathbb{T}^k$ such that $W(t)$ and $V(t)$ are both positive definite and decreasing for $t \in [t_0, \infty)$ with

$$\lim_{t \rightarrow \infty, t \in T} W(t) = \lim_{t \rightarrow \infty, t \in T} V(t) = 0. \tag{9}$$

Furthermore, multiplication of $W(t)$ and $V(t)$ is commutative at point where both exist and $W(t)V(t) = V(t)W(t)$ is positive definite for $t \in [t_0, \infty)$.

Proof. Since $X(t)$ is non-oscillatory and prepared, we begin by choosing $t_0 \in T^k$ so that $I + \mu(t)W(t) > 0$ for $t \in [t_0, \infty)$. Since $Q(t)$ is positive definite, we see from the Riccati equation (4), Ostrowski’s inequality, and Weyl’s inequality that $W^\Delta(t) < 0$ for $t \in [t_0, \infty)$. Hence by Weyl’s inequality, each eigenvalue $\lambda_i[W(t)]$ ($1 \leq i \leq n$), is a decreasing function of t for $t \in [t_0, \infty)$. Furthermore, each $\lambda_i[W(t)]$ is bounded below for $t \in [t_0, \infty)$ since $I + \mu(t)W(t) > 0$, so $\lim_{t \rightarrow \infty} \lambda_i[W(t)]$ exists for $1 \leq i \leq n$. Since the eigenvalues of $I + \mu(t)W(t)$ decrease but remain positive, the eigenvalues of $[I + \mu(t)W(t)]^{-1}$ are positive and increasing for $t \in [t_0, \infty)$. From (4) and the eigenvalue inequalities mentioned above we obtain

$$\begin{aligned} \lambda_i[-W^\Delta(t)] &> \lambda_i\{W(t)[I + \mu(t)W(t)]^{-1}W(t)\} \\ &\geq \lambda_i[W^2(t)]\lambda_{\min}([I + \mu(t)W(t)]^{-1}) \\ &\geq \{\lambda_i[W(t)]\}^2\lambda_{\min}([I + \mu(t_0)W(t_0)]^{-1}) \end{aligned} \tag{10}$$

for $1 \leq i \leq n$ and $t \in [t_0, \infty)$. Now we claim

$$\lim_{t \rightarrow \infty, t \in T} \lambda_i[W(t)] = 0 \tag{11}$$

holds for $1 \leq i \leq n$. Suppose not. We choose i_0 with $1 \leq i_0 \leq n$ such that

$$\lim_{t \rightarrow \infty, t \in T} \lambda_{i_0}[W(t)] = \lambda_0 \neq 0. \tag{12}$$

Combining (10) and (12), we can choose $t_1 \in [t_0, \infty)$ and a positive number δ such that

$$\lambda_{i_0}[-W^\Delta(t)] > \delta \quad \text{for } t \in [t_1, \infty). \tag{13}$$

But

$$\begin{aligned} \lambda_{\max}[-W(t) + W(t_1)] &= \lambda_{\max}\left[\int_{t_1}^t -W^\Delta(\tau)\Delta\tau\right] \geq \frac{1}{n} \operatorname{tr}\left[\int_{t_1}^t -W^\Delta(\tau)\Delta\tau\right] \\ &= \frac{1}{n} \int_{t_1}^t \operatorname{tr}[-W^\Delta(\tau)]\Delta\tau \geq \frac{1}{n} \int_{t_1}^t \lambda_{i_0}[-W^\Delta(\tau)]\Delta\tau. \end{aligned}$$

By (13), this implies that $\lambda_{\max}[-W(t) + W(t_1)] \rightarrow \infty$ and $\lambda_{\max}[W(t)] \rightarrow -\infty$ as $t \rightarrow \infty$. This contradicts the fact the eigenvalues of $W(t)$ are bounded below for $t \in [t_0, \infty)$ and proves that (11) holds. Consequently, $\lim_{t \rightarrow \infty, t \in T} W(t) = 0$. Therefore, $W(t)$ is positive for $t \in [t_0, \infty)$. From (3), $\mu(t)V(t) = I - [I + \mu(t)W(t)]^{-1}$, so the eigenvalues of $V(t)$ are also positive and decreasing for $t \in [t_0, \infty)$ with $\lim_{t \rightarrow \infty} \lambda_i[V(t)] = 0$ for $1 \leq i \leq n$ showing that (9) holds.

Finally, from (3), we see that

$$[I + \mu(t)W(t)][I - \mu(t)V(t)] = I = [I - \mu(t)V(t)][I + \mu(t)W(t)],$$

from which it follows that

$$\mu(t)W(t)V(t) = \mu(t)V(t)W(t) = W(t) - V(t)$$

at all $t \in \mathbb{T}^k$ where both $W(t)$ and $V(t)$ exist. Since

$$\begin{aligned} V(t)[I + \mu(t)W(t)]V(t) &= \mu(t)V(t)W(t)V(t) + V^2(t) \\ &= [W(t) - V(t)]V(t) + V^2(t) = W(t)V(t), \end{aligned}$$

we see that $W(t)V(t) = V(t)W(t)$ is positive for $t \in [t_0, \infty)$ completing the proof of the lemma. \square

Theorem 3.7. *Suppose $Q(t)$ is Hermitian and positive definite for all $t \in \mathbb{T}^k$. Then (2) is oscillatory if and only if*

$$\int_a^\infty t \lambda_{\max}[Q(t)] \Delta t = \infty \quad (14)$$

holds.

Proof. First, we assume $m = 1$ in (2), the general case will be treated later. Suppose (14) holds but (2) has a non-oscillatory prepared solution $X(t)$. Applying Lemma 3.6, we choose $t_0 \in \mathbb{T}^k$ so that $X(t)$ is invertible and matrices $W(t)$, $V(t)$ and $W(t)V(t) = V(t)W(t)$ are all positive definite for $t \in [t_0, \infty)$. Then

$$\begin{aligned} [X^{-1}(t)X^{*-1}(t)]^\Delta &= [X^{-1}(t)]^\Delta X^{*-1}(\sigma(t)) + X^{-1}(t)[X^{*-1}(t)]^\Delta \\ &= -X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)X^{*-1}(\sigma(t)) \\ &\quad - X^{-1}(t)X^{*-1}(\sigma(t))X^{*\Delta}(t)X^{*-1}(t) \\ &= -X^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)) - X^{-1}(t)V(t)X^{*-1}(t). \end{aligned} \quad (15)$$

Using the product rule for Δ -derivatives we have

$$\begin{aligned} [A(t)B(t)C(t)D(t)E(t)]^\Delta &= A^\sigma(t)B^\sigma(t)C^\sigma(t)D^\sigma(t)E^\Delta(t) + A^\sigma(t)B^\Delta(t)C^\sigma(t)D^\sigma(t)E(t) \\ &\quad + A^\sigma(t)B(t)C^\Delta(t)D^\sigma(t)E(t) + A^\sigma(t)B(t)C(t)D^\Delta(t)E(t) \\ &\quad + A^\Delta(t)B(t)C(t)D(t)E(t), \end{aligned}$$

and we obtain

$$\begin{aligned} [tX^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)X^{*-1}(\sigma(t))]^\Delta &= \sigma(t)X^{-1}(\sigma^2(t))X^\Delta(\sigma(t))X^{-1}(\sigma(t))[X^{*-1}(\sigma(t))]^\Delta \\ &\quad + \sigma(t)[X^{-1}(\sigma(t))]^\Delta X^\Delta(\sigma(t))X^{-1}(\sigma(t))X^{*-1}(\sigma(t)) \end{aligned}$$

$$\begin{aligned}
 & + \sigma(t)X^{-1}(\sigma(t))[X^\Delta(t)]^\Delta X^{-1}(\sigma(t))X^{*-1}(\sigma(t)) \\
 & + \sigma(t)X^{-1}(\sigma(t))X^\Delta(t)[X^{-1}(t)]^\Delta X^{*-1}(\sigma(t)) \\
 & + X^{-1}(\sigma(t))X^\Delta(t)X^{-1}(t)X^{*-1}(\sigma(t)) \\
 = & -\sigma(t)X^{-1}(\sigma^2(t))W^2(\sigma(t))X^{*-1}(\sigma^2(t)) \\
 & -\sigma(t)X^{-1}(\sigma(t))V(\sigma(t))W(\sigma(t))X^{*-1}(\sigma(t)) - \sigma(t)Q(\sigma(t)) \\
 & - \sigma(t)X^{-1}(\sigma(t))V(t)W(t)X^{*-1}(\sigma(t)) + X^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)). \tag{16}
 \end{aligned}$$

Applying the product rule gives

$$\begin{aligned}
 & [A(t)B(t)C(t)D(t)E(t)]^\Delta \\
 = & A^\sigma(t)B^\sigma(t)C^\sigma(t)D^\Delta(t)E^\sigma(t) + A^\sigma(t)B^\sigma(t)C^\Delta(t)D(t)E^\sigma(t) \\
 & + A^\sigma(t)B^\Delta(t)C(t)D(t)E^\sigma(t) + A^\sigma(t)B(t)C(t)D(t)E^\Delta(t) \\
 & + A^\Delta(t)B(t)C(t)D(t)E(t),
 \end{aligned}$$

and we find that

$$\begin{aligned}
 & [tX^{-1}(t)X^\Delta(t)X^{-1}(\sigma(t))X^{*-1}(t)]^\Delta \\
 = & -\sigma(t)X^{-1}(\sigma(t))W(\sigma(t))V(\sigma(t))X^{*-1}(\sigma(t)) - \sigma(t)Q(\sigma(t)) \\
 & - \sigma(t)X^{-1}(\sigma(t))W(t)V(t)X^{*-1}(\sigma(t)) - \sigma(t)X^{-1}(t)V^2(t)X^{*-1}(t) \\
 & + X^{-1}(t)V(t)X^{*-1}(t). \tag{17}
 \end{aligned}$$

Combining (15)–(17), we have

$$\begin{aligned}
 & [X^{-1}(t)X^{*-1}(t)]^\Delta \\
 = & -X^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)) - X^{-1}(t)V(t)X^{*-1}(t) \\
 = & -[tX^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t))]^\Delta - [tX^{-1}(t)V(t)X^{*-1}(t)]^\Delta \\
 & - 2\sigma(t)Q(\sigma(t)) - \sigma(t)H(t), \tag{18}
 \end{aligned}$$

where

$$\begin{aligned}
 H(t) = & X^{-1}(\sigma^2(t))W^2(\sigma(t))X^{*-1}(\sigma^2(t)) + X^{-1}(t)V^2(t)X^{*-1}(t) \\
 & + X^{-1}(\sigma(t))[2V(\sigma(t))W(\sigma(t)) + 2V(t)W(t)]X^{*-1}(\sigma(t)).
 \end{aligned}$$

Integrating both side of (18) from t_0 to t yields

$$\begin{aligned}
 & \int_{t_0}^t [X^{-1}(\tau)X^{*-1}(\tau)]^\Delta \Delta\tau \\
 = & - \int_{t_0}^t [\tau X^{-1}(\sigma(\tau))W(\tau)X^{*-1}(\sigma(\tau))]^\Delta \Delta\tau - 2 \int_{t_0}^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau
 \end{aligned}$$

$$-\int_{t_0}^t [\tau X^{-1}(\tau)V(\tau)X^{*-1}(\tau)]^\Delta \Delta\tau - \int_{t_0}^t \sigma(\tau)H(\tau)\Delta\tau,$$

and hence

$$\begin{aligned} 2 \int_{t_0}^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau &= - \int_{t_0}^t \sigma(\tau)H(\tau)\Delta\tau - X^{-1}(t)X^{*-1}(t) \\ &\quad - tX^{-1}(\sigma(t))W(t)X^{*-1}(\sigma(t)) \\ &\quad - tX^{-1}(t)V(t)X^{*-1}(t) + C, \end{aligned} \quad (19)$$

where C is a constant Hermitian matrix.

Now all the terms except C on the right-hand side of (19) are negative definite for all $t \in [t_0, \infty)$, and consequently there is a real constant M_1 such that

$$\lambda_{\max} \left[\int_{t_0}^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau \right] \leq M_1 \quad \text{for } t \in [\sigma(t_0), \infty).$$

By Weyl's inequality, there is another constant M_2 so that

$$\lambda_{\max} \left[\int_a^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau \right] \leq M_2 \quad \text{for } t \in [\sigma(t_0), \infty). \quad (20)$$

However,

$$\begin{aligned} \lambda_{\max} \left[\int_a^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau \right] &\geq \frac{1}{n} \operatorname{tr} \left[\int_a^t \sigma(\tau)Q(\sigma(\tau))\Delta\tau \right] \\ &= \frac{1}{n} \int_a^t \operatorname{tr}[\sigma(\tau)Q(\sigma(\tau))] \Delta\tau \\ &\geq \frac{1}{n} \int_a^t \lambda_{\max}[\sigma(\tau)Q(\sigma(\tau))] \Delta\tau. \end{aligned}$$

By (14), $\int_a^t \lambda_{\max}[\sigma(\tau)Q(\sigma(\tau))] \Delta\tau \rightarrow \infty$ as $t \rightarrow \infty$ contradicting (20). This proves that (14) is a sufficient condition for (2) to be oscillatory in the case $m = 1$.

Next, we will prove the general case. Suppose (14) holds but there is a positive integer m such that (2) has a prepared non-oscillatory solution $X_0(t)$. Since $X_0(t)$ is non-oscillatory, we choose $t_0 \in [a, \infty)$ such that $X_0(t)$ is invertible for $t \in [t_0, \infty)$ and $W_0(t)$ and $V_0(t)$ are positive definite for $t \in [t_0, \infty)$. Set

$$Q_0(t) = X_0^{m-1}(\sigma(t))Q(\sigma(t))X_0^{*m-1}(\sigma(t)), \quad t \in [t_0, \infty).$$

It is not difficult to verify that $Q_0(t)$ is Hermitian and positive definite for $t \in [t_0, \infty)$ and $X_0(t)$ is also a non-oscillatory prepared solution of

$$X^{\Delta^2} + X(\sigma(t))Q_0(t)X^*(\sigma(t))X(\sigma(t)) = 0, \quad t \in [t_0, \infty). \tag{21}$$

So $X_0^*(t)X_0(t)$ and $X_0(t)X_0^*(t)$ have the same eigenvalues; furthermore, we have

$$\begin{aligned} [X_0^*(t)X_0(t)]^\Delta &= X_0^*(\sigma(t))X_0^\Delta(t) + X_0^{*\Delta}(t)X_0(t) \\ &= X_0^*(\sigma(t))V_0(t)X_0(\sigma(t)) + X_0^*(t)W_0(t)X_0(t). \end{aligned}$$

It follows that $[X_0^*(t)X_0(t)]^\Delta > 0$ for $t \in [t_0, \infty)$, so the eigenvalues of $X_0(t)X_0^*(t)$ are increasing. Hence we can choose a positive real number δ so that $\lambda_{\min}[X_0(t)X_0^*(t)] > \delta$ for $t \in [t_0, \infty)$. By Ostrowski's inequality

$$\lambda_{\max}[Q_0(t)] \geq \lambda_{\max}[Q(\sigma(t))]\delta^{m-1} \quad \text{for } t \in [t_0, \infty).$$

Hence $Q_0(t)$ is Hermitian and positive definite for $t \in [t_0, \infty)$ with

$$\int_a^\infty t\lambda_{\max}[Q_0(t)]\Delta t = \infty.$$

So $X_0(t)$ is oscillatory solution of (20), even though $Q_0(t)$ may only be positive semi-definite rather than positive definite for $t \in [a, t_0)$, it is clear from the first part of the proof that (21) is oscillatory. Since $X_0(t)$ is a non-oscillatory solution, we get a contradiction. This completes the proof that (2) is oscillatory if (14) holds.

Now we prove that (14) is a necessary condition if (14) is to be oscillatory. Suppose that

$$\int_a^\infty t\lambda_{\max}[Q(t)]\Delta t < \infty.$$

We need to show that there is at least one non-oscillatory prepared solution $X(t)$ of (14). Here we recall some facts from [9] that will be used in what follows. Let M_n denote the set of $n \times n$ complex matrices, $|x|$ denote the modulus of the complex number x , and let A_{ij} denote the entry in the i th row and j th column of a matrix A . Let $\|\cdot\|_\infty$, $\|\cdot\|_1$ and $\|\cdot\|_2$ be the matrix norms on M_n induced by the l_∞ , l_1 , and l_2 , respectively. Then $\|\cdot\|_\infty$ is the maximum row sum norm, $\|\cdot\|_1$ is the maximum column sum norm, and $\|\cdot\|_2$ is the spectral norm with $\|A\|_2 = [\lambda_{\max}(AA^*)]^{1/2}$ for $A \in M_n$. $\|H\|_2 = \lambda_{\max}(H)$ when H is Hermitian and positive semi-definite. The relations

$$\|A\|_\infty \leq \sqrt{n}\|A\|_2, \quad \|A\|_1 \leq \sqrt{n}\|A\|_2, \quad \|A\|_1 \leq n\|A\|_\infty$$

hold for all $A \in M_n$.

Let $t_0 \in T$ be a fixed point. We define an $n \times n$ complex matrix-valued function $X(t)$ for $t \in [t_0, \infty)$ by

$$X(t) = I - \int_{\sigma(t)}^\infty (s-t)[X^m(s)Q(s)X^{*m}(s)]X(s)\Delta s \tag{22}$$

which satisfies (2) for $t \in [a, \infty)$. In the following discussion we use operator theory to show that $X(t)$ is a prepared non-oscillatory solution of (2). From the assumption, we choose $t_0 \in [a, \infty)$ so large that

$$\int_{\sigma(t_0)}^{\infty} s \lambda_{\max}[Q(s)] \Delta s < n^{-1/2} 2^{-2m} \left(\frac{3m}{2} + 1\right)^{-1}. \quad (23)$$

Let H_{t_0} denote the set of all $n \times n$ complex matrix-valued functions $Z(t)$ defined for $t \in [t_0, \infty)$ and such that $\lim_{t \rightarrow \infty} Z(t)$ exists as a finite matrix. For $Z \in H_{t_0}$, let

$$\|Z\| = \sup_{t \in [t_0, \infty)} \|Z(t)\|_{\infty}.$$

H_{t_0} equipped with this norm is a Banach space. Let $\mathcal{A} = \{Z \in H_{t_0} : \|Z - I\| \leq 1\}$. Then \mathcal{A} is a nonempty closed subset of H_{t_0} . Define TX by

$$TX(t) = I - \int_{\sigma(t)}^{\infty} (s-t) [X^m(s) Q(s) X^{*m}(s)] X(s) \Delta s \quad \text{for } X \in \mathcal{A}. \quad (24)$$

Then for $X \in \mathcal{A}$, and $s \geq t$,

$$\begin{aligned} & \left| [(s-t) X^m(s) Q(s) X^{*m}(s) X(s)]_{ij} \right| \\ & \leq \|(s-t) X^m(s) Q(s) X^{*m}(s) X(s)\|_{\infty} \\ & \leq s \|X(s)\|_{\infty}^{m+1} \|X^m(s)\|_{\infty} \|Q(s)\|_{\infty} \leq s \|X\|^{m+1} \|X^m(s)\|_{\infty} \sqrt{n} \|Q(s)\|_2 \\ & \leq 2^{2m+1} n^{1/2} s \lambda_{\max}[Q(s)]. \end{aligned} \quad (25)$$

From (25), we see that the integral on the right-hand side of (24) is convergent as $t \rightarrow \infty$. Moreover, from (23) and (24) we see that, for $t \in [t_0, \infty)$,

$$\|TX(t) - I\|_{\infty} \leq 2^{2m+1} n^{1/2} \int_{\sigma(t_0)}^{\infty} s \lambda_{\max}[Q(s)] \Delta s < 1,$$

so $\|TX - I\| \leq 1$, that is, $TX(t) \in \mathcal{A}$. Thus T is a mapping from \mathcal{A} into \mathcal{A} . For X and Y both in \mathcal{A} , we have

$$\begin{aligned} & \left| [TX(t) - TY(t)]_{ij} \right| \\ & \leq \int_{\sigma(t_0)}^{\infty} s \|X^m(s) Q(s) X^{*m}(s) X(s) - Y^m(s) Q(s) Y^{*m}(s) Y(s)\|_{\infty} \Delta s. \end{aligned} \quad (26)$$

Shortening the notation in a self-evident way,

$$\begin{aligned} & \|X^m Q X^{*m} X - Y^m Q Y^{*m} Y\|_{\infty} \\ & \leq \|X^m Q X^{*m} X - X^m Q X^{*m} Y\|_{\infty} + \|X^m Q X^{*m} Y - X^m Q Y^{*m} Y\|_{\infty} \\ & \quad + \|X^m Q Y^{*m} Y - Y^m Q Y^{*m} Y\|_{\infty} \end{aligned}$$

$$\begin{aligned} &\leq \|X\|_\infty^m \sqrt{n} \lambda_{\max}[Q] \|X^m\|_\infty \|X - Y\|_\infty + \|X^m\|_\infty \sqrt{n} \lambda_{\max}[Q] \|X^m \\ &\quad - Y^m\|_\infty \|Y\|_\infty + \|X^m - Y^m\|_\infty \sqrt{n} \lambda_{\max}[Q] \|Y\|_\infty^{m+1} \end{aligned} \tag{27}$$

and

$$\begin{aligned} &\|X^m - Y^m\|_\infty \\ &\leq \|X^m - X^{m-1}Y\|_\infty + \|X^{m-1}Y - X^{m-2}Y^2\|_\infty + \dots + \|XY^{m-1} - Y^m\|_\infty \\ &\leq \|X^{m-1}(X - Y)\|_\infty + \|X^{m-2}(X - Y)Y\|_\infty + \dots + \|(X - Y)X^{m-1}\|_\infty \\ &\leq m2^{m-1} \|X - Y\|_\infty. \end{aligned} \tag{28}$$

Combining (27) and (28) yields

$$\|X^m Q X^{*m} X - Y^m Q Y^{*m} Y\|_\infty \leq \left(\frac{3m}{2} + 1\right) 2^{2m} n^{1/2} \lambda_{\max}[Q] \|X - Y\|_\infty. \tag{29}$$

From (26) and (29) we find

$$\|TX - TY\| \leq \left[\left(\frac{3m}{2} + 1\right) 2^{2m} n^{1/2} \int_{\sigma(t_0)}^\infty s \lambda_{\max}(Q(s)) \Delta s\right] \|X - Y\|.$$

Therefore, from (23) it follows that $T : \mathcal{A} \rightarrow \mathcal{A}$ is a contraction mapping. Consequently, there is a solution $X(t)$ of (24) which is also a solution of (2) for $t \in [t_0, \infty)$. Extending this solution backward to $t = a$, we obtain a solution satisfying (2) for $t \in [a, \infty)$. Since

$$\lim_{t \rightarrow \infty} X(t) = I \quad \text{and} \quad \lim_{t \rightarrow \infty} X^\Delta(t) = 0,$$

it follows that $X(t)$ is a prepared solution of (2). Finally,

$$\lim_{t \rightarrow \infty} W(t) = \lim_{t \rightarrow \infty} X^\Delta(t) X^{-1}(t) = 0.$$

So $\lim_{t \rightarrow \infty} [W(t) + I] = I$ making $X(t)$ a non-oscillatory solution of (2). This completes the proof of Theorem 3.7. \square

4. Examples

The following examples illustrate the applications of our oscillation criteria.

Example 1. Consider the second-order matrix system (2) on time scale $\mathbb{T} = h\mathbb{Z} = \{hk : k \in \mathbb{Z}\}$ ($h > 0$); where

$$Q(t) = \begin{pmatrix} t+2 & 0 \\ 0 & 3 \end{pmatrix}.$$

For $t \in \mathbb{T}$; $\sigma(t) = t+h$; $\mu(t) = h$. Let $t_0 \in \mathbb{T}$ be given and pick $k_0 \in \mathbb{Z}$ so that $a := hk_0 > t_0$. For $t \in \mathbb{T}$; consider

$$\begin{aligned} \int_a^\infty (t+h)(t+h+2)\Delta t &= \sum_{j=k_0}^\infty (hj+h)(hj+h+2) \\ &= h^2 \sum_{j=k_0}^\infty \left[(j+1)^2 + \frac{2}{h}(j+h) \right] = \infty. \end{aligned}$$

Hence from Theorem 3.7, we get that this equation is oscillatory on \mathbb{T} .

Example 2. It will show that the q -difference equation

$$X^{\Delta^2}(t) + [X^m(t)q(q-1)t^2 X^{*m}(t)]^\sigma X(\sigma(t)) = 0$$

is oscillatory on $\mathbb{T} = q^{\mathbb{N}_0}$, where $q > 1$ is a constant. In fact, $t_0 \in [1; \infty)$ is given and pick $k_0 \in \mathbb{N}$ so that $a := q^{k_0} > t_0$. For $t \in \mathbb{T}$; let

$$\bar{Q}(t) = \sigma(t)\lambda_{\max}[Q(\sigma(t))] = qt \frac{1}{q(q-1)(qt)^2} = \frac{1}{q^2(q-1)t}$$

and

$$\begin{aligned} \int_a^{n'} \bar{Q}(t)\Delta t &= \int_{q^{k_0}}^{q^n} \bar{Q}(t)\Delta t = \sum_{j=k_0}^n \bar{Q}(q^j)\mu(q^j) = \sum_{j=k_0}^n \frac{1}{(q-1)q^{j+2}}(q-1)q^j \\ &= \sum_{j=k_0}^n \frac{1}{q^2} = \frac{1}{2q^2}(n+k_0)(n-k_0+1) = \frac{n^2+n-k_0^2+k}{2q^2} = \infty. \end{aligned}$$

Since $\lim_{n \rightarrow \infty} \frac{n^2+n-k_0^2+k}{2q^2} = \infty$. That is $\int_a^\infty \sigma(t)\lambda_{\max}[Q(\sigma(t))]\Delta t = \infty$.

Remark. When $\mathbb{T} = \mathbb{R}$ and $\mathbb{T} = \mathbb{Z}$, argument in this paper is just as [4,8], respectively.

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