

Solar pond powered liquid desiccant evaporative cooling



Esam Elsarrag^{a,*}, Opubo N. Igobo^b, Yousef Alhorr^a, Philip A. Davies^b

^a Gulf Organisation for Research and Development, Qatar Science and Technology Park, Doha, Qatar

^b Sustainable Environment Research Group, School of Engineering and Applied Science, Aston University, Birmingham B4 7ET, UK

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ABSTRACT

Liquid desiccant cooling systems (LDCS) are energy efficient means of providing cooling, especially when powered by low-grade thermal sources. In this paper, the underlying principles of operation of desiccant cooling systems are examined, and the main components (dehumidifier, evaporative cooler and regenerator) of the LDCS are reviewed. The evaporative cooler can take the form of direct, indirect or semi-indirect. Relative to the direct type, the indirect type is generally less effective. Nonetheless, a certain variant of the indirect type – namely dew-point evaporative cooler – is found to be the most effective amongst all. The dehumidifier and the regenerator can be of the same type of equipment: packed tower and falling film are popular choices, especially when fitted with an internal heat exchanger. The energy requirement of the regenerator can be supplied from solar thermal collectors, of which a solar pond is an interesting option especially when a large scale or storage capability is desired.

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* Corresponding author. Tel.: + 97444049016.

E-mail addresses: e.elsarrag@gord.qa, elsarrag@hotmail.com (E. Elsarrag).

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1. Introduction

Temperature and humidity of ambient air are two critical factors that determine comfort levels of occupants in a given space. In hot climates, it is desirable to reduce the ambient air temperature (cooling) to improve comfort levels; however in hot and humid climates (as in some Gulf countries), removal of moisture from the air (dehumidification) is almost as important as cooling [1]. Besides occupant discomfort, insufficient dehumidification can also adversely result to mould and mildew growth. ASHRAE Standard 55 [2] recommends temperature 19–28 °C and less than 65% relative humidity for comfort conditions.

Conventional air conditioning systems (for example vapour compression systems) address these issues by cooling air below its dew point such that water vapour condenses on a cooling coil, thus removing moisture from the air. The dehumidified air is then reheated to the desired temperature [3]. This process of deep cooling to dew point and reheating consequently leads to higher energy requirement. Alternatively, desiccants can be employed to use their hygroscopic properties to dehumidify the air [4,5]. Studies have reported that desiccant systems can reduce energy consumption by as much as 40% [6–8].

Desiccants are natural or synthetic substances, having a high affinity for water, capable of absorbing water vapour from their immediate vicinity. They are available in both liquid and solid states. Solid desiccants are compact and less corrosive. On the other hand, liquid desiccant offer several benefits, including, lower regeneration temperature, lower pressure drop of air across the desiccant material, suitability for dust removal by filtration, and flexibility in utilisation especially when handling large volumes of air [9–11].

In desiccant cooling cycles, the desiccant (brought into contact with air) reduces the humidity of the air by absorbing moisture from the air. Then the air temperature is reduced by conventional cooling coils or other components such as evaporative coolers [12]. However, the moisture impregnated desiccants need to be dried in a regenerator, in which the water vapour previously absorbed evaporated out from it by heating. The heat required to regenerate the desiccant can be supplied from low-temperature sources [13] such as waste heat or solar energy. Utilising solar energy for this application is particularly interesting because the greatest demand for cooling occurs during times of highest solar insolation. There are different means by which the solar thermal energy can be harnessed for this purpose; examples include conventional solar thermal collectors, solar ponds, and salt works. Besides collecting solar thermal energy, solar ponds have the inherent ability of also storing the thermal energy, and have been widely studied as such.

This paper will review the technologies used for desiccant cooling systems and solar ponds; different options will be compared and evaluated (in the preliminary sense) with regards to complexity, cost and performance, for the operating conditions prevalent the Gulf region. Also, specific technical risks and challenges will be identified and assessed for systematic appraisal. Fig. 1 shows the proposed system that combines the solar pond, the seawater bittern desiccant and the indirect/direct evaporative cooling.

2. Liquid desiccant evaporative cooling

2.1. Liquid desiccant materials

Desiccant materials play a crucial role in the development of desiccant air conditioning. The characteristics of the desiccant material being utilised impact the performance of the desiccant air conditioning systems significantly [14]. Materials for the liquid desiccants should have low vapour pressure, low viscosity and good heat transfer characteristics. The surface tension of liquid desiccant is also important as it directly influences static hold up and wetting of desiccant air contact surface [15]. Commonly used desiccants include aqueous solutions of lithium chloride, calcium chloride, lithium bromide and triethylene glycol. Other desiccants include seawater bitterns, $MgCl_2$ [16], $KCOOH$, glycols like triethylene glycol (TEG), diethylene glycol (DEG), MEG, propylene glycol, and mixtures of desiccants $LiCl + LiBr$ or $LiCl + CaCl_2$ [15,17].

One key principle for selecting appropriate desiccant materials is that the desiccant materials should possess largely saturated adsorption amount and can be reactivated easily. The water absorption capacity of a desiccant solution depends on its equilibrium vapour pressure which in turn depends on its temperature and concentration. The higher the concentration and lower the temperature, the higher would be the moisture absorption capacity. But at high concentrations and low temperatures, there is an adverse possibility of crystallisation of the desiccant. Therefore, different desiccants have different optimum operating concentration levels, e.g. 55–60% for lithium bromide, 30–45% for lithium chloride, 35–45% for $CaCl_2$, < 35% for $MgCl_2$, and 95–97% for TEG [18,19].

The ethylene glycols are material friendly, in that, they are not corrosive and do not crystallise during the dehumidification process. However, they are quite prone to evaporating into the air stream. Brines (especially $LiCl$ and $CaCl_2$) are a popular choice though having the drawback of been corrosive and crystallising at concentrations higher than 40% [20]. The physical properties of some common desiccants are compared in Table 1.

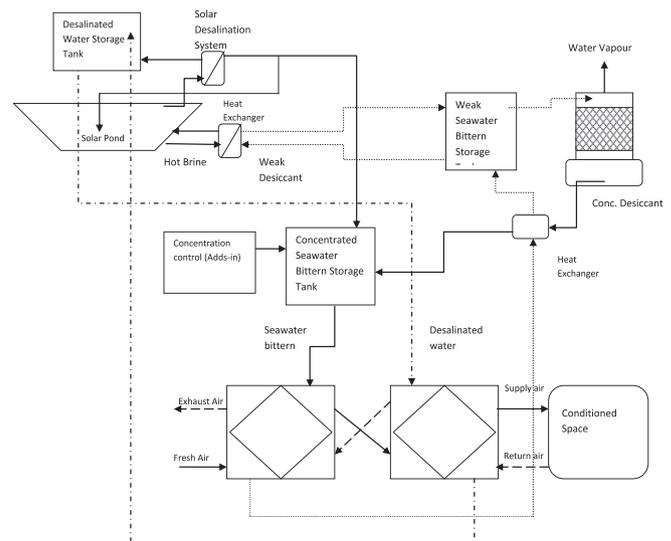


Fig. 1. Schematic of the proposed system (GORD TechnoHub).

Desiccant mixtures have been proposed in order to combine the advantages of the individual components and to improve the overall characteristics of the desiccant. For example, in an attempt to obtain a liquid desiccant with lower cost than aqueous lithium chloride, but more stable than calcium chloride, aqueous solutions containing a mixture of these two salts have been investigated by Etras et al. [24]. They calculated the heat and mass transfer coefficients for the desiccant air systems in a packed bed absorption tower using empirical correlation from the literature. Three desiccants were compared: lithium chloride, calcium chloride and mixture of both lithium and calcium chlorides. The mixture solution was found to improve the mass transfer greatly compared to the calcium chloride solution while the heat transfer coefficients in liquid side were similar for the three salt solutions.

In addition to dehumidification, an added benefit of the desiccants is that they are capable of absorbing inorganic and organic contaminants in the air. The absorption process has the potential to remove biological pollutants such as bacteria, fungi and viruses so improving indoor air quality [25,26]. However, in some circumstances, there is a benefit in adding a desiccant dehumidifier to the cooling system to control humidity separately from air temperature. The benefits are greater where the moisture loads are high compared to the sensible heat loads, or where they peak at different times [27].

2.2. Thermodynamic cycles used for liquid desiccant evaporative cooling

The schematic of a typical liquid desiccant cooling system is depicted in Fig. 2. The system is composed of three major components, namely, the dehumidification unit, regeneration unit and cooling unit (heat exchanger evaporative coolers) [28]. The liquid desiccant is pumped into the dehumidification unit, where it is distributed over a large surface area and comes in contact with the humid air stream from which it absorbs moisture. The resulting diluted desiccant is fed to the regeneration unit to re-concentrate the diluted solution to an acceptable concentration for reuse, so as maintain continual operation of the cycle. The cooling unit cools the dehumidified air; this could take the form of direct evaporative

Table 1
Physical properties of common liquid desiccants at 25 °C.

Desiccant by weight	$\rho \cdot 10^{-3} (\text{kg/m}^3)$	$\mu \cdot 10^3 (\text{N s/m}^2)$	$\gamma \cdot 10^3 (\text{N/m})$	$C_p (\text{kJ/kg } ^\circ\text{C})$
95% TEG [21]	1.1	28	46	2.3
55% LiBr [22]	1.6	6	89	2.1
40% CaCl ₂ [23]	1.4	7	93	2.5
40% LiCl [24]	1.2	9	96	2.5

Note: ρ – density; μ – viscosity; γ – surface tension; C_p – specific heat.

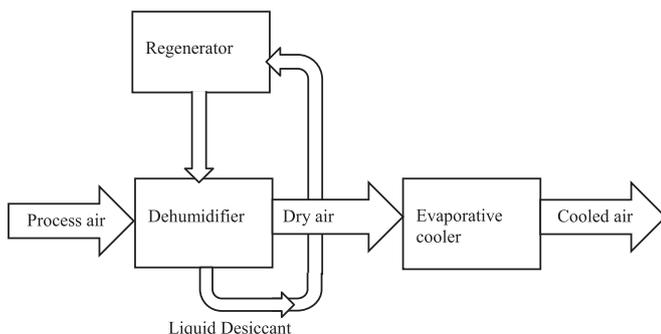


Fig. 2. Schematic of basic liquid desiccant evaporative cooling [28].

cooling and/or indirect evaporative cooling [29], in accordance to the desired comfort level. Direct evaporative cooling is simply when water evaporates into the air to be cooled, simultaneously humidifying it, as it is been cooled. In contrast, for indirect evaporative cooling, the air to be cooled is separated from the evaporation process, by a heat exchange membrane, such that it is cooled without been humidified.

The liquid desiccant cooling system can be deployed in diverse technological arrangements/configurations. The most common configuration uses a desiccant stage preceding a direct evaporative stage. However alternative configurations can include indirect evaporative stages or heat recuperative/recovery stages. There are also choices as regards recirculation of internal air and mixing with external fresh air.

Some heat recuperative/recovery configurations employ heat exchanger to use the return air from the indoor conditioned space to pre-cool the dehumidified air before it is evaporatively cooled [30]. Another heat recuperative approach commonly encountered is the linking of the absorber and regenerator via a liquid-to-liquid heat exchanger to reduce the regenerator residual heat dumping back to the conditioner. Here, the cool dilute desiccant from the outlet conditioner was used to precool the warm concentrated solution transferred from the regenerator to the conditioner. This improved the dehumidifier performance and also reduces the heat input to the regenerator by 10–15% [15].

A complete configuration of a desiccant evaporative cooling system was presented by Elsarrag et al. [31]. In the proposed system, a wide range of outdoor air flow rates were used (450 to 1000 m³/h). In their configuration, the outside air was initially cooled and dehumidified by the desiccant and then cooled via a direct evaporative cooler. A supply air temperature as low as 19 °C was obtained in a hot, humid climate.

A configuration incorporating both direct and indirect evaporative coolers was presented by Tu et al. [32]. In the proposed system, process air from the atmosphere was first dehumidified by the dehumidifier and then cooled without any moisture content variation in an indirect evaporative cooler, where the exhaust air from the air-conditioning space was utilised as the secondary air. Finally, the process air was cooled in a direct evaporative cooler adiabatically. Because the cooling energy of exhaust air was already recovered in the indirect evaporative cooler to the process air, air recirculation was not necessary.

A configuration involving the recirculation of internal air and mixing with external fresh air was studied by Kessling et al. [33]. In the configuration (Fig. 3), the outside air was dehumidified and mixed with returning indoor air; the mixed air was then cooled in an indirect evaporative cooler and resupplied to the conditioned

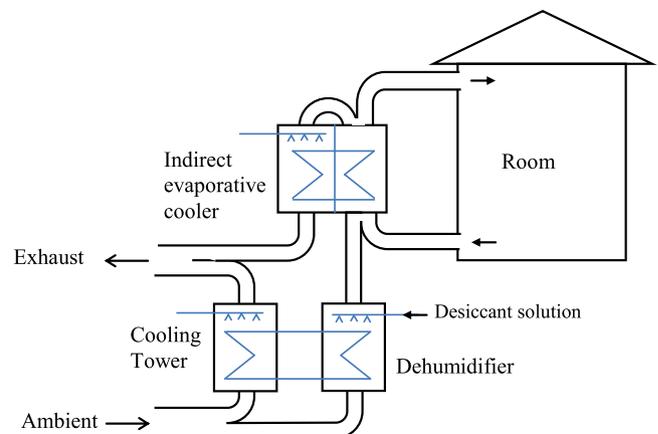


Fig. 3. Schematic of liquid desiccant cooling configuration with indirect evaporative cooling of external air mixed with recirculating internal air [33].

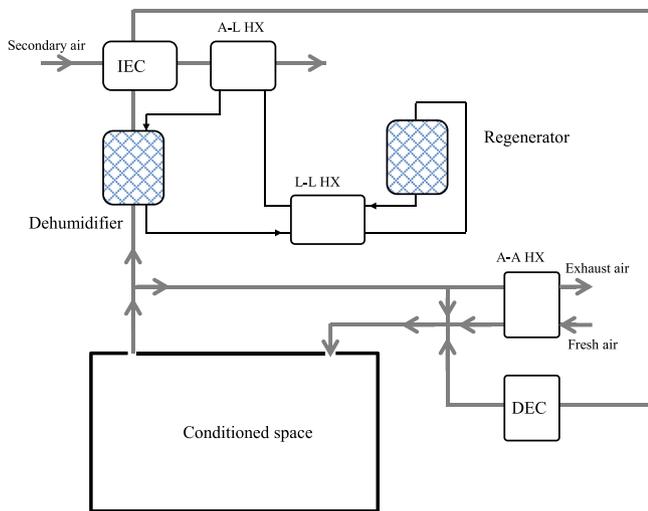


Fig. 4. Schematic of liquid desiccant cooling system with a combination of configurations [34].

space. However, before being delivered to the room, a part of the mixed air was diverted as the secondary air to provide the evaporative cooling, and then released as exhaust.

A configuration that involved the combination of bits of all the configurations above was presented in Ref. [34]. There (Fig. 4), the return air from the cooled room was divided into three portions; the first part of the return air was dehumidified, and then cooled by adiabatically saturated outside air in a heat exchanger (indirect evaporative cooling-IEC). The dehumidified air then underwent direct evaporative cooling (DEC) before being mixed with recirculated air (the second portion of the air returned from the cooled room) and pre-cooled fresh air (the fresh air was pre-cooled by the third part of the return air in a heat recovery exchanger). The mixture was then introduced into the conditioned space to satisfy both the sensible and the latent loads. The diluted desiccant solution (leaving the dehumidifier) was preheated in a liquid-liquid heat recovery exchanger, before entering the regenerator. The simulation showed that the influence of the heat recovery from the regenerator far exceeded those from the other heat exchangers involving these air streams.

2.3. Different types of components used

The equipment used for the different components of a desiccant system are air-contacting equipment for liquid-air interactions designed for enhanced heat and mass transfer for handling the low liquid flow and large process air flow rates, with minimal air pressure drop, while providing the desired large contact surface area [15]. In many compact configurations, the dehumidifier and the regenerator are made of a similar type of equipment [35,36]. An important issue of concern in the design of the contacting equipment is the undesirable phenomenon of carryover of some molecules/droplets of desiccant along with the air stream [37]. Besides resulting in monetary losses over time, large quantities of carryover can also pose serious health hazards [38]. A good dehumidifier/regenerator system should minimise carryover as much as possible. In the following sub-sections, each component is reviewed separately concerning the above considerations.

2.3.1. Dehumidifiers

The principal component of liquid desiccant dehumidification systems is the inside geometry of the absorber (i.e., the kind of packing) employed. The basic configurations commonly encountered mainly include spray tower, packed tower and falling film

arrangements [39]. To compensate for the adverse temperature rise during the dehumidification process, the desiccant could be externally cooled before entering the dehumidifier or better still internally cooled within the dehumidifier to improve performance [40,41]. This can be implemented by having coils or plate heat exchangers as an integral part of the dehumidifier.

The performance of the dehumidifier can be expressed in terms of the dehumidifier effectiveness/efficiency, moisture removal rate, or mass transfer coefficient [18,42–44]. The dehumidifier effectiveness is the ratio of the achieved change in the humidity level of the air exiting the dehumidifier, to the maximum theoretical change.

$$\varepsilon_d = \frac{w_{in} - w_{out}}{w_{in} - w_{equ}}$$

where w_{in} and w_{out} are the water contents of the inlet and outlet air streams respectively; while w_{equ} is the water content of the air which is at equilibrium with the desiccant solution at the inlet concentration and temperature.

The moisture removal rate, m_w , can be given in terms of the air flow rate, \dot{m}_a , as [44]

$$m_w = \dot{m}_a (w_{a,in} - w_{a,out})$$

The mass transfer coefficient K (for vapour phase) can be obtained from empirical correlations in terms of non-dimensional parameters Sherwood number (Sh), Reynolds number (Re) and Schmidt number (Sc) [45].

$$Ka \left(\frac{M_w d_{eq}^2}{D_{va} \rho_a} \right) = Sh$$

$$Sh \propto Re Sc \frac{L}{G}$$

where d_{eq} is equivalent diameter in the dehumidifier; M_w is the molecular weight of water; D_{va} is the water vapour's diffusion coefficient in air; ρ_a is the density of the air, a is the packing's specific surface area; L and G are the mass flux of the liquid desiccant and air respectively.

2.3.1.1. Spray tower. In spray tower arrangement, gas (air) usually flows upwards, while liquid (the desiccant solution) is fed from the top of the tower through the spray nozzle. The nozzles are used to break the liquid down into small droplets, such that in operation, the gas and liquid interact over the outside surface of the small liquid droplets; thus providing large surface area for heat and mass transfer. The spray towers have the merits of simplicity, low cost, and low air side pressure drop, however, their major drawbacks are low absorption effectiveness and large carryover [15].

In minimising carryover, conventional spray chambers employ dense cellulose pads (demisters) to restrict the liquid droplets from escaping the chamber [46], however, this adversely increases the pressure drop on the air side [38]. To overcome this issue, different techniques have been proposed.

Kumar et al. [38] proposed using stainless steel wire mesh to eliminate the carryover. Experimental results show improvement in performance of conventional spray tower by about 30% without increasing air side pressure drop.

To enhance the mass transfer rate and to avoid carryover of liquid particles, Chung and Wu [47] proposed a "U-shape" tunnel spray tower with eliminators in the spray tower. Unlike in conventional arrangements, the air was introduced from the top of the tower to contact the liquid particles co-currently. This co-current contact of air and solution reduced the carryover of liquid particles. In an experimental study of the design, with 95% TEG desiccant solution, it was observed the mass transfer coefficient increases linearly with an increase in air flow rate. The achieved

mass transfer coefficients varied from 1.78 to 2.95 mol/m³ s, corresponding to heights of a single transfer unit of 0.63 to 0.38 m, respectively. The efficiencies of the spray tower typically varied from 64% to 86%. In a later study [48], they presented empirical correlation of the mass transfer coefficient as:

$$Sh = 4.0 * 10^{-5} Re^{1.73} Sc^{0.33} \left(\frac{P_s}{P_{total}} \right)^{-0.5} \left(\frac{L}{G} \right)^{1.15}$$

2.3.1.2. Packed tower. The packed tower consists of a column packed with materials having a large surface to volume ratios. To promote mass transfer, it is desired that the desiccant wet the packing and spread evenly over its surface. Considerations for the choice of packing materials for the dehumidification process include pressure drop, sensitivity to fouling, liquid holdup, ease of handling high or low desiccant flow rate, resistance to corrosion and cost [49].

The materials may be packed in random or structured patterns. The random packing may employ different or same materials and sizes. Examples include polypropylene Pall rings, partition rings, glass Raschig rings, flexi rings, Lessing rings, Berl saddles, Tell-ettes, and ceramic Intalox saddles. These types of random packing materials offer large contact area in a relatively small volume compared to structured packing, thus facilitating more mass transfer. However, they generally cause high air pressure drop [50].

On the other hand, structured packing exhibits high efficiency and high capacity for mass and heat transfer, in contrast to the traditional random packing. They have shown excellent performance characteristics with a relatively low ratio of pressure drop to heat and mass transfer coefficient per unit volume, in addition to easy installation [50]. Examples of structured packings include cellulose rig pads, wood grids, expanded metal lash, double spiral rings. Some commonly structured packings types can also be categorised as gauze type and sheet types. These packings can be arranged as corrugated sheets, such that air and liquid flowing between adjacent sheets undergo periodic redistribution within the packing.

Gandhidasan [49] developed a model for estimating the pressure drop in a packed tower dehumidifier for both random and structured packings. Three different structured packing materials (Gempack 2A, sheet-type Mellapak 250 Y and Gauze type) and four random materials (Pall rings, Berl saddles, Raschig rings and Intalox saddles) were considered in the analysis. It was shown that among random packing materials the Intalox saddles can give the least pressure drop while among the structured packings, the sheet type (mellapak 250 Y) promised the least pressure drop.

Abdul-Wahab et al. [51] experimentally studied the effect of the effect of packing densities, on the performance of dehumidifier

with structured packings of arrays of stacked plates and TEG desiccant solution. Lower dehumidification effectiveness was observed for the higher packing density, as a result to poor wetting conditions in high packing density.

Elsarrag [52,53] conducted theoretical and experimental studies of the simultaneous heat and mass transfer to evaluate a packed dehumidifier effectiveness using high outdoor air flow rates. Due to packing arrangements, the tested dehumidifier showed high efficiency (80% to 90%), low pressure drop and minimum solution carry over. In his previous study [54], the mass transfer coefficient was empirically correlated within +/- 15% as.

$$Sh = 6.18 * 10^{-6} Re^{1.3} Sc^{0.33} \left(1 - \frac{P_s}{P_w} \right)^{-0.77} \left(\frac{L}{G} \right)^{0.55}$$

Incidentally, the method of distributing the liquid over the packed tower could also influence the performance as observed by Patnaik et al. [55]. Two methods of liquid distribution, namely: gravity tray distributor and spray nozzle system where studied. Higher capacities (40–50% increase) and lower pressure drop (30–40% reduction) for the air flow were observed with the spray system.

2.3.1.3. Wetted wall (falling film) column. Wetted wall/falling film column arrangements consist of a set of tubes (Fig. 5a) or plates (Fig. 5b) over which desiccant solution flows down by gravity while air is blown through it. The liquid flows as thin film over the vertical surfaces represented by the tubes or plates, and the air is brought into contact with the surface of flowing liquid film. Besides having low pressure drop and low initial cost, these columns also provide large contact surface area per unit volume [56]. However, in practice there is the difficulty of ensuring a thin film over the entire surface, especially for large towers [57,58]. The measure of the degree of wetness achieved is termed wetness factor or wettability, and can influence the performance of the system. Studies have shown that the wettability can be enhanced using micro/nano scale surface treatment [59]. The experimental study by Kim et al. [59] emphasised that as a result of the improved wettability achieved on roughened tubes, higher heat and mass transfer performances was observed for the roughened tubes (relative to smooth tubes).

Besides tube surfaces, the plate type arrangements are widely studied in the literature [60–62]. The plates could be flat or corrugated, and the arrangements are often internally cooled. A typical internally cooled plate dehumidifier could entail cooling water circulated in polypropylene double plates involved an upward airflow and a downward solution flow. A special distributor of liquid desiccant on top of each plate could help the solution flow uniformly over the exchanger surface. The

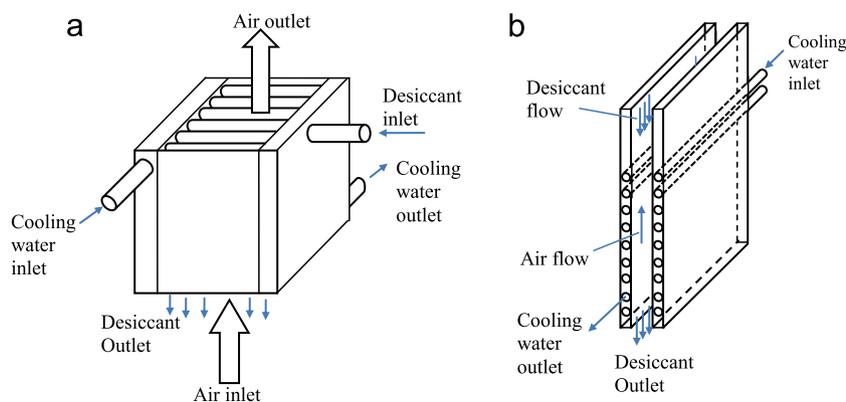


Fig. 5. Schematics of wetted wall falling film system [60]; (a) tube type (b) plate type.

performance of plate dehumidifiers systems can be influenced by the setup of the system.

Ali et al. [63] performed a comparative study between air and falling desiccant solution film in parallel and counter-flow configurations, with nanoparticles suspensions (Cu-ultrafine particles) added to the desiccant solution to investigate the heat and mass transfer enhancements. The numerical results showed that, for a wide range of parameters, the parallel flow arrangement indicated better dehumidification and cooling of the air, than the counter-flow channel. This was said to be a result of the exit humidity ratio and air temperature being lower in the parallel flow arrangement than in the counter flow. However, elsewhere [64], counter flow arrangement has been shown to provide better performance.

Furthermore, a study by Park et al. [65] found that a decrease in the mass flow rate of the air resulted in a better control of the humidity ratio and lower temperature for the air. Yigit [27] obtained the heat and mass transfer coefficients of the absorption process in a falling film LiBr–water absorber. This author also studied the effect of varying coolant flow rate, solution flow rate and coolant temperature on the absorber performance. Deng and Ma [66] used a falling film absorber that was made up of 24 horizontal rows of smooth tubes. The results showed that while the mass transfer coefficient was increased with the increase of the spray density, the heat transfer coefficient was increased only in a small spray density range.

Other kinds of performance enhancement have also included the adoption of fin heat exchangers in the implementation of internally cooled film dehumidification, taking the form of plate-fin-heat exchanger (PFHE) [56,67] or fin-tube heat exchanger [68].

To further enhance performance, some designs adopt evaporative cooling in the internal cooling channels of the absorber. Here, a standard plate heat exchanger, PHE, with several flow passages separated from each other by thin plastic plates, is employed such that dehumidification is carried out on one side of the plate, while evaporative cooling is concurrently effected on the other side, in a cross flow manner. Each thin plate, besides separating the water–air passage from the solution–air passage, also provides a contact area for heat and mass transfer between the fluids flowing in each passage. Saman and Alizadeh [69] conducted numerical analysis and indicated that the dehumidification efficiency of the PHE increases as the solution mass flow rate increases and up to 85% efficiency could be achieved at an optimal primary air velocity of about 0.7 m/s (0.3 kg/s) however; the performance achieved in an experimental study by Alizadeh [70] was only about 60%. Furthermore, an experimental study by Saman and Alizadeh [71] indicated the performance of the system is also dependent on the angle of inclination of the PHE, with an optimal angle about 25–45°.

2.3.1.4. Other novel systems. A novel rotary absorber system was patented by Riffat [72]; the proposed system employed flexible fibre needle-impeller rotors/fan to improve heat and mass transfer in the absorber (and evaporator) units. Unlike in conventional desiccant systems, it is possible to achieve a large transfer area per unit volume. The fan could perform the function of the absorber (or evaporator) by feeding the fibres with a desiccant solution (or water) [73]. Oliveira et al. [74] studied the system experimentally, and developed a model for characterizing its performance in different system parameters.

Another novel rotary contacting device, in a rotating disc configuration (Fig. 6), was studied by Lowenstein et al. [75]. Besides high surface area density and low air side pressure drop, a salient characteristic of this system that distinguishes it from conventional ones is its relatively very low flows of liquid desiccant (typically 20 times lower), making it less prone to carryover.

Another dehumidification technology that has been considered extensively to address the desiccant droplets carry over phenomenon,

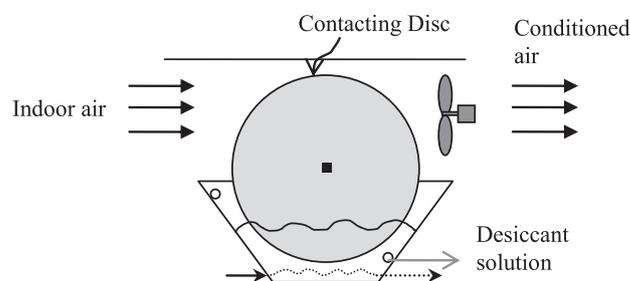


Fig. 6. Rotating disc air contacting device [76].

involve indirect contact, employs semi-permeable membrane, separating the air and liquid desiccant streams, such that only water vapour is allowed to permeate from the air to the liquid stream, but prevents the transport of liquid.

A further dehumidification technology that has been extensively considered to address the liquid desiccant droplets carry over phenomenon involves indirect contact between the air and liquid streams via a hydrophobic semi-permeable micro-porous membrane, which allows only water vapour to permeate while preventing the transmission of liquid, thus eliminating the desiccant carryover problem [77–81]. Researchers have proposed membrane designs such as flat plate type [82–86] or hollow tube fibre type [87–90]. Though the flat plate membrane type is simpler in construction, the hollow fibre membrane type promises relatively better effectiveness, due to the latter's considerable higher packing density [91]. Studies [92,93] have highlighted that although considerable vapour flux could be obtainable with the membranes, the dehumidification effectiveness was generally low, as the membranes offered resistance to mass transfer.

2.3.2. Evaporative cooler

Although evaporative cooling systems can be built in a variety of arrangements or configurations, as introduced earlier (in Section 2.2) they are no more than various combinations of three basic types, namely: direct evaporative cooling (DEC), indirect evaporative cooling (IEC), and semi-indirect evaporative cooling (SIEC).

2.3.2.1. Direct evaporative coolers. Direct evaporative cooling (DEC) is the oldest and simplest type of evaporative cooling and involves bringing the process air into direct contact with water. One of the main evaporative cooling strategies often encountered is the fan-pad system [94]. The fan-pad arrangement includes a fan/blower and an evaporation pad (example include: metal pads, cellulose pad, organic pad, inorganic pad (GLASdek, PVC pad, etc.) which provides the needed large surface area over which the air and water are contacted for effective evaporation. Often these coolers have the fan, the pad and ancillary systems all enclosed in a box (Fig. 7), such that the pad is kept moist by continuously dripping water onto the upper edges of the pad, the water gets distributed further by gravity and capillary action. The falling water is collected in a water basin underneath the pad and recirculated by a water pump [95]. The drip-type coolers are the cheapest and simplest evaporative coolers but have some problems including pad clogging, pad scaling. Alternatives, requiring less maintenance (though at a higher cost) are Slinger-type, sprayed-pad and rotary-pad evaporative coolers [96].

The performance of DEC can be indicated with the cooling or saturation efficiency or effectiveness, generally defined in terms of the wet-bulb temperature

$$\eta_{wb} = \frac{T_{in} - T_{out}}{T_{in} - T_{wb}}$$

where η_{wb} is the wet-bulb effectiveness, T_{in} and T_{wb} are respectively the dry-bulb and wet-bulb temperatures of the air at the inlet condition, while T_{out} is the dry-bulb temperature at the outlet of the system. Most of the existing commercial DEC coolers in market can achieve 70–95% saturation efficiency.

2.3.2.2. Indirect evaporative coolers. Besides the air to be cooled (primary air), indirect evaporative coolers (IEC) employ a secondary air stream that is brought in direct contact with water and have the resulting cooling effect transferred via heat exchange medium to the primary air; i.e. a direct evaporative cooled secondary air stream is used to cool indirectly a primary air stream. Depending on the kind of heat exchanger employed, IEC can be categorised as tubular type IEC, plate type IEC and heat pipe type

IEC as depicted in Fig. 8(a–c) respectively. Since the primary air does not make direct contact with water in the IEC, the temperature of the primary air decreases without a change in its absolute humidity as shown the psychrometric chart (Fig. 8e).

The wet-bulb effectiveness of IEC can be expressed in terms of the wet-bulb temperature of the secondary air as

$$\eta_{wb} = \frac{T_{in} - T_{out}}{T_{in} - T_{wb,sec}}$$

where T_{in} and T_{out} are the inlet and outlet dry-bulb temperatures of the primary air respectively; while $T_{wb,sec}$ is the inlet wet bulb temperature of the secondary air. The effectiveness of IEC is generally around 50–70% [98].

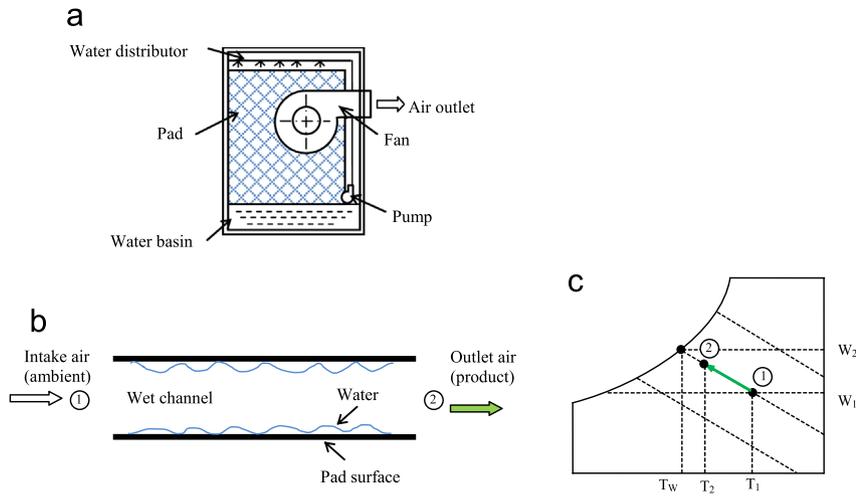


Fig. 7. (a) Schematic of drip-type DEC [95]; (b and c) typical air and water interaction and psychrometric process [97].

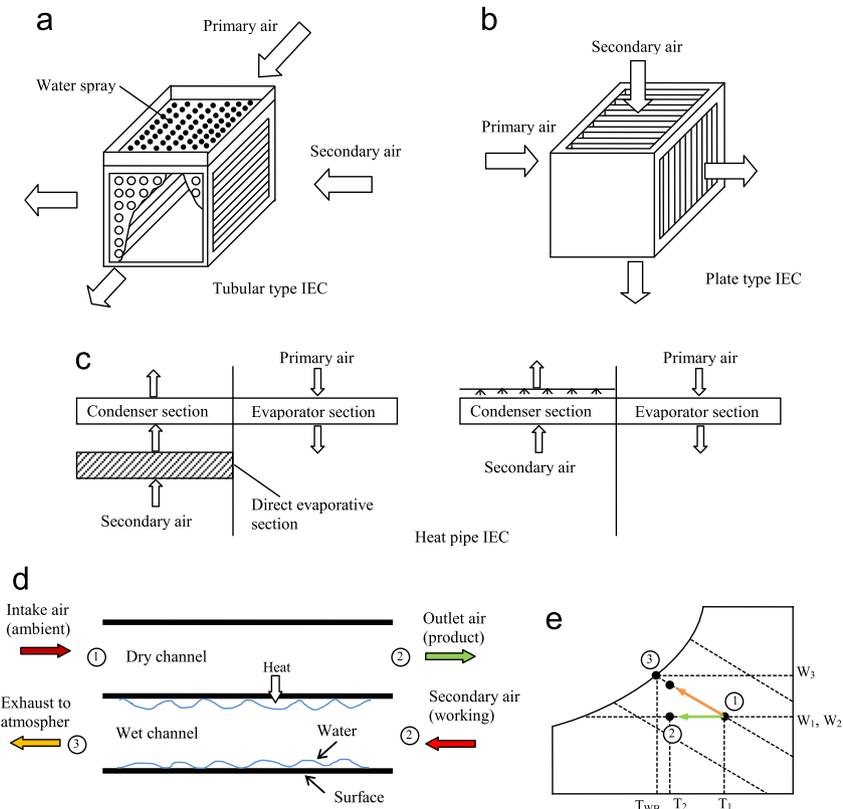


Fig. 8. (a)–(d) Schematics of IEC and (e) psychrometric process [95,97].

2.3.2.3. *Semi-indirect evaporative coolers.* Semi indirect evaporative cooler (SIEC) employ porous materials such as porous ceramic tubes or hollow bricks [99] to effect heat (and mass) transfer. A typical schematic of the system is depicted in Fig. 9. Water (and secondary air) is contained/flow inside the channel/hollow of the material while the primary air flows over the outside surface. The porosity of the material allows the water inside the tube/brick to be capillary transported through the walls to the outside surface of the material, where it evaporates into the primary air if its vapour pressure is higher than that of the air (thereby acting as a DEC). However, if the vapour pressure of the outdoor air is higher than that of the water at the surface, the system works merely as an IEC. Thus the heat and mass transfer is between the processes of DEC and IEC [100]. And the wet-bulb effectiveness of the system can be obtained as outline earlier, and could be in the range of 40–80% [98].

2.3.2.4. *Dew point indirect evaporative (DPEC) cooling.* Dew point evaporative cooling is somewhat a configuration of indirect evaporative cooling comprising adjacent wet and dry air passages/channels.

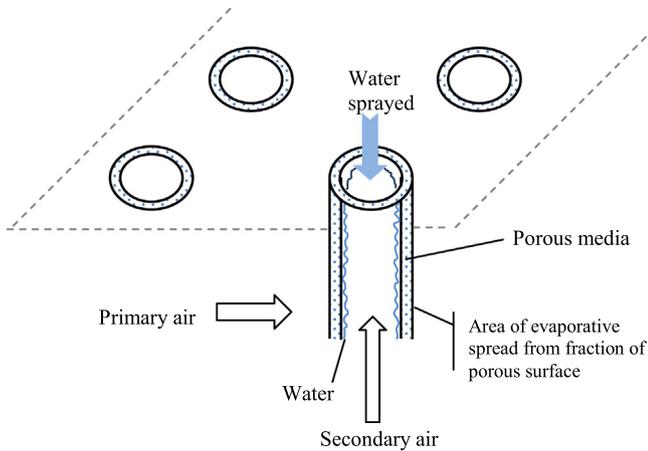


Fig. 9. Schematic of a SIEC [101].

It consists of specially made plates that are designed to wick water evenly on side and transfer heat through the other side; there are numerous holes distributed in the air flow channels of the incoming working air [102,103] (Fig. 10). On operation, the working air initially enters dry channels and is fractionated into multiple streams which are directed into the wet channels through the holes. However, some variants (often called regenerative evaporative coolers) do not have holes but redirect a portion of the air exiting the dry channel into the wet channel [104–106]. As a result of evaporation, the air in the wet channel absorbs heat from the product air flowing in the adjacent side. This process occurs multiple times in a short physical space within the exchanger, thus, resulting in progressively colder product air temperatures [107].

The arrangement enables the temperatures of the product air to be cooled nearly to the dew-point temperature of the incoming working air, which is considerable lower than the wet bulb temperature (the achievable limit for direct evaporative cooling) [108].

For DPEC, the saturation efficiency can be expressed based in terms of dew point temperature as

$$\eta_{dew} = \frac{T_{in} - T_{out}}{T_{in} - T_{dew,in}}$$

where, T_{in} and T_{out} are the inlet and outlet dry-bulb temperatures of the product air, $T_{dew,in}$ is the dew-point temperature of the working air at the inlet. Generally, the dew point saturation efficiency can be between 55% and 85%, however, the wet-bulb efficiency (based on the wet-bulb temperature) can be as high as 110–122% [97].

The DPEC has been studied by several researchers [98,109,110]. Zhan [111] found that for optimum performance, the optimum flow rate ratio of working-to-product air was about 50%, and the dimensionless channel length (ratio of channel length to height) should be between 100 and 300. And it has also been shown to exhibit greater (over 15%) cooling effectiveness, when operated in counter flow configuration compared to cross flow [109].

Cui et al. [112] simulated the behaviour of a DPEC and presented correlations for the heat and mass transfer coefficients. The mass transfer coefficient (h_m) was given in terms of the Sherwood

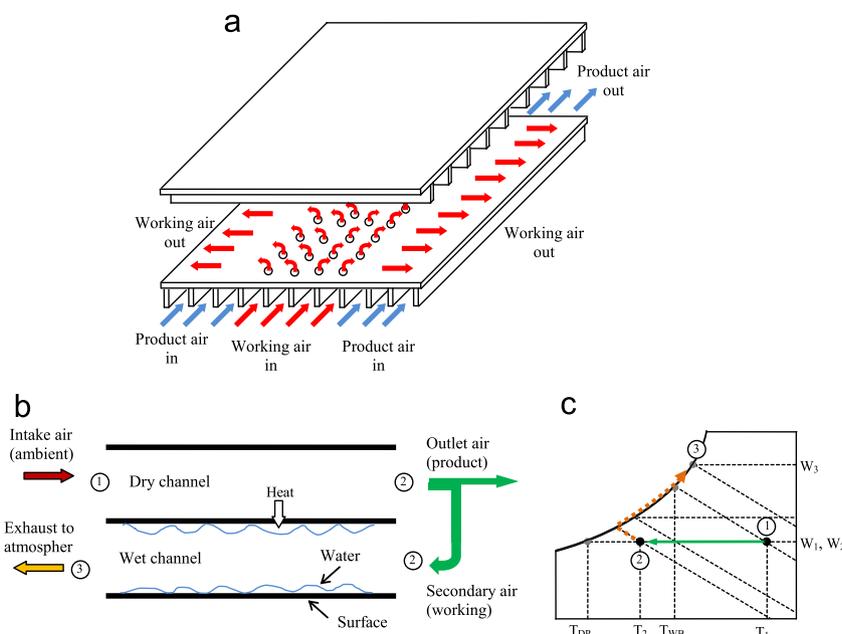


Fig. 10. (a), (b) schematics of DPEC and (c) psychometric process [97,107].

number correlation as

$$Sh = \frac{h_m D_p}{D_{va}} = 2.0 + 0.6Re^{1/2} Sc^{1/3}$$

While the heat transfer coefficient (h) was given in terms of Nusselt number, Nu , correlation as

$$Nu = \frac{h D_p}{k_a} = 2.0 + 0.6Re^{1/2} Pr^{1/3}$$

where D_p is the diameter of particle water droplet; k_a is the thermal conductivity of air, Pr is Prandtl number.

2.3.3. Regenerators

As explained above, evaporative coolers are employed to cool the dehumidified air from the dehumidification unit; however the liquid desiccant employed to effect the dehumidification gets diluted in the process and thus needs to be re-concentrated by a regenerator before being reused. The regenerator is a very crucial heat and mass transfer component in a liquid desiccant system. The heat used for the desiccant regeneration represents the largest energy requirement associated with the liquid desiccant system; hence the overall system performance can be greatly influenced by the effectiveness or efficiency of the desiccant regeneration process [113].

The effectiveness of the regenerator can be given of the change in moisture content of the air stream flowing through the regenerator [114]

$$\epsilon_{re} = \frac{W_{out} - W_{in}}{W_{out,max} - W_{in}}$$

Alternatively, the effectiveness can also be given in terms of the change in concentration of the desiccant solution flowing through [115]:

$$\epsilon_{re} = \frac{C_{s,out} - C_{s,in}}{C_{s,sat} - C_{s,in}}$$

where $C_{s,in}$ and $C_{s,out}$ are the concentrations of the desiccant solutions flow in and out of the regenerator respectively, while $C_{s,sat}$ is the concentration of the saturation solution at the given average temperature of the regenerator.

Elsarrag and Abdalla [116] presented a new regenerator effectiveness definition based on the desiccant properties and assessed experimentally. The definition may be helpful to the regenerator designers to evaluate the effectiveness using the air and solution vapour pressures, the proposed definition and the presented correlation are shown below respectively.

$$\epsilon_{re} = \frac{P_{s,in} - P_{s,out}}{P_{s,in} - P_{a,in}}$$

$$\epsilon_{re} = 79.12 + 1.21 \times \left(1 - \frac{P_{a,in}}{P_{s,in}}\right) + 4.37 \times \frac{m_a}{m_L}$$

where P_s and P_a are the solution and air partial pressures respectively; m_a and m_L are the air and desiccant mass flow rates respectively.

The heat required for the regeneration process can be taken from a suitable heat source, for example, solar thermal collectors via a thermal fluid (and heat exchangers) to heat the desiccant solution and/or air which are brought into contact in a regenerator. This arrangement can be regarded as an indirect solar utilising regenerator (Fig. 11); however, in alternative arrangements, the regeneration process can be realized directly in the solar collector [117].

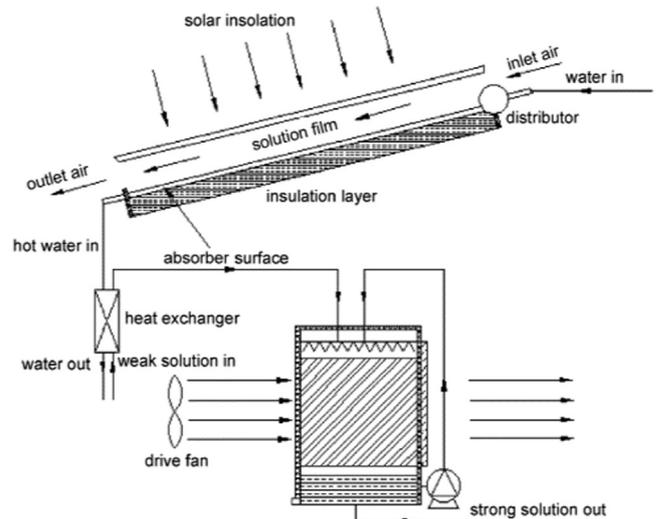


Fig. 11. Schematic of indirect solar energy utilisation for regeneration [115].

2.3.3.1. Indirect use of solar energy for regeneration. The air contacting equipment of the regenerator can be of the same configuration as the dehumidifier, i.e., spray tower, packed tower and falling film column (as discussed in Section 2.3); however, the processes occurring within them are in reverse. The membrane based air contacts have also been considered for the regenerator [118].

The packed regenerator has been widely investigated because it offers large contact area for heat and mass transfer [119]. Longo and Gasparella [120] carried out an experimental analysis of lithium bromide desiccant regeneration in packed columns. Their results showed that the desiccant regeneration required temperature levels of about 50 °C; and the regeneration performance of the random packed column showed 20–25% higher than structured packed column, whereas the structured column showed air side pressure drop 65–75% lower. A study by Elsarrag [121] on TEG regeneration in the structured packed column, suggested that the desiccant regeneration requires a higher solution temperature in humid climates compared to dry climates.

In typically packed regenerators, heat and mass transfer happen only between the air and desiccant. There is no additional heat transferred into the regenerator. Thus, the desiccant temperature and consequently the mass transfer could deteriorate in the regenerator. Internally heated regeneration (just like internally cooled dehumidifier) could be an alternative to solve this issue [122,123]. The internal heating can easily be implemented in spray towers and falling film regenerators with the aid of coils and plates.

2.3.3.2. Direct open or closed types. Unlike the indirect heat regenerator systems, the direct variant does not require separate regenerator equipment, as the desiccant solution is being regenerated directly in the solar collector [124]. This solar collector regenerator arrangement can be of an open or a closed type.

The open-type regenerator is quite a simple configuration; consisting basically a distributor, a tilted blackened surface, and an insulating layer underneath (Fig. 12). On operation, the weak desiccant solution is distributed and flows over the tilted surface, where it gets exposed to ambient air, as it is open to the atmosphere. And mass transfer from the solution to the air occurs, since the vapour pressure of the air is lower than that of the solution.

Being open to the atmosphere, the system can easily be affected by adverse weather conditions and dust contamination; and is also prone to heat loss from the solution to the ambient, which will adversely reduce the regeneration temperature.

2.3.3.3. Closed-type. The closed-type regenerator can take the form of simply providing a transparent glazing cover for the aforementioned open-type variant (Fig. 13). The configuration is similar to that of a solar still if both ends of the glazing are sealed. The solar radiation passes through the glass to the solution film flowing over the inclined collector surface; then upon evaporation, the water vapour released from the solution rises to the underside of the glass, where it condenses and is tapped off.

Although the closed-type arrangement may protect against the adverse surrounding atmospheric conditions, and also reduce the heat loss to the ambient; if the basic arrangement lacks ventilation, this will inadvertently lower the driving force for the regeneration process, which is the vapour pressure difference between the solution film and the contained air, because the condensation of vapour underneath the glazing will consequently lead to increase in the vapour pressure of the contained air [115]. However, experimental studies [76] have also reported that the performance can be significantly enhanced if a means of cooling is provided for the glass cover.

2.3.3.4. Solar collector regenerator with natural convection and forced convection. The arrangement of the closed-type solar collector can be subjected to natural or forced convection if the ends of the glazing are open for ventilation [125]. For the natural convection type, the performance can be at the mercy of random wind flow direction. However, studies [126] have indicated that the water evaporation rate can be relatively higher in comparison to the open-type because the reduction in the heat losses can increase the solutions temperature and vapour pressure sufficiently to overcome the associated reduction in the mass-transfer coefficient. Nevertheless, McCormick et al. [127] have reported that there exists an optimal glazing height, beyond which the system performance becomes similar to that of the open-type variant. An experimental study by Yang and Wang [128] found an optimal glazing height as 0.07 m.

On the other hand, for the forced convection type, a continuous flow of air is supplied through the glazing ends. Studies have reported the forced flow configuration to be relatively more effective in comparison to the natural flow variant [129]. Ji and wood [130] indicated that increasing air flow rate could improve performance. However, an experimental study by Kabeel [131] on forced cross-flow also reported similar improvement in performance relative to natural flow. Evaporation rate increases strongly

with an increase in air flow rate. However, the evaporation decreases beyond a certain high flow rate. The phenomenon was attributed to the fact that though the increasing air flow rate enhances the mass transfer coefficient, excessive flow velocity adversely results in a decrease in the regenerator temperature, and consequently a decrease in the vapour pressure, which may ultimately result in a decrease in performance. This phenomenon has also been reported for parallel flow configuration [132,133].

Elsarrag [134] developed a novel hybrid solar regeneration and studied the influence of varying air flow rate, inlet desiccant temperature, as well as desiccant concentration and inlet air humidity on the evaporation rate. Moreover, he reported the optimum desiccant-to-air flow ratio to maximise evaporation rate, see Fig. 14.

2.4. Discussion of liquid desiccant cooling systems

Liquid desiccant cooling systems are especially suitable for solar energy applications since the liquid desiccant can be regenerated at temperatures below 80 °C. The solar energy can be collected and indirectly utilised to re-concentrate weak desiccant solution in air contacting regenerator equipment. On the other hand, direct solar collector regenerators obviate the need for separate regenerator equipment, as the regeneration is directly carried out in the solar collector itself.

Given the intermittent nature of solar energy, energy storage is essential to provide continuous or extended operation of the liquid desiccant cooling system. Researchers [135,136] have proposed storage of the concentrated and diluted desiccant solutions, to provide for extended air dehumidification and cooling.

With respect to dehumidification and energy storage, the mass flow ratio ($MR = \frac{\dot{m}_{air}}{\dot{m}_{sol}}$) of air to desiccant the solution is an important factor for absorber efficiency and system capacity. Previous studies on dehumidifier performance indicated that smaller MR generally results in better performance [20]. On the contrary, Kessling et al. [33] pointed out that storage capacity increases with higher MR . As such air-to-solution flow ratios in the liquid desiccant system needs to be adjusted to the thermodynamical requirements for both air dehumidification and energy storage to be possible at the same time [137]. Laevemann and Sizmann [138] showed that salt solution desiccants are well suited as storage material for dehumidification and that storage capacities up to 1000 MJ/m³ are achievable.

From the preceding, it can be seen that direct solar collector regenerators and energy storage capability are both desirable features that are been sought in advancing liquid desiccant cooling systems; therefore it can be deduced that an arrangement that inherently combines these two features would present a promising field of study. And given that salt solution desiccants are well suited as a storage material for dehumidification, it can be proposed that the salt desiccant solution reservoir can be fashioned in the form of a solar pond to collect directly and store the solar energy, whilst providing the needed desiccant for dehumidification and cooling.

In a nutshell, in conventional practice, the typical solar pond (like other conventional solar collectors such as flat plate, evacuated tube, parabolic trough) can be employed to capture solar energy that can be delivered via heat exchangers to re-concentrate weak desiccant solution in the regenerator equipment. However, as an alternative with a minimal number of components, this paper is recommending a potential arrangement where the solar pond is itself the regenerator, thus having the combined features of the solar collector, energy storage and desiccant regeneration. Nevertheless, the proposed concept will require further research

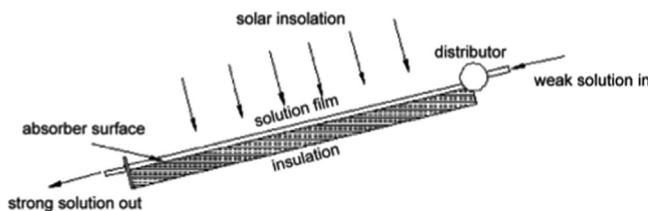


Fig. 12. Schematic of open-type solar regenerator [115].

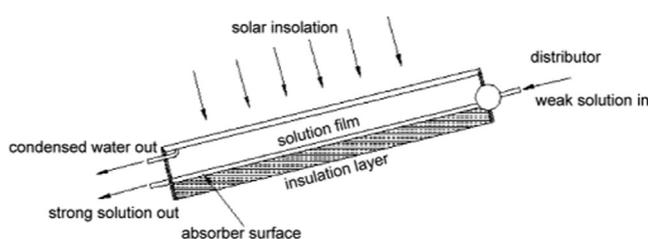


Fig. 13. Schematic of a closed-type solar regenerator [115].

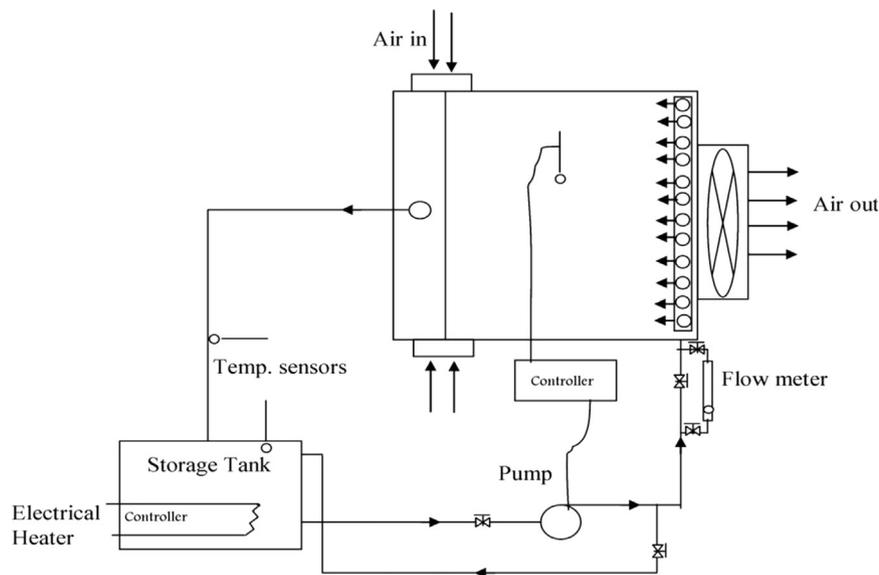


Fig. 14. Schematic of the hybrid solar regenerator [134].

work in investigating the practical realisation of the concept. The next section will review the state of the art in solar pond technology.

3. Solar ponds

In this section, we review solar ponds with a focus on their potential application in liquid desiccant cooling. Back in 1902, Kalecsinsky observed a natural salt lake in Transylvania in East Europe and published his report on a natural solar lake [139,140]. It was noted that the water had a temperature of 70 °C at a depth of 1.32 m during summer and a minimum temperature of 26 °C. The bottom salinity was near 26% of NaCl. A similar lake was reported in Washington USA by Anderson [141,142], and a temperature of 50 °C was observed at a depth of 2 m during summer. In 1948, Bloch [143] proposed the salinity gradient solar pond (SGSP) as a solar energy collector and a thermal storage device. These observations encouraged the theoretical and experimental studies aimed at designing and constructing artificial solar ponds to collect and store solar thermal energy. Tabor, Weinberger and Tabor and Matz did extensive pioneering work on SGSP [144–146]. Besides the proposed use in liquid desiccant cooling, solar ponds can be used in various of applications such as heating and cooling of buildings, power production, desalination, power productions and many [147].

A solar pond is considered to be a basin of water with a gradient concentration of dissolved salts that collects solar energy and stores it as thermal energy within its depth, so it acts as a collector and a storage device at the same time. When the sun rays fall on a pond, the water molecules heat up and the temperature increases towards the bottom of the pond. This would normally cause the water to rise; however, this is avoided in salt gradient solar ponds prevent as dissolved salt in the bottom layer of the makes the water too dense to rise to the surface. Therefore, solar thermal energy accumulates at the bottom of the pond, causing the temperature to rise up to 100 °C or even more [148]. Such high temperatures can provide a heat source which is accessed by withdrawing brine or using a heat exchanger [149]. The various types of solar ponds fall into two main categories: non-convecting and convecting solar ponds [150].

3.1. Non-convecting solar ponds

This type of pond inhibits the heat loss due to convection by stopping the currents of convection from occurring within the fluid. The name comes from the non-convecting zone between the upper convective zone and the lower zone [151]. Non-convecting ponds consist of three salt water layers, where the highest salinity concentration is in the bottom layer, and it is divided into four sub-types: salinity gradient solar ponds, membrane solar ponds, viscosity stabilized ponds, partitioned solar ponds and saturated solar ponds [152].

3.1.1. Salinity gradient solar ponds (SGSP)

The SGSP consists of three different zones or layers. The first is the upper convective zone (UCZ) or the surface zone, which has the least salinity. The second layer is the non-convective zone (NCZ) or the gradient zone, with a graduate increase of density. The third layer is the lower convective zone (LCZ), which also referred as the storage zone with a uniform density and the highest concentration of salinity as shown in Fig. 15.

SGSP is a device that collects solar energy using salt solution with different densities to inhabit the natural convection and stores it as thermal energy [160]. The SGSP consists of three layers; the upper convecting zone (UCZ), the non-convecting zone (NCZ) and the lower convecting zone (LCZ) as shown in Fig. 16.

3.1.1.1. The upper convective zone. This zone consists of fresh or low salinity water that acts as a zone for solar absorption and transmission. The water temperature within this zone is close to ambient temperature. Usually, the depth or thickness of this layer is between 0.2 and 0.5 m, and it is better to keep this layer as shallow as possible, typically at 0.3 m. UCZ usually influenced by wind agitation and convective mixing.

3.1.1.2. The non-convective zone. This zone is located in the middle of the solar pond and separates the UCZ and the LCZ. This layer is much thicker than the UCZ and it is recommended to be between 0.8 and 1.5 m this with an optimum thickness if 1 m. This layer is not homogeneous because the temperature and the salinity increase with depth as shown in Fig. 16. Therefore, NCZ provides stability to the pond at which it prevents any gravitational overturn also it inhabits the heat loss due to convection.

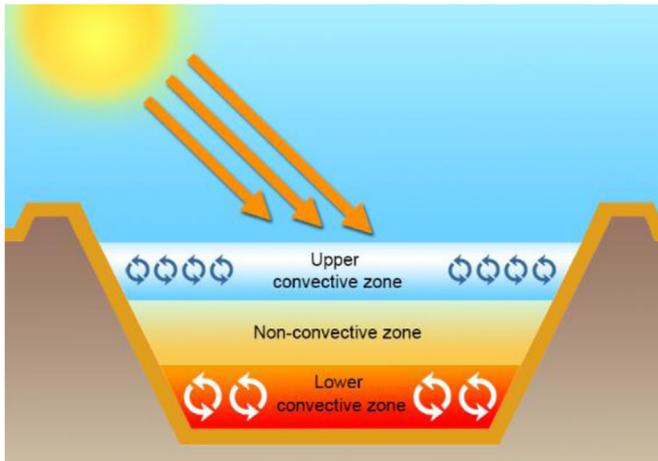


Fig. 15. Schematic representation of a salinity-gradient solar pond.

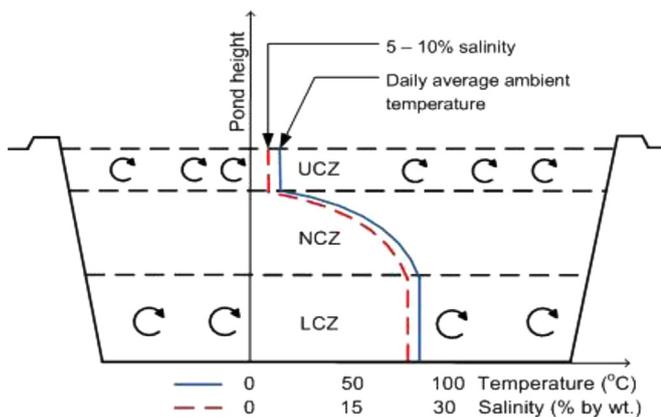


Fig. 16. Schematic showing the different salinity gradient zones.

3.1.1.3. The lower convective zone. This zone is a homogenous layer that has the highest salt concentration and the highest temperature, and it is constant within this layer; this layer stores the solar energy as thermal energy and it can be withdrawn in and out of the pond by extracting the hot brine. The depth of this layer can be as the depth of NCZ, but it is typical to be 1 m deep with an option to be more.

3.1.2. Membrane solar ponds (MS)

Membrane solar ponds are similar to the SGSP. In membrane solar ponds, however, a thin transparent membrane is installed to separate the zones of the pond and to suppress the convection; although the heat is exchanged in a similar manner in SGSP. Membrane solar ponds have horizontal sheets, vertical tubes and vertical sheets [153].

3.1.3. Viscosity stabilized solar pond (VSSP)

SGSP can lead to environmental pollution, in the case of a salt leakage. Moreover, the salt gradient layer requires constant maintenance. To overcome such difficulties, Shaffer [154] proposed a hybrid solar pond that contains a transparent polymer gel to act as a non-convective layer or zone. The polymers used in such pond should have a high transmittance for solar radiation, high efficiency of the chosen thickness and should be able to operate at temperatures up to 60°C. Starch, Gelatin and Arabic gum can be suitable materials to use in viscosity stabilized solar ponds [155].

3.1.4. Partitioned solar pond (PSP)

This solar pond has a similar principle as the membrane solar pond [155]. In this type, two transparent partitions are installed. This idea occurred when Tabor [156] has noticed some problems during the operations of a solar pond. Bacterial and algae growth was a common problem facing most of the solar ponds. Moreover, the accumulation of dirt and dust in the pond caused a decrease in the transparency of the pond. Hence, less solar radiation absorbed. More problems such as evaporation have an effect on the salt concentration, making the top layer with high concentrations of salt [157]. In order to overcome these problems, two transparent partitions are installed one on top or few centimeters blow the surface of the pond, and the other at a depth of 1–2 m. There are some disadvantages associated with the thin layer of water above the top partition. The disadvantages include evaporative cooling and reflectivity increase due to wave movements, especially in windy sites. However, on the other hand, the reflective losses are decreased due to the lower index of refraction of water than plastics. An added advantage of installing partitions would be that the lower partition separates the insulating layer from the convective layer from the convective layer. This improves the stability of the solar pond and eases the heat extraction [139,157].

3.1.5. Saturated solar ponds (STSP)

The principle of a saturated solar pond is to have salt whose solubility increases with temperature, saturating the pond at all levels. This pond requires less maintenance, due to its ability to self-sustain the salt gradient and its stability. STSP are best used for short-term energy storage due to the rapid rise in temperature of the pond water [158].

3.2. Convecting solar ponds

Convecting solar ponds are quite different to non-convecting solar ponds in that they consist of one layer of homogenous fluid and covered with a transparent cover to inhibit heat loss due to evaporation and convection/conduction. Moreover, the cover can protect the solar pond from dust and any falling impurities. Convecting solar ponds were identified according to its basis of operational modes, however, Kreider and Keith categorised these ponds according to depth [149]. On the other hand, some researchers considered all convective solar ponds to be shallow solar ponds [140] whereas other researchers considered shallow solar ponds to be those having depths between 4 and 15 cm [155]. Shallow solar ponds are not a new concept. In early twentieth century, Willis and Boyle used the idea to produce shaft power [159]. They approached different designs of the solar pond and one of the solar ponds consisted of a wooden tank with a tar paper lining and covered by a window made of glass while the pond was insulated with hay. The water depth in that pond was 7.5 cm. More designs had asphalt and sand as insulation materials.

3.3. Design of solar ponds

3.3.1. General considerations

The solar pond designer needs to consider the type of fluid to be eventually heated (e.g. liquid or air), the target temperature and heating amount to be delivered. The storage temperature should be higher than the delivered temperature to account for losses. The designer also needs to consider the availability of fresh and saline water, land, contractors and labourers for construction. Local contractors and labour are preferred.

3.3.2. Site selection

An ideal site to constructs a solar pond should would the following characteristic [161]. It is recommended to select a site with

a free draining soil. A dry soil will and soil with good cohesion for forming stable walls.

- free draining and dry and solid soil.
- adjacent free or low-cost saline water.
- easy access to water supply for the pond.
- high incident solar radiation to achieve a good thermal performance.
- low wind speeds to minimise the wave-induced mixing and the depth of the top mixed zone.
- low amount of wind-borne debris to maintain cleanliness of the pond.
- flat land to minimise earth moving requirements.
- a method to withdraw heat readily.
- a stationary or deep groundwater to minimise heat loss on the ground.

3.3.3. Thermal output and sizing

The thermal performance of solar pond depends on the absorption of solar radiation within the layers of the pond. Therefore, the water in the pond should always be clear as much as possible in order to get the maximum amount of solar radiation within the storage zone. The more radiation that reaches there, the higher efficiency of energy and operating temperatures of the pond will be achieved [159].

Usually, a solar pond is around 3 m deep, and a storage zone with 1-metre thickness can receive between 20% and 25% of radiation. Taking into consideration the heat losses to the surrounding ground, a pond might get around 15–20% of the radiation that can be extracted into the desired application. Usually, the heat delivery would be around 40–50° above the average daily temperature of the location [161,162].

To estimate the pond surface area required to achieve the desired thermal load, the following should be done:

- I. look up the annual solar energy incident on a square metre of horizontal surface at the location of the pond.
- II. calculate the horizontal surface area on which the incoming solar radiation over a year is equal to the annual load desired to be supplied.
- III. multiply this surface area by a factor of 5–10 to estimate the surface area of the solar pond.

other factors that can impact the actual design of a solar pond is the brine used and the water quality and transparency.

3.3.4. Site preparation, excavation and lining

When constructing a pond, it is better to choose a land that is flat as possible. Moreover, to minimise the heat losses to the ground, it is recommended that underground water is 5 m or more below the natural ground surface. If this option is not available, then using insulation at the bottom of the pond is required.

In large solar ponds that can be 1000 m square and above, it is recommended to construct the pond by establishing the walls using the soil excavated from the periphery of the pond. The bottom of the pond will thus be below the ground level. Such arrangement can provide the head required for gravity feeding of the surface water from the solar pond to the adjacent evaporation pond.

Although unlined ponds can operate well, in many locations pond lining is necessary to prevent any leakages of brine and heat. When choosing a liner material, a material with high resistance to heat and ultraviolet radiation should be considered. The material should also be chemically stable and can withstand the mechanical strain of the solar pond. Usually, failure of liners is the most faced problems while operating a pond [162].

3.3.5. Source of salt

The commonly used salts in SGSP are sodium chlorides and bitterns. Bitterns usually consist of magnesium–potassium solutions as a result of salt production and desalination of seawater. Therefore, it is economically and environmentally beneficial to use sea water bitterns instead of sodium chloride.

It is also important to recycle the salt extracted from the pond by surface washing. This step would minimise the cost of operating the pond and will minimise the burden on the environment. The salt solution flushed from the surface of the solar pond can be collected in an adjacent evaporation pond and there concentrated for later injection back into the storage or gradient zones of the pond. An evaporation pond needs to be at least equal or more than the total area of the solar pond. Fig. 17 shows a solar pond with an evaporation pond.

Dissolved salts and water are the main requirements to establish the SGSP; it only needs highly concentrated brines and low salinity brine or fresh water. Brines used in ponds effect the overall cost of the solar ponds depending on the physical and chemical properties [148,155].

3.3.6. Source of water

A source of fresh water or low salinity water hence, less than 50,000 ppm salt concentration, should be available. The amount of fresh water required to establish a pond is measure by volume from the surface of the pond to the middle of the gradient layer. The amount of water needed to maintain the gradient depends on the losses due to evaporation and the flow rate of the overflow system removing the surface flushing water that contains the salt that has diffused upwards.

The rate of adding water to the surface zone must not exceed the rate of removal through the overflow by the rate of evaporation [161,162].

3.4. Examples of solar ponds

In the past decades, many solar ponds were constructed to be used in heat or power supply. Some of the main projects are reviewed here according to the country.

Lots of efforts and studies into deploying solar ponds technology, therefore the first commercial scale solar pond in the world was constructed in Ein Boqek in December 1979 [163]. The power units that were constructed near the dead sea are listed below [164]:

- A solar pond in Ein Boqek at the shore of the Dead Sea. The pond had a surface area of 7500 m² and a depth of 2.6 m and the maximum temperature achieved was 92 °C. It provided between 150 and 170 kW with efficiency between 15% and 19.4%.
- A solar pond in Bet Havara with a surface area of 25,000 m² to supply 5 MW of power.
- A Solar pond in Yavne with a surface area of 1500 m² providing 6 kW of power.

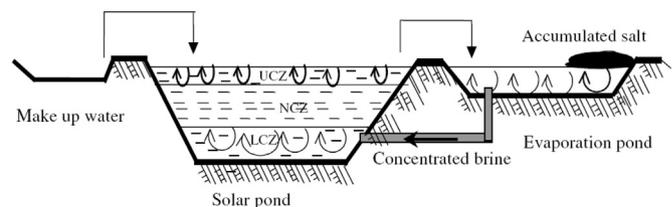


Fig. 17. A solar pond with an evaporation pond.

- A Solar Pond at the Dead Sea Potash Works with a surface area of 1100 m² that has a maximum temperature of 103 °C and had an efficiency of 15%.

Australia started deploying solar ponds for the production of salt. Therefore, a project was set up at Pyramid Hill Salt Pty Ltd. with collaboration with RMIT University. The application of this solar pond was for industrial process heating and drying process in commercial salt production.

Major solar ponds in Australia have included [164–166]:

- Pyramid Hill Solar Pond with a surface area of 3000 m² providing up to 60 kW of heat for salt production. HDPE [Nyllex Millennium] was used as a liner for this pond, and it had a thickness of 1 mm.
- Alice Springs Solar Pond with an area of between 1600 and 2000 m². The pond had a depth of 2.3 m and the hot brine obtained from the storage zone was between 82 and 90 °C. The pond operated at an efficiency of 12–15% to deliver 20 kW.

Margherita Di Savoia Solar Pond was constructed in the southern of Italy. The pond had a surface area of 25,000 m² with a depth of 4 m and it supplied 500 kW of process heat. HD PVC and HDPE pipes were used for bitterns or sea water. On other hand, insulated fibreglass pipes were used for extracting hot brine from the storage zone. Polypropylene lining were used to line the pond and it was 2.5 mm thick [167].

North America applied lots of research on solar ponds technology since 1974. Some of the solar ponds constructed were the following [157,164]:

- Ohio State University built a 200 m² solar pond for energy storage. The depth of the pond was 2.5 m and maximum temperature achieved was 66 °C.
- Again in Wooster, Ohio, a pond with a surface area of 156 m² and a depth of 3 m. The aim for this solar pond was to provide heat for greenhouses. It was noted that the pond provided around 20 GJ in less than two months of its operation.
- The University of New Mexico constructed a 175 m² solar pond to use it for heat extraction. The maximum temperature achieved was 109 °C at a depth of 2.5 m. The energy of 63 GJ was extracted in a period of 12 months.
- Miamisburg, Ohio used a 2020 m² solar pond for swimming pool heating. The pond had a depth of 3.5 m and achieved a maximum temperature of 66 °C with an efficiency of 15%.
- One of the most popular ponds was designed and operated by University of Texas, El Paso solar pond. El Paso provided between 100 and 120 kW of power from a surface area around 3000 m². The depth of the pond was 3.2 m and the maximum temperature achieved in the storage zone was around 93 °C. However, this pond faced lots of operating difficulties due to liner failures.
- A 700 m² pond in Montreal, Canada was developed to preheat air injected into an industrial air dryer. The pond was only 2 m deep and provided around 360 GJ of power annually. The maximum temperature recorded from this pond was 70 °C.

Bhuj Solar pond is a 6000 m² pond used to provide heat for Dairy industry at which it heated up around 8000 l a day in India. The heat was extracted at a depth of 3 m and a temperature of 70 °C. The pond was lined with an inexpensive lining scheme made of alternated layers of clay and LDPE films. However, this solar pond has faced many problems regarding the lining [167].

Al-Marafie constructed a 1700 m² area solar pond of 3.5 m depth, with 1:1 slope, at Kuwait Institute of Scientific Research, Kuwait, where severe weather conditions exist, with the aim of

producing 25 m³ of fresh water using Multistage Flash Desalination unit. A maximum storage zone temperature of 58 °C could be achieved. The pond lining was achieved with PVC sheets of 500 μm thickness placed under XR-5 liner [168].

4. Conclusion

Liquid desiccant cooling systems are attractive in providing space cooling at low energy requirement. The desiccant solution is employed to remove moisture from process air (in a dehumidifier equipment) before been sensibly cooled (in an evaporative cooler), whilst the resulting diluted solution is regenerated for reuse. A review of the various components showed that: the packed tower dehumidifier is quite popular; its air-to-solution flow ratio is generally below 0.5 for optimum dehumidification effectiveness. Of the desiccant solutions, though LiCl and TEG are widely studied, MgCl₂ is more cost effective; here solution concentration below 35% is required to avoid crystallisation issues. On the other hand, for the evaporative coolers, the DPEC was found to be the most efficient (substantially lower temperatures can be obtained). The liquid desiccant can be regenerated at temperatures below 80 °C making it well suited to low-grade solar energy applications.

The regenerator can be of the same type of equipment as the dehumidifier (for example packed bed, spray tower or falling film), in which case, the required thermal energy for the regeneration process can be indirectly sourced from conventional solar thermal collectors via heat exchangers. However, in alternative arrangements, the desiccant solution can be directly regenerated in an appropriate solar collector system, thus obviating the need for separate regenerator equipment.

The regenerated desiccant solution can potentially be stored to provide a high energy storage capacity for extended air dehumidification and cooling; however, this will require sufficiently large solar collector size. Of the solar collector types, a solar pond is a well-suited option for this purpose of large scale solar collection and thermal storage. The solar pond option is worthy of further research and development. The schematic diagram of the future experimental work with all components is presented which consists of salt gradient solar pond (SGSP) and indirect–direct evaporative cooler.

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