

RESEARCH

Open Access



# Controlled g-frames and dual g-frames in Hilbert spaces

Hui-Min Liu<sup>1</sup>, Yan-Ling Fu<sup>2</sup> and Yu Tian<sup>3\*</sup>

\*Correspondence:

[yutian@zzuli.edu.cn](mailto:yutian@zzuli.edu.cn)

<sup>3</sup>Department of Mathematics and Information Science, Zhengzhou University of Light Industry, Zhengzhou, Henan 450002, P.R. China

Full list of author information is available at the end of the article

## Abstract

As generalizations of g-frames and controlled frames, the theory of controlled g-frames has been deeply studied. This paper addresses the controlled g-frames and dual g-frames in Hilbert spaces. We first present some equivalent characterizations of controlled g-frames. Then, we introduce the concepts of controlled dual g-frames and controlled dual g-frames operator, get some properties of them. Finally, we obtain some characterizations of the controlled dual g-frames for a given controlled g-frame by the method of operator theory.

**MSC:** 42C15; 42A38

**Keywords:** G-frames; Controlled g-frames; Controlled dual g-frames

## 1 Introduction

A sequence  $\{f_j\}_{j \in J}$  in a separable Hilbert space  $\mathcal{H}$  is called a frame if there exist  $0 < A \leq B < \infty$  such that

$$A\|f\|^2 \leq \sum_{j \in J} |\langle f, f_j \rangle|^2 \leq B\|f\|^2$$

for all  $f \in \mathcal{H}$ . The concept of frames was introduced by Gabor in 1946 and Duffin and Schaeffer in 1952. Gabor in [12] proposed the idea of decomposing a general signal in terms of elementary signals, and Duffin and Schaeffer in [10] abstracted “these elementary signals” as the notion of frame. The frame theory has been developing rapidly since Daubechies, Grossmann, and Meyer [9] had put forward the definition of frames for Hilbert spaces formally in 1986. So far, the theory of frame has achieved fruitful success in pure mathematics, science, and engineering [4, 5, 8, 13, 14, 21, 24]. In the last decades, various generalizations of frame have been put forward for special purposes such as frame of subspaces [6], fusion frame [7], bounded quasi-projector [11], and g-frame [22]. In particular, among these generalizations, a g-frame covers all others, and the research of g-frames has obtained many results [16, 23, 25]. Controlled frames have been introduced to improve the numerical efficiency of iterative algorithms for inverting the frame operator on abstract Hilbert spaces [2]. A sequence  $\{f_j\}_{j \in J} \subset \mathcal{H}$  is called a  $C$ -controlled frame if there exist positive constants

© The Author(s) 2023. **Open Access** This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

$0 < A_2 \leq B_2 < \infty$  such that

$$A_2 \|f\|^2 \leq \sum_{j \in J} \langle f, f_j \rangle \langle C f_j, f \rangle \leq B_2 \|f\|^2$$

for all  $f \in \mathcal{H}$ , where  $C \in \mathcal{GL}(\mathcal{H})$ . However, they are only used as a tool to study spherical wavelets [3]. Later, some scholars noticed that these frames can give a generalized way to check the frame conditions while offering numerical advantages in the sense of preconditioning. Since then, controlled frames have been widely studied [15, 17–20]. Rahimi et al. in [18] first introduced the notion of controlled g-frames (see Definition 2.3), which is an extension of g-frames and controlled frames.

Inspired by the above research, in this paper we address the characterization of controlled g-frames and controlled dual g-frames, and it is organized as follows: In Sect. 2, we recall some basic notions, properties, and related results. Section 3 is devoted to the characterization of controlled g-frames, we obtain some equivalent conditions of controlled g-frames. In Sect. 4, we introduce the notion of controlled dual frames in Hilbert spaces and obtain some characterizations of the controlled dual g-frames for a given controlled g-frame by the method of operator theory.

## 2 Preliminaries

We begin this section with some basic notions and results of g-frames (see [8, 18, 20, 22, 25] for details).

Given separable Hilbert spaces  $\mathcal{H}$  and  $\mathcal{V}$ , let  $\{\mathcal{V}_j : j \in J\}$  be a sequence of closed subspaces of  $\mathcal{V}$  with  $J$  being a subset of integers  $\mathbb{Z}$ . The identity operator on  $\mathcal{H}$  is denoted by  $I_{\mathcal{H}}$ . The set of all bounded linear operators from  $\mathcal{H}$  into  $\mathcal{V}_j$  is denoted by  $L(\mathcal{H}, \mathcal{V}_j)$ . As a special case,  $L(\mathcal{H})$  is a collection of all bounded linear operators on  $\mathcal{H}$ . The set of all bounded linear operators on  $\mathcal{H}$  with a bounded inverse is denoted by  $\mathcal{GL}(\mathcal{H})$ . If  $P, Q \in \mathcal{GL}(\mathcal{H})$ , then  $P^*$ ,  $P^{-1}$ , and  $PQ$  are also in  $\mathcal{GL}(\mathcal{H})$ . Let  $\mathcal{GL}^+(\mathcal{H})$  be the set of all positive operators in  $\mathcal{GL}(\mathcal{H})$ . A bounded operator  $P : \mathcal{H} \rightarrow \mathcal{H}$  is positive if  $\langle Pf, f \rangle > 0$  for all  $f \neq 0$ . In a complex Hilbert space, every bounded positive operator is self-adjoint. In addition, as a technical condition, we also assume that any two positive operators involved in this paper commute with each other. Define

$$\bigoplus_{j \in J} \mathcal{V}_j = \left\{ \{a_j\}_{j \in J} : a_j \in \mathcal{V}_j, \|\{a_j\}_{j \in J}\|^2 = \sum_{j \in J} \|a_j\|^2 < \infty \right\}.$$

Then  $\bigoplus_{j \in J} \mathcal{V}_j$  is a Hilbert space under the following inner product:

$$\langle \{a_j\}_{j \in J}, \{b_j\}_{j \in J} \rangle = \sum_{j \in J} \langle a_j, b_j \rangle \quad \text{for } \{a_j\}_{j \in J}, \{b_j\}_{j \in J} \in \bigoplus_{j \in J} \mathcal{V}_j.$$

Suppose that  $\{e_{j,k}\}_{k \in K_j}$  is an orthonormal basis (simply o. n. b.) for  $\mathcal{V}_j$ , where  $K_j \subset \mathbb{Z}$ ,  $j \in J$ . Define  $\tilde{e}_{j,k} = e_{j,k} \delta_j$ , where  $\delta$  is the Kronecker symbol. Then  $\{\tilde{e}_{j,k}\}_{j \in J, k \in K_j}$  is an o. n. b. for  $\bigoplus_{j \in J} \mathcal{V}_j$  (see [25]).

**Definition 2.1** ([22]) A sequence  $\{\Lambda_j \in L(\mathcal{H}, \mathcal{V}_j)\}_{j \in J}$  is called a g-frame for  $\mathcal{H}$  with respect to (simply w. r. t.)  $\{\mathcal{V}_j\}_{j \in J}$  if

$$A\|f\|^2 \leq \sum_{j \in J} \|\Lambda_j f\|^2 \leq B\|f\|^2 \quad (2.1)$$

for all  $f \in \mathcal{H}$  and some positive constants  $A \leq B$ . The numbers  $A, B$  are called the frame bounds. If only the right-hand inequality of (2.1) is satisfied,  $\{\Lambda_j\}_{j \in J}$  is called a g-Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with bound  $B$ . If  $A = B = \lambda$ ,  $\{\Lambda_j\}_{j \in J}$  is called a  $\lambda$ -tight g-frame. In addition, if  $\lambda = 1$ ,  $\{\Lambda_j\}_{j \in J}$  is called a Parseval g-frame.

**Definition 2.2** ([25]) Let  $\{\Lambda_j\}_{j \in J}$  be a g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ . A g-frame  $\{\Gamma_j\}_{j \in J}$  is called an alternate dual g-frame for  $\{\Lambda_j\}_{j \in J}$  if

$$f = \sum_{j \in J} \Gamma_j^* \Lambda_j f \quad \text{for } f \in \mathcal{H}.$$

Moreover,  $\{\Lambda_j\}_{j \in J}$  is also an alternate dual g-frame for  $\{\Gamma_j\}_{j \in J}$ , that is,

$$f = \sum_{j \in J} \Lambda_j^* \Gamma_j f \quad \text{for } f \in \mathcal{H}.$$

**Definition 2.3** ([8]) Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . A sequence  $\{\Lambda_j\}_{j \in J}$  is called a  $(P, Q)$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ . If there exist two positive constants  $A$  and  $B$  such that

$$A\|f\|^2 \leq \sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle \leq B\|f\|^2, \quad \forall f \in \mathcal{H}. \quad (2.2)$$

We call  $A$  and  $B$  the lower and upper frame bounds for  $(P, Q)$ -controlled g-frame, respectively.

If the right-hand side of (2.2) holds, then  $\{\Lambda_j\}_{j \in J}$  is called a  $(P, Q)$ -controlled g-Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .

If  $Q = I_{\mathcal{H}}$ , then we call  $\{\Lambda_j\}_{j \in J}$  a  $P$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .

If  $P = Q$ , then we call  $\{\Lambda_j\}_{j \in J}$  a  $P^2$  (or  $(P, P)$ )-controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .

**Lemma 2.1** ([8]) Every bounded and positive operator  $P : \mathcal{H} \rightarrow \mathcal{H}$  has a unique bounded and positive square root  $W$ . If  $P$  is self-adjoint, then  $W$  is self-adjoint. If  $P$  is invertible, then  $W$  is also invertible.

For a  $(P, Q)$ -controlled g-Bessel sequence  $\{\Lambda_j\}_{j \in J}$  with bound  $B$ , the operator  $T_{P \wedge Q}$

$$T_{P \wedge Q} : \bigoplus_{j \in J} \mathcal{V}_j \rightarrow \mathcal{H}, \quad T_{P \wedge Q} F = \sum_{j \in J} (PQ)^{\frac{1}{2}} \Lambda_j^* f_j, \quad \forall F = \{f_j\}_{j \in J} \in \bigoplus_{j \in J} \mathcal{V}_j$$

is well defined, and its adjoint is given by

$$T_{P \wedge Q}^* : \mathcal{H} \rightarrow \bigoplus_{j \in J} \mathcal{V}_j, \quad T_{P \wedge Q}^* f = \{\Lambda_j (QP)^{\frac{1}{2}} f\}_{j \in J}, \quad \forall f \in \mathcal{H}.$$

$T_{P\Lambda Q}$  is called the synthesis operator and  $T_{P\Lambda Q}^*$  is called the analysis operator of  $\{\Lambda_j\}_{j \in J}$ . For a  $(P, Q)$ -controlled g-frame  $\{\Lambda_j\}_{j \in J}$  with bounds  $A$  and  $B$ , the operator

$$S_{P\Lambda Q} : \mathcal{H} \rightarrow \mathcal{H}, \quad S_{P\Lambda Q} f = \sum_{j \in J} Q \Lambda_j^* \Lambda_j P f, \quad \forall f \in \mathcal{H}$$

is called the frame operator of  $\{\Lambda_j\}_{j \in J}$ . From the definition,  $S_{P\Lambda Q} = P S_{\Lambda} Q$  is positive and invertible, where  $S_{\Lambda}$  is a frame operator of g-frame  $\{\Lambda_j\}_{j \in J}$ , and it is bounded, invertible, self-adjoint, positive, and  $A I_H \leq S_{\Lambda} \leq B I_H$ . Let  $\tilde{\Lambda}_j = \Lambda_j S_{\Lambda}^{-1}$ , then  $\{\tilde{\Lambda}_j\}_{j \in J}$  is a g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with frame operator  $S_{\Lambda}^{-1}$  and frame bounds  $\frac{1}{B}$  and  $\frac{1}{A}$ , respectively.  $\{\tilde{\Lambda}_j\}_{j \in J}$  is called the canonical dual g-frame of  $\{\Lambda_j\}_{j \in J}$  (see [22]).

**Definition 2.4** ([20]) Let  $\mathcal{H}$  be a Hilbert space and  $C \in \mathcal{GL}(\mathcal{H})$ . Suppose that  $\{\psi_j\}_{j \in J} \subseteq \mathcal{H}$  is a  $C$ -controlled frame and  $\{\phi_j\}_{j \in J} \subseteq \mathcal{H}$  is a Bessel sequence. Then  $\{\phi_j\}_{j \in J} \subseteq \mathcal{H}$  is said to be a  $C$ -controlled dual of  $\{\psi_j\}_{j \in J} \subseteq \mathcal{H}$  if the following condition is satisfied:

$$f = \sum_{j \in J} \langle f, \phi_j \rangle C \psi_j$$

for all  $f \in \mathcal{H}$ .

### 3 Controlled g-frames in Hilbert spaces

In this section, we present the characterization of controlled dual g-frames, and some equivalent conditions of  $(P, Q)$ -controlled g-frames are obtained. For this purpose, we first give some equivalent conditions of bounded and positive operators.

**Lemma 3.1** ([8]) Let  $T : \mathcal{H} \rightarrow \mathcal{H}$  be a linear operator. Then the following are equivalent:

- (i) There exist two constants  $0 < c \leq C < \infty$  such that  $c I_{\mathcal{H}} \leq T \leq C I_{\mathcal{H}}$ .
- (ii)  $T$  is positive and there exist two constants  $0 < c \leq C < \infty$  such that

$$c \|f\|^2 \leq \|T^{\frac{1}{2}} f\|^2 \leq C \|f\|^2.$$

- (iii)  $T \in \mathcal{GL}^+(\mathcal{H})$ .

The following lemma gives a characterization of  $(P, Q)$ -controlled g-frames in Hilbert space. By Proposition 2.1 in [1], if  $P, Q \in \mathcal{GL}^+(\mathcal{H})$  and  $PQ = QP$ , then we have  $PQ \in \mathcal{GL}^+(\mathcal{H})$ .

**Lemma 3.2** Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . Then  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  if and only if  $\{\Lambda_j\}_{j \in J}$  is a g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .

*Proof* Suppose that  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with bounds  $A, B$ . For any  $f \in \mathcal{H}$ , we have

$$\begin{aligned} A \|f\|^2 &= A \|(PQ)^{\frac{1}{2}} (PQ)^{-\frac{1}{2}} f\|^2 \\ &\leq A \|(PQ)^{\frac{1}{2}}\|^2 \|(PQ)^{-\frac{1}{2}} f\|^2 \\ &\leq \|(PQ)^{\frac{1}{2}}\|^2 \sum_{j \in J} \langle \Lambda_j P (PQ)^{-\frac{1}{2}} f, \Lambda_j Q (PQ)^{-\frac{1}{2}} f \rangle \end{aligned}$$

$$\begin{aligned}
&= \|(PQ)^{\frac{1}{2}}\|^2 \langle QS_{\Lambda}P(PQ)^{-\frac{1}{2}}f, (PQ)^{-\frac{1}{2}}f \rangle \\
&= \|(PQ)^{\frac{1}{2}}\|^2 \langle S_{\Lambda}P(PQ)^{-\frac{1}{2}}f, Q(PQ)^{-\frac{1}{2}}f \rangle \\
&= \|(PQ)^{\frac{1}{2}}\|^2 \langle S_{\Lambda}P^{\frac{1}{2}}(Q)^{-\frac{1}{2}}f, Q^{\frac{1}{2}}(P)^{-\frac{1}{2}}f \rangle \\
&= \|(PQ)^{\frac{1}{2}}\|^2 \langle (P)^{-\frac{1}{2}}Q^{\frac{1}{2}}S_{\Lambda}P^{\frac{1}{2}}(Q)^{-\frac{1}{2}}f, f \rangle = \|(PQ)^{\frac{1}{2}}\|^2 \langle S_{\Lambda}f, f \rangle.
\end{aligned}$$

Thus

$$\frac{A}{\|(PQ)^{\frac{1}{2}}\|^2} \|f\|^2 \leq \sum_{j \in J} \|\Lambda_j f\|^2, \quad \forall f \in \mathcal{H}.$$

For any  $f \in \mathcal{H}$ , it follows that

$$\begin{aligned}
\sum_{j \in J} \|\Lambda_j f\|^2 &= \langle S_{\Lambda}f, f \rangle = \langle (PQ)^{-\frac{1}{2}}(PQ)^{\frac{1}{2}}S_{\Lambda}f, f \rangle \\
&= \langle (PQ)^{\frac{1}{2}}S_{\Lambda}f, (PQ)^{-\frac{1}{2}}f \rangle \\
&= \langle S_{\Lambda}(PQ)(PQ)^{-\frac{1}{2}}f, (PQ)^{-\frac{1}{2}}f \rangle \\
&= \langle PS_{\Lambda}Q(PQ)^{-\frac{1}{2}}f, (PQ)^{-\frac{1}{2}}f \rangle \\
&\leq B \|(PQ)^{-\frac{1}{2}}f\|^2 \leq B \|(PQ)^{-\frac{1}{2}}\|^2 \|f\|^2.
\end{aligned}$$

Hence  $\{\Lambda_j\}_{j \in J}$  is a g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with bounds  $\frac{A}{\|(PQ)^{\frac{1}{2}}\|^2}$  and  $B \|(PQ)^{-\frac{1}{2}}\|^2$ .

On the other hand, suppose that  $\{\Lambda_j\}_{j \in J}$  is a g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with bounds  $A_1, B_1$ . Then

$$\langle A_1 f, f \rangle \leq \langle S_{\Lambda}f, f \rangle \leq \langle B_1 f, f \rangle \quad \text{for any } f \in \mathcal{H}.$$

Since  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ , by Lemma 3.1, there exist constants  $c, c_1, C, C_1$  ( $0 < c, c_1, C, C_1 < \infty$ ) such that

$$cI_{\mathcal{H}} \leq P \leq CI_{\mathcal{H}}, \quad c_1I_{\mathcal{H}} \leq Q \leq C_1I_{\mathcal{H}}.$$

Using  $\langle PS_{\Lambda}f, f \rangle = \langle f, S_{\Lambda}Pf \rangle = \langle f, PS_{\Lambda}f \rangle$ , we get

$$cA \leq S_{\Lambda}P = PS_{\Lambda} \leq CB.$$

Similarly, we have

$$cc_1A \leq QS_{\Lambda}P \leq CC_1B.$$

It follows that

$$cc_1A \|f\|^2 \leq \sum_{j \in J} \langle \Lambda_j Pf, \Lambda_j Qf \rangle \leq CC_1B \|f\|^2, \quad \forall f \in \mathcal{H}.$$

Therefore,  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ . The proof is completed.  $\square$

**Lemma 3.3** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . Then  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  if and only if  $\{\Lambda_j\}_{j \in J}$  is a  $((QP)^{\frac{1}{2}}, (QP)^{\frac{1}{2}})$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .*

*Proof* For any  $f \in \mathcal{H}$ , we have

$$\begin{aligned} \sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle &= \left\langle \sum_{j \in J} Q \Lambda_j^* \Lambda_j P f, f \right\rangle = \langle Q S_\Lambda P f, f \rangle \\ &= \langle Q P S_\Lambda f, f \rangle = \langle (QP)^{\frac{1}{2}} S_\Lambda (QP)^{\frac{1}{2}} f, f \rangle \\ &= \left\langle \sum_{j \in J} (QP)^{\frac{1}{2}} \Lambda_j^* \Lambda_j (QP)^{\frac{1}{2}} f, f \right\rangle \\ &= \sum_{j \in J} \langle \Lambda_j (QP)^{\frac{1}{2}} f, \Lambda_j (QP)^{\frac{1}{2}} f \rangle. \end{aligned}$$

Hence,  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  is equivalent to

$$A \|f\|^2 \leq \sum_{j \in J} \langle \Lambda_j (QP)^{\frac{1}{2}} f, \Lambda_j (QP)^{\frac{1}{2}} f \rangle \leq B \|f\|^2, \quad \forall f \in \mathcal{H},$$

where  $A$  and  $B$  are frame bounds of  $\{\Lambda_j\}_{j \in J}$ . Thus  $\{\Lambda_j\}_{j \in J}$  is a  $((QP)^{\frac{1}{2}}, (QP)^{\frac{1}{2}})$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ . The proof is completed.  $\square$

**Lemma 3.4** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . Then  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  if and only if  $\{\Lambda_j\}_{j \in J}$  is a  $QP$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .*

*Proof* The proof is similar to that of Lemma 3.3.  $\square$

**Lemma 3.5** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . Then  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  if and only if  $\{u_{j,k}\}_{j \in J, k \in K_j}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$ , where  $\{u_{j,k}\}_{j \in J, k \in K_j}$  is the sequence induced by  $\{\Lambda_j\}_{j \in J}$  w. r. t.  $\{e_{j,k}\}_{j \in J, k \in K_j}$  (i.e.,  $u_{j,k} = \Lambda_j^* e_{j,k}$ ).*

*Proof* Noting that  $\{e_{j,k}\}_{k \in K_j}$  is an o.n.b. for  $\mathcal{V}_j$  for each  $j \in J$ , for any  $f \in \mathcal{H}$ , we have  $\Lambda_j f \in \mathcal{V}_j$ . It follows that

$$\Lambda_j P f = \sum_{k \in K_j} \langle \Lambda_j P f, e_{j,k} \rangle e_{j,k} = \sum_{k \in K_j} \langle f, P \Lambda_j^* e_{j,k} \rangle e_{j,k}$$

and

$$\Lambda_j Q f = \sum_{k \in K_j} \langle \Lambda_j Q f, e_{j,k} \rangle e_{j,k} = \sum_{k \in K_j} \langle f, Q \Lambda_j^* e_{j,k} \rangle e_{j,k}.$$

It is easy to check that

$$\langle \Lambda_j P f, \Lambda_j Q f \rangle = \sum_{k \in K_j} \langle f, P \Lambda_j^* e_{j,k} \rangle \langle Q \Lambda_j^* e_{j,k}, f \rangle = \sum_{k \in K_j} \langle f, P u_{j,k} \rangle \langle Q u_{j,k}, f \rangle.$$

Hence

$$\sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle = \sum_{j \in J} \sum_{k \in K_j} \langle f, P u_{j,k} \rangle \langle Q u_{j,k}, f \rangle.$$

Thus

$$A \|f\|^2 \leq \sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle \leq B \|f\|^2 \quad \text{for any } f \in \mathcal{H}$$

is equivalent to

$$A \|f\|^2 \leq \sum_{j \in J} \sum_{k \in K_j} \langle f, P u_{j,k} \rangle \langle Q u_{j,k}, f \rangle \leq B \|f\|^2 \quad \text{for any } f \in \mathcal{H}.$$

The proof is completed.  $\square$

**Lemma 3.6** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . Then  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  if and only if  $\{P u_{j,k}\}_{j \in J, k \in K_j}$  is a  $QP^{-1}$ -controlled frame for  $\mathcal{H}$ , where  $\{u_{j,k}\}_{j \in J, k \in K_j}$  is the sequence induced by  $\{\Lambda_j\}_{j \in J}$  w. r. t.  $\{e_{j,k}\}_{j \in J, k \in K_j}$  (i.e.,  $u_{j,k} = \Lambda_j^* e_{j,k}$ ).*

*Proof* From the proof of Theorem 3.5, we have

$$\sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle = \sum_{j \in J} \sum_{k \in K_j} \langle f, P \Lambda_j^* e_{j,k} \rangle \langle Q \Lambda_j^* e_{j,k}, f \rangle.$$

If we take  $u_{j,k} = \Lambda_j^* e_{j,k}$ ,  $f_{j,k} = P u_{j,k}$ , then

$$A \|f\|^2 \leq \sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle \leq B \|f\|^2 \quad \text{for any } f \in \mathcal{H}$$

is equivalent to

$$A \|f\|^2 \leq \sum_{j \in J} \sum_{k \in K_j} \langle f, P u_{j,k} \rangle \langle Q P^{-1} P u_{j,k}, f \rangle \leq B \|f\|^2 \quad \text{for any } f \in \mathcal{H}.$$

The proof is completed.  $\square$

Combining Lemmas 3.2–3.6, we get Theorem 3.1.

**Theorem 3.1** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . Then the following are equivalent:*

- (i)  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .
- (ii)  $\{\Lambda_j\}_{j \in J}$  is a  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .
- (iii)  $\{\Lambda_j\}_{j \in J}$  is a  $((QP)^{\frac{1}{2}}, (QP)^{\frac{1}{2}})$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .
- (iv)  $\{\Lambda_j\}_{j \in J}$  is a  $QP$ -controlled  $g$ -frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ .
- (v)  $\{u_{j,k}\}_{j \in J, k \in K_j}$  is a  $(P, Q)$ -controlled frame for  $\mathcal{H}$ , where  $\{u_{j,k}\}_{j \in J, k \in K_j}$  is the sequence induced by  $\{\Lambda_j\}_{j \in J}$  w. r. t.  $\{e_{j,k}\}_{j \in J, k \in K_j}$ .
- (vi)  $\{P u_{j,k}\}_{j \in J, k \in K_j}$  is a  $QP^{-1}$ -controlled frame for  $\mathcal{H}$ , where  $\{u_{j,k}\}_{j \in J, k \in K_j}$  is the sequence induced by  $\{\Lambda_j\}_{j \in J}$  w. r. t.  $\{e_{j,k}\}_{j \in J, k \in K_j}$ .

#### 4 Controlled dual g-frames in Hilbert spaces

In this section, we introduce the notion of controlled dual frames and obtain some characterizations of the controlled dual g-frames for a given controlled g-frame by the method of operator theory.

**Definition 4.1** Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ ,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  be  $(P, P)$ -controlled and  $(Q, Q)$ -controlled g-Bessel sequences for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ , respectively. If for any  $f \in \mathcal{H}$

$$f = \sum_{j \in J} P \Lambda_j^* \Gamma_j Q f,$$

then  $\{\Gamma_j\}_{j \in J}$  is called a  $(P, Q)$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$ . In particular, if  $Q = I_{\mathcal{H}}$ , then  $\{\Gamma_j\}_{j \in J}$  is called a  $P$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$ .

**Definition 4.2** Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ ,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  be  $(P, P)$ -controlled and  $(Q, Q)$ -controlled g-Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ , respectively. We define a  $(P, Q)$ -controlled dual g-frame operator for this pair of controlled g-Bessel sequence as follows:

$$S_{P\Lambda\Gamma Q} f = \sum_{j \in J} P \Lambda_j^* \Gamma_j Q f, \quad \forall f \in \mathcal{H}.$$

As mentioned before,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  are also two g-Bessel sequences. It is easy to check that  $S_{P\Lambda\Gamma Q}$  is a well-defined and bounded operator, and

$$S_{P\Lambda\Gamma Q} = T_{P\Lambda P} T_{Q\Gamma Q}^* = P T_{\Lambda} T_{\Gamma}^* Q = P S_{\Lambda\Gamma} Q,$$

where  $S_{\Lambda\Gamma} = \sum_{j \in J} \Lambda_j^* \Gamma_j$ . From Definition 4.1,  $\{\Gamma_j\}_{j \in J}$  is a  $(P, Q)$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$  if and only if  $S_{P\Lambda\Gamma Q} = I_{\mathcal{H}}$ .

**Proposition 4.1** Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ ,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  be  $(P, P)$ -controlled and  $(Q, Q)$ -controlled g-Bessel sequences with bounds  $B_{\Lambda}$  and  $B_{\Gamma}$ , respectively. If  $S_{P\Lambda\Gamma Q}$  is bounded below, then  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  are  $(P, P)$ -controlled and  $(Q, Q)$ -controlled g-frames, respectively.

*Proof* Suppose that there exists a constant  $\lambda > 0$  such that

$$\|S_{P\Lambda\Gamma Q} f\| \geq \lambda \|f\| \quad \text{for all } f \in \mathcal{H}.$$

By the Cauchy–Schwarz inequality, we have

$$\begin{aligned} \lambda \|f\| &\leq \|S_{P\Lambda\Gamma Q} f\| = \sup_{\|g\|=1} \left| \left\langle \sum_{j \in J} P \Lambda_j^* \Gamma_j Q f, g \right\rangle \right| \\ &= \sup_{\|g\|=1} \left| \sum_{j \in J} \langle \Gamma_j Q f, \Lambda_j P g \rangle \right| \\ &\leq \sup_{\|g\|=1} \left( \sum_{j \in J} \|\Gamma_j Q f\|^2 \right)^{\frac{1}{2}} \left( \sum_{j \in J} \|\Lambda_j P g\|^2 \right)^{\frac{1}{2}} \end{aligned}$$



$$\leq \sqrt{B_\Lambda} \left( \sum_{j \in J} \|\Gamma_j Qf\|^2 \right)^{\frac{1}{2}}.$$

Thus

$$\frac{\lambda^2}{B_\Lambda} \|f\|^2 \leq \sum_{j \in J} \|\Gamma_j Qf\|^2 \quad \text{for } f \in \mathcal{H}.$$

On the other hand, since

$$S_{P\Lambda\Gamma Q}^* = (PS_{\Lambda\Gamma}Q)^* = QS_{\Lambda\Gamma}^*P = QS_{\Gamma\Lambda}P = S_{Q\Gamma\Lambda P},$$

then  $S_{Q\Gamma\Lambda P}$  is also bounded below. Similarly, we can prove that  $\{\Lambda_j\}_{j \in J}$  is a  $(P, P)$ -controlled  $g$ -frame. The proof is completed.  $\square$

**Theorem 4.1** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ ,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  be  $(P, P)$ -controlled and  $(Q, Q)$ -controlled  $g$ -Bessel sequences for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ , respectively. Then the following conditions are equivalent:*

- (i)  $f = \sum_{j \in J} P\Lambda_j^* \Gamma_j Qf, \forall f \in \mathcal{H};$
- (ii)  $f = \sum_{j \in J} Q\Gamma_j^* \Lambda_j Pf, \forall f \in \mathcal{H};$
- (iii)  $\langle f, g \rangle = \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle = \sum_{j \in J} \langle \Gamma_j Qf, \Lambda_j Pg \rangle, \forall f, g \in \mathcal{H};$
- (iv)  $\|f\|^2 = \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qf \rangle = \sum_{j \in J} \langle \Gamma_j Qf, \Lambda_j Pf \rangle, \forall f \in \mathcal{H}.$

*In case the equivalent conditions are satisfied,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  are  $(P, P)$ -controlled and  $(Q, Q)$ -controlled  $g$ -frames, respectively.*

*Proof* (i)  $\Leftrightarrow$  (ii). Let  $T_{P\Lambda P}$  be the synthesis operator of the  $(P, P)$ -controlled  $g$ -Bessel sequence  $\{\Lambda_j\}_{j \in J}$  and  $T_{Q\Gamma Q}$  be the synthesis operator of the  $(Q, Q)$ -controlled  $g$ -Bessel sequence  $\{\Gamma_j\}_{j \in J}$ . In these conditions (i) means that  $T_{P\Lambda P} T_{Q\Gamma Q}^* = I_{\mathcal{H}}$ , this is equivalent to  $T_{Q\Gamma Q} T_{P\Lambda P}^* = I_{\mathcal{H}}$ , which is identical to statement (ii). Conversely, (ii) implies (i) similarly.

(ii)  $\Leftrightarrow$  (iii). It is clear that (ii)  $\Rightarrow$  (iii). Next we prove (iii) implies (ii) for any  $f, g \in \mathcal{H}$ ,  $\langle f, g \rangle = \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle$  shows that

$$\left\langle f - \sum_{j \in J} Q\Gamma_j^* \Lambda_j Pf, g \right\rangle = 0, \quad \forall g \in \mathcal{H}.$$

Hence (ii) is followed.

(iii)  $\Leftrightarrow$  (iv). (iii)  $\Rightarrow$  (iv) is obvious. To prove that (iv)  $\Rightarrow$  (iii), applying condition (iv), we have

$$\begin{aligned} \|f + g\|^2 &= \sum_{j \in J} \langle \Lambda_j P(f + g), \Gamma_j Q(f + g) \rangle \\ &= \sum_{j \in J} \langle \Lambda_j Pf + \Lambda_j Pg, \Gamma_j Qf + \Gamma_j Qg \rangle \\ &= \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qf \rangle + \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle \\ &\quad + \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qf \rangle + \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qg \rangle. \end{aligned}$$

Similarly,

$$\begin{aligned}\|f - g\|^2 &= \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qf \rangle - \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle \\ &\quad - \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qf \rangle + \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qg \rangle, \\ \|f + \mathbf{i}g\|^2 &= \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qf \rangle - \mathbf{i} \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle \\ &\quad + \mathbf{i} \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qf \rangle + \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qg \rangle, \\ \|f - \mathbf{i}g\|^2 &= \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qf \rangle + \mathbf{i} \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle \\ &\quad - \mathbf{i} \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qf \rangle + \sum_{j \in J} \langle \Lambda_j Pg, \Gamma_j Qg \rangle.\end{aligned}$$

By polarization identity,

$$\begin{aligned}\langle f, g \rangle &= \frac{1}{4} (\|f + g\|^2 - \|f - g\|^2 + \mathbf{i}\|f + \mathbf{i}g\|^2 - \mathbf{i}\|f - \mathbf{i}g\|^2) \\ &= \sum_{j \in J} \langle \Lambda_j Pf, \Gamma_j Qg \rangle.\end{aligned}$$

In case the equivalent conditions are satisfied,  $S_{Q\Gamma\Lambda P} = I_{\mathcal{H}}$  implies  $\|S_{Q\Gamma\Lambda P}\| = 1$ , by Proposition 4.1,  $\{\Lambda_j\}_{j \in J}$  and  $\{\Gamma_j\}_{j \in J}$  are  $(P, P)$ -controlled and  $(Q, Q)$ -controlled  $g$ -frames, respectively. The proof is completed.  $\square$

**Lemma 4.1** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ . A sequence  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled  $g$ -Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with bound  $B$  if and only if the operator*

$$T_{P\Lambda Q} : \bigoplus_{j \in J} \mathcal{V}_j \rightarrow \mathcal{H}, \quad T_{P\Lambda Q}(\{f_j\}_{j \in J}) = \sum_{j \in J} (PQ)^{\frac{1}{2}} \Lambda_j^* f_j$$

*is well defined and bounded with  $\|T_{P\Lambda Q}\| \leq \sqrt{B}$ .*

**Proof** The necessary condition follows from the definition of  $(P, Q)$ -controlled  $g$ -Bessel sequence. We only need to prove that the sufficient condition holds. Suppose that  $T_{P\Lambda Q}$  is well defined and bounded operator with  $\|T_{P\Lambda Q}\| \leq \sqrt{B}$ . For any  $f \in \mathcal{H}$ , we have

$$\begin{aligned}\sum_{j \in J} \langle \Lambda_j Pf, \Lambda_j Qf \rangle &= \sum_{j \in J} \langle Q\Lambda_j^* \Lambda_j Pf, f \rangle = \langle QS_{\Lambda} Pf, f \rangle \\ &= \langle (QP)^{\frac{1}{2}} S_{\Lambda} (QP)^{\frac{1}{2}} f, f \rangle \\ &= \left\langle \sum_{j \in J} (QP)^{\frac{1}{2}} \Lambda_j^* \Lambda_j (QP)^{\frac{1}{2}} f, f \right\rangle \\ &\leq \|T_{P\Lambda Q}\| \left( \sum_{j \in J} \|\Lambda_j (QP)^{\frac{1}{2}} f\|^2 \right)^{\frac{1}{2}} \|f\|\end{aligned}$$

$$= \|T_{P\Lambda Q}\| \left( \sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle \right)^{\frac{1}{2}} \|f\|.$$

Hence we get

$$\sum_{j \in J} \langle \Lambda_j P f, \Lambda_j Q f \rangle \leq \|T_{P\Lambda Q}\|^2 \|f\|^2 \leq B \|f\|^2.$$

This shows that  $\{\Lambda_j\}_{j \in J}$  is a  $(P, Q)$ -controlled g-Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with bound  $B$ . The proof is completed.  $\square$

**Theorem 4.2** *Let  $P, Q \in \mathcal{GL}^+(\mathcal{H})$ ,  $\{\Lambda_j\}_{j \in J}$  be a  $(P, P)$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with the synthesis operator  $T_{P\Lambda P}$ . Then a  $(Q, Q)$ -controlled g-frame  $\{\Gamma_j\}_{j \in J}$  is a  $(P, Q)$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$  if and only if*

$$Q\Gamma_j^* e_{j,k} = U(e_{j,k} \delta_j), \quad j \in J, k \in K_j,$$

where  $U: \bigoplus_{j \in J} \mathcal{V}_j \rightarrow \mathcal{H}$  is a bounded left-inverse of  $T_{P\Lambda P}^*$ .

*Proof* If  $\{g_j\}_{j \in J} \in \bigoplus_{j \in J} \mathcal{V}_j$ , then

$$\{g_j\}_{j \in J} = \sum_{j \in J} g_j \delta_j = \sum_{j \in J} \sum_{k \in K_j} \langle g_j, e_{j,k} \rangle e_{j,k} \delta_j.$$

Roughly speaking,  $\{e_{j,k} \delta_j\}_{j \in J, k \in K_j}$  is an o. n. b. of  $\bigoplus_{j \in J} \mathcal{V}_j$ . If there exist  $U: \bigoplus_{j \in J} \mathcal{V}_j \rightarrow \mathcal{H}$  is a bounded left-inverse of  $T_{P\Lambda P}^*$  such that

$$Q\Gamma_j^* e_{j,k} = U(e_{j,k} \delta_j), \quad j \in J, k \in K_j.$$

By Lemma 4.1,  $\{\Gamma_j\}_{j \in J}$  is a  $(Q, Q)$ -controlled g-Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ . For any  $f \in \mathcal{H}$ , we have

$$\begin{aligned} f &= UT_{P\Lambda P}^* f = U \left( \sum_{j \in J} \sum_{k \in K_j} \langle \Lambda_j P f, e_{j,k} \rangle e_{j,k} \delta_j \right) \\ &= \sum_{j \in J} \sum_{k \in K_j} \langle f, P \Lambda_j^* e_{j,k} \rangle U(e_{j,k} \delta_j) \\ &= \sum_{j \in J} \sum_{k \in K_j} \langle f, P u_{j,k} \rangle Q\Gamma_j^* e_{j,k} \\ &= \sum_{j \in J} Q\Gamma_j^* \left( \sum_{k \in K_j} \langle P f, u_{j,k} \rangle e_{j,k} \right) = \sum_{j \in J} Q\Gamma_j^* \Lambda_j P f, \end{aligned}$$

where  $u_{j,k} = \Lambda_j^* e_{j,k}$ . By the definition of controlled dual g-frame,  $\{\Gamma_j\}_{j \in J}$  is a  $(P, Q)$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$ .

On the other hand, suppose that a  $(Q, Q)$ -controlled g-frame  $\{\Gamma_j\}_{j \in J}$  is a  $(P, Q)$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$ . For any  $f \in \mathcal{H}$ , we have

$$f = \sum_{j \in J} P \Lambda_j^* \Gamma_j Q f = \sum_{j \in J} Q\Gamma_j^* \Lambda_j P f,$$

that is,  $T_{Q\Gamma Q}T_{P\Lambda P}^* = I_{\mathcal{H}}$ . Let  $U = T_{Q\Gamma Q}$ , then  $U : \bigoplus_{j \in J} \mathcal{V}_j \rightarrow \mathcal{H}$  is a bounded left-inverse of  $T_{P\Lambda P}^*$ . A calculation as above shows that

$$\sum_{j \in J} \sum_{k \in K_j} \langle f, Pu_{j,k} \rangle Q\Gamma_j^* e_{j,k} = f = \sum_{j \in J} \sum_{k \in K_j} \langle f, Pu_{j,k} \rangle U(e_{j,k} \delta_j), \quad \forall f \in \mathcal{H}.$$

Combining this with the fact  $\{e_{j,k}\}_{k \in K_j}$  is an o. n. b. of  $\mathcal{V}_j$ , we have

$$Q\Gamma_j^* e_{j,k} = U(e_{j,k} \delta_j), \quad j \in J, k \in K_j.$$

The proof is completed.  $\square$

**Theorem 4.3** *Let  $P \in \mathcal{GL}^+(\mathcal{H})$ ,  $\{\Lambda_j\}_{j \in J}$  be a  $(P, P)$ -controlled g-frame for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$  with the synthesis operator and frame operator  $T_{P\Lambda P}$  and  $S_{P\Lambda P}$ , respectively. Then  $\{\Gamma_j \in L(\mathcal{H}, \mathcal{V}_j)\}_{j \in J}$  is a  $P$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$  if and only if*

$$\Gamma_j f = (Tf)_j + \Lambda_j S_{P\Lambda P}^{-1} P f, \quad j \in J, f \in \mathcal{H},$$

where  $T : \mathcal{H} \rightarrow \bigoplus_{j \in J} \mathcal{V}_j$  is a bounded linear operator satisfying  $T_{P\Lambda P} T = 0$ .

*Proof* If  $T : \mathcal{H} \rightarrow \bigoplus_{j \in J} \mathcal{V}_j$  is a bounded linear operator satisfying  $T_{P\Lambda P} T = 0$ , then  $\{\Gamma_j \in L(\mathcal{H}, \mathcal{V}_j)\}_{j \in J}$  is a g-Bessel sequence for  $\mathcal{H}$  w. r. t.  $\{\mathcal{V}_j\}_{j \in J}$ . In fact, for any  $f \in \mathcal{H}$ , we have

$$\begin{aligned} \sum_{j \in J} \|\Gamma_j f\|^2 &= \sum_{j \in J} \|(Tf)_j + \Lambda_j S_{P\Lambda P}^{-1} P f\|^2 \\ &\leq 2 \left( \sum_{j \in J} \|\Lambda_j S_{P\Lambda P}^{-1} P f\|^2 + \|Tf\|^2 \right) \\ &\leq 2(B \|S_{P\Lambda P}^{-1} P\|^2 + \|T\|^2) \|f\|^2, \end{aligned}$$

where  $B$  is the upper bound of  $\{\Lambda_j\}_{j \in J}$ . Furthermore,

$$\begin{aligned} \sum_{j \in J} P\Lambda_j^* \Gamma_j f &= \sum_{j \in J} P\Lambda_j^* ((Tf)_j + \Lambda_j S_{P\Lambda P}^{-1} P f) \\ &= T_{P\Lambda T} Tf + \sum_{j \in J} P\Lambda_j^* \Lambda_j S_{P\Lambda P}^{-1} P f = f. \end{aligned}$$

Thus  $\{\Gamma_j \in L(\mathcal{H}, \mathcal{V}_j)\}_{j \in J}$  is a  $P$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$ .

Now we prove the converse. Assume that  $\{\Gamma_j \in L(\mathcal{H}, \mathcal{V}_j)\}_{j \in J}$  is a  $P$ -controlled dual g-frame of  $\{\Lambda_j\}_{j \in J}$ . Define the operator  $T$  as follows:

$$T : \mathcal{H} \rightarrow \bigoplus_{j \in J} \mathcal{V}_j, \quad f \mapsto Sf \quad (\forall f \in \mathcal{H})$$

satisfying

$$\Gamma_j f = (Tf)_j + \Lambda_j S_{P\Lambda P}^{-1} P f, \quad j \in J.$$

For any  $f \in \mathcal{H}$ , we have

$$\begin{aligned}\|Tf\|^2 &= \sum_{j \in J} \|\Gamma_j f - \Lambda_j S_{P\Lambda P}^{-1} P f\|^2 \\ &\leq \sum_{j \in J} \|\Gamma_j f\|^2 + \sum_{j \in J} \|\Lambda_j S_{P\Lambda P}^{-1} P f\|^2 + 2 \left( \sum_{j \in J} \|\Gamma_j f\|^2 \right)^{\frac{1}{2}} \left( \sum_{j \in J} \|\Lambda_j S_{P\Lambda P}^{-1} P f\|^2 \right)^{\frac{1}{2}} \\ &\leq (B_1 + A^{-1} + 2\sqrt{B_1 A^{-1}}) \|f\|^2,\end{aligned}$$

where  $B_1$  is the frame upper bound of  $\{\Gamma_j\}_{j \in J}$ ,  $A$  is the frame lower bound of  $\{\Lambda_j\}_{j \in J}$ . Thus  $T$  is a linear bounded operator. Moreover, for any  $f, g \in \mathcal{H}$ , we have

$$\begin{aligned}\langle T_{P\Lambda P} T f, g \rangle &= \sum_{j \in J} \langle P \Lambda_j^* T f, g \rangle = \sum_{j \in J} \langle P \Lambda_j^* (\Gamma_j f - \Lambda_j S_{P\Lambda P}^{-1} P f), g \rangle \\ &= \sum_{j \in J} \langle P \Lambda_j^* \Gamma_j f, g \rangle - \sum_{j \in J} \langle P \Lambda_j^* \Lambda_j S_{P\Lambda P}^{-1} P f, g \rangle \\ &= \langle f, g \rangle - \langle f, g \rangle = 0.\end{aligned}$$

That is,  $T_{P\Lambda P} T = 0$ . The proof is completed.  $\square$

#### Acknowledgements

The authors thank the referees for their comments which greatly improve the readability of this article.

#### Funding

This paper is supported by the Science and Technology Research Project of Henan Province (No. 222102210335) and the Educational Commission of Henan province of China (No. 20A110036).

#### Availability of data and materials

Not applicable.

#### Declarations

##### Competing interests

The authors declare no competing interests.

##### Author contributions

Conceptualization, HML, YLF, YT; Formal analysis, TY, HML; Validation, HML, YLF, YT; Writing—original draft, HML, YLF, YT. All the authors contributed equally and they read and approved the final manuscript for publication.

##### Author details

<sup>1</sup>Institute of Applied Mathematics, Zhengzhou Shengda University, Zhengzhou, Henan 451191, P.R. China. <sup>2</sup>School of Statistics and Mathematics, Henan Finance University, Zhengzhou, Henan 450000, P.R. China. <sup>3</sup>Department of Mathematics and Information Science, Zhengzhou University of Light Industry, Zhengzhou, Henan 450002, P.R. China.

Received: 3 May 2022 Accepted: 13 April 2023 Published online: 02 May 2023

#### References

1. Abdollahpour, M.R., Alizadeh, Y.: Controlled continuous g-frames and their multipliers in Hilbert spaces. *Sahand Commun. Math. Anal.* **15**(1), 37–48 (2019)
2. Balazs, P., Antoine, J.P., Grybos, A.: Weighted and controlled frames: mutual relationship and first numerical properties. *Int. J. Wavelets Multiresolut. Inf. Process.* **8**(1), 109–132 (2010)
3. Bogdanova, I., Vandergheynst, P., Antoine, J.P., Jacques, L., Morvidone, M.: Stereographic wavelet frames on the sphere. *Appl. Comput. Harmon. Anal.* **16**, 223–252 (2005)
4. Candès, E.J.: Harmonic analysis of neural networks. *Appl. Comput. Harmon. Anal.* **6**, 197–218 (1999)
5. Casazza, P.G.: The art of frame theory. *Taiwan. J. Math.* **4**(2), 129–201 (2000)
6. Casazza, P.G., Kutyniok, G.: Frames of subspaces. *Wavelets, frames and operator theory. Contemp. Math.* **345**, 87–113 (2004)
7. Casazza, P.G., Kutyniok, G., Li, S.: Fusion frames and distributed processing. *Appl. Comput. Harmon. Anal.* **25**(1), 114–132 (2008)

8. Christensen, O.: An Introduction to Frames and Riesz Bases. Birkhäuser, Boston (2003)
9. Daubechies, I., Grossmann, A., Meyer, Y.: Painless nonorthogonal expansion. *J. Math. Phys.* **27**, 1271–1283 (1986)
10. Duffin, R.J., Schaeffer, A.C.: A class of nonharmonic Fourier series. *Transl. Am. Math. Soc.* **72**, 341–366 (1952)
11. Fornasier, M.: Quasi-orthogonal decompositions of structured frames. *J. Math. Anal. Appl.* **289**, 180–199 (2004)
12. Gabor, D.: Theory of communications. *J. Inst. Electr. Eng.* **93**, 429–457 (1946)
13. Han, D., Sun, W.: Reconstruction of signals from frame coefficients with erasures at unknown locations. *IEEE Trans. Inf. Theory* **60**(7), 4013–4025 (2014)
14. Khosravi, A., Musazadeh, K.: Fusion frames and g-frames. *J. Math. Anal. Appl.* **342**, 1068–1083 (2008)
15. Khosravi, A., Musazadeh, K.: Controlled fusion frames. *Methods Funct. Anal. Topol.* **18**(3), 256–265 (2012)
16. Mirzaee, A.M., Khosravi, A.: Duals and approximate duals of g-frames in Hilbert spaces. *J. Linear Topol. Algebra* **4**(4), 259–265 (2016)
17. Musazadeh, K., Khandani, H.: Some results on controlled frames in Hilbert spaces. *Acta Math. Sci.* **36**(3), 655–665 (2016)
18. Rahimi, A., Fereydooni, A.: Controlled g-frames and their g-multipliers in Hilbert spaces. *An. Ştiinţ. Univ. 'Ovidius' Constanţa* **21**(2), 223–236 (2013)
19. Ramezani, S.M., Nazari, A.: Weighted and controlled continuous g-frames and their multipliers in Hilbert spaces. *Çankaya Univ. J. Sci. Eng.* **13**(1), 31–39 (2016)
20. Rashidi-Kouchi, M., Rahimi, A., Shah, F.A.: Dual and multipliers of controlled frames in Hilbert spaces. *Int. J. Wavelets Multiresolut. Inf. Process.* **5**, 1850057 (2018)
21. Strohmer, T.: Approximation of dual Gabor frames, window decay, and wireless communication. *Appl. Comput. Harmon. Anal.* **11**, 243–262 (2001)
22. Sun, W.C.: G-frames and g-Riesz bases. *J. Math. Anal. Appl.* **322**(1), 437–452 (2006)
23. Sun, W.C.: Stability of g-frames. *J. Math. Anal. Appl.* **326**(2), 858–868 (2007)
24. Zhang, W.: Dual and approximately dual Hilbert-Schmidt frames in Hilbert spaces. *Results Math.* **73**(1), 4 (2018)
25. Zhu, Y.C.: Characterizations of g-frames and g-Riesz bases in Hilbert spaces. *Acta Math. Sin. Engl. Ser.* **24**(10), 1727–1736 (2008)

## Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

**Submit your manuscript to a SpringerOpen<sup>®</sup> journal and benefit from:**

- Convenient online submission
- Rigorous peer review
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

---

Submit your next manuscript at ► [springeropen.com](https://www.springeropen.com)