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## EXISTENCE OF SOLUTIONS FOR HIGHER ORDER BVP WITH PARAMETERS VIA CRITICAL POINT THEORY

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**Abstract.** This paper is concerned with the existence of at least one solution of the nonlinear  $2k$ -th order BVP. We use the Mountain Pass Lemma to get an existence result for the problem, whose linear part depends on several parameters.

### 1. Introduction

There has recently been an increased interest in studying the existence of solutions for boundary value problems (BVPs) of higher order differential equations (cf. [1, 4–6, 9]). Most of the earlier discussions were devoted to the fourth order BVPs, for example see [3, 7]. In this paper, we consider the depending on real parameters family of  $2k$ th order ( $k \geq 2$ ) BVP,

$$(1) \quad \begin{cases} (-1)^k x^{(2k)} + \sum_{j=1}^k \lambda_j x^{(2k-2j)} = (-1)^{i-1} f(t, x^{(2i-2)}), \\ x^{(2j)}(0) = x^{(2j)}(1) = 0, \quad j = 0, \dots, k-1, \end{cases},$$

where  $f : [0, 1] \rightarrow \mathbb{R}$  is a continuous function. Here,  $i$  is a fixed integer  $1 \leq i \leq k$ . Notice that the nonlinear term  $f$  depends only on the  $2i - 2$ -th derivative of unknown function. It is seen that for some unions of  $\lambda$ s, the differential operator that corresponds to the left-hand side of (1) is invertible and is not for others (see [4]). The second case, commonly called a resonance one, needs additional conditions of Landesman–Lazer type and was examined in [3], [4]. Here, we focus on the nonresonant case. Jurkiewicz [6] established the existence of infinitely many solution for (1), by applying the Rabinowitz's theorem about unbounded sequence of critical points.

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**THEOREM 1.** [6] Assume that  $\lambda \in \Delta_+$  (see p. 55) and let  $f$  be odd with respect to the second variable, i.e.  $f(t, -u) = -f(t, u)$  for all  $t \in [0, 1]$  and  $u \in \mathbb{R}$ . If  $f$  satisfies the following conditions

- (i)  $\limsup_{u \rightarrow 0} \frac{f(t, u)}{u} < \frac{\pi^{2k} + \Lambda(1)}{\pi^{2i-2}}$  (definition of  $\Lambda$  – (2)),
- (ii)  $\liminf_{u \rightarrow +\infty} \frac{f(t, u)}{u} = +\infty$ ,
- (iii) there exist  $k \in [0, 1/2)$  and  $N > 0$ , such that  $\int_0^w f(t, u) du \leq kwf(t, w)$ , for  $|w| \geq N$ ,  $t \in [0, 1]$ ,

then the problem (1) possesses infinitely many solutions.

It is well known that in a lot of problems of the form  $Lu = N(u)$ , where  $L$  is a linear operator and  $N$  – a nonlinear one, the existence of at least  $m$  solution is obtained if an asymptotic behaviour of  $N$  near 0 and near  $\infty$  is similar to  $\mu_0 I$  and  $\mu_\infty I$ , respectively ( $I$  – the identity operator), and there are exactly  $m$  eigenvalues of  $L$  in the interval  $(\mu_0, \mu_\infty)$ . Assumptions (i) and (ii) of Theorem 1 mean that in this interval sit infinitely many eigenvalues, although we generalize the notion of eigenvalue as you will see in Section 2: the eigenvalues are  $k$ -dimensional vectors, which forms a sequence  $(H_n)$   $k - 1$ -dimensional hyperplanes and the segment in  $\mathbb{R}^k$  joining points with all coordinates 0 except  $2(k + 1 - i)$ -th, where there are limits  $\mu_0$  from condition (i) and  $\mu_\infty$  from (ii), respectively, intersects all these hyperplanes. Thus, it is natural to ask if there is at least  $m$  solution to (1), if in assumption (ii), the limit is a number  $\mu_\infty$  such that the above mentioned segment intersect exactly  $H_1, \dots, H_m$ . The present paper is an answer to this question for  $m = 1$ . This enables us to drop the assumption of oddness of  $f$ .

## 2. Preliminaries

Assume that  $k \geq 2$  and  $i = 1, \dots, k - 1$  are fixed positive integer numbers and let

$$(2) \quad \Lambda(x) = \sum_{j=1}^k (-1)^{k-j} \lambda_j (x^2 \pi^2)^{k-j}.$$

**DEFINITION 1.** (see [4], [5]) A point  $\lambda = (\lambda_1, \dots, \lambda_k) \in \mathbb{R}^k$  will be called a  $k$ -dimensional eigenvalue iff the homogeneous problem

$$(3) \quad \begin{cases} (-1)^k x^{(2k)}(t) + \lambda_1 x^{(2k-2)}(t) + \lambda_2 x^{(2k-4)}(t) \\ \quad + \dots + \lambda_{k-1} x''(t) + \lambda_k x(t) = 0, \\ x^{(2j)}(0) = x^{(2j)}(1) = 0, \text{ for } j = 0 \dots k - 1, \end{cases}$$

has a nonzero solution. The set of all such  $k$ -tuples will be denoted by  $\sigma^k$ .

It can be proved that the set  $\sigma^k$  has the form

$$\sigma^k = \bigcup_{n \in \mathbb{N}} H_n,$$

where  $H_n$  is a hyperplane of the form  $H_n := \{\lambda \in \mathbb{R}^k \mid (n^2\pi^2)^k + \Lambda(n) = 0\}$  (see [4], [5]).

**THEOREM 2.** (see [4]) *Let  $s \in \mathbb{N}$  and  $n_1, n_2, \dots, n_s \in \mathbb{N}$  be such that  $n_i \neq n_j$ ,  $i \neq j$ .*

- (1) *If  $s \leq k$ , then  $W = \bigcap_{i=1}^s H_{n_i} \neq \emptyset$  is an affine subspace in  $\mathbb{R}^k$  and  $\dim W = k - s$ .*
- (2) *If  $s > k$ , then  $\bigcap_{i=1}^s H_{n_i} = \emptyset$ .*

*Shortly, hyperplanes  $H_n$  are in a general position.*

Let us put  $\Delta_+ := \bigcap_{n \in \mathbb{N}} \{\lambda \in \mathbb{R}^k \mid \Lambda(n) \geq 0\}$ . It is easily seen that  $\Delta_+ \neq \emptyset$ . Indeed, putting

$$D_+ := \begin{cases} \{\lambda \in \mathbb{R}^k \mid \lambda^s \leq 0 \text{ if } s \text{ is odd and } \lambda^s \geq 0 \text{ if } s \text{ is even}\}, & \text{if } k \text{ is an even number,} \\ \{\lambda \in \mathbb{R}^k \mid \lambda^s \geq 0 \text{ if } s \text{ is odd and } \lambda^s \leq 0 \text{ if } s \text{ is even}\}, & \text{if } k \text{ is an odd number,} \end{cases}$$

we see that  $D_+ \subset \Delta_+$ . Furthermore, due to the inequality  $(n^2\pi^2)^k + \Lambda(n) > 0$ ,  $n = 1, 2, \dots$ , we get  $\Delta_+ \cap \sigma^k = \emptyset$ .

**DEFINITION 2.** (see [8]) A sequence  $\{y_n\} \subset X$  is a *Palais–Smale sequence* for  $\varphi \in C^1(X, \mathbb{R})$ , if  $\{\varphi(y_n)\}$  is bounded while  $\varphi'(y_n) \rightarrow 0$  as  $n \rightarrow \infty$ .

**DEFINITION 3.** (see [8]) We say  $\varphi \in C^1(X, \mathbb{R})$  satisfies (P.-S.) condition, if any Palais–Smale sequence has a (strongly) convergent subsequence.

**THEOREM 3.** (Mountain Pass Lemma (MPL), [8], Theorem 6.1) *Let  $X$  be a real Banach space and  $\varphi \in C^1(X, \mathbb{R})$  such that  $\varphi$  satisfies (P.-S.) condition and  $\varphi(0) = 0$ . Furthermore*

- (1) *there exist  $\alpha > 0$  and  $r > 0$  such that  $\varphi(y) \geq \alpha$  for all  $y \in \partial B(0, r)$ ;*
- (2) *there exists  $y_0 \in X$  such that  $\varphi(y_0) < \alpha$  with  $\|y_0\| \geq r$ .*

*Then  $\varphi$  possesses a critical value  $c \geq \alpha$ .*

If  $x$  is a solution to (1) and  $y = x^{(2i-2)}$ , then we have (see [4], [5] and [6])

$$y(t) = (-1)^{i-1} \int_0^1 \mathcal{H}_i(t, s) f(s, y(s)) ds,$$

where

$$(4) \quad \mathcal{H}_i(t, s) = \sum_{n=1}^{\infty} \frac{(-1)^{i-1} (n\pi)^{2i-2}}{(n^2\pi^2)^k + \Lambda(n)} \cdot \sin(n\pi s) \sin(n\pi t).$$

Putting

$$(T_i y)(t) = (-1)^{i-1} \int_0^1 \mathcal{H}_i(t, s) f(s, y(s)) ds,$$

we see that  $T_i$  maps  $C$  – the space of real continuous functions on  $[0, 1]$  – into itself.

Let  $(H_i z)(t) = (-1)^{i-1} \int_0^1 \mathcal{H}_i(t, s) z(s) ds$  and  $(fy)(s) = f(s, y(s))$  (both operators act in  $C$ ), then  $T_i$  can be described as a composition of  $H_i$  and  $\mathbf{f}$ . Consider the unique extension of the operator  $H_i$  to the Hilbert space  $L^2$  denoted also  $H_i$  for simplicity. The operator  $H_i$  is continuous, self-adjoint and  $\sigma(H_i) = \sigma_p(H_i) \cup \sigma_c(H_i)$ , where  $\sigma_p(H_i) = \{(n\pi)^{2i-2} \cdot [(n^2\pi^2)^k + \Lambda(n)]^{-1} \mid p = 1, 2, \dots\}$  and  $\sigma_c(H_i) = \{0\}$  (see [6]). Moreover, if  $\lambda \in \Delta_+$  then  $\sigma(H_i) \subset [0, +\infty)$  and  $H_i$  is a positive operator. This implies that there exists a unique positive and self-adjoint  $S_i$  such that  $S_i^2 = H_i$  (see [2], Theorem 2.2.10). Below, the norm without subscript stands for the norm in the space  $L^2$ ; the supremum norm in the space of continuous functions will be denoted by  $\|\cdot\|_C$ .

**REMARK.** Hereinafter, it will be assumed that  $\lambda \in \Delta_+$ .

If we reason in the similar way as in [4], we can deduce that

$$(S_i z)(t) = \sum_{n=1}^{\infty} \frac{(n\pi)^{i-1}}{\sqrt{(n\pi)^{2k} + \Lambda(n)}} \cdot \int_0^1 \sin(n\pi s) z(s) ds \cdot \sin(n\pi t).$$

(i) The function

$$\mathcal{S}_i(t, s) = \sum_{n=1}^{\infty} \frac{(n\pi)^{i-1}}{\sqrt{(n\pi)^{2k} + \Lambda(n)}} \sin(n\pi s) \sin(n\pi t)$$

is continuous.

(ii) Operator  $S_i$  maps  $L^2$  into  $C$  and it has the form

$$(S_i z)(t) = \int_0^1 \mathcal{S}_i(t, s) z(s) ds.$$

It easy to see that the sequence  $(n\pi)^{2i-2} \cdot [(n^2\pi^2)^k + \Lambda(n)]^{-1}$  is decreasing, thus by Theorem 2.2.5 [2], it is easy to calculate the norms of  $H_i$  and  $S_i$ , treating them as operators from  $L^2$  into itself

$$(5) \quad \|H_i\| = \pi^{2i-2} \cdot \left(\pi^{2k} + \Lambda(1)\right)^{-1} \quad \text{and} \quad \|S_i\| = \pi^{i-1} \cdot \left(\pi^{2k} + \Lambda(1)\right)^{-\frac{1}{2}}.$$

After [6], one can notice that

- (1) has a solution if  $T_i = H_i \circ \mathbf{f}$  has a fixed point;
- fixed points of the operator  $S_i \circ \mathbf{f} \circ S_i$  in  $L^2$  are also fixed points of  $T_i = H_i \circ \mathbf{f}$  in  $C$ ;
- if  $\psi : C \rightarrow \mathbb{R}$  is defined by the formula

$$\psi y = \int_0^1 \int_0^{y(t)} f(t, u) du dt,$$

then functionals  $\psi$  and  $\psi \circ S_i$  are Fréchet differentiable on  $C$  and  $L^2$ , respectively and  $(\psi'(y))h = \langle \mathbf{f}y, h \rangle_{L^2}$ ,  $(\psi \circ S_i)'y = (S_i \circ \mathbf{f} \circ S_i)y$ .

Let  $\varphi_i : L^2 \rightarrow \mathbb{R}$ , be the functional of the form

$$(6) \quad \varphi_i(y) = \frac{1}{2} \langle y, y \rangle_{L^2} - (\psi \circ S_i)y.$$

We have

$$(7) \quad \varphi_i'(y) = y - (S_i \circ \mathbf{f} \circ S_i)y,$$

for  $y \in L^2$ .

Due to the above arguments, solutions to (1) are critical points of  $\varphi_i$ .

### 3. Main result

**LEMMA 1.** [6] Assume that there are  $k \in [0, 1/2)$  and  $N > 0$ , such that for  $|w| \geq N$ , we have

$$\int_0^w f(t, u) du \leq kwf(t, w)$$

then the functional  $\varphi_i$  satisfies the (P.S.) condition.

**REMARK.** If  $f$  is odd then functions  $\mathbb{R} \ni w \mapsto \int_0^w f(t, u) du$  and  $\mathbb{R} \ni w \mapsto w \cdot f(t, w)$  are even for any  $t \in [0, 1]$ . Therefore, to verify assumption of Lemma 1, it is sufficient to check the inequality for  $w \geq N > 0$ .

Now we can prove the main theorem.

**THEOREM 4.** Assume that  $\lambda \in \Delta_+$  and let  $f : [0, 1] \times \mathbb{R} \rightarrow \mathbb{R}$  be a continuous function that satisfies the following conditions

- (i)  $\limsup_{u \rightarrow 0} \frac{f(t, u)}{u} < \frac{\pi^{2k} + \Lambda(1)}{\pi^{2i-2}},$
- (ii')  $\liminf_{u \rightarrow +\infty} \frac{f(t, u)}{u} > \frac{\pi^{2k} + \Lambda(1)}{\pi^{2i-2}},$
- (iii) there exist  $k \in [0, 1/2)$  and  $N > 0$ , such that for  $|w| \geq N$ , we have

$$\int_0^w f(t, u) du \leq kwf(t, w),$$

for each  $t \in [0, 1]$ . Then problem (1) possesses at least one nonzero solution.

**Proof.** We shall use the Mountain Pass Lemma. The considered functional has the form

$$\varphi_i(y)(t) = \frac{1}{2} \|y\|^2 - \int_0^1 \int_0^{(S_i y)(t)} f(t, u) du dt.$$

It is obvious that  $\varphi_i(0) = 0$ , furthermore we explained on the page 56, that

$$\frac{\pi^{2k} + \Lambda(1)}{\pi^{2i-2}} = \|H_i\|^{-1}.$$

Due to assumption, there exist  $\delta > 0$  and  $\varepsilon_1 \in (0, \|H_i\|^{-1})$  such that

$$\frac{f(t, u)}{u} \leq \|H_i\|^{-1} - \varepsilon_1, \quad \text{for } |u| \leq \delta.$$

This implies that

$$f(t, u) \leq (\|H_i\|^{-1} - \varepsilon_1)u, \quad \text{for } u \in [0, \delta],$$

and

$$f(t, u) \geq (\|H_i\|^{-1} - \varepsilon_1)u, \quad \text{for } u \in [-\delta, 0].$$

Thus we have, for  $w \in [0, \delta]$ ,

$$\int_0^w f(t, u) du \leq (\|H_i\|^{-1} - \varepsilon_1) \int_0^w u du = (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} w^2,$$

and, for  $w \in [-\delta, 0]$ ,

$$\int_0^w f(t, u) du = - \int_w^0 f(t, u) du \leq -(\|H_i\|^{-1} - \varepsilon_1) \int_w^0 u du = (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} w^2.$$

The above calculations imply that

$$(8) \quad \int_0^w f(t, u) du \leq (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} w^2,$$

for  $|w| \leq \delta$ .

Let  $y \in L^2$ , the kernel  $\mathcal{S}_i$  of  $S_i$  is a positive continuous function. Therefore, let  $B_i > 0$  be its maximal value. This and the Hölder's inequality imply that

$$\|S_i y\|_C \leq B_i \int_0^1 |y(s)| ds \leq B_i \left( \int_0^1 |y(s)|^2 ds \right)^{\frac{1}{2}} = B_i \|y\|.$$

Therefore, if  $\|y\| = r$ , where  $r = B^{-1}\delta$ , we get

$$\|S_i y\|_C \leq \delta.$$

Now, the last estimate together with (8), give us the following condition

$$\begin{aligned}
\varphi_i(y) &= \frac{1}{2} \|y\|^2 - \int_0^1 \int_0^{(S_i y)(t)} f(t, u) du dt \\
&\geq \frac{1}{2} \|y\|^2 - (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} \int_0^1 ((S_i y)(t))^2 dt \\
&= \frac{1}{2} \|y\|^2 - (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} \langle S_i y, S_i y \rangle_{L^2} \\
&= \frac{1}{2} \|y\|^2 - (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} \langle H_i y, y \rangle_{L^2} \\
&\geq \frac{1}{2} \|y\|^2 - (\|H_i\|^{-1} - \varepsilon_1) \frac{1}{2} \|H_i\| \|y\|^2 = \frac{1}{2} \|H_i\| \|y\|^2 \varepsilon_1 \\
&= \frac{1}{2} \|H_i\| r^2 \varepsilon_1.
\end{aligned}$$

Thus  $\varphi_i(y) \geq \alpha$ ,  $\alpha = \frac{1}{2} \|H_i\| r^2 \varepsilon_1$ , for  $y \in \partial B(0, r)$ ,  $r = B_i^{-1} \delta$ , and assumption (1) of MPL holds. Assumption (ii) implies the existence of such  $N > 0$  and  $\varepsilon_2 > 0$ , that

$$\frac{f(t, u)}{u} \geq \|H_i\|^{-1} (1 + \varepsilon_2), \quad \text{for } u > N \text{ and } t \in [0, 1].$$

Then

$$(9) \quad f(t, u) \geq \|H_i\|^{-1} (1 + \varepsilon_2) u, \quad \text{for } u > N \text{ and } t \in [0, 1].$$

Because the function  $f(t, u) - \|H_i\|^{-1} (1 + \varepsilon_2) u$  is continuous on  $[0, 1] \times [0, N]$ , there exists  $M > 0$  such that

$$(10) \quad f(t, u) \geq \|H_i\|^{-1} (1 + \varepsilon_2) u - M, \quad \text{for } u \in [0, N] \text{ and } t \in [0, 1].$$

The inequalities (9) and (10) led us to the following conclusion

$$f(t, u) \geq \|H_i\|^{-1} (1 + \varepsilon_2) u - M, \quad \text{for } u \geq 0, t \in [0, 1].$$

Integrating the above inequality, we get

$$(11) \quad \int_0^w f(t, u) du \geq \frac{1}{2} \|H_i\|^{-1} (1 + \varepsilon_2) w^2 - Mw,$$

for  $w \geq 0$  and uniformly for  $t \in [0, 1]$ .

We have explained that

$$H_i u = \sum_{n=1}^{\infty} \xi_n^2 \cdot \langle e_n, u \rangle_{L^2} e_n \quad \text{and} \quad S_i u = \sum_{n=1}^{\infty} \xi_n \cdot \langle e_n, u \rangle_{L^2} e_n,$$

where

$$\xi_n^2 = \frac{(n\pi)^{2i-2}}{(n\pi)^{2k} + \Lambda(n)} \quad \text{and} \quad e_n(t) = \sqrt{2} \sin(n\pi t).$$

Furthermore

$$\xi_1^2 = \frac{\pi^{2i-2}}{\pi^{2k} + \Lambda(1)} = \|H_i\|.$$

It easily seen that

$$(12) \quad S_i e_1 = \xi_1 e_1 = \sqrt{\|H_i\|} e_1 \geq 0.$$

For any real  $\tau$ , we have from (11) and (12)

$$\begin{aligned} \varphi_i(\tau e_1) &= \frac{1}{2} \langle \tau e_1, \tau e_1 \rangle_{L^2} - \int_0^1 \int_0^{(S_i(\tau e_1))(t)} f(t, u) du dt \\ &\leq \frac{1}{2} \tau^2 - \frac{1}{2} \|H_i\|^{-1} (1 + \varepsilon_2) \int_0^1 (S_i(\tau e_1))^2(t) dt \\ &\quad + M \int_0^1 (S_i(\tau e_1))(t) dt \\ &= \frac{1}{2} \tau^2 - \frac{1}{2} \tau^2 \|H_i\|^{-1} (1 + \varepsilon_2) \langle S_i e_1, S_i e_1 \rangle_{L^2} \\ &\quad + M \tau \int_0^1 (S_i(e_1))(t) dt \\ &= \frac{1}{2} \tau^2 - \frac{1}{2} \tau^2 \|H_i\|^{-1} (1 + \varepsilon_2) \|H_i\| + M \tau \sqrt{\|H_i\|} \int_0^1 e_1(t) dt \\ &= -\frac{1}{2} \varepsilon_2 \tau^2 + M \sqrt{\|H_i\|} \frac{2\sqrt{2}}{\pi} \tau. \end{aligned}$$

Let  $\tau > 0$ . The above estimate implies that  $\varphi_i(\tau e_1) \rightarrow -\infty$  and  $\|\tau e_1\| = \tau \rightarrow +\infty$  as  $\tau \rightarrow +\infty$ .

Therefore, there exists  $\tau_0 > r$  such that  $\varphi_i(y_0) = \varphi_i(\tau_0 e_1) < 0 < \alpha$  and assumption (2) of MPL is satisfied. Due to MPL, we get the assertion. ■

It has to be emphasized that we do not assume oddness of a nonlinear part.

**EXAMPLE.** Let us consider the following problem

$$\begin{cases} u^{(8)} - \pi^2 u^{(6)} + \pi^4 u^{(4)} - \pi^6 u'' + \pi^8 u = f(t, u^{(4)}), \\ u^{(2j)}(0) = u^{(2j)}(1) = 0, \quad \text{for } j = 0 \dots 3, \end{cases}$$

where

$$f(t, w) = \begin{cases} w^3 + 5\pi^4 + 1, & \text{for } w < -1, \\ w^2 + 5\pi^4 - 1, & \text{for } w \in [-1, 1], \\ w^2 \arctan(w) + 5\pi^4 - \frac{1}{4}\pi, & \text{for } w > 1. \end{cases}$$

It is seen that  $\|H_3\|^{-1} = 5\pi^4$ , furthermore it is easy to verify that  $f$  is continuous, satisfies conditions (i)–(iii) of Theorem 4 and does not satisfy assumptions of Theorem 1.



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