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Gasket
Hanford

Retention:
Permanent

**DEVELOPMENT OF REMOTE HANFORD CONNECTOR GASKET
REPLACEMENT TOOLING FOR DWPF**

Jeff Coughlin
Dan Krementz

DECEMBER 2008

Savannah River National Laboratory
Savannah River Nuclear Solutions
Aiken, SC 29808

**Prepared for the U.S. Department of Energy Under
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LIST OF ACRONYMS

CDMC	Contact Decontamination and Maintenance Cell
DWPF	Defense Waste Processing Facility
EMM	Electro-mechanical manipulator
FY	fiscal year
MCU	Modular Caustic Side Solvent Extraction Unit
MSM	Master-slave manipulator
REDC	Remote Equipment Decontamination Cell
SRNL	Savannah River National Laboratory

1.0 EXECUTIVE SUMMARY

The Defense Waste Processing Facility (DWPF) requested the Savannah River National Laboratory (SRNL) to develop tooling and equipment to remotely replace gaskets in mechanical Hanford connectors to reduce personnel radiation exposure as compared to the current hands-on method. It is also expected that radiation levels will continually increase with future waste streams. The equipment is operated in the Remote Equipment Decontamination Cell (REDC), which is equipped with compressed air, two master-slave manipulators (MSM's) and an electro-mechanical manipulator (EMM) arm for operation of the remote tools. The REDC does not provide access to electrical power, so the equipment must be manually or pneumatically operated. The MSM's have a load limit at full extension of ten pounds, which limited the weight of the installation tool.

In order to remotely replace Hanford connector gaskets several operations must be performed remotely, these include: removal of the spent gasket and retaining ring (retaining ring is also called snap ring), loading the new snap ring and gasket into the installation tool and installation of the new gasket into the Hanford connector. SRNL developed and tested tools that successfully perform all of the necessary tasks. Removal of snap rings from horizontal and vertical connectors is performed by separate air actuated retaining ring removal tools and is manipulated in the cell by the MSM. In order install a new gasket, the snap ring loader is used to load a new snap ring into a groove in the gasket installation tool. A new gasket is placed on the installation tool and retained by custom springs. An MSM lifts the installation tool and presses the mounted gasket against the connector block. Once the installation tool is in position, the gasket and snap ring are installed onto the connector by pneumatic actuation. All of the tools are located on a custom work table with a pneumatic valve station that directs compressed air to the desired tool and vents the tools as needed.

Extensive testing of tooling operation was performed in the DWPF manipulator repair shop. This testing allowed the operators to gain confidence before the equipment was exposed to radioactive contamination. The testing also led to multiple design improvements. On July 17 and 29, 2008 the Remote Gasket Replacement Tooling was successfully demonstrated in the REDC at the DWPF of The Savannah River Site.

2.0 INTRODUCTION

The DWPF glass melter and the equipment that prepares waste for vitrification are housed inside a large enclosed facility called a “canyon”. In order to perform the necessary maintenance and modifications within the canyon remotely, the canyon walls are outfitted with an array of pipe nozzles. Two nozzles within the canyon may be connected by a jumper, which is a pipe that is hung by a crane and has Hanford connectors on both ends. Each Hanford connector contains a gasket that seals to its respective canyon wall or vessel nozzle. The Hanford connector has a tapered skirt to assist the crane with placement of the connector on the nozzle and three fingers that pull against the back side of the nozzle via a remotely tightened ACME screw (Figure 1). There are both vertical and horizontal Hanford connectors, which vary only by connector orientation and the geometry of the connector skirt.

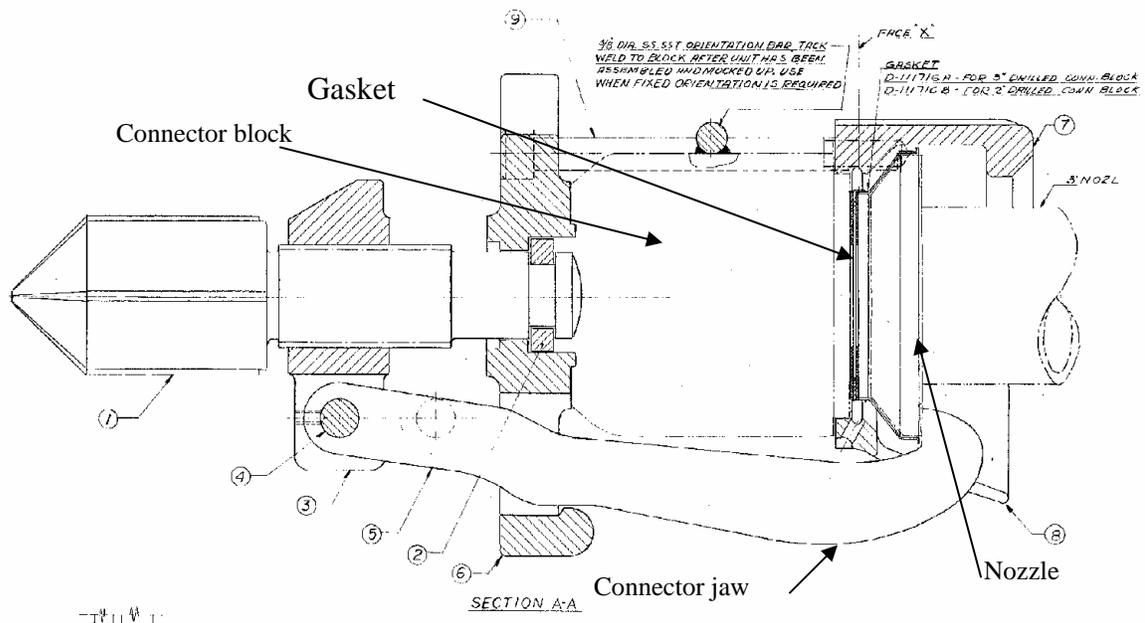


Figure 1: Drawing of Hanford Connector with Nozzle

When a Hanford connector gasket fails, the current course of action is to remove the jumper, decontaminate it as much as possible and transport the jumper to the Contact Decontamination and Maintenance Cell (CDMC) within the canyon. In this location, maintenance personnel wear protective clothing to prevent contamination and manually replace the gasket. This process requires significant planning and cost because of the risk of personnel contamination and radiation exposure.

The remote gasket replacement tooling was developed as an alternative to the hands-on gasket replacement approach. The Modular Caustic Side Solvent Extraction Unit (MCU) became operational in FY08 to process salt waste. As a result of the MCU process, an increasingly cesium-laden waste stream will be fed to DWPF over the next two years. As

this waste enters into the DWPF system, hands-on replacement of gaskets will incur much higher personnel exposure rates than the current waste stream, thus making remote gasket replacement even more advantageous.

When the DWPF customer first requested SRNL to develop remote gasket tooling, the goal was less ambitious than it is today. Originally the task was to develop tools that would allow gasket replacement from several feet away thus eliminating hands-on contact with the jumper to reduce radiation exposure. Increasing the distance from the jumper during gasket replacement could also minimize the need for jumper decontamination prior to gasket replacement. The tools developed were designed to use a hands-on approach to load snap rings and gaskets onto an installation tool. The installation tool would then be attached to an extension arm and transported into the CDMC, where the gasket and snap ring would be installed in a Hanford connector. The goal was to develop a low cost disposable design so that decontamination between uses would not be necessary. The introduction of more highly radioactive waste to DWPF necessitated a fully remote solution.

3.0 DISCUSSION

3.1 REMOTE EQUIPMENT DECONTAMINATION CELL (REDC)

As the name indicates, the REDC is an area of the DWPF canyon equipped for remote equipment decontamination. The cell has a large shielded window for viewing the decontamination processes. Below and in front of the window on the cell side is a 36"x72" platform for placing items to be decontaminated or in this case, gasket replacement tooling. Available for operator use are a pair of MSM's (right and left hands), an electro-mechanical manipulator (EMM), an overhead bridge crane and 100 psi compressed air supply. The MSM's are capable of handling up to 10 lb at full reach. The EMM is capable of handling up to 100 lb. The gasket replacement work table and all associated tooling will be placed on the REDC platform during gasket replacement activities (See Figure 2).

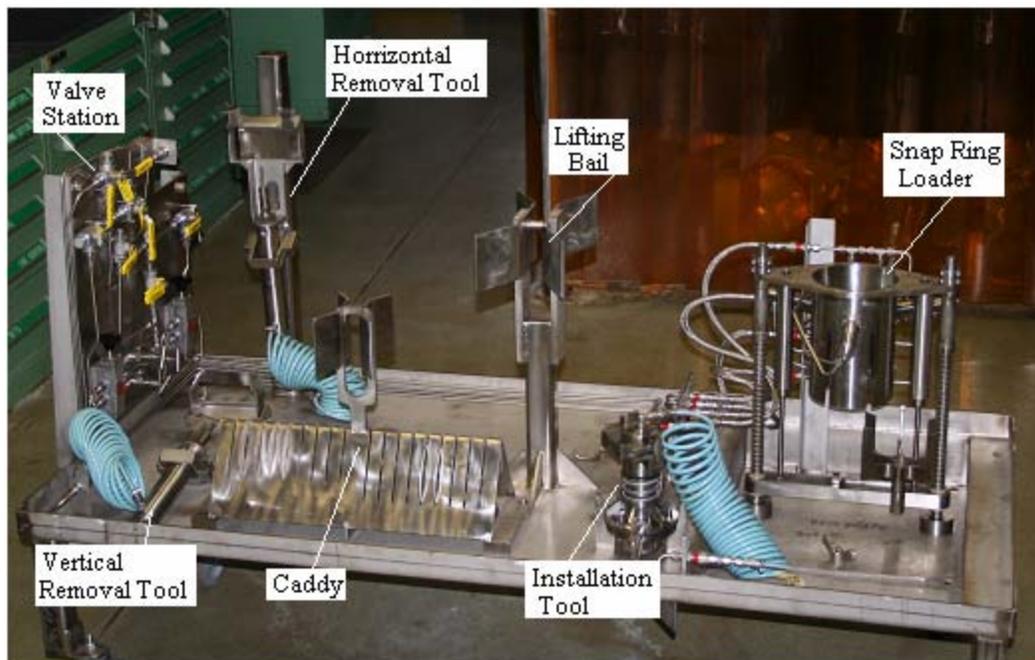


Figure 2: Gasket Installation Work Table w/ Valve Station and Tools

3.2 GASKET REPLACEMENT TOOLING

Several tools were developed to perform the gasket replacement task. Two snap-ring-removal tools were developed, one for the horizontal and the other for the vertical Hanford connectors. An installation tool was developed that installs both a gasket and snap ring in a vertical or horizontal Hanford connector. A snap-ring-loading tool was developed to load a snap ring into the installation tool in preparation for installation of the snap ring and gasket into the Hanford connector. The installation tool storage platform is used for gasket loading onto the installation tool. All of the tools are stored and deployed off of a stainless steel work table that has a lifting attachment that allows a crane to carry the work table in and out of the REDC as needed. On the work table is space for a removable caddy which carries

nine gaskets and nine snap rings. The caddy is equipped with a separate lifting bail. Ideally, several caddies can be built and used to re-supply the table with new snap rings and gaskets. On the left end of the work table is a valve station that includes all of the pneumatic valves needed to run the various tools.

Before any gaskets can be replaced, the gasket replacement work table and associated tooling must be lowered onto the REDC platform by the bridge crane. The bridge crane is then used to transport the jumper into position over the work table. The EMM is used to orient the jumper so the appropriate Hanford connector is directed toward the viewing window for optimum visibility. The EMM is also used to stabilize the jumper during gasket removal and installation operations. For this task, a special EMM attachment has been designed by DWPF engineering to slide over the Acme nut of the Hanford connector.

The first operation that must be performed during remote replacement of a Hanford connector gasket is removal of the snap ring, which is used to retain the gasket against the Hanford connector block. The Hanford connector skirts on DWPF jumpers have three holes spaced 120° apart that allow direct access to the snap ring. A punch can be placed in any one of the holes, which are angled such that a hammer-blow to the punch will eject the ring from its groove. These design features were utilized in development of the snap-ring-removal tools, which use an air cylinder extension to “punch” the snap ring out its groove. The only difference between the two removal tools is that one of brackets is designed to accommodate the geometry of a horizontal Hanford connector and the other that of a vertical Hanford connector.

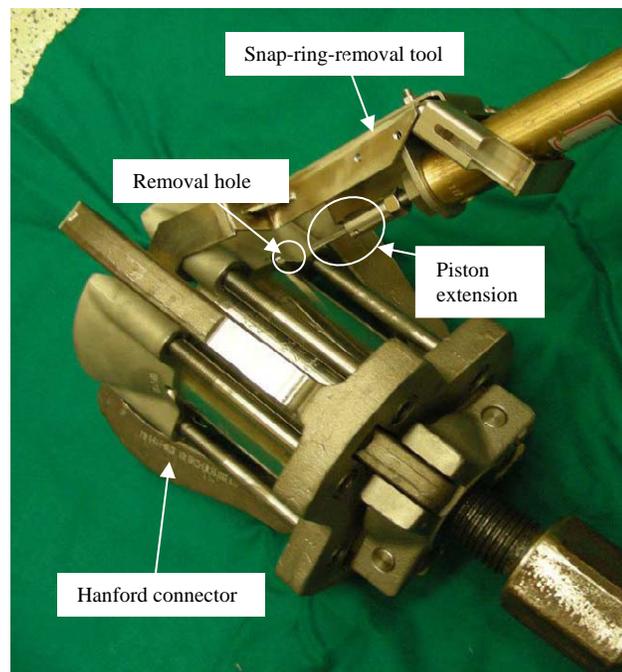


Figure 3. Snap Ring Removal

In order to use the snap-ring-removal tool, the operator must position the tool where the removal tool cylinder and bracket straddle the Hanford connector skirt and align the cylinder

axis as well as possible with the axis of the connector hole (see Figure 3). Once the tool is in position, another operator opens a valve to supply pressurized air to the removal tool. This air pressure actuates the tool piston, forcing the pin through the connector hole and ejecting the snap ring. The cylinder is then vented so that the piston retracts. At this point, the snap ring has been removed and the gasket usually falls away from the jumper. If the gasket remains in the jumper, it is scraped off of the jumper with the MSM fingers.

3.2.1 Snap-Ring-Loading Tool

Before the gasket installation tool can be used, a snap ring must be “loaded” into a groove on the installation tool with geometry similar to that of a face seal o-ring groove. This is required because when the snap ring is ejected from the installation tool into the Hanford connector, the ring must already be compressed or its diameter will be too large to fit in the connector groove (see Figure 4).

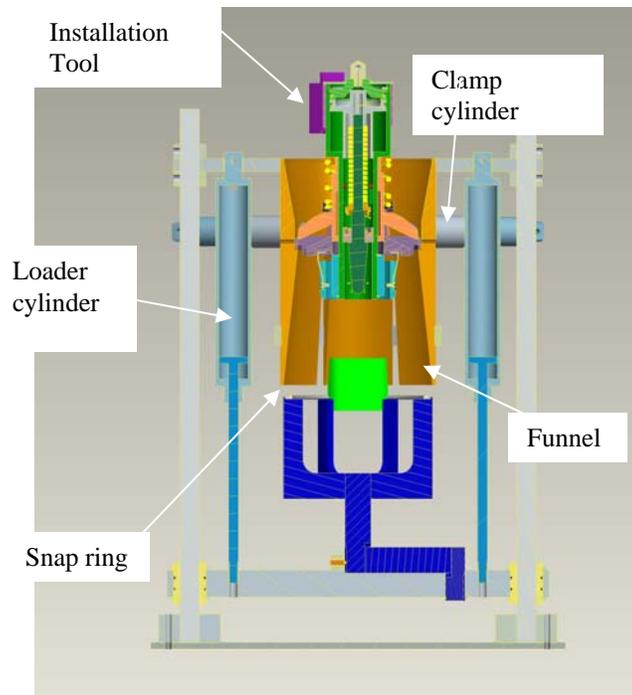


Figure 4. Snap Ring Loader Staged for Loading

The snap ring loader loads a snap ring into the installation tool by performing the following steps (see Figure 5). The manual operations are performed remotely using the REDC MSM's.

1. A snap ring is placed on the snap ring loader fingers.
2. The fingers are rotated under the loading funnel until the hard stop is hit.
3. The installation tool is placed in the funnel.
4. The clamp cylinders are actuated to lock the installation tool in position.
5. The loader cylinders are actuated to raise and compress the snap ring into the installation tool.

After the snap ring has been loaded in the installation tool, a gasket is placed on the installation tool storage mount and the installation tool is placed on top of the gasket. Six

custom springs are mounted on the head of the installation tool to retain the gasket on the installation tool (see Figure 6).

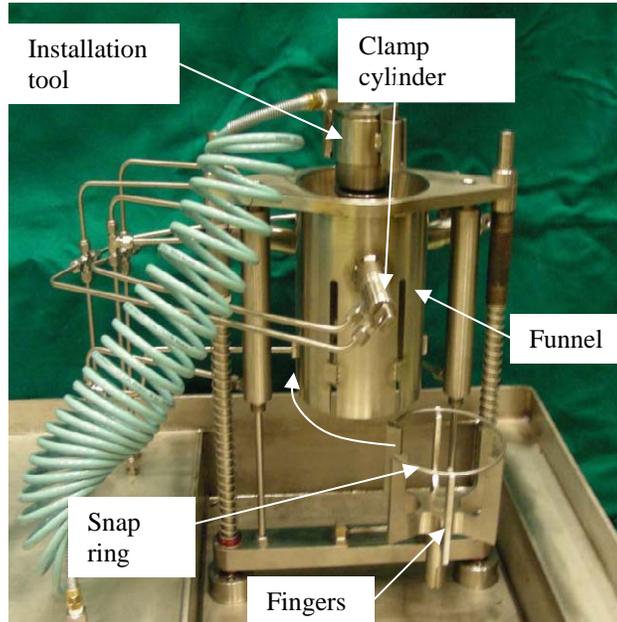


Figure 5. Snap-Ring-Loading Preps

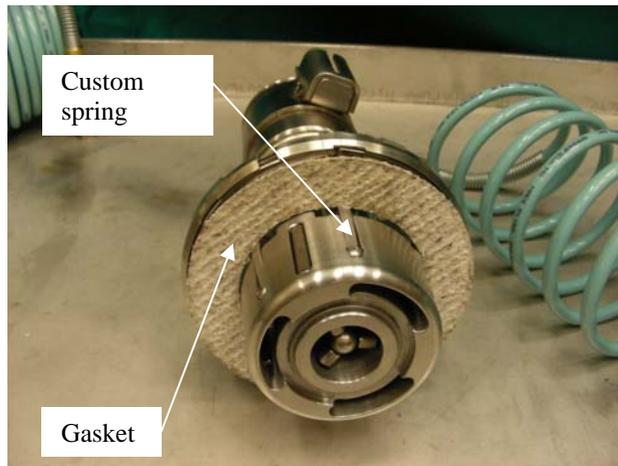


Figure 6. Illustration of Loaded Gasket

3.2.2 Gasket Installation Tool

The gasket installation tool is designed to replace 3" diameter gaskets, which represent approximately 60% of the Hanford-style gaskets in service in DWPF. However, 80% of the gasket replacements during 2007 were performed on 3" Hanford connectors.

To use the gasket installation tool, an MSM operator first places the tool against the sealing face of a Hanford connector. With the tool in this position, 100 psi compressed air is provided to the tool. The air actuation causes the following sequence of actions:

1. The tool locates itself concentrically with the connector block center hole.
2. The tool anchors itself to the connector.
3. The tool advances both the gasket and the snap ring into position.
4. The snap ring expands into its groove in the connector firmly fixing the gasket.

Figure 7 shows a cross section of the installation tool inserted into a Hanford connector. In this view the tool is retracted (not pressurized). Features of interest in this view are: the MSM grips, snap ring ejector fingers, gasket, snap ring, gasket retention clips, and the Hanford connector.

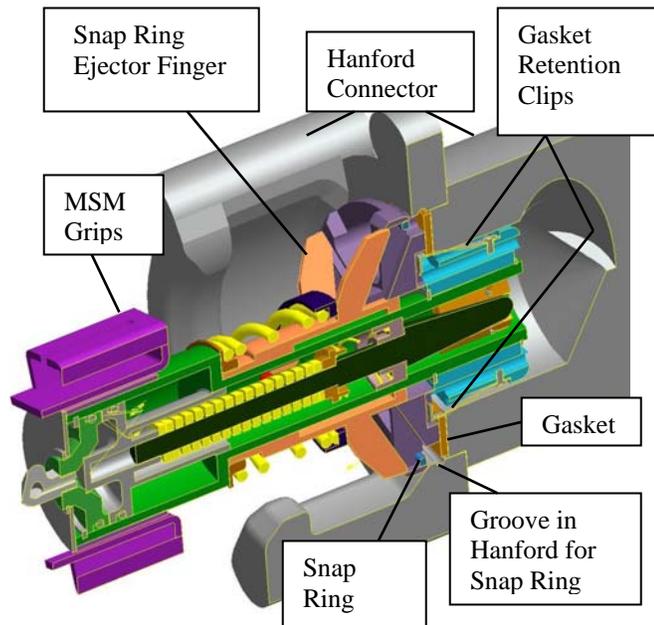


Figure 7. View 1 of Installation Tool in Hanford Connector (3-D Model)

The Hanford connector is illustrated in gray and the installation tool is shown in multi-color format. The MSM (not shown) positions the installation tool as shown against the Hanford connector via the MSM grips. When compressed air enters the tool (discussed later) the snap ring is forced forward into the Hanford connector groove by the snap ring ejector fingers.

The gasket thickness is such that the snap ring bears against the gasket allowing it to maintain its position in the connector.

Figure 8 shows another cross-section of the installation tool. Items of interest in this figure are: dogs, wedge, pins, piston, springs and the compressed air inlet port.

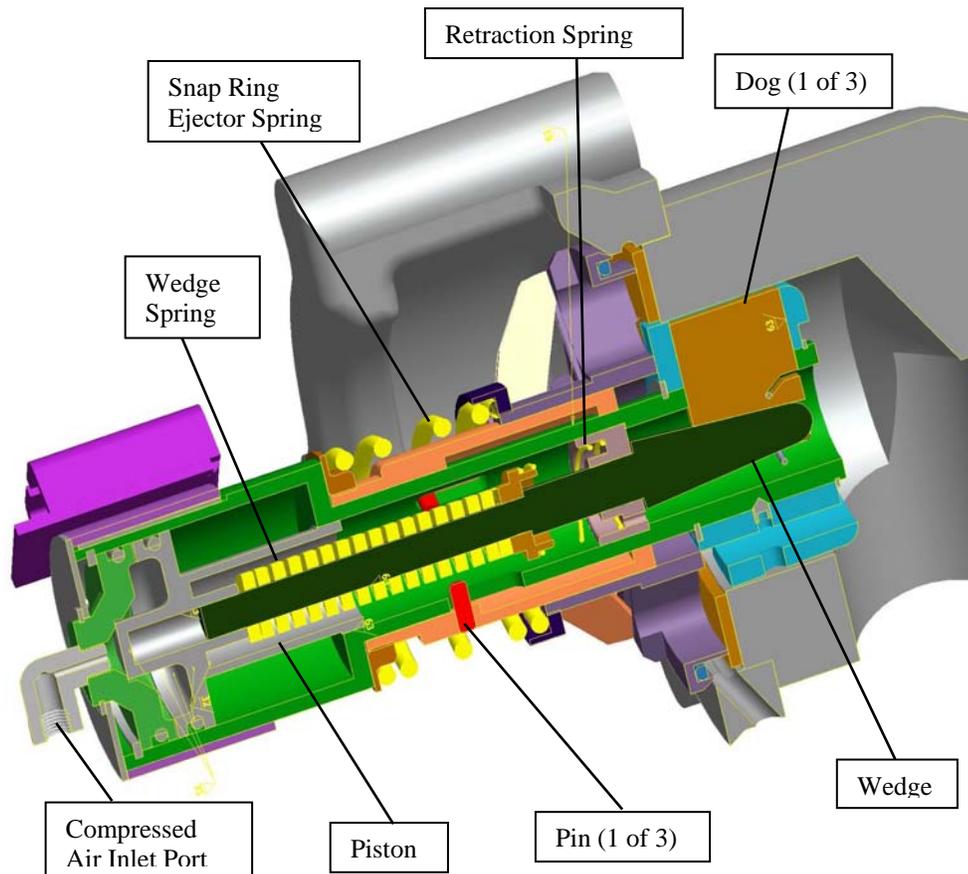


Figure 8. View 2 of Installation Tool in Hanford Connector (3-D Model)

When compressed air is introduced and builds pressure in the inlet port, the piston moves right (Figure 8) starting a sequence of tool motions. The wedge is forced right, causing the dogs to bear against the bore of the connector. After the dogs make contact with the bore no further rightward motion is possible for the wedge. Further piston stroke causes compression of the wedge spring; this adds more load on the dogs in turn increasing anchorage and alignment forces between the tool and the connector. The leading edge of the piston makes contact with three red pins. The pins are radially oriented and are part of the snap ring ejector. After contact, the pins and snap ring ejector move to the right with the piston. The snap ring ejector spring resists accidental snap ring ejection that could be caused by inadvertent motion of the snap ring ejector fingers during tool movement. The spring is compressed until the snap ring is ejected from its groove in the tool and transferred to the connector. The retraction spring is present to help retract the wedge which enhances dog retraction into the tool after the air pressure has been isolated from the tool. A garter spring

(not annotated but fitted into a slot milled in each dog) retains each dog within the tool after removal from the connector bore.

Use of the MSM requires that the tool weight not exceed 10 lbs due to MSM load limitations. The maximum operating pressure available to the tool is limited to that existing in the facility plant air system (~110 psig). The weight and air pressure limitations drove the custom design and a lot of the engineering optimization undertaken as part of the development of the tool.

The proportioning of the total load provided by the piston between the wedge and pins is dictated by wedge angle, spring characteristics and the extent of any preloading in the snap ring ejector spring. Examples of the analysis used to optimize features such as the wedge angle and spring selection are shown in Appendix A. The springs were chosen to proportion a large percentage of the available piston force to anchorage and alignment of the tool within the connector's hole. The geometry of the installation tool is designed to minimize the gap between the contacting surfaces of the installation tool and the connector skirt. The snap ring is radially compressed as it is loaded into the installation tool and will spring radially outward if it encounters a gap during its transit out of the installation tool to the connector. If a gap exists during installation large enough for the ring to expand open radially before reaching the snap ring groove in the connector skirt, it is expected that the installation would have to be terminated and another ring reloaded into the installation tool.

The installation tool and loading tool both have components that slide relative to each other, requiring very tight tolerances (some less than .001"). The tool must be fabricated out of stainless steel due to nitric acid exposure. Austenitic stainless is prone to gall, therefore the design called for 304 stainless components to be mated against Nitronic 60 components. The sliding surfaces are lubricated with Fel-Pro C-100 or Loctite Heavy Duty Anti-Seize. Dow-Corning High Vacuum silicone grease or Dow Molykote 55 silicone grease are used to lubricate the o-rings. For the threaded components, Leak Lock thread sealant by Highside Chemical is used in lieu of Teflon tape. Leak Lock is a blue paste that has no Teflon or chlorides. Appendix B provides lubrication data and supporting documentation for lubrication selection.



Figure 9. Installation Tool in Hanford Connector

3.3 TESTING

Functional testing of the gasket replacement tooling prototypes has been performed in multiple stages. Testing of the removal tool concepts was performed using a mockup MSM in 773-50A. This initial test verified that the removal tools could eject a snap ring from a Hanford connector. Functionality of the installation tool, loading tool, removal tools and other table components were tested without an MSM in the 723-A assembly area prior to delivery to DWPF. The testing in 723-A (without an MSM) had no acceptance criteria other than verification that the equipment could perform all of the tasks required to remotely replace gaskets. Cold manipulator testing was performed in the DWPF manipulator repair shop. This testing allowed the equipment operators to comment on the function of the tools and also facilitated development of an operating procedure. Multiple changes to the tools resulted from this testing. The manipulator grips were redesigned to be closer to the center of gravity of the removal tools to reduce fatigue. The grips were also made a closed style to minimize the risk of the tool slipping from the manipulator grasp. Further testing led the grips on the horizontal tool to be flipped to enhance maneuverability. The work table was modified to incorporate quick-disconnect pneumatic fittings to allow modular replacement of the installation tool, loading tool and removal tools upon failure in the REDC. The design of the gasket and snap ring storage caddy was modified. The initial design was fixed to the table and involved stacking the gaskets and snap rings in two separate stacks. The new design stores gaskets and snap rings on a single modular caddy that has a lifting bail to allow removal and replacement with another caddy already loaded with gaskets and snap rings. This design has slots for nine gaskets and nine snap rings. The slotted design facilitates handling of the snap rings and gaskets by the MSM.

On July 17 and 29, 2008 the Remote Gasket Tool was successfully demonstrated by DWPF Operations personnel in the REDC cell using a process jumper.

A second unit of the entire system has been fabricated, functionally tested in 723-A and delivered to DWPF. The design of the second unit incorporates the design changes implemented after testing the first unit. This unit will be used for training of operations personnel to support testing of development installation tools and as a source of spare parts if needed.

4.0 SUMMARY

The Hanford connector gasket replacement tooling has been successfully demonstrated using MSM's to manipulate the various tools. On July 17 and 29, 2008 the Remote Gasket Tool was successfully demonstrated in the REDC cell using a process jumper. Deployment of the existing system in the DWPF REDC for system jumper maintenance is expected during FY09. Development of installation tools for replacement of additional single hole (1-5/8", 2") and multi-hole gaskets is planned.

5.0 FUTURE WORK

DWPF has expressed interest in development of installation tools for replacement of other single hole (1-5/8", 2") and multi-hole gaskets. A test was performed by DWPF personnel using the existing installation tool with the bore locking feature removed to determine whether snap rings could be installed without this feature. If this is possible, design of tools for replacement of multi-hole gaskets becomes much less complex. Unfortunately, the test was unsuccessful. Lessons learned from development and testing of the 3" gasket installation tool will be applied to development of the other installation tools.

6.0 ACKNOWLEDGEMENTS

The following SRS employees all played important roles in support of development, testing or deployment of the gasket replacement tooling:

SRNL

George Crow
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DWPF Engineering

Jim Gee
Brian Metzger
Randy Neuville

DWPF Operations

Rickey Jackson
Greg Lawson
Darryl Perry
Leonard Perry

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D. Kremetz, J. T. Coughlin, R. B. Milling, M. J. Dalmaso, "Development of Remote Hanford Connector Gasket Replacement Tooling for the Savannah River Site's Defense Waste Processing Facility", 2nd International Joint Topical Meeting on Emergency Preparedness and Response and Robotic and Remote Systems Conference Proceedings.

B. A. Metzger, J. T. Gee, D. Kremetz, J. T. Coughlin, R. B. Milling, M. J. Dalmaso, "Development of Remote Hanford Connector Gasket Replacement Tooling for the Savannah River Site's Defense Waste Processing Facility", 2009 Waste Management Conference Abstract #9457.

APPENDIX A. INSTALLATION TOOL FORCE CALCULATIONS

Problem - Determine "centering force" at location of MSM grip when pneumatic installation tool is pressurized. Examine design of tool for adequacy/optimization with respect to other operational requirements (relative to spring selection and available piston force)

Tool Operation Summary - When air pressure is introduced to the installation tool (Fig. 1), a series of events occurs sequentially as follows:

Piston is driven to the right compressing the lighter retract spring.

The wedge slides to the right as the retract spring is compressed.

As the wedge slides rightward, the dogs (total of three spaced at 120 deg around the conical-shaped wedge) are forced radially outward. This motion is required to align the axis of the installation tool with the axis of the connector block axis. If alignment is not achieved prior to the release of the snap ring out of the holder (finish of step 9 below this section), then it is likely that the spring will expand or jump out through the gap between the snap ring holder and the connector skirt (gap created due to the misalignment). If this would occur, the installation would need to be restarted by loading another snap ring into the tool.

Contact is made on the connector block hole bore which stops the retract spring compression, any further piston motion begins compressing the heavier dog spring.

The dog spring compression continues alone until the front surface of the piston makes contact with the dowel pins.

Further piston movement is then accompanied with both the continued compression of the dog spring and movement of the snap ring ejector.

Movement of the snap ring ejector initially compresses only the installation spring until the bottom of each snap ring ejector leg bears against the left side of the snap ring (start pos.).

Further piston motion will then add one additional force, (along with the building dog spring force -- if snap ring is moving, installation spring compression should be holding steady) that of the drag of the snap ring (compressed in the snap ring holder groove ~17.5 lbf max).

Further motion should eventually cause the snap ring to be released from the holder into the skirt (this should slightly relieve the radial bearing load causing ring drag).

Further piston motion should cause the snap ring to drop into the finish position (note that due to the circular cross-sectional shape of the snap ring this will likely finish by pulling away from the ejector legs).

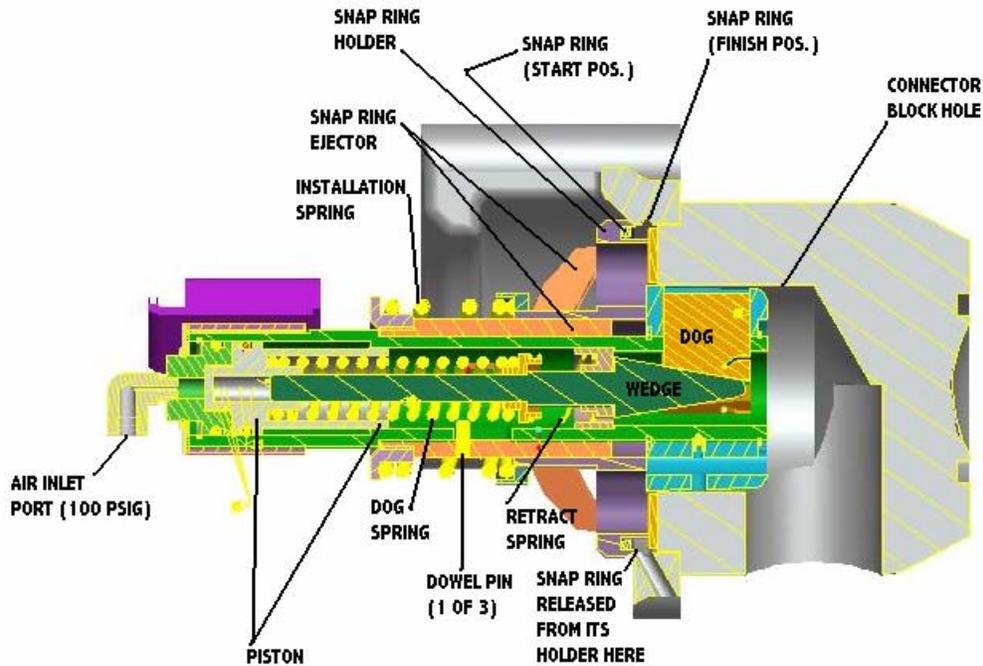


FIG A1: Pneumatic Installation Tool Cross-Section

Variable Definitions

- F1=wedge force during pressurization of piston
- F2=wedge force required to "pull away from dogs" when piston is depressurized
- R1=reaction force of dog onto the wedge during wedge advance
- R2=reaction force of dog onto the wedge during wedge withdrawal
- W1=wedge force on dog
- B=bore reaction force on dog
- H=housing reaction on dog
- Hf=friction force between dog and housing
- $\alpha=1/2$ of the included conical angle of the wedge or angle of "out of square cut" on dog
- ϕ =friction angle (always measured to surface normal and directed to oppose motion)
- P=piston load
- X=piston travel
- kd=spring constant of dog spring, century D-1434, 405 #/in, Lfree=3.0, no preload
- kr=spring constant of retract spring, century S-1256, 3.9 #/in, Lfree=1.31, Lsolid=.19, preload=1.27#
- ki=spring constant of install spring, century S-1651, 43 #/in, Lfree=1.94, Lsolid=.96, no preload
- i=counter to set up a range variable to evaluate piston load at .01 in travel increments
- x1min=X @ minimum tolerance connector block hole diameter, 3.009 in (Small Hole)
- x1max=X @ maximum tolerance connector block hole diameter, 3.027 in (Big Hole)
- x2=X @ piston contact with dowels, represents start of snap ring ejector motion (ki buildup starts)
- x3=X @ start of snap ring movement, this stops ki buildup & starts ring drag = 17.5#
- x4=X @ snap ring ejection (release) from snap ring holder, reduces ring drag to unknown. **Guess=12**
- C=magnitude of couple created by misaligned dogs
- A=aligning force measured at the center of the MSM grip

Develop a relation/curve showing the piston loading, P as a function of its travel, X from start. From this relation/curve we will later determine the wedge force F1.

kd := 405 x1min:= .709
kr := 3.9 x1max:= .785
ki := 43 x2 := .986
i := 0..151 x3 := 1.219
 x4 := 1.328
 $X_i := \frac{i}{100}$

Loop to determine piston load using the small hole case:

```
P1 := | r ← 0
      | for i ∈ 0..151
      |   pr ← 1.27 + Xi · kr if Xi < x1min
      |   pr ← 1.27 + x1min · kr + (Xi - x1min) · kd if x1min ≤ Xi < x2
      |   pr ← 1.27 + x1min · kr + (Xi - x1min) · kd + (Xi - x2) · ki if x2 ≤ Xi < x3
      |   pr ← 1.27 + x1min · kr + (Xi - x1min) · kd + (x3 - x2) · ki + 17.5 if x3 ≤ Xi < x4
      |   pr ← 1.27 + x1min · kr + (Xi - x1min) · kd + (x3 - x2) · ki + 17.5 otherwise
      |   r ← r + 1
      | p
```

Loop to determine piston load using the large hole case:

```
P2 := | r ← 0
      | for i ∈ 0..151
      |   pr ← 1.27 + Xi · kr if Xi < x1max
      |   pr ← 1.27 + x1max · kr + (Xi - x1max) · kd if x1max ≤ Xi < x2
      |   pr ← 1.27 + x1max · kr + (Xi - x1max) · kd + (Xi - x2) · ki if x2 ≤ Xi < x3
      |   pr ← 1.27 + x1max · kr + (Xi - x1max) · kd + (x3 - x2) · ki + 17.5 if x3 ≤ Xi < x4
      |   pr ← 1.27 + x1max · kr + (Xi - x1max) · kd + (x3 - x2) · ki + 17.5 otherwise
      |   r ← r + 1
      | p
```

Wedge force load for the small hole case:

$$\text{Wedge_s_h} := \left\{ \begin{array}{l} r \leftarrow 0 \\ \text{for } i \in 0..151 \\ \left\{ \begin{array}{l} w_r \leftarrow 0 \text{ if } X_i < x_{1\text{min}} \\ w_r \leftarrow (X_i - x_{1\text{min}}) \cdot kd \text{ otherwise} \\ r \leftarrow r + 1 \end{array} \right. \\ w \end{array} \right.$$

Wedge force load for the large hole case:

$$\text{Wedge_b_h} := \left\{ \begin{array}{l} r \leftarrow 0 \\ \text{for } i \in 0..151 \\ \left\{ \begin{array}{l} w_r \leftarrow 0 \text{ if } X_i < x_{1\text{max}} \\ w_r \leftarrow (X_i - x_{1\text{max}}) \cdot kd \text{ otherwise} \\ r \leftarrow r + 1 \end{array} \right. \\ w \end{array} \right.$$

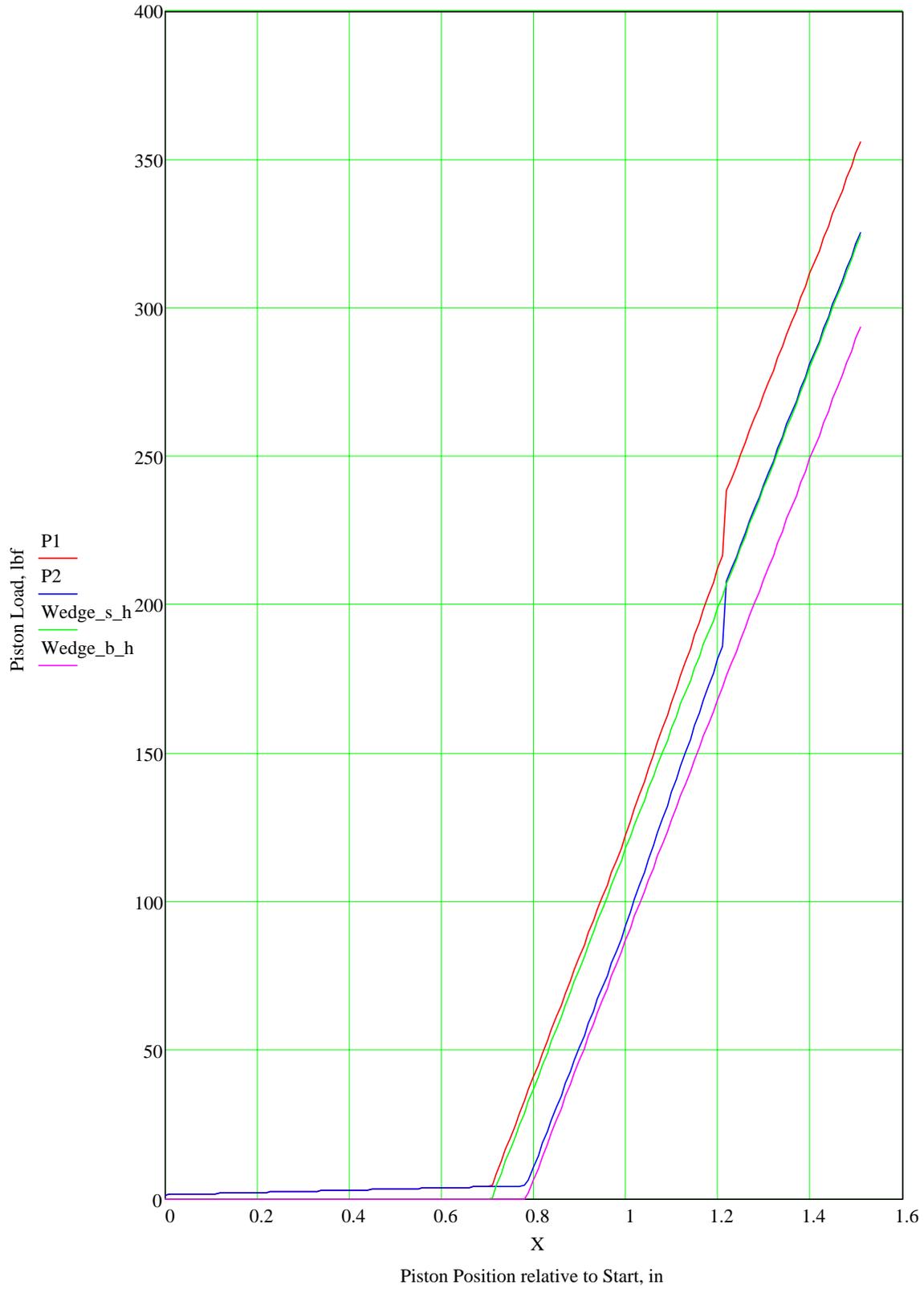


Figure A2: Piston Load vs Piston Position

Determination of alignment force at center of MSM grip location

To complete this part of the calculation, a relation will be developed between the wedge force applied to the dogs and the radial force applied to the connector bore by the dogs. Then another relation will be written expressing the alignment force at the MSM grip location in terms of the radial dog force couple. Friction is included in the first expression -- various values of friction will be evaluated using a range variable. The proper dog spring input force on the wedge will be determined from the earlier plot relating the piston force to the piston location. A high and low value for this force will need to also be considered as the connector hole diameter has a wide tolerance range. Final results for this section will be presented graphically.



Figure A3: Orientation of Forces on Wedge during Dog Extension

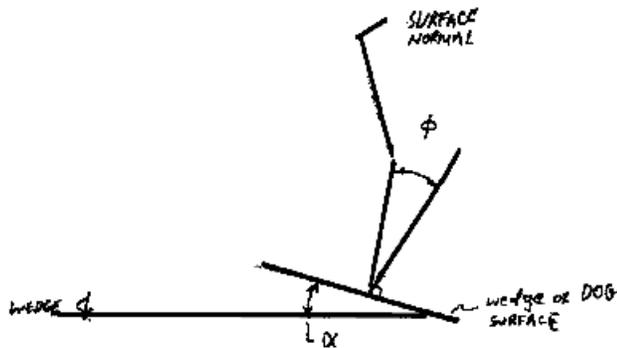


Figure A4: Generic diagram showing unlabeled force oriented at ϕ to the surface normal (wedge motion assumed from left to right -- illustrates how friction affects orientation of reaction w.r.t surface normal)

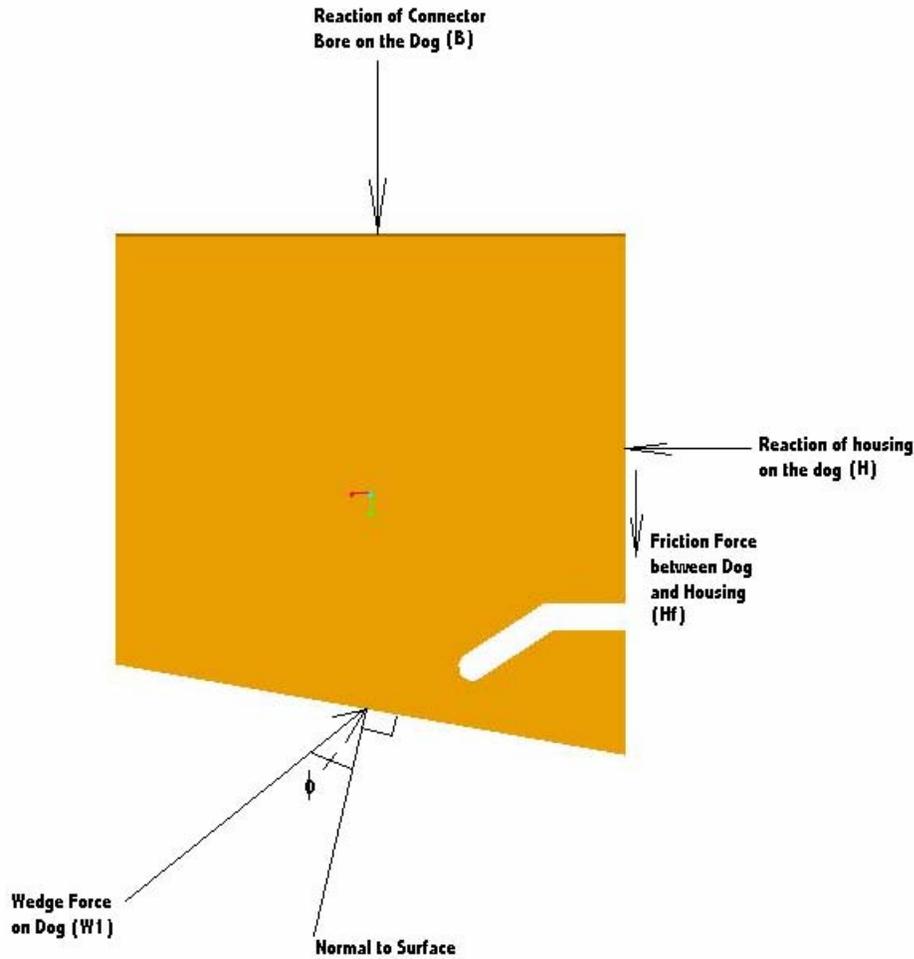


Figure A5: FBD of Dog with Equilibrium Forces Labeled

See Figures A3-A5 above for the following:

For the wedge:

From force analysis of piston vs movement from above:

$$Patejectminhole = (x4 - x1min) \cdot kd$$

$$Patejectminhole = 250.695$$

$$Patejectmaxhole = (x4 - x1max) \cdot kd$$

$$Patejectmaxhole = 219.915$$

$$F1s := Patejectminhol$$

$$F1b := Patejectmaxhol$$

Using friction as a range variable relate wedge force to dog rxn (Fig A3 FBD of Wedge).

$$n := 0..70 \quad j := 5, 6..10$$

$$\alpha_j := j \cdot \frac{2 \cdot \pi}{360}$$

$$\mu_n := \frac{n}{100}$$

$$\phi_n := \text{atan}(\mu_n)$$

$$R1s_{n,j} := \frac{F1s}{3 \cdot \cos\left[\pi - \left(\frac{\pi}{2} + \phi_n + \alpha_j\right)\right]}$$

$$R1b_{n,j} := \frac{F1b}{3 \cdot \cos\left[\pi - \left(\frac{\pi}{2} + \phi_n + \alpha_j\right)\right]}$$

From Fig A5 -- FBD of Dog

We know that the magnitude of $W1=R1$, using this and summation of x-dir forces we get:

$$W1s_{n,j} := R1s_{n,j} \quad W1b_{n,j} := R1b_{n,j}$$

$$Hs_{n,j} := W1s_{n,j} \cdot \sin(\phi_n + \alpha_j) \quad Hb_{n,j} := W1b_{n,j} \cdot \sin(\phi_n + \alpha_j)$$

From the friction triangle (ref. Fig 3) and apply to H and Hf

$$Hfs_{n,j} := \tan(\phi_n) \cdot Hs_{n,j} \quad Hfb_{n,j} := \tan(\phi_n) \cdot Hb_{n,j}$$

From the summation in the y-dir and the above we get:

$$Bs_{n,j} := W1s_{n,j} \cdot \cos(\phi_n + \alpha_j) - Hfs_{n,j} \quad Bb_{n,j} := W1b_{n,j} \cdot \cos(\phi_n + \alpha_j) - Hfb_{n,j}$$

If the axis of the installation tool is not lined up with the axis of the connector, then the force Bs_n will cause a couple of magnitude= $3 \cdot 1.25 \cdot Bs_n$

$$Cs_{n,j} := 1.25 \cdot Bs_{n,j} \quad Cb_{n,j} := 1.25 \cdot Bb_{n,j}$$

The distance from the center of this couple to the center of the MSM grip is approximately 6.7 in. Therefore the aligning force measured at the MSM grip center is:

$$As_{n,j} := \frac{Cs_{n,j}}{6.7} \quad Ab_{n,j} := \frac{Cb_{n,j}}{6.7}$$

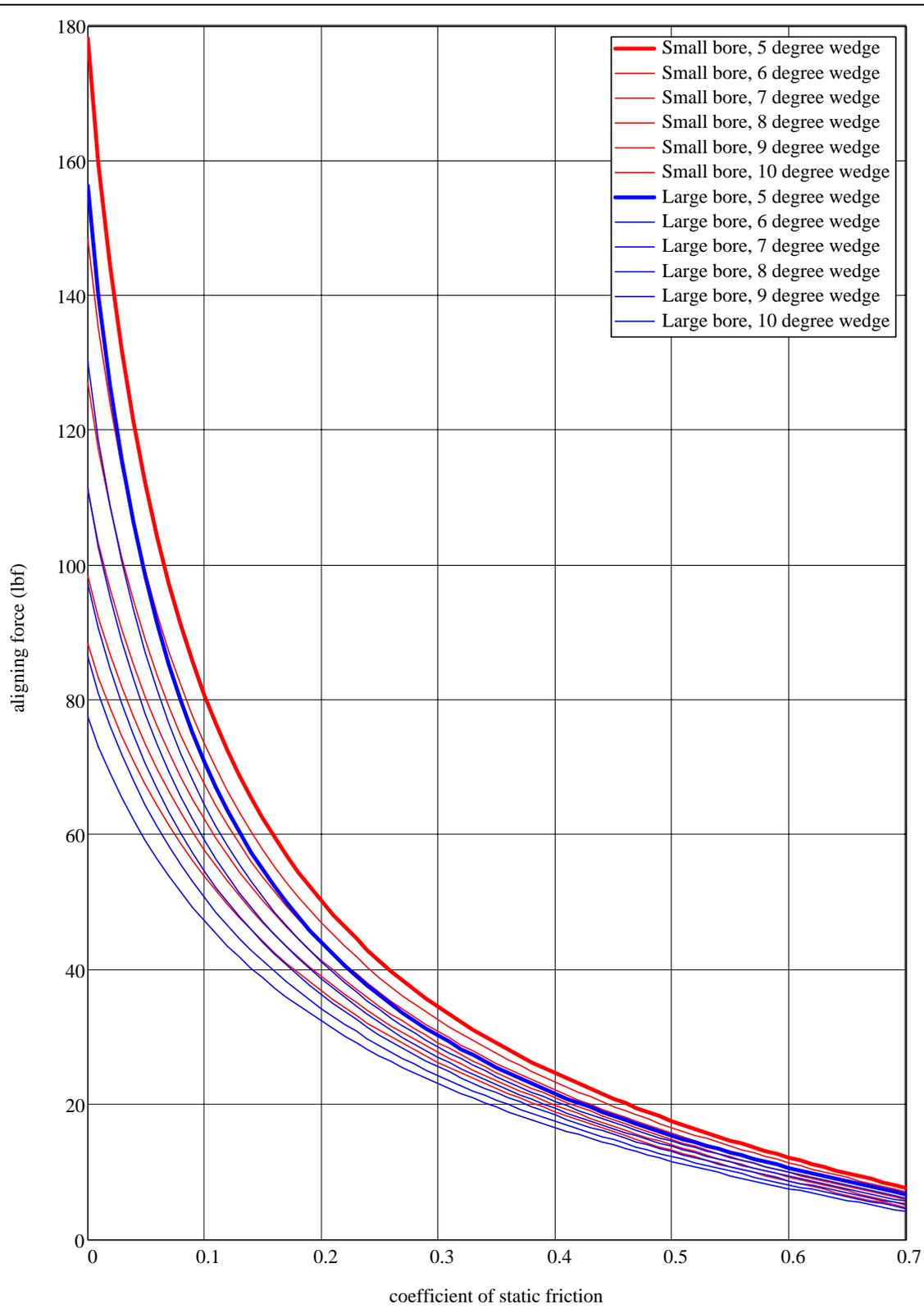


Figure A6: Effect of friction coefficient on aligning force

Conclusions

The family of curves in Figure A6 shows the effect of the coefficient of friction on the aligning force. The effect of variations in the wedge angle is also seen. Any variation away from the current design value of 5 deg. would have to be reviewed to see if the tool would operate properly. It could be easy to erroneously assume that increasing the actuation pressure above 100 psig would increase the alignment force. Per this calculation, a higher pressure would not change the alignment force since the dog spring would still be compressed the same amount at the snap ring ejection. On the other hand, it is possible that increasing the actuation pressure could momentarily increase the alignment force if the blind hole in the piston acts as an air spring as the wedge slides down in the piston. This is not easy to realistically quantify and has been ignored in this calculation. The dog spring cannot be preloaded since it would prevent the wedge from retracting when the air pressure is removed. A potential way to improve the alignment force is to select a new dog spring. Note that a stiffer dog spring would probably require a larger piston or higher pressure.

Fel-Pro C-100 anti-seize was used to lubricate the stainless-on-stainless mating surfaces. Per Fel-Pro and Loctite literature (see Appendix B), the torque coefficient of Fel-Pro C-100 is .19 and the friction coefficient is 2/3 of the torque coefficient, which in the application makes the friction coefficient .127. Given this friction coefficient, Figure A6 indicates that the aligning force will be between 60-70 lbf depending on actual bore diameter.

Figure A2 indicates that the maximum piston load (P_{1max}) = 356 lbf.

A piston diameter of 2.141" @ 100 psig thus provides enough force to overcome the piston load. ϕ 2.1875 would give an extra 20 lbf if needed for internal binding or friction. The piston ID was thus designed at 2.1875" to provide this margin. Any additional increase of the piston ID makes the resulting spacing between MSM grips greater than the MSM's grip range.

APPENDIX B. LUBRICATION INFORMATION


WASHINGTON SAVANNAH RIVER COMPANY
 INTEROFFICE MEMORANDUM

 LWO-WSE-2006-00001
 RMS Tracking #: 10080

March 22, 2006

 TO: S. W. Wilkerson, 704-S
 G. E. Lawson, 210-S
 A. H. Welch, 210-S

 FROM: M. S. Miller, 704-S
 J. T. Gee, 704-25S

SUBJECT: Engineering Position: Acceptable Thread Lubricant for Mechanical Fasteners (U)

Background

There is some confusion over the proper thread lubricant for mechanical fasteners to be used with the DWPF Piping Specifications (T-ESR-S-00010). Many of the DWPF Piping Specifications suggest the use of "graphite oil thread lubricant. Engineering Guide No.15060 suggests the use of a lubricant similar to "Fel-Pro C-100 Antiseize Compound" for fasteners. This product has been replaced with a lead free version of C-100 (i.e., C-102) called "Heavy Duty Anti-Seize Compound." The product is based on graphite/calcium fluoride. Discussions with key personnel from within DWPF have suggested that a LOCTITE, copper based product, called "C5-A" had been used as fastener lubricant. The use of this product did not follow either the DWPF Piping Specification or the site Engineering Guide 15060.

Objective

This Engineering Position will provide a list of acceptable fastener lubricants that can be used in DWPF piping systems. The intent of the document will be to expand the list of acceptable lubricant choices and, if necessary, set limits where these products cannot be used. While specific products will be listed in this document, other similar products may be acceptable after engineering review and approval.

Discussion

WSE has reviewed documentation on several different types of anti-seize lubricants for threaded fasteners. Products reviewed included compounds based on nickel/graphite, copper copper/graphite, and graphite-oil. Several products are available as "nuclear grade" which will ensure low halide content for stainless steel service. Product literature clearly states that copper based thread lubricants should not be used in concentrated acid service (i.e., nitric acid, etc.). All of these products appear to be acceptable as anti-seize compounds, although some are limited in highly oxidizing environments.

An effort was made to determine the basis for the "graphite-oil thread lubricant" criteria in many of the DWPF Piping Specifications. Some of the original DuPont P-codes specified "graphite/oil" fastener lubricant. Tyler French of the Piping and Valves Committee was not aware of the original basis, but stated that in his opinion any commercial anti-seize compound would be acceptable.

LWO-WSE-2006-00001

Page 2 of 3

The list of possible fastener lubricants was also reviewed with Eric Skidmore and Charlie Jenkins of the Materials Technology Section (SRNL). They concurred that any of the commercial anti-seize compounds would be acceptable for most services. For nitric acid service, they agreed that copper based anti-seize compounds (e.g., C5-A) were not compatible. Even in this case, however, the joint would have to leak for the nitric acid to attack the thread lubricant. At worst, this may lead to seizing between the fastener components. It was noted that nuclear grade anti-seize compounds were available that should meet all our fastener lubricant needs. Such products would be available at premium prices, however. The consensus opinion was that selection of fastener lubricant should be based on cost and availability, providing special needs are met (e.g., halide content on stainless steels, nitric acid service, etc.).

Engineering Position

Engineering approves the use, with limitations noted, of the following commercial anti-seize compounds for fasteners contained within DWPF piping systems. Fastener lubricants specified within DWPF Piping Specifications will be considered guidance only and will not limit the choices outlined in this memorandum.

1. Graphite-Oil Thread Lubricant (generic)
2. Graphite/Calcium Fluoride Based Products
 - a. LOCTITE "Fel-Pro C-100 Anti-Seize Compound"
 - b. LOCTITE "Heavy Duty Anti-Seize"
 - i. C-102 (lead free C-100 replacement)
3. Nickel/Graphite Based Products
 - a. NEVER-SEEZ "Nickel Special, Nuclear Grade"¹
4. Nickel/Graphite in Petroleum Carrier Based Products
 - a. LOCTITE "N-5000" (low halide content, suitable for stainless steel)
5. Calcium Oxide/Graphite Based Products
 - a. LOCTITE "N-7000" (low halide content, suitable for stainless steel)
6. Copper Based Products
 - a. LOCTITE "C5-A"
7. Copper/Graphite with Petroleum Carrier Based Products
 - a. LOCTITE "N-1000"

General Restrictions on Anti-Seize Compounds:

1. Copper based lubricants should not be used for piping containing nitric acid.
2. Stainless steel piping systems that are expected to experience temperatures in excess of 104 °F should use low chloride anti-seize compounds (i.e., Nuclear Grade).

¹NOTE: DWPF has a large quantity (three 1-gal. cans) of "Pure Nickel Special, Nuclear Grade" (Material ID: 714S-5353) of surplus lubricant that was purchased for an earlier gasket study. This is considered acceptable for all DWPF piping service.



Technical Information

FOR REFERENCE ONLY.
COPY

C-100 vs HEAVY DUTY ANTI-SEIZE (formerly C-102)

TECHNICAL COMPARISONS

	Color	Composition	30 day 600°F Anti-seize Test*	Torque Coefficient**	
C-100	Black	Molybdenum Disulfide Graphite Lead Oxide Petroleum	145 ft-lb No seizing	.16	.19
HEAVY DUTY ANTI-SEIZE (C-102)	Black	Graphite Calcium Fluoride Petroleum	145 ft-lb No seizing	.15	.18

Replacing C-100 with HEAVY DUTY ANTI-SEIZE will produce no changes in bolted joint performance. Both anti-seize and thread friction performance will be the same.

- * Anti-seize test of 3/4" diameter bolts, removal torque.
- ** Torque Coefficient, k, is the relationship between torque, bolt diameter and clamping force of bolted joints.

Torque = k x (clamp load) x (bolt diameter)

8-23-93

Fel-Pro Incorporated
Chemical Products Division
7450 North McCormick Blvd.
Skokie, Illinois 60076-8205

Fel-Pro Incorporated
6120 E. 58th Avenue
Commerce City, CO 80022

Fel-Pro of Canada, Ltd.
6105 Keatrel Road
Mississauga, Ontario L5T 1Y8
Canada

Torque Guide

Proper clamp load is an essential part of any bolted assembly for trouble-free operations. Torquing either nut or bolt creates the clamp load. An anti-seize lubricant used on a bolt helps to develop greater clamp load for the same torque compared to an unlubricated bolt. An additional benefit is greater uniformity in clamp load among a series of bolts. The relationship between torque and clamp load is expressed in the following equation: $T = KFD$



Where:

- T = Torque (in.-lb., ft.-lb., N-m)
- F = Clamp Load (lb., N)
- D = Nominal diameter of bolt (in., ft., m)
- K = Torque coefficient or nut factor, determined experimentally

K Factors: K factors are obtained on Grade 8, 1/2" steel bolts and grade 5 nuts by a test procedure that measures torque tension properties. Lubricant was applied to the bolt threads and both faces of the washer.

See the Properties Chart for the torque coefficient or K value for the anti-seize compounds.

Henkel Corporation believes that this data fairly represents performance to be expected. However, Henkel makes no warranty of specific performance on any individual fastener. In critical applications, it is necessary to determine K values independently.

Note: There are two "coefficients" used to express the relationship between torque and tension: torque coefficient (also called "nut factor") is the most commonly used. A different concept is the "friction coefficient," which has value 1/3 (or 67%) of the torque coefficient.

Loctite® Anti-Seize Properties Chart

	PRODUCT	Item Number	Package Type & Size	TEMPERATURE RESISTANCE	COLOR	K-VALUE					
GENERAL PURPOSE	C5-A® Copper Anti-Seize Lubricant	51299	2 g pouch	1800°F (982°C)	Copper	0.16					
		51277	7 g pouch								
		51001	1 oz. tube								
		51002	4 oz. tube								
		51144	4 oz. brush-top can								
		51147	8 oz. brush-top can								
		51005	10 oz. brush-top can								
		51003	12 oz. net wt. aerosol								
		51004	13 oz. cartridge								
		51006	1 lb. can								
51007	1 lb. brush-top can										
39643	1 lb. brush-top metal can										
51008	2.5 lb. can										
51009	8 lb. can										
38694	25 lb. pail										
51011	42 lb. pail										
51146	425 lb. drum										
GENERAL PURPOSE	QuickStix™ C5-A® Copper Anti-Seize	37229	20 g stick								
		39222	40 g stick								
GENERAL PURPOSE	Silver Grade Anti-Seize	38181	7 g pouch	1600°F (871°C)	Silver	0.18					
		80208	4 oz. brush-top can								
		76732	8 oz. brush-top can								
		76759	12 oz. net wt. aerosol								
		76764	1 lb. brush-top can								
		80206	1 gallon can								
		76775	5 gallon pail								
		GENERAL PURPOSE	QuickStix™ Silver Grade Anti-Seize				37230	20 g stick			
							39223	40 g stick			
		GENERAL PURPOSE	Nickel Anti-Seize				77124	8 oz. brush-top can	2400°F (1315°C)	Silver	0.13
51286	12 oz. net wt. aerosol										
51102	1 lb. can										
77164	1 lb. brush-top can										
51152	8 lb. can										
77175	5 gal. pail										
HIGH PERFORMANCE	Heavy Duty Anti-Seize	51609	1 oz. tube	2400°F (1315°C)	Black	0.16					
		51605	9 oz. brush-top can								
		51606	12 lb. brush-top can								
		51607	2.3 lb. can								
		51608	45 lb. pail								
HIGH PERFORMANCE	QuickStix™ Heavy Duty Anti-Seize	41205	20 g stick	2400°F (1315°C)	Black	0.16					
		34395	8 oz. brush-top can								
		34026	16 oz. brush-top can								
		34517	8 oz. brush-top can								
HIGH PERFORMANCE	White Hi-Temp Anti-Seize	34518	16 oz. brush-top can	2000°F (1093°C)	White	0.16					
SPECIALTY	Food Grade Anti-Seize	51168	8 oz. brush-top can	750°F (400°C)	White	0.13					
		51170	2 lb. can								
		51171	40 lb. pail								
	SPECIALTY	Graphite-50™ Anti-Seize	51084	1 lb. can	900°F (482°C)	Black	0.13				
SPECIALTY	Moly Paste	51050	12 oz. net wt. aerosol	750°F (400°C)	Black	0.11					
		51048	8 oz. brush-top can								
		51049	1 lb. brush-top can								
		51145	15 lb. can								
SPECIALTY	Moly-50™ Anti-Seize	51094	1 lb. can	750°F (400°C)	Black	0.13					
SPECIALTY	Zinc Anti-Seize	39901	1 lb. can	750°F (400°C)	Grey	0.15					
HIGH PURITY	N-7000™ High Purity Anti-Seize	51272	8 oz. brush-top can	2400°F (1315°C)	Silver	0.16					
		51270	1 lb. brush-top can								
		51273	2 lb. can								
	HIGH PURITY	N-5000™ High Purity Anti-Seize	51346	1 oz. tube	2400°F (1315°C)	Silver	0.15				
			51243	8 oz. brush-top can							
			51269	1 lb. brush-top can							
			51246	2 lb. can							
			51245	8 lb. can							
	HIGH PURITY	High Performance N-5000™ High Purity Anti-Seize	51572	1 lb. brush-top can	2400°F (1315°C)	Silver	0.15				
HIGH PURITY	N-1000™ High Purity Anti-Seize	51115	8 oz. brush-top can	1800°F (982°C)	Copper	0.17					
		51116	1 lb. can								
		51117	2 lb. can								



Eric Skidmore /SRNL/Srs
05/22/2007 01:38 PM

To James Gee/WSRC/Srs@Srs
cc Daniel Krementz/SRNL/Srs@Srs
bcc
Subject Re: Fw: O-ring lubricants 

The Molykote 55 product appears to be a stearate-based silicone grease (most Dow products are silicones) which should be highly compatible with Viton, particularly for the application in mind. Silicone oils and greases in general are very compatible with Viton (worst combination is silicone grease on silicone O-rings, like dissolves like problem, same for hydrocarbons and EPDM). A little swelling is acceptable and usually normal (5-10%). We use Dow-Corning High Vacuum silicone grease on Viton GLT O-rings in the 9975 shipping container and I do not know of any compatibility problems.

The problem with the other product (anti-seize) was a question on the lead oxide compatibility with the Viton (as I recall). The Molykote 55 appears to be a safer choice. Not sure if the O-ring or lubricant will see any direct chemical exposure, but silicones are not highly resistant to acids or strong bases. If only in the surrounding environment (nitric used for decon, etc.), the silicone should be fine.

The best bet for compatibility is to use a product recommended by the O-ring manufacturer (Parker, etc.) if possible, but they usually also recommend end-user testing so not always practical.

Eric Skidmore
SAVANNAH RIVER NATIONAL LABORATORY
Materials Science & Technology
Phone: 803-725-2236
FAX: 803-725-1744
James Gee/WSRC/Srs

James Gee/WSRC/Srs
05/22/2007 01:12 PM

To Eric Skidmore/SRNL/Srs@Srs
cc Daniel Krementz/SRNL/Srs@Srs
Subject Fw: O-ring lubricants

Eric,

Dan has proposed using Molykote 55 O-ring lubrication for the remote gasket replacement tooling. He was a little concerned about its suitability with Viton. I looked up a spec sheet for this product and for a room temperature application (assumed), it looks acceptable (i.e., relatively stable) with Viton. What are your thoughts? Do you have another recommendation. Feel free to contact Dan directly if you need more specific information on the application.

----- Forwarded by James Gee/WSRC/Srs on 05/22/2007 01:05 PM -----

Daniel Krementz /SRNL/Srs
05/11/2007 02:45 PM

To James Gee/WSRC/Srs@Srs
cc
Subject Re: O-ring lubricants 

Jim,

Per the message below, I have some Dow-Corning Molykote 55 o-ring lube. Do you know if this product is acceptable?

Thanks,
Dan Kremetz
Development Engineer
Savannah River National Laboratory
Robotics, Remote & Specialty Equipment
Building 723-A, Savannah River Site
Phone: 803-725-2410
Page: 803-725-7243, ID# 10758

Daniel Kremetz/SRNL/Srs

Daniel Kremetz /SRNL/Srs

05/11/2007 12:47 PM

To James Gee/WSRC/Srs

cc

Subject O-ring lubricants

Jim,

The anti-seize compound that I am using on the gasket installation tool is mildly incompatible with Viton . Do you have a list of silicone based o-ring lubes that are approved for DWPF use?

Thanks,
Dan Kremetz
Development Engineer
Savannah River National Laboratory
Robotics, Remote & Specialty Equipment
Building 723-A, Savannah River Site
Phone: 803-725-2410
Page: 803-725-7243, ID# 10758