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Job Scheduling for Hybrid Assembly Differentiation Flow Shop to Minimize Total Actual Flow Time considering Multi-Due-Dates

R Maulidya, Suprayogi, R Wangsaputra and AH Halim

Industrial Engineering Faculty, Institut Teknologi Bandung, Bandung 40132,
Indonesia

rahmimaulidya@gmail.com, yogi@mail.ti.itb.ac.id, rwangsap@mail.ti.itb.ac.id,
ahakimhalim@ti.itb.ac.id

Abstract. The hybrid assembly differentiation flow shop is a three-stage flow shop system with machining, assembly and differentiation stages. The machining stage produces k parts in independently unrelated dedicated machines. After k parts of a job completed, they are assembled at the assembly stage and assigned to dedicated machines for a final process. At the end, several types of finished products are resulted. The finished products should be delivered at their respective different due dates. The problem is to find a schedule considering multi due dates, and the criterion of minimizing total actual flow time. This paper proposes a model for job scheduling in a hybrid assembly differentiation flow shops and its algorithm for solving the problems. The initial solution is defined using SPT-based heuristic and it is optimized using variable neighbourhood descend method. The proposed model is tested using a set of hypothetic data. The solution shows that the algorithm can solve the problems effectively.

Keywords: job scheduling, hybrid assembly differentiation flow shop, total actual flow time, multi due dates

1. Introduction

This paper deals with a three-stage hybrid flow shop that consists of machining parts, an assembly operation and processing different end products called Hybrid Assembly Differentiation Flow Shop. The first stage is the machining stage where several dedicated machines produce different parts in parallel manner. The second stage is the stage where all parts of a product will be assembled in a single machine after they completed. The final stage is the differentiation stage consists of dedicated machines where an assembled part is processed into a certain type of products. The application of this system is illustrated from the electronic manufacturing where the system consists of a three-stage production system producing different types of products.

The recent pieces of research [1-4] developed the three-stage production system for job scheduling problem. According to [1], the three stage of production system consists of machining, transportation and assembly stages. Transportation is seen as an important aspect in job scheduling problem. The difference of [1], [2] define a three-stage production system as the machining processes in three stages. Other pieces of research [3-4] developed a three-stage production system that consists of machining, assembly and differentiation stages. In this paper, we extend the research proposed in [4] to cover a condition of multi-due-date.



The literature of [1-3] and [5] for job scheduling usually solve the problem using forward approach with the assumption of parts that should be available at time zero. The Model proposed in [3] uses the total flow time as the criteria to minimize the time spending by parts in the shop from time zero until the completion time. Other criteria developed by [5] using the performance measure of total tardiness to minimize the penalty between the job's due date and its completion time. In this paper, we use backward approach and the criterion of minimizing total actual flow time to minimize the interval time of parts spend in the shop from the arrival time until its due date. Total actual flow time is defined for some cases where parts are not available simultaneously in time zero, but will arrive when its needed, and other cases that consider the delivery time from due date of parts [6].

This paper deals with a problem of job scheduling model for a hybrid assembly differentiation flow shop to minimize the total actual flow time. We extend the problem in [4] to cover a condition where the finished products are demanded at several due dates meaning that there are several delivery times within a production planning. This paper is organized as section 2 for formulating the model, section 3 for the proposed algorithm, section 4 for the illustration and section 5 for the conclusion and the future research.

2. Method

2.1. Problem Formulation

Consider the problem of scheduling J jobs at a hybrid assembly differentiation flow shop to make H different types of finished products. We can denote the jobs belong to a certain type as JH_h . An illustration in Figure 1 show that there are four jobs in the system that consist of product type 1, $JH_1=J_1, J_2$, and product type 2, $JH_2=J_3, J_4$. Each job consists of part#1, part#2...part# k produced by unrelated parallel machines in the machining stage. Parts are processed on each machine in the same order. After all parts of a job are completed, they are assembled in a single assembly machine. The differentiation stage processes the assembled parts into a certain types of products in particular dedicated machines. There is a condition where the products must be delivered in different due dates. It means that each job must fulfil their own due date.

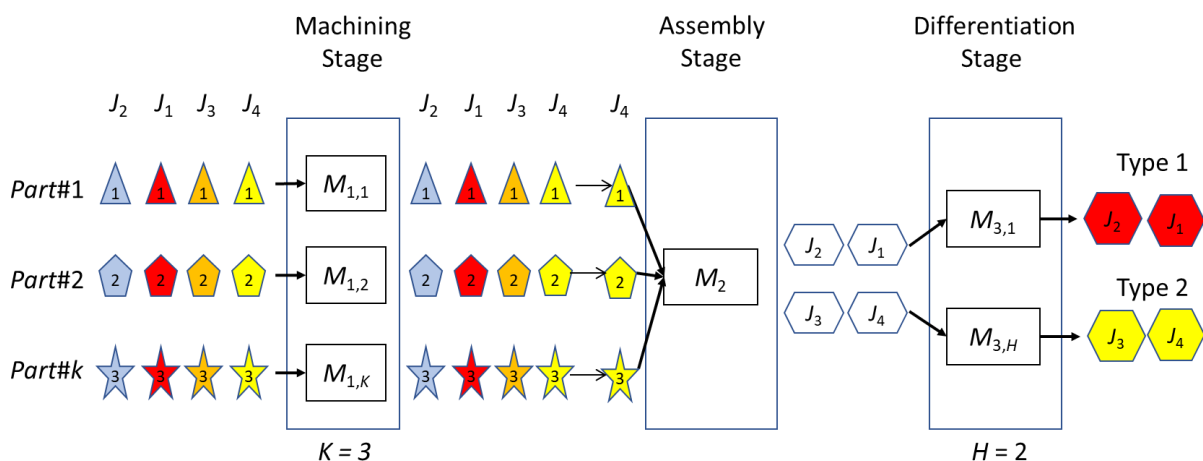


Figure 1. The three stages production system

The assumptions in this paper are:

- Production are finished at their corresponding due dates
- Each machine can process at most one job at a time
- Each job can be processed on at most one machine at a time
- Machines are always available

- Travel time between stages are neglected
- Job processing cannot be interrupted, until the completion of job.
- Jobs are available for processing at a stage immediately after processing completion at the previous stage.

2.2. Model

The actual flow time of a job ($F_{[i]}^a$), defined by [7], is the time spend by a job from its arrival time in the shop until its due date. The formulation for $F_{[i]}^a$ is as follows.

$$F_{[i]}^a = d - B_{[i]}, \quad i=1,2,\dots,J \quad (1)$$

Where d is a due date and $B_{[i]}$ is the starting time for processing J_j . The schedule is started backwardly and the position of $[i]$ is started from its due date.

The formulation of the actual flow time of a job with a due date is as follows.

$$F_{[i]}^a = d - \min_{k \leq K} (B_{[i],k}^{(1)}), \quad \forall i, \forall k \quad (2)$$

Figure 2 shows the actual flow time of several due dates d_1 and d_2 , respectively.

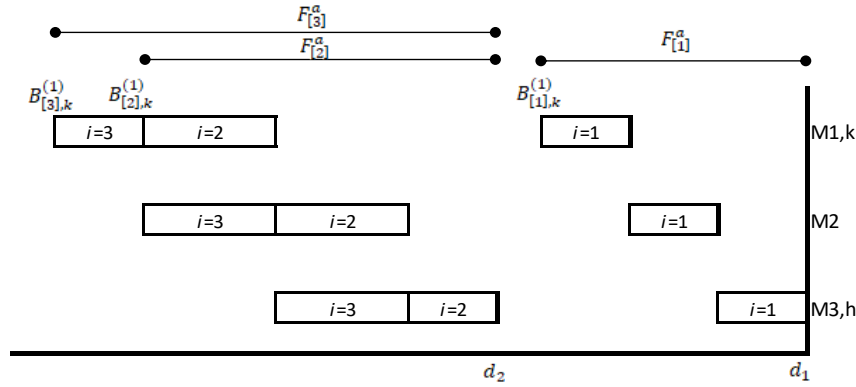


Figure 2. Actual Flow Time for multi due dates

From Figure 2, we have the actual flow time for position $i=1,2,3$.

$$\begin{aligned} F_{[1]}^a &= d_1 - \min_{k \leq K} (B_{[1],k}^{(1)}) \\ F_{[2]}^a &= d_2 - \min_{k \leq K} (B_{[2],k}^{(1)}) \\ F_{[3]}^a &= d_2 - \min_{k \leq K} (B_{[3],k}^{(1)}) \\ TAFT &= F_{[1]}^a + F_{[2]}^a + F_{[3]}^a \\ TAFT &= \sum_{i=1}^J (d_j - \min_{k \leq K} (B_{[i],k}^{(1)})) \end{aligned} \quad (3)$$

Notation

Index

j = index of jobs, $j=1, 2, \dots, J$

i = index of positions, $i=1, 2, \dots, J$

k = index of machines at the machining stage, $k=1, 2, \dots, K$

h = index of machines and the product types at the differentiation stage, $h=1, 2, \dots, H$

Parameter

K = number of machines at the machining stage

H = number of machines at the differentiation stage

J = number of processed job

JH_h = number of job processed in machine h

d_j = due date for job j

G_g = interval of two consecutive due dates

M_{1k} = machine for processing part k of all the jobs at the machining stage, $k = 1, 2 \dots K$
 M_2 = assembly machine in the assembly stage
 M_{3h} = differentiation machine for processing types of products in the differentiation stage, $h = 1, 2 \dots H$
 $p_{j,k}^{(1)}$ = the processing time of part k job j in machine M_{1k} at the machining stage
 $p_j^{(2)}$ = the processing time of assembly operation of job j on machine M_2 at the assembly stage
 $p_{j,h}^{(3)}$ = the processing time of job j type h in machine M_{3h} at the differentiation stage. $p_{j,h}^{(3)} > 0$ if $j \in N_h$; 0, otherwise.
 $A_{j,h}$ = the binary variable equals 1 if job j is assigned in machine h with the processing time $p_{j,h}^{(3)} > 0$; otherwise 0
 Decision variables
 $X_{j[i]}$ = the binary variable equals 1 if job j is assigned to position i ; otherwise 0
 $Y_{[i],h}$ = the binary variable for the differentiation stage equals 1 if job in position i is processed in machine h ; otherwise 0;
 $B_{[i],k}^{(1)}$ = the starting time of job in position i in machine M_{1k} at the machining stage
 $B_{[i]}^{(2)}$ = the starting time of assembly job in position i in machine M_2 at the assembly stage
 $B_{[i],h}^{(3)}$ = the starting time of job in position i in machine M_{3h} at the differentiation stage
 Objective function
 $TAFT$ = total actual flow time

The problem can be formulated as follows.

$$\text{Min } TAFT = \sum_{i=1}^n \left((X_{j[i]} * d_j) - \min_{k \leq K} (B_{[i],k}^{(1)}) \right) \quad (4)$$

Subject to:

$$B_{[i],h}^{(3)} = Y_{[i],h} \left(X_{j[i]} (d_j - p_{j,h}^{(3)}) - G_{[z],h} \left((d_j * X_{j[z]}) - B_{[z],h}^{(3)} \right) \right), \quad z \leq i, \forall i, \forall h \quad (5)$$

$$B_{[i]}^{(2)} + \sum_{j=1}^n (X_{j[i]} \cdot p_j^{(2)}) \leq d_j - (Y_{[i],h} * \sum_{j=1}^n \sum_{i^*=1}^i (X_{j[z]} \cdot p_{j,h}^{(3)})), \quad z \leq i, \forall i, \forall h \quad (6)$$

$$B_{[i+1]}^{(2)} \leq B_{[i]}^{(2)} - \sum_{j=1}^n (X_{j[i+1]} \cdot p_j^{(2)}), \quad i < n, \forall i \quad (7)$$

$$B_{[i],k}^{(1)} + \sum_{j=1}^n (X_{j[i]} \cdot p_{j,k}^{(1)}) \leq B_{[i]}^{(2)} \quad \forall i, \forall k \quad (8)$$

$$B_{[i+1],k}^{(1)} \leq B_{[i],k}^{(1)} - \sum_{j=1}^n (X_{j[i+1]} \cdot p_{j,k}^{(1)}), \quad i < n, \forall i, \forall k \quad (9)$$

$$A_{j,h} = \begin{cases} 1, & \text{if } p_{j,h}^{(3)} > 0 \\ 0, & \text{if } p_{j,h}^{(3)} = 0 \end{cases} \quad j = 1, 2 \dots n, \forall h \quad (10)$$

$$\sum_{j=1}^n (X_{j[i]} \cdot A_{j,h}) = Y_{[i],h} \quad \forall i, \forall h \quad (11)$$

$$\sum_{j=1}^n X_{j[i]} = 1, \quad i = 1, 2 \dots n \quad (12)$$

$$\sum_{i=1}^n X_{j[i]} = 1, \quad j = 1, 2 \dots n \quad (13)$$

$$G_{[z],h} = \begin{cases} 1, & \text{if } B_{[z],h}^{(3)} < (d_j * Y_{[z],h} * X_{j[z]}) \\ 0, & \text{if } B_{[z],h}^{(3)} \geq (d_j * Y_{[z],h} * X_{j[z]}) \end{cases} \quad z < i, j = 1, 2 \dots n, \forall h \quad (14)$$

$$X_{j[i]} \in \{0,1\} \quad (15)$$

$$G_{[z],h} \in \{0,1\} \quad (16)$$

$$B_{[i],k}^{(1)}, B_{[i]}^{(2)}, B_{[i],h}^{(3)} \geq 0, \text{ and integer} \quad (17)$$

The objective function (4) shows the total actual flow time that is calculated from the actual flow time of all position where the actual flow time of each position is the longest interval between the part being processed in the first stage until its common due date. Constraint (5) defines the starting time of job in position i in machine h at the third stage from the due date of the job considering the decision that position i is assigned in machine h and there is no starting time of other job before the due date d_j . Constraint (6) defines the starting time of job in position i at the second stage from backward based on job in position i at the third stage, with condition where $i^* \leq i$. Constraint (7) and (9) ensure that each position can only be processed at the same stage after the next position is finished. Constraint (8) defines the starting time of job in position i on machine k at the first stage based on the starting time of the same job in position i at the second stage. Constraint (10) defines the job with the processing time at the third stage greater than zero, is processed in machine h at the third stage. Constraint (11) decides the job in position i that is assigned on machine h at the third stage only if the value is 1. Constraint (12) and (13) ensure that each position in the sequence of job is assigned to only one job, and each job is assigned only to one position in the sequence of job. Constraint (14) defines that there is no other job of position z processed until the due date. Constraint (15) and (16) define the domain of the decision variables. Constraint (17) ensures that the starting time is feasible from time zero.

2.3. Algorithm

We develop a solution using SPT based heuristic and optimized by Variable Neighbourhood Descent (VND) methods. The multi-due-date has condition where the jobs must be scheduled to meet their due dates. Figure 3 show that there are several due dates and between two consecutive due dates the jobs must be processed. The proposed algorithm divided the jobs according to the interval they belong.

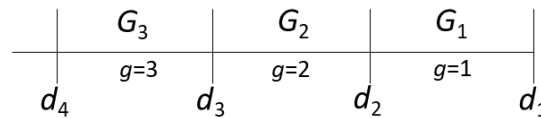


Figure 3. Interval of two consecutive due dates

SPT-based heuristic generates the job sequences based on the processing time of the three stages in increasing orders. The jobs are scheduled from their corresponding due dates and the value of TAFT is defined. The best initial solution from SPT-based heuristic is optimized using VND method. VND with the insert move determined the job sequence that minimizes the total actual flow time. In VND-insert move, a job is moved to a position so that the current positions are shifted one position forward along the solution [8]. The stopping rule is the condition where the iterations give no new minimum total actual flow time after a set of iterations.

The proposed algorithm

Step 0: Initialize the problem

Step 1: Sequence the due dates in increasing order, the greatest due dates will be $g=1$.

Step 2: Determine G_g as the interval between two consecutive due dates using:

$$G_g = \begin{cases} d_g - d_{g+1}; & g = 1, \dots, r-1 \\ d_r; & g = r \end{cases}$$

Step 3: Set $g=1$

Step 4: Generate the job sequences in increasing orders for all jobs in interval G_g based on the SPT-based heuristic for $\max_{1 \leq k \leq 3} (p_{j,k}^{(1)}), p_j^{(2)}, p_{j,h}^{(3)}$, $\max_{1 \leq k \leq 3} (p_{j,k}^{(1)}) + p_j^{(2)}, p_j^{(2)} + p_{j,h}^{(3)}$ and $\max_{1 \leq k \leq 3} (p_{j,k}^{(1)}) + p_j^{(2)} + p_{j,h}^{(3)}$, respectively. Schedule the jobs from their corresponding due dates.

Step 5: Set the best total actual flow time as the best initial solution.

Step 6: Perform procedure Variable Neighbourhood Descent (insert move) as follows.

- For all the jobs, $i=1,2,\dots,J$, in vn_{seq} , repeat
- Set i^{th} job in vn_{seq} sequence as J_{vn}^i
- Insert J_{vn}^i in all possible positions in vn_{seq} to get $N^l(x)$, a subset of $N(x)$.
- Find $TAFT$ of all sequences in $N^l(x)$
- Set sequence with minimum $TAFT$ in vn_{seq} .
- Output the final sequence vn_{best} .

Step 6: Is the solution better than the best initial solution?

If Yes, output the best solution

If No, then stop.

3. Result and Discussion

Consider an illustration of eight jobs ($J=8$) to analyse the model. There are two product types (Type 1 and Type 2). Table 1 shows the data that Type 1 consists of jobs J_1, J_2, J_3 and J_4 , written as $JH_1=\{J_1, J_2, J_3, J_4\}$ and type 2 consists of jobs J_5, J_6, J_7 and J_8 written as $JH_2=\{J_5, J_6, J_7, J_8\}$. The number of machine in the machining stage (K)=3, and the number of machine in the differentiation stage (H)=2. This illustration is run using the processor of Intel Core i7-6500U CPU, 2,50 GHz and 12 GB RAM.

Table 1. Processing time and due date of jobs

Job	Type	$p_{j,1}^{(1)}$	$p_{j,2}^{(1)}$	$p_{j,3}^{(1)}$	$p_j^{(2)}$	$p_{j,1}^{(3)}$	$p_{j,2}^{(3)}$	d_j
J_1	1	5	4	3	3	6	0	990
J_2	1	6	3	4	9	10	0	990
J_3	1	6	4	10	3	9	0	980
J_4	1	3	5	5	4	5	0	1000
J_5	2	3	4	5	6	0	8	980
J_6	2	3	4	6	4	0	7	990
J_7	2	10	4	6	5	0	6	980
J_8	2	5	4	3	10	0	4	1000

We can divide the due dates into three sections ($g=3$) and the jobs are put from their corresponding due dates backwardly. Table 2 shows the initial solution using SPT-based heuristic. There are two sequences with the best TAFT, $J_4-J_8-J_1-J_6-J_2-J_5-J_3-J_7$ and $J_4-J_8-J_1-J_6-J_2-J_5-J_7-J_3$.

Table 2. SPT-based heuristic for multi-due-date

$\max_{k \leq K}(p_{j,k}^{(1)})$	J_8 5	J_4 5	J_1 5	J_2 6	J_6 6	J_5 5	J_3 10	J_7 10	TAFT 241
$p_{j,2}^{(1)}$	J_4 4	J_8 10	J_1 3	J_6 4	J_2 9	J_3 3	J_7 5	J_5 6	216
$p_{j,h}^{(3)}$	J_8 4	J_4 5	J_1 6	J_1 7	J_2 10	J_7 6	J_5 8	J_3 9	218
$\max_{k \leq K}(p_{j,k}^{(1)}) + p_{j,2}^{(1)}$	J_4 9	J_8 15	J_1 8	J_6 10	J_2 15	J_5 11	J_3 13	J_7 15	214
$p_{j,2}^{(1)} + p_{j,h}^{(3)}$	J_4 9	J_8 14	J_1 9	J_6 11	J_2 19	J_7 11	J_3 12	J_5 14	219
$\max_{k \leq K}(p_{j,k}^{(1)}) + p_{j,2}^{(1)} + p_{j,h}^{(3)}$	J_4 14	J_8 19	J_1 14	J_6 17	J_2 25	J_5 19	J_7 21	J_3 22	214

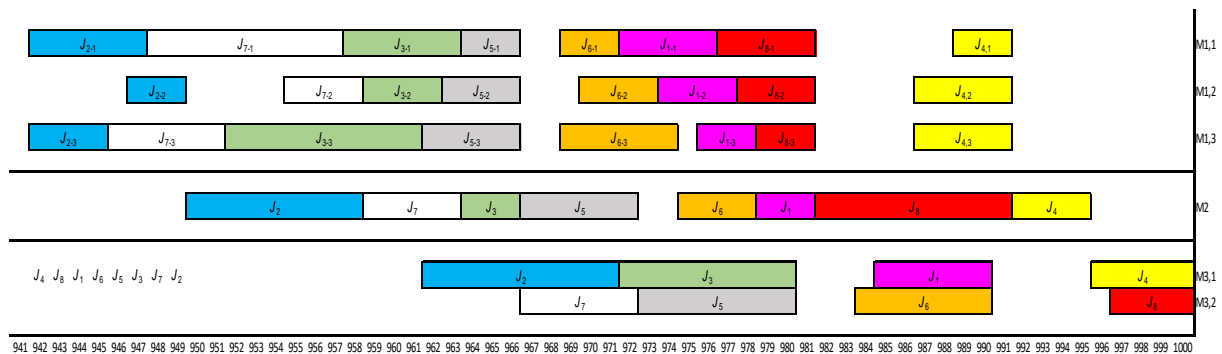
The proposed algorithm optimized the initial solution using variable neighbourhood descent with the insert moves that can be seen in Table 3. From the two best initial solution, we select the first sequence $J_4-J_8-J_1-J_6-J_2-J_5-J_3-J_7$. The iteration of Variable Neighbourhood Descent started with the first job of J_4 to be inserted into vn_{seq} (sequence 1 until sequence 7) with different positions. The $TAFT$ of

each sequences are defined. In iteration 1, there are no improvement for the vm_{best} . The iteration continued with the next job from the sequence selected. In iteration 5 and 8, we get the new vm_{best} for the same TAFT value of 211. Those sequences are J_4 - J_8 - J_1 - J_6 - J_5 - J_3 - J_7 - J_2 and J_4 - J_8 - J_1 - J_6 - J_7 - J_2 - J_5 - J_3 . We can see that J_2 with the longest processing time in both assembly and differentiation stages is scheduled at the third section (the respective due date). It is because the interval between the second and the third due date are smaller than the total three job's processing time (J_1 , J_2 , J_6). Figure 4 is the Gantt chart for the best sequence after the optimization. Figure 4 also shows the cluster of jobs according to the interval between two due dates and the position of J_2 .

Table 3. Variable Neighbourhood Descent-insert moves

Iteration 1 (J_4)										Iteration 2 (J_8)									
vm_{best}	J4	J8	J1	J6	J2	J5	J3	J7	214	vm_{best}	J4	J8	J1	J6	J2	J5	J3	J7	214
1	J8	J4	J1	J6	J2	J5	J3	J7	216	1	J8	J4	J1	J6	J2	J5	J3	J7	216
2	J8	J1	J4	J6	J2	J5	J3	J7	244	2	J4	J1	J8	J6	J2	J5	J3	J7	254
3	J8	J1	J6	J4	J2	J5	J3	J7	241	3	J4	J1	J6	J8	J2	J5	J3	J7	248
4	J8	J1	J6	J2	J4	J5	J3	J7	243	4	J4	J1	J6	J2	J8	J5	J3	J7	262
5	J8	J1	J6	J2	J5	J4	J3	J7	248	5	J4	J1	J6	J2	J5	J8	J3	J7	256
6	J8	J1	J6	J2	J5	J3	J4	J7	253	6	J4	J1	J6	J2	J5	J3	J8	J7	248
7	J8	J1	J6	J2	J5	J3	J7	J4	254	7	J4	J1	J6	J2	J5	J3	J7	J8	247
Iteration 3 (J_1)										Iteration 4 (J_6)									
vm_{best}	J4	J8	J1	J6	J2	J5	J3	J7	214	vm_{best}	J4	J8	J1	J6	J2	J5	J3	J7	214
1	J1	J4	J8	J6	J2	J5	J3	J7	306	1	J6	J4	J8	J1	J2	J5	J3	J7	307
2	J4	J1	J8	J6	J2	J5	J3	J7	254	2	J4	J6	J8	J1	J2	J5	J3	J7	265
3	J4	J8	J6	J1	J2	J5	J3	J7	214	3	J4	J8	J1	J6	J2	J5	J3	J7	214
4	J4	J8	J6	J2	J1	J5	J3	J7	237	4	J4	J8	J1	J2	J6	J5	J3	J7	239
5	J4	J8	J6	J2	J5	J1	J3	J7	222	5	J4	J8	J1	J2	J5	J6	J3	J7	246
6	J4	J8	J6	J2	J5	J3	J1	J7	229	6	J4	J8	J1	J2	J5	J3	J6	J7	250
7	J4	J8	J6	J2	J5	J3	J7	J1	232	7	J4	J8	J1	J2	J5	J3	J7	J6	250
Iteration 5 (J_2)										Iteration 6 (J_5)									
vm_{best}	J4	J8	J1	J6	J2	J5	J3	J7	214	vm_{best}	J4	J8	J1	J6	J5	J3	J7	J2	211
1	J2	J4	J8	J1	J6	J5	J3	J7	349	1	J5	J4	J8	J1	J6	J2	J3	J7	399
2	J4	J2	J8	J1	J6	J5	J3	J7	301	2	J4	J5	J8	J1	J6	J2	J3	J7	229
3	J4	J8	J2	J1	J6	J5	J3	J7	233	3	J4	J8	J5	J1	J6	J2	J3	J7	269
4	J4	J8	J1	J2	J6	J5	J3	J7	239	4	J4	J8	J1	J5	J6	J2	J3	J7	247
5	J4	J8	J1	J6	J5	J2	J3	J7	219	5	J4	J8	J1	J6	J2	J5	J3	J7	214
6	J4	J8	J1	J6	J5	J3	J2	J7	215	6	J4	J8	J1	J6	J2	J3	J5	J7	213
7	J4	J8	J1	J6	J5	J3	J7	J2	211	7	J4	J8	J1	J6	J2	J3	J7	J5	230
Iteration 7 (J_3)										Iteration 8 (J_7)									
vm_{best}	J4	J8	J1	J6	J5	J3	J7	J2	211	vm_{best}	J4	J8	J1	J6	J5	J3	J7	J2	211
1	J3	J4	J8	J1	J6	J2	J5	J7	401	1	J7	J4	J8	J1	J6	J2	J5	J3	379
2	J4	J3	J8	J1	J6	J2	J5	J7	273	2	J4	J7	J8	J1	J6	J2	J5	J3	325
3	J4	J8	J3	J1	J6	J2	J5	J7	231	3	J4	J8	J7	J1	J6	J2	J5	J3	265
4	J4	J8	J1	J3	J6	J2	J5	J7	249	4	J4	J8	J1	J7	J6	J2	J5	J3	238
5	J4	J8	J1	J6	J3	J2	J5	J7	233	5	J4	J8	J1	J6	J7	J2	J5	J3	211
6	J4	J8	J1	J6	J2	J3	J5	J7	213	6	J4	J8	J1	J6	J2	J7	J5	J3	216
7	J4	J8	J1	J6	J2	J5	J7	J3	230	7	J4	J8	J1	J6	J2	J5	J7	J3	230

The optimal model has run for five hours using a programming software, but the result is still local optimal with the best TAFT=346. The performance from this illustrative example is 14.31%. For this illustration, the result is better than the optimal model. Though it still need more illustrative data to make the best conclusion.

Figure 4. Gantt Chart for $TAFT=211$

4. Conclusions

This paper deals with job scheduling problems for hybrid assembly differentiation flow shop to minimize total actual flow time with the condition of multi-due-date. The results of this paper are job scheduling model for multi-due-date condition and the proposed algorithm consists of SPT based heuristic for initial solution and variable neighbourhood descend method for optimization. The illustration is only for eight jobs and there must be more experiments to have a better conclusion. The proposed algorithm can give the better solution and shows the improvement from the initial solution. The future research is to find the proposed algorithm that can give optimal solution in short time compare to the current approach.

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