

# Detecting Galactic MACHOs with VERA through Astrometric Microlensing of Distant Radio Sources

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## Abstract

We consider the properties of astrometric microlensing of distant radio sources (QSOs and radio galaxies) due to MACHOs, and discuss their implications for VERA (VLBI Exploration of Radio Astrometry). First, we show that in the case of astrometric microlensing of distant sources, the event duration is only a function of the lens mass and tangential velocity, but independent of the lens distance, in contrast to the well-known three-fold degeneracy for photometric microlensing. Moreover, the lens mass,  $M$ , is scaled by the tangential velocity,  $v_{\perp}$ , as  $M \propto v_{\perp}$ , rather than  $M \propto v_{\perp}^2$ , which is the case for photometric microlensing. Thus, in astrometric microlensing the dependence of the lens mass on the unknown parameter,  $v_{\perp}$ , is weaker, indicating that the duration of an astrometric microlensing event is a better quantity to study the mass of lensing objects than that of photometric microlensing. We also calculate the optical depth and event rate, and show that within  $20^\circ$  of the galactic center a typical event rate for a  $10 \mu\text{as}$ -level shift is larger than  $2.5 \times 10^{-4}$  event per year, assuming that a quarter of the halo is made up of MACHOs. This indicates that if one monitors a few hundred sources for  $\sim 20$  years, such an astrometric microlensing event is detectable. Since a typical event duration has been found to be fairly long (5 to 15 years), the frequency of the monitoring observation can be relatively low, i.e., once per six months, which is rather reasonable for practical observations. We discuss a practical strategy for observing astrometric microlensing with VERA, and argue that an astrometric microlensing event due to MACHOs can be detected by VERA within a few decades.

**Key words:** astrometry — Galaxy: halo — gravitational microlensing — radio continuum: galaxies — VERA

## 1. Introduction

Gravitational microlensing is one of the most powerful tools to trace Massive Astrophysical Compact Halo Objects (MACHOs) in the Galaxy's halo. After the first proposal by Paczyński (1986), a number of extensive searches for gravitational microlensing have been performed toward the Magellanic Clouds and the galactic bulge. In such studies, more than a million of stars are being monitored frequently, typically once per night, to look for any brightness variation caused by gravitational microlensing. To date, searches for such 'photometric microlensing' events have detected more than a dozen of events toward the Magellanic Clouds (e.g., Alcock et al. 1993, 1997, 2000; Aubourg et al. 1993). Based on a statistical study of the detected events, MACHO collaboration (Alcock et al. 1997, 2000) has obtained a lens mass of  $0.5 M_{\odot}$ , and has suggested that the MACHOs in the galactic halo may be old white dwarfs. However, the lens mass is strongly dependent on the halo model, and a more or less massive lens is also consistent with the observations, depending on the halo model of the Galaxy (e.g., Honma, Kan-ya 1998). Moreover, the uncertainty in the lens distance allows different interpretations of observed microlensing events other than MACHOs. In fact, there are several arguments that the lensing objects may be stars in a warped disk (e.g., Evans et al. 1998), stars in previously unknown intervening objects (e.g., Zaritsky, Lin 1997; Zhao 1998), or stars in the Magellanic Clouds, themselves (e.g., Sahu 1994). Thus, the

nature of MACHOs remains unclear.

In order to reveal the nature of MACHOs, some additional information other than what comes from photometric lensing is highly important. One potential way to extract additional information for microlensing events is to measure a positional shift due to microlensing. Several investigations have been made to study the implications of such an astrometric observation of microlensing events, demonstrating that such a positional shift can be detected by upcoming space satellite missions, and also that from astrometric observations one can determine the lens parameters, such as the lens distance and lens mass (e.g., Høg et al. 1995; Miyamoto, Yoshii 1995; Walker 1995). These astrometric observations are to be performed after event detection based on photometric monitoring, and in this sense, supplementary to photometric microlensing event.

On the other hand, it is also known that astrometric observations alone can be used to study the nature of lensing objects. For instance, it has been argued that an astrometric effect of gravitational microlensing can be used to measure the mass of nearby stars (e.g., Hosokawa et al. 1993; Paczyński 1996, 1998; Miralda-Escude 1996). Recently, the fluctuation of the radio reference frame by microlensing due to disk stars and MACHOs in the Galaxy has been studied by Hosokawa et al. (1997), and possibility to observe astrometric microlensing events with a ground-based or space optical-interferometer have been discussed by Miralda-Escude (1996), Boden et al. (1998), Paczyński (1998), and Dominik and Sahu (2000). These studies have revealed that astrometric microlens-

ing events are practically detectable and useful for studying the nature of lensing objects, if we obtain a position accuracy at the  $10 \mu\text{as}$  level. Thus, astrometric microlensing will soon become one of major tools to study lensing objects.

Following recent studies on astrometric microlensing, in this paper we consider the astrometric microlensing of distant sources (QSOs and radio sources) due to MACHOs, while focusing on a possible application to the VERA project (VLBI Exploration of Radio Astrometry). The VERA project (see for detail Sasao 1996; Kawaguchi et al. 2000; Honma et al. 2000), which aims at radio astrometry at the  $10 \mu\text{as}$  level, was approved in 2000, and is anticipated to start observations by 2003. Although distant radio sources, like QSOs and radio galaxies, which are one of the major observational objects of VERA, are potential targets for tracing astrometric microlensing with VERA, few studies have been made concerning the astrometric microlensing of distant radio sources after the pioneering work by Hosokawa et al. (1997). For these reasons, we consider the astrometric microlensing of distant radio sources and discuss the implications for VERA.

The plan of this paper is as follows: in section 2, we briefly review astrometric microlensing, in particular parameters that can be extracted from the image trajectory. In section 3 we investigate the event duration of astrometric microlensing. In sections 4 and 5, we calculate the optical depth and event rate, and show that one can detect astrometric microlensing based on monitoring a few hundred sources for 10 to 20 years. Finally, in section 6 we discuss the implication of astrometric microlensing for VERA, and present a practical strategy for detecting astrometric microlensing.

## 2. Brief Review on Astrometric Microlensing

### 2.1. Astrometric Microlensing Event

In this chapter we briefly review the characteristics of astrometric microlensing. When a source is closely aligned with a lens, the gravitational deflection of light produces two images, whose positions are given by (e.g., Paczyński 1986)

$$r_{1,2} = \frac{u \pm \sqrt{u^2 + 4}}{2}. \quad (1)$$

Here,  $r_{1,2}$  is the separation between the lens and the two images in the lens plane, and  $u$  is the separation between the source and the lens in the lens plane. Note that both  $r_{1,2}$  and  $u$  are normalized with the Einstein ring radius,  $R_E$ ; for instance, the lens–source separation,  $u$ , can be written as

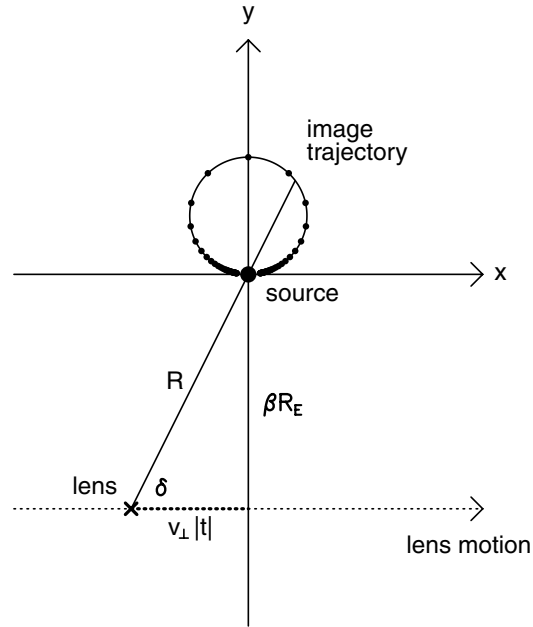
$$u = \frac{R}{R_E}, \quad (2)$$

where  $R$  is the lens–source distance projected onto the lens plane. As widely known, the Einstein radius,  $R_E$ , is given by (e.g., Paczyński 1986)

$$R_E = \sqrt{\frac{4GM}{c^2} \frac{D_d D_{ds}}{D_s}}. \quad (3)$$

Here,  $M$  is the lens mass, and  $D_d$ ,  $D_s$ , and  $D_{ds}$ , are the lens distance, source distance, and lens–source distance, respectively.

Here, we introduce a coordinate system on the lens plane where the source is at the origin and the lens is moving parallel



**Fig. 1.** Schematic view of the location of a lens, source, and lensed image in the lens plane. The trajectory of an image is a circle in the case of the lens–source separation  $u \gg 1$ . The dots along the trajectory circle show the image position with a constant time interval,  $0.4 t_q$ .

to the  $x$ -axis (figure 1). The origin of time  $t = 0$  is set at the time of the closest approach between the lens and the source. In such a coordinate system, the lens position is described as  $(v_{\perp} t, -\beta R_E)$ , where  $v_{\perp}$  is the tangential velocity of the lens, and  $\beta$  is the impact parameter normalized with  $R_E$  (note that  $\beta$  is always positive). With the parameters described above, the lens–source distance,  $R$ , can be written as

$$R = \sqrt{(v_{\perp} t)^2 + (\beta R_E)^2}. \quad (4)$$

Here, we calculate the positional shift of sources due to gravitational microlensing. Generally, two images produced by gravitational microlensing cannot be resolved, but the centroid of two images can be observed to trace the astrometric effect in microlensing. If the lens is far from the source in the lens plane (i.e.,  $u \gg 1$ ), the secondary image becomes too faint, and the image centroid coincides with that of the primary image. Since most astrometric microlensing events with a  $10 \mu\text{as}$ -level positional shift have  $u \gg 1$  (as we will see in next sections), in the present paper we concentrate on the case  $u \gg 1$ , and approximate the image centroid motion by that of the primary image (for more general treatment, see Boden et al. 1998; Dominik, Sahu 2000).

In case that  $u \gg 1$ , the position of primary image [equation (1)] is well approximated by

$$r = u + \frac{1}{u}. \quad (5)$$

The first term,  $u$ , corresponds to the lens–source separation in the lens plane, and the second term,  $1/u$ , describes the image shift due to gravitational microlensing. Hence, the angular positional shift of the image relative to the original source position is obtained as

$$\theta_s = \frac{1}{u} \theta_E. \quad (6)$$

Here,  $\theta_E$  is the angular Einstein radius, which is related to the Einstein ring radius,  $R_E$ , as

$$\theta_E = \frac{R_E}{D_d}. \quad (7)$$

The angular position of the image in the lens plane can be described as

$$(\theta_x, \theta_y) = (\theta_s \cos \delta, \theta_s \sin \delta), \quad (8)$$

where the angle  $\delta$  is defined as (see figure 1)

$$\tan \delta = -\frac{\beta R_E}{v_\perp t}. \quad (9)$$

Using the equations described above, one may rewrite the image position as

$$(\theta_x, \theta_y) = \left[ \frac{-(\theta_E/\beta)(t/\beta t_E)}{(t/\beta t_E)^2 + 1}, \frac{\theta_E/\beta}{(t/\beta t_E)^2 + 1} \right], \quad (10)$$

where we have introduced the Einstein ring crossing time,  $t_E$ , which is defined as

$$t_E \equiv \frac{R_E}{v_\perp}. \quad (11)$$

After a simple calculation, one may easily find the following relation between  $\theta_x$  and  $\theta_y$ :

$$\theta_x^2 + \left( \theta_y - \frac{\theta_E}{2\beta} \right)^2 = \left( \frac{\theta_E}{2\beta} \right)^2. \quad (12)$$

Hence, the trajectory of the image is a circle centered on  $(0, \theta_E/2\beta)$  with a diameter of  $\theta_E/\beta$  (Boden et al. 1998; Dominik, Sahu 2000). We hereafter refer to this image trajectory as a ‘trajectory circle’. In figure 1, we show a schematic view of the image motion along the trajectory circle. The time intervals between adjacent dots are equal to  $0.4 \times (\beta t_E)$ . As can be seen in figure 1, the image motion is faster in the upper half of the trajectory circle than in the lower half, and vanishes toward the origin where the source should be located in case of no microlensing. The largest image shift parallel to the  $x$ -axis occurs when  $t = \pm t_q = \pm \beta t_E$ , i.e.,  $R = \sqrt{2} \beta R_E$ . Note that an image goes through an upper quarter of the trajectory circle within a time interval of  $t_q$ . Thus,  $t_q$  gives a characteristic time-scale of an astrometric microlensing event. Note that from an observation of the trajectory circle one can obtain  $t_q (= \beta t_E)$  and  $\theta_E/\beta$ .

## 2.2. Angular Size of Astrometric Lens

Here, we estimate the angular size of astrometric lenses. Since we mainly consider the implications of astrometric microlensing for VERA, in the following analysis we assume that the sources are radio galaxies and QSOs which are much more distant (at least a few Mpc) than the lens (typically  $\sim 10$  kpc). In such a case, the source distance,  $D_s$ , and the lens–source distance,  $D_{ds}$ , are much greater than the lens distance,  $D_d$ , and the Einstein ring radius [equation (3)] is well approximated as

$$R_E = \sqrt{\frac{4GM}{c^2}} D_d. \quad (13)$$

Similarly, the angular Einstein ring radius,  $\theta_E$ , may be approximated as

$$\theta_E = \sqrt{\frac{4GM}{c^2 D_d}}. \quad (14)$$

If one substitutes typical parameters of MACHOs (e.g., Alcock et al. 1997, 2000), the angular Einstein ring can be estimated as

$$\theta_E = 0.72 \times \left( \frac{M}{0.5 M_\odot} \right)^{1/2} \left( \frac{D_d}{8 \text{ kpc}} \right)^{-1/2} \text{ mas}. \quad (15)$$

Since the angular diameter of lens trajectory is given by  $\theta_E/\beta$ , the maximum value of  $\beta$  for a detectable event is given by

$$\beta_{\max} = \theta_E/\theta_{\min}, \quad (16)$$

where  $\theta_{\min}$  is the minimum position shift that can be measured. The astrometric projects planned to start within a decade (e.g., SIM, GAIA, VERA) aim at a position accuracy of  $10 \mu\text{as}$  or higher. Since we consider the observation of astrometric microlensing with those projects (in particular VERA), we set  $\theta_{\min} = 10 \mu\text{as}$ . Thus, the maximum value of  $\beta$  ( $\beta_{\max}$ ) is given as

$$\beta_{\max} = 72 \times \left( \frac{M}{0.5 M_\odot} \right)^{1/2} \left( \frac{D_d}{8 \text{ kpc}} \right)^{-1/2} \left( \frac{\theta_{\min}}{10 \mu\text{as}} \right)^{-1}. \quad (17)$$

This indicates that the astrometric microlensing is detectable even when the minimum lens–source separation is larger than the Einstein ring radius by several tens. This makes the probability of astrometric microlensing much higher than the normal microlensing.

## 3. Event Duration

### 3.1. Basic Equations

In this section, we investigate the event duration of astrometric microlensing. Usually, the duration of a microlensing event is defined as the time during which the source is inside the lens. For photometric microlensing, the lens size is equal to the Einstein ring radius,  $R_E$ , and the event duration,  $t_{\text{ph}}$ , is given as the time for which  $R \leq R_E$ . Similarly, the lens size of an astrometric microlensing event is given by  $\beta_{\max} R_E$ , and the duration of an astrometric microlensing event is defined as the time for which  $R \leq \beta_{\max} R_E$  (in other words, the time during which the image position shift is larger than the accuracy of a position measurement,  $\theta_{\min}$ ). Thus, the event duration,  $t_{\text{ast}}$ , can be written as

$$t_{\text{ast}} = \frac{2\beta_{\max} R_E}{v_\perp} \cos \phi. \quad (18)$$

See figure 2 for a schematic view of the lens–source geometry and a definition of the angle  $\phi$ . The average event duration can be obtained by integrating  $t_{\text{ast}}$  over the possible range of  $\phi$ . Since the probability of an event with a certain value of  $\phi$  is proportional to  $\cos \phi$ , the average event duration can be given as

$$\bar{t}_{\text{ast}} = \frac{\int t_{\text{ast}} \cos \phi d\phi}{\int \cos \phi d\phi}. \quad (19)$$

Substituting equation (18) into equation (19) and integrating with respect to  $\phi$ , one obtains

$$\bar{t}_{\text{ast}} = \frac{\pi}{2} \left( \frac{\beta_{\text{max}} R_E}{v_{\perp}} \right). \quad (20)$$

Substituting the expressions of  $R_E$  and  $\beta_{\text{max}}$  [equations (13), (14), and (16)], one obtains

$$\bar{t}_{\text{ast}} = \frac{2\pi GM}{c^2 v_{\perp} \theta_{\text{min}}}. \quad (21)$$

Interestingly, the average duration,  $\bar{t}_{\text{ast}}$ , contains only two unknown parameters, the lens mass,  $M$ , and its tangential velocity,  $v_{\perp}$ , but independent of the lens distance,  $D_d$ . Hence, the degree of degeneracy in the event duration is lower than that in the case of photometric microlensing, where the event duration depends on three parameter:  $v_{\perp}$ ,  $D_d$ , and  $M$ . (Note that this independence of the lens distance comes from the assumption of distant source; if this assumption is invalid, the event duration,  $\bar{t}_{\text{ast}}$ , depends also on the lens distance  $D_d$ .) Moreover, the average event duration,  $\bar{t}_{\text{ast}}$ , is proportional to the lens mass,  $M$ , and inversely proportional to the tangential velocity,  $v_{\perp}$ . Thus, once the average event duration is observed, the mass is scaled as  $M \propto v_{\perp} \bar{t}_{\text{ast}}$ . This dependence contrasts to that of photometric microlensing, where the event duration,  $\bar{t}_{\text{ph}}$ , is proportional to  $M^{1/2} v_{\perp}^{-1}$  (e.g., Paczyński 1986). Hence, for photometric microlensing events, the lens mass,  $M$ , is scaled as  $M \propto (v_{\perp} \bar{t}_{\text{ph}})^2$ , depending more strongly on the unknown parameter,  $v_{\perp}$ , than in the case of astrometric microlensing. This indicates that the event duration of astrometric microlensing is a better quantity to investigate the mass and the nature of MACHOs rather than that of photometric microlensing.

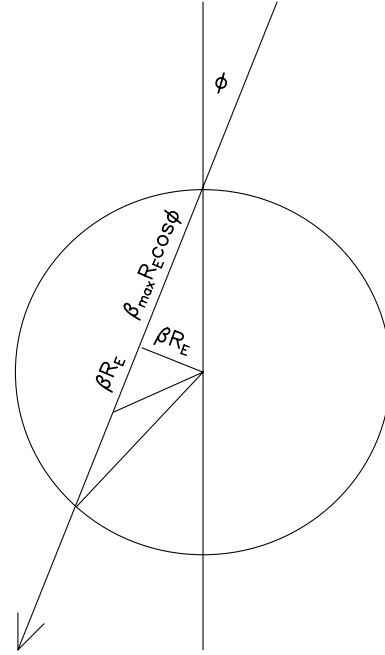
### 3.2. Halo Microlensing

Here we estimate a typical value of the event duration for the halo MACHO case based on the same parameters as those used in the previous sections. Substituting  $M = 0.5 M_{\odot}$ ,  $v_{\perp} = 200 \text{ km s}^{-1}$ , and  $\theta_{\text{min}} = 10 \mu\text{as}$ , the event duration is obtained as

$$\bar{t}_{\text{ast}} = 15.3 \times \left( \frac{M}{0.5 M_{\odot}} \right) \left( \frac{v_{\perp}}{200 \text{ km s}^{-1}} \right)^{-1} \times \left( \frac{\theta_{\text{min}}}{10 \mu\text{as}} \right)^{-1} \text{ yr}. \quad (22)$$

As can be seen in above equation, the event duration of an astrometric microlensing event is significantly longer than that of a photometric microlensing event. This is due to the large  $\beta_{\text{max}}$  for astrometric microlensing, typically  $\sim 70$ , while  $\beta_{\text{max}}$  is unity for photometric microlensing. In fact, if one takes a typical value of  $t_E = 40 \text{ d}$  from LMC microlensing (e.g., Alcock et al. 1997, 2000), a rough estimate gives  $t_{\text{ast}} \sim 2\beta_{\text{max}} t_E = 15 \text{ yr}$ .

An event duration of  $\sim 15 \text{ yr}$  may seem to be too long for practical monitoring observations. This is because the event duration,  $t_{\text{ast}}$ , is the time during which the image shift is larger than  $\theta_{\text{min}}$ . On the other hand, we have already shown in figure 1 that the image trajectory is a circle, and that the image motion is faster in the upper half of the trajectory circle than in the lower half. As shown in previous section, tracing a quarter of the trajectory circle is sufficient to extract physical parameters for astrometric microlensing, such as  $t_q (= \beta t_E)$  and  $\theta_E/\beta$ . Thus, it is practically necessary to trace the image motion for the time interval  $t_q$ , which was defined in section 2 as the time



**Fig. 2.** Schematic view of the motion of source relative to a lens. The large circle gives the lens size, which is equal to  $\beta_{\text{max}} R_E$ .

during which the image passes the upper quarter of the trajectory circle. This duration,  $t_q$ , is given by (see figure 2)

$$t_q = \beta t_E = \frac{\beta_{\text{max}} R_E}{v_{\perp}} |\sin \phi|. \quad (23)$$

Similarly to  $\bar{t}_{\text{ast}}$  [equation (19)], by integrating with respect to  $\phi$  we can obtain the average of  $t_q$  as

$$\bar{t}_q = \frac{1}{2} \frac{\beta_{\text{max}} R_E}{v_{\perp}}. \quad (24)$$

Comparing equations (20) and (24), one finds that  $\bar{t}_q = \bar{t}_{\text{ast}}/\pi$ , and thus a typical value of  $\bar{t}_q$  is  $\sim 5 \text{ yr}$ . This means that one can obtain physical parameters of astrometric microlensing, such as  $\beta t_E (= t_q)$  and  $\theta_E/\beta$ , based on  $\sim 5 \text{ yr}$  monitoring of the event, which is rather reasonable for practical observations.

### 3.3. Disk Microlensing

Here, we estimate the event duration for disk star lensing. As a typical mass of disk stars, we take a mass of  $M = 0.3 M_{\odot}$ , corresponding to a lower main-sequence star. Since we mainly consider disk star lensing at relatively high latitude (i.e.,  $b \geq 10^\circ$ ) in which the lens is likely to be a nearby star, we take a tangential velocity of  $20 \text{ km s}^{-1}$ , corresponding to a random velocity of a disk star in the vicinity of the Sun. With these parameters, the event duration for disk star microlensing is obtained as

$$\bar{t}_{\text{ast}} = 92 \left( \frac{M}{0.3 M_{\odot}} \right) \left( \frac{v_{\perp}}{20 \text{ km s}^{-1}} \right)^{-1} \left( \frac{\theta_{\text{min}}}{10 \mu\text{as}} \right)^{-1} \text{ yr}. \quad (25)$$

Thus, the event duration for disk stars is much longer than that for halo MACHOs. This applies to most sky regions, except for the galactic plane, and hence discrimination of disk



lensing from MACHO lensing is easy. However, if one observes sources in the galactic plane, the tangential velocity of the disk star is dominated by the galactic rotation, which is  $\sim 200 \text{ km s}^{-1}$ . This indicates that in the galactic plane the event duration of disk lensing can be quite close to that of MACHO lensing, and hence sources in the middle of the galactic plane are not suitable for studying astrometric microlensing due to MACHOs.

#### 4. Optical Depth

##### 4.1. Basic Equations

Similarly to the optical depth of photometric microlensing (e.g., Paczyński 1986), the optical depth for the astrometric microlensing can be defined as follows (Miralda-Escude 1996):

$$\tau_{\text{ast}} = \int \pi \beta_{\text{max}}^2 R_E^2 \frac{\rho(D_d)}{M} dD_d. \quad (26)$$

Here,  $\rho$  is the density,  $D_d$  the lens distance from the observer, and  $M$  the lens mass. For simplicity we assume here that the lens mass,  $M$ , is unique, as is usually assumed in microlensing studies.

Substituting equations (13), (14), and (16), the optical depth (for distant sources) can be written as

$$\tau_{\text{ast}} = \frac{16\pi G^2 M}{c^4 \theta_{\text{min}}^2} \int \rho dD_d. \quad (27)$$

As is already known (e.g., Miralda-Escude 1996), the optical depth for astrometric microlensing is proportional to the lens mass,  $M$ , in contrast to that for photometric lensing, which is independent of  $M$ . It is also remarkable that the optical depth is simply proportional to the column density,  $\int \rho dD_d$ . This simple dependence on the column density comes from an approximation of distant source in equations (13) and (14). In a more general case, the optical depth is proportional to  $\int \rho(1-x^2) dD_d$ , where  $x \equiv D_d/D_s$  is the fractional distance to the lens normalized by the source distance (Dominik, Sahu 2000).

##### 4.2. Halo Microlensing

In order to calculate the optical depth due to MACHOs in the galactic halo, we introduce here an axisymmetric logarithmic halo model (Binney, Tremaine 1987) to describe the halo density distribution. The density distribution of the axisymmetric logarithmic halo model is given by

$$\rho(R, z) = \frac{v_0^2}{4\pi G q^2} \frac{(2q^2 + 1)R_c^2 + R^2 + (2 - q^{-2})z^2}{(R_c^2 + R^2 + z^2 q^{-2})^2}. \quad (28)$$

Here,  $R$  and  $z$  describe the cylindrical coordinates, and  $v_0$ ,  $R_c$ , and  $q$  are halo parameters which describe the circular rotation velocity, the core radius, and the halo flatness, respectively. In the following analysis, we set  $R_c = 5 \text{ kpc}$  and  $v_0 = 200 \text{ km s}^{-1}$ , which are typical values used in microlensing studies. We also introduce a cut-off radius beyond which the density vanishes. In the present study the cut-off radius is set to be 100 kpc, but note that our result would only be slightly changed by varying the cut-off radius, as we show later. In addition to the halo parameters in equation (28), the mass of

the lens is also necessary for an optical depth calculation, because  $\tau_{\text{ast}}$  depends on the lens mass [equation (27)]. We set the MACHO mass to  $M = 0.5 M_\odot$ , according to a recent result from LMC microlensing (e.g., Alcock et al. 1997, 2000). We also assume that the distance to the galactic center,  $R_0$ , is 8.5 kpc.

The optical depth for astrometric microlensing was calculated for two values of  $q$ ;  $q = 1$  (spherically symmetric halo) and 0.75 (flattened halo). Figure 3 shows the optical-depth variation with galactic longitude,  $l$ . As can be seen in figure 3, the optical depth,  $\tau_{\text{ast}}$ , is quite high toward the galactic center, being  $2\text{--}3 \times 10^{-2}$ . For a comparison, we note that the optical depth for photometric microlensing,  $\tau_{\text{ph}}$ , is  $5.4 \times 10^{-6}$  for  $l = 0^\circ$  and  $b = 0^\circ$  ( $q = 1$  is assumed). This high optical depth for astrometric microlensing can be easily understood from the fact that the typical  $\beta_{\text{max}}$  is more than 70 (see previous section). From the high value of  $\tau_{\text{ast}}$ , one can expect that one of the 30 to 50 distant sources seen around the galactic center is always being lensed, if the halo fully consists of MACHOs. Recent results of LMC microlensing indicate that the halo MACHO fraction is around 25–50%, and thus the optical depth may be 2 to 4-times smaller than what is obtained above. However, the probability is still as high as  $5 \times 10^{-3}$ , indicating that at least one of a few hundred sources is always being lensed. Note that in figure 3 the optical depth is larger for the flat halo case ( $q = 0.75$ ) than for the spherical case ( $q = 1$ ). This is because the halo density at the galactic center increases with flattening of the halo. For instance, at the galactic center ( $R = 0$ ,  $z = 0$ ) the halo density is proportional to  $(2q^2 + 1)/q^2$ , which is 3.778 for  $q = 0.75$  while 3 for  $q = 1$ .

In order to study a typical lens distance, in figure 4 we plot the differential optical depth for astrometric microlensing, which is given by

$$\frac{d\tau_{\text{ast}}}{dD_d} = \frac{16\pi G^2 M}{c^4 \theta_{\text{min}}^2} \rho. \quad (29)$$

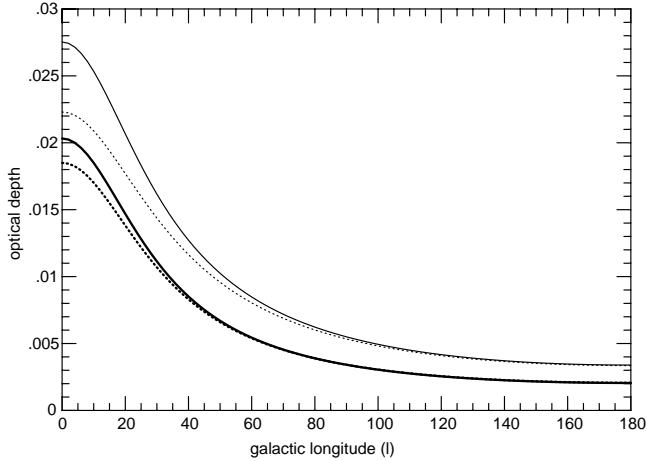
Figure 4 shows that the largest contribution to the optical depth occurs at  $D \approx 8.5 \text{ kpc}$ , i.e., around the galactic center. This is of course because that the halo density is largest at the galactic center region. As can be seen in figure 4, the differential optical depth beyond 50 kpc is quite small compared to the galactic center region. Therefore, the optical depth,  $\tau_{\text{ast}}$ , only slightly depends on the value of the cut-off radius (which is assumed to be 100 kpc), provided that it is sufficiently large.

##### 4.3. Disk Microlensing

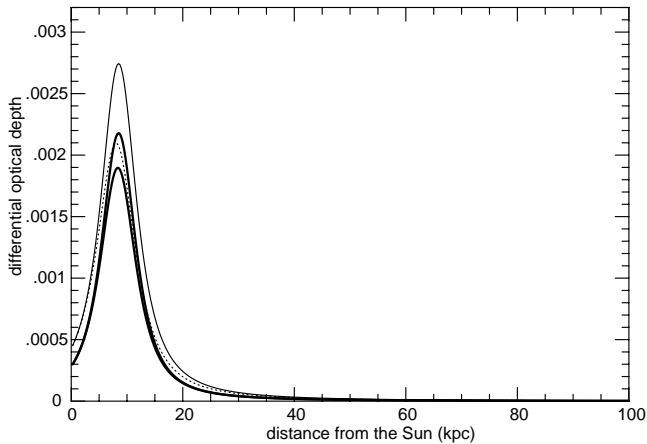
Since the stellar disk is a dominant component in the inner Galaxy, we must take into account its contribution to astrometric microlensing. In order to calculate the optical depth due to disk stars, we assume here a disk which has an exponential profile in both radial and vertical directions, namely

$$\rho_d(R, z) = \rho_0 \exp\left(-\frac{R - R_0}{d} - \frac{|z|}{h}\right). \quad (30)$$

Here,  $\rho_0$  is the local disk density, and  $d$  and  $h$  are the radial and vertical scale lengths, respectively. We take typical values for these parameters as  $\rho_0 = 0.08 M_\odot \text{ pc}^{-3}$ ,  $d = 3.5 \text{ kpc}$ , and  $h = 300 \text{ pc}$ , which are the same as those used in previous studies (e.g., Hosokawa et al. 1997; Dominik, Sahu 2000). We show in figure 5 the optical depth for astrometric microlensing

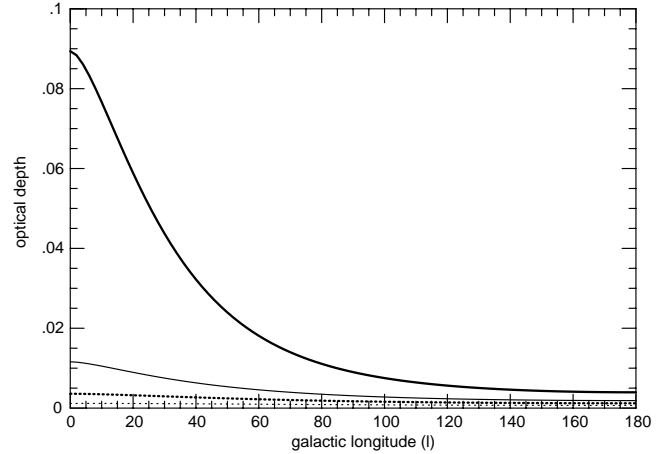


**Fig. 3.** Optical depth for astrometric microlensing due to MACHOs. The mass of the MACHO is assumed to be  $0.5 M_{\odot}$ . The thick line corresponds to  $(b, q) = (0^{\circ}, 1)$ , the thin line to  $(0^{\circ}, 0.75)$ , the thick dashed line to  $(10^{\circ}, 1)$ , and the thin dashed line  $(10^{\circ}, 0.75)$ . The optical depth becomes larger with a more flattened halo, because the halo density at the galactic center increases with decreasing  $q$ .

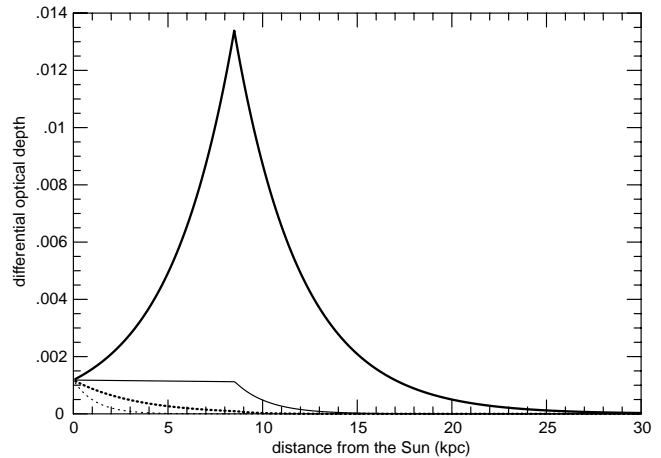


**Fig. 4.** Differential optical depth for astrometric microlensing due to MACHOs. The notations are the same as those in figure 3.

due to disk stars, assuming  $M = 0.3 M_{\odot}$ . As can be seen in figure 5, the optical depth is close to 0.1 at the galactic center, indicating that one of about 10 sources is always being lensed. This optical depth by disk stars is consistent with previous studies, such as Hosokawa et al. (1997). If one observes a source relatively far from the galactic center, but in the middle of the galactic plane ( $b = 0^{\circ}$ ), the optical depth due to the disk star is larger than 0.02 for  $l \leq 50^{\circ}$ . Therefore, as long as one observes sources in the galactic plane, the optical depth is significantly higher than that for halo MACHOs, and hence sources in the galactic plane are not suitable for an astrometric microlensing study of MACHOs (but of course they are useful for studying the galactic disk, particularly the stellar mass and the disk scale length; e.g., Hosokawa et al. 1993; Dominik, Sahu 2000). However, as can be seen in figure 5, the optical depth due to disk stars decreases quite rapidly with increasing the galactic longitude. Thus, a source at relatively high



**Fig. 5.** Optical depth for astrometric microlensing due to disk stars. The mass of the disk stars is assumed to be  $0.3 M_{\odot}$ . From top to bottom, the four lines correspond to  $b = 0^{\circ}, 5^{\circ}, 10^{\circ}$ , and  $20^{\circ}$ .



**Fig. 6.** Differential optical depth for astrometric microlensing due to disk stars. The notations are the same as those in figure 5.

galactic latitude ( $b \geq 10^{\circ}$ ) may be used to search for astrometric microlensing due to MACHOs.

Similarly to the halo case, in figure 6 we show the differential optical depth for disk stars. As can be easily understood, the differential optical depth in the galactic plane ( $b = 0^{\circ}$ ) becomes maximum at the galactic center. On the other hand, for sources at relatively high galactic latitude, the differential optical depth for disk stars is largest at  $D_d = 0$ , and hence it is dominated by local stars located within a few kpc from the sun. In such a case, one can discriminate the disk star microlensing from halo MACHO microlensing based on the event duration, as shown in the previous section.

## 5. Event Rate

The event rate is another important quantity in a microlensing study, because the event rate is tightly related to the observational strategy of a microlensing search. Once the optical depth,  $\tau_{\text{ast}}$ , and the average event duration,  $\bar{\tau}_{\text{ast}}$ , are known, the

event rate,  $\Gamma_{\text{ast}}$ , is obtained as

$$\Gamma_{\text{ast}} = \frac{\tau_{\text{ast}}}{\bar{t}_{\text{ast}}}. \quad (31)$$

Substituting equations (21) and (27) into the above equation, the event rate for astrometric microlensing may be written as

$$\Gamma_{\text{ast}} = \frac{8Gv_{\perp}}{c^2\theta_{\min}} \int \rho dD_d. \quad (32)$$

Remarkably, the event rate,  $\Gamma_{\text{ast}}$ , does not depend on the MACHO mass,  $M$ , as is the case for the optical depth for photometric microlensing ( $\tau_{\text{ph}}$ ). Also, the event rate,  $\Gamma_{\text{ast}}$ , is simply proportional to the column density,  $\int \rho dD_d$ . These facts indicate that the event rate of astrometric microlensing is a good tracer of the density distribution rather than the mass of individual lenses.

If we put into equation (31)  $\bar{t}_{\text{ast}} = 15$  yr and  $\tau_{\text{ast}} = 1.5 \times 10^{-2}$ , which corresponds to the optical depth at  $20^\circ$  away from the galactic center, we obtain

$$\Gamma_{\text{ast}} = 1.0 \times 10^{-3} \left( \frac{v_{\perp}}{200 \text{ km s}^{-1}} \right) \left( \frac{\theta_{\min}}{10 \mu\text{as}} \right)^{-1} \text{ event yr}^{-1}. \quad (33)$$

Thus, if one observes 100 sources for 10 yr, at least one event will be detected. However, note that this calculation is for the case that the halo totally consists of MACHOs. Since the halo MACHO fraction has been estimated to be 25–50% by recent studies (Alcock et al. 1997, 2000), one has to observe 2–4 times more sources or for longer periods to detect an event. This indicates that it is necessary to monitor a few hundred sources for a few decades. This number of source and the time span may seem to be long, but the frequency of monitoring can be fairly low because of the long event duration, and thus such an observation can be done with upcoming astrometric projects, like VERA (we will discuss this in next section in detail).

For disk star lensing, the event rate is expected to be much smaller than that for halo MACHO lensing, because the event duration  $t_{\text{ast}}$  is significantly larger. From figure 5, the optical depth for disk star lensing at  $b = 20^\circ$  is  $1.2 \times 10^{-3}$  (note that this value is almost independent of the galactic latitude  $l$ ). Using an event duration of 92 yr, one obtains an event rate for astrometric microlensing due to a disk star as  $1.3 \times 10^{-5}$ , which is smaller by two orders of magnitude than that for halo MACHO lensing. Thus, the contribution of disk star lensing is negligible in the off-plane region.

## 6. Implications for VERA

In this section we discuss the implication of astrometric microlensing for VERA. As briefly mentioned in section 1, VERA is a new VLBI array to measure the relative position of two adjacent sources based on the phase-referencing technique. Although VERA aims at astrometry with  $10 \mu\text{as}$ -level accuracy, similarly to other space missions (e.g., SIM, GAIA), VERA is very unique because it is an array of ground-based radio telescopes. The advantage of using VERA for astrometric searches is that the project lifetime can be much longer than that of other space missions, being  $\sim 20$  yr (as for space missions like SIM and GAIA, the mission lifetime is around 5 yr). As shown in the previous sections, the event duration is as long

as 10 yr, and thus monitoring span exceeding 10 yr is indispensable for studying astrometric microlensing events.

As we have shown previously, to detect an astrometric microlensing event, a few hundred sources should be monitored for a few decades. If one wants to detect more events for statistical studies, the number of sources to be observed becomes larger. Thus, it is important to examine whether there are a sufficient number of sources for an astrometric microlensing search with VERA. The main targets of VERA are compact continuum sources and maser sources. The compact continuum sources are mainly distant radio galaxies and QSOs, and are thus suitable for astrometric microlensing studies. On the other hand, the maser sources are mostly late-type stars and star-forming regions in the Galaxy, and thus unsuitable for the purpose of the present study. As for continuum sources, about 2000 VLBI sources (which are compact enough to be observed with VLBI) are currently known (e.g., ICRF catalog, Ma et al. 1998; VLBA Calibrator Survey, Peck, Beasley 1998). At high galactic latitude, where VLBI sources are searched relatively deeply, the average number of VLBI sources is close to 0.08 per square degree. This number roughly corresponds to one VLBI source in a circle with a radius of  $2^\circ$ . If the same source distribution applies to the sky region toward the galactic center, one can expect to find about 100 sources within  $20^\circ$  of the galactic center, and 220 sources within  $30^\circ$  of the galactic center, indicating that there is a sufficient number of VLBI sources that can be observed with VERA. Moreover, there are several hundreds of VLBI source candidates like those in Jodrel-Bank VLA Astrometric Survey (JVAS; Patnaik et al. 1992; Browne et al. 1998; Wilkinson et al. 1998). By conducting a deeper and more massive survey, one can expect to increase the number of VLBI sources that can be used for an astrometric microlensing search. Hence, one can expect to have plenty of VLBI sources around the galactic center regions.

We next estimate the time required for such a monitoring observation. The signal-to-noise ratio (S/N) of VLBI can be estimated using the following equation (e.g., Thompson et al. 1998):

$$R_{\text{S/N}} = \frac{\eta}{2k} \sqrt{\frac{A_1 A_2}{T_{\text{sys}1} T_{\text{sys}2}}} \sqrt{2\Delta\nu t_i} S. \quad (34)$$

Here,  $A$  is the effective antenna collecting area,  $T_{\text{sys}}$  the system noise temperature,  $\Delta\nu$  the bandwidth,  $t_i$  the integration time,  $k$  the Boltzmann constant,  $\eta$  the quantization efficiency, and  $S$  the source flux (subscripts denote the observational stations). The major specifications of VERA telescopes are currently anticipated as follows: an effective collecting area,  $A$ , of  $157 \text{ m}^2$  (assuming 20 m diameter and antenna efficiency of 0.5); a system noise temperature,  $T_{\text{sys}}$ , of 120 K; a bandwidth,  $\Delta\nu$ , of 256 MHz; and a quantization efficiency,  $\eta$ , of 0.88 (two-bit quantization). With these values, the S/N ratio  $R_{\text{S/N}}$  is  $\sim 16$  for a 100 mJy source with an integration time,  $t_i$ , of 300 s. Since the accuracy of a fringe phase measurement is determined to be  $1/R_{\text{S/N}}$  in radians, its accuracy will be 0.063 radian, or  $3.6^\circ$ . This corresponds to an error in the geometric delay of 0.13 mm ( $= 3.6 \times \pi/180 \times \lambda$ , where  $\lambda$  is the wavelength) at a wavelength of 1.3 cm, which is one of the major frequency bands of VERA. The position accuracy can be roughly estimated as

$(0.13 \text{ mm} / 2300 \text{ km}) = 5.65 \times 10^{-11}$  radian, which equals to  $11.7 \mu\text{as}$  (2300 km is the longest baseline of VERA). Thus, for sources with a flux of  $\sim 100 \text{ mJy}$ , the thermal error can be reduced to the  $10 \mu\text{as}$  level within 5 min.

If one spends 20 min for a single measurement (one measurement of the separation of two adjacent sources), the total number of sources that can be observed in 24 hr exceeds 100 (note that two sources are observed in a single measurement). Thus, 2–3 d are sufficient for observing a few hundred sources. In practice, one separation measurement for each pair is not enough for detecting a position shift of  $\sim 10 \mu\text{as}$ . To achieve a higher position accuracy (i.e., a few  $\mu\text{as}$ ), we may need 10 sets of observations of a few hundred sources, which requires a total observation period of 20–30 d. On the other hand, a typical timescale for a image to move along a quarter of the trajectory is about 5 yr, and thus the interval of such observations can be as long as six months. If we spend 30 d for astrometric microlensing during six months, this requires 15% of the telescope time to be dedicated to such a monitoring observation. This is, indeed, a massive expense, but is worth spending when one considers the significance of the scientific output; in addition to astrometric microlensing, one can establish a radio reference frame with an accuracy of  $10 \mu\text{as}$ , which is more accurate by two orders of magnitude than the reference frame currently achieved, and also one can measure proper motions of nearby AGNs (up to a few tens Mpc), from which the 3-dimensional structure of the local universe can be studied.

One possible way to incorporate such a massive microlensing search with VERA is to perform a geodetic observation based on a dual-beam observation. A geodetic observation is necessary to determine the baseline parameters with sufficient accuracy. Usually, a geodetic observation is made at the S (2 GHz) and X (8 GHz) bands with a single beam. In the case of an S/X geodetic observation, the baseline parameters

and the absolute position of radio sources with an accuracy of 1 mas are solved based on a few hundred observations of the radio sources. On the other hand, baseline measurements are also possible based on the relative fringe phase of two sources that are observed with the dual-beam system of VERA. In the case of a dual-beam geodetic observation, what can be obtained are the baseline parameters and the ‘relative’ position of adjacent two sources with an accuracy of  $10 \mu\text{as}$  level. Thus, if a dual-beam geodetic observation is performed, one can obtain the relative position of radio sources for a few hundred sources with an accuracy at  $10 \mu\text{as}$ . Currently, VERA is planned to perform a one-day geodetic observation every week, and thus the observation frequency is just what we need for an astrometric microlensing search (i.e., 15% of the telescope time). Therefore, a dual-beam geodetic observation, if possible, is more practical for the massive monitoring of astrometric microlensing.

## 7. Conclusion

We have investigated the properties of astrometric microlensing of distant sources due to MACHOs. We have shown that in the case of astrometric microlensing of distant sources, the event duration depends only on two unknown parameters: the lens mass,  $M$ , and the tangential velocity,  $v_{\perp}$ , in contrast to that for photometric microlensing of nearby stars. We have also shown that a typical event duration of astrometric microlensing is 15 years, and that the event rate of astrometric microlensing is larger than  $2.5 \times 10^{-4}$  within  $20^\circ$  of the galactic center, assuming that 25% of Galaxy’s halo is made up of MACHOs. This implies that one can detect an astrometric microlensing event if a few hundred sources are monitored for 20 years. Detections of astrometric microlensing will be possible with VERA within decades, and thus astrometric microlensing will become a new tool to study the nature of MACHOs.

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