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Quantitative Risk Evaluation of Obstacle Limitation Surfaces for Final Approaches at Airports

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Abstract

Obstacle limitation surfaces (OLS) are the main safeguard against objects that can pose a hazard to aircraft operations at and around airports. The standard dimensions of the most of those surfaces were estimated using the pilot's experience at the time when they were included in the standard documents. As a result, some of these standards may have been overestimated, while others may not provide an adequate level of safety. With airports moving to the Safety Management System (SMS) approach to design and operations safety, proper evaluation of the level of safety provided by OLS at specific sites becomes important to airport operators. Therefore, this study attempts to collect actual flight path data using information provided by air traffic control radars and to construct a methodology to assess the probability of aircraft deviating from their approach path. This will be helpful to estimate safe and efficient standard dimensions of the OLS and assess the risk level of objects to the aircraft operations around airports. The methodology is presented using the aircraft trajectories of approaches at Ottawa International Airport (CYOW). Estimated dimensions of Code 3 approach surfaces also are presented.

Keywords: obstacle limitation surfaces, aviation safety, quantitative risk analysis

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Introduction

Aerodrome design standards are the main framework used for planning and design of airport facilities. They were established over 60 years ago in order to maintain safe aircraft movements at and around aerodromes. Obstacle limitation surfaces (OLS) are part of aerodrome standards. They are a set of imaginary surfaces defined at and around airports to protect airborne aircraft operations from obstacles that can pose a hazard to their movements. Most often, those safety surfaces extend well beyond the airport property and, as a result, certain areas around airports are considered as integral parts of the aerodrome environment (ICAO, 1983). Furthermore, OLS are identified as an important design standard affecting the orientation of the runway system layout.

Internationally agreed standards for airport design were established as Annex 14 to the Chicago Convention on Civil Aviation (ICAO, 1999). However, each country uses its own standards for planning criteria related to aerodromes. Although most of those national standards are based on Annex 14, some countries may elect to develop and adopt their own standards. AC 150/5300-13 in the USA (FAA, 2004), TP 312 in Canada (Transport Canada, 1993), and CAP 168 in the United Kingdom (CAA, 2011) are examples of national standards used in different countries. In all those standards, shapes and dimensions of the OLS and their objectives are defined. A careful review of those standards reveals that there are some differences in dimensions and shapes of OLS among those documents. For instance, in contrast to the trapezium shape longitudinal cross section of obstacle free zone (OFZ) prescribed by the International Civil Aviation Organization (ICAO), a rectangular section is defined in Federal Aviation Administration (FAA) standards (FAA, 2004). Generally, aviation safety organizations allow deviations from these standards when designing the airfields, if the designer can prove that an adequate level of safety is achieved.

According to ICAO (1983), the significance of any existing or proposed objects to the safety of aircraft operations within the aerodrome boundary or vicinity of the aerodrome is assessed by the use of two separate sets of criteria defining airspace requirements. Obstacle limitation surfaces are the main standard defined in Annex 14 to minimize the collision risk of airborne aircraft near airports. The second set of criteria comprises obstacle assessment surfaces (OAS), also known as PANS-OPS surfaces (ICAO, 2006; Litesheim & Xiao, 2006). The main purpose of PANS-OPS surfaces or OAS is to provide guidance for procedure designers to estimate the obstacle clearance height (OCH) in an airport and assess the risk of obstacles near the runways. OCH is the height at which aircraft can initiate a missed approach in a low visibility condition when it uses the instrument approach procedures. Pilots are

only allowed to descend below this level if they have clear sight that the aircraft is correctly aligned with the runway and there are sufficient visual cues to continue the approach.

The height of the objects that penetrate the OAS surfaces, the characteristics of aircraft, and navigation facilities at a runway are used to calculate its OCH using the OAS. The OAS consists of six sloping plane surfaces whose shape and dimensions are determined by linear equations. The coefficients and constants of those equations are available in the PANS-OPS OAS software provided by ICAO.

In coming years, it is expected that air transportation will experience greater growth than what has been observed during the last decade. With this expected traffic growth, airports will need to expand their facilities to increase aircraft operation capacity (Hall et al., 2008). In such situations, it may be impractical or impossible to meet the requirements of existing OLS standards due to space limitations at and around airports. As a result, airports may have to use new dimensions for the OLS and check the level of safety of the modified surfaces.

A thorough review of the literature has identified very few studies done to justify the level of safety of existing or modified OLS standards, plus a few studies that were carried out to measure the level of safety of OFZs using simulated flight paths (Eddowes, Hancox, & MacInnes, 2001; ICAO, 2005b). Recently, studies done by Fricke and Thiel (2013) assessed the level of safety provided by OLS and PANS-OPS using the radar data. The methodology presented in their studies did not consider the dependency between the lateral and vertical deviation data that significantly affects the analysis results. Other studies have focused on the flight path deviation analysis (Thiel & Fricke, 2010; Thiel, Seiß, Vogel, & Fricke, 2012). Marco and Auria (2014) analyzed the flight trajectories generated with 6 degrees of freedom (6DoF) flight simulations and developed a methodology to calculate the collision risk with objects near airports. The analysis was based on the simulated flight paths generated by Monte Carlo simulation. Cramer and Rodriguez (2013) studied the path steering error (PSE) effect on the calculated lateral aircraft deviation. PSE is defined as distance from estimated aircraft position to a beam point on the lateral computed path. In that study, the effect of the total system error on the calculated aircraft deviation was studied. There also are computer programmes such as SAT-P, PDTToolKit (MITRE, 2015) available commercially to identify the hazardous obstacles with respect to the existing standards.

In the 1960s, a joint effort by the FAA's flight standards organization and ICAO's obstacle clearance panel (OCP) developed the collision risk model (CRM) for instrument landing system (ILS) operations. The main objective of this model was to determine the area that needed to be protected when an aircraft is making an ILS approach. This model is

Table 1.
Approach surface dimensions. Source: ICAO, 1999.

Surface and dimensions	Non-instrument code number				Non-precision approach code number			Precision approach category		
	1	2	3	4	1,2	3	4	Cat I		Cat II, III
								1,2	3,4	
Length of inner edge (m)	60	80	150	150	150	300	300	150	300	300
Distance from threshold (m)	30	60	60	60	60	60	60	60	60	60
Divergence (each side)	10%	10%	10%	10%	15%	15%	15%	15%	15%	15%
First section										
Length (m)	1600	2500	3000	3000	2500	3000	3000	3000	3000	3000
Slope (m)	5 ⁰	4 ⁰	3.33 ⁰	2.5 ⁰	3.33 ⁰	2 ⁰	2 ⁰	2.5 ⁰	2 ⁰	2 ⁰
Second section										
Length (m)	NA	NA	NA	NA	NA	3600	3600	12000	3600	3600
Slope (m)	NA	NA	NA	NA	NA	2.5%	2.5%	3%	2.5%	2.5%
Horizontal section										
Length (m)	NA	NA	NA	NA	NA	8400	8400	8400	8400	8400
Total length (m)	NA	NA	NA	NA	NA	15000	15000	15000	15000	15000

still being used to assess the risk of obstacles below the decision height (DH) in ILS operation by aviation authorities. The main shortcoming of the model is that it can only be used to analyze the ILS approaches. Therefore, it only considers the instrumental errors of the ILS system. However, deviation due to aircraft characteristics, pilot techniques, and weather condition are ignored in the model (ICAO, 1980).

It was found that in most recent studies related to airport standards, the dimensions of a safety standard can vary with respect to the geographical location of an airport and local weather condition (Eddowes et al., 2001). Therefore, it is more cost effective if an airport can estimate the required dimensions of OLS according to their local weather and geographical conditions. The expected move in the United States and Canada to a Safety Management Systems (SMS) approach to airport regulation (ICAO, 2012) confirms this perception. To address this rising issue, this study proposes a methodology to estimate the probability of aircraft deviation from standard flight paths using actual flight trajectories. Moreover, an extension of the methodology can be used to estimate the dimensions of the OLS that provide the acceptable level of safety for aircraft operations. The analysis is presented using the aircraft trajectories at Ottawa International Airport (CYOW). As an example, approach surface dimensions for ICAO Code 3 instrument and non-instrument were estimated and compared with the existing OLS and PANS-OPS surface dimensions.

According to ICAO (1999), the objective of the approach surface is to protect the aircraft when approaching a runway. Its dimensions depend on the aircraft code number and the approach category. The aircraft code number mainly represents the kinetic energy of an aircraft on final approach, using the aircraft's reference field length as a

proxy. The approach category represents the type of approach (i.e., visual or instrument, precision or non-precision) according to weather conditions and available navigation instruments. The standard dimensions and geometric shape of the approach surface are shown in Table 1 and Figure 1.

To the best of our knowledge, there are no studies publicly available that explain the rationale for the ICAO standards presented in Table 1. By analyzing actual aircraft trajectories, one can estimate the probability density functions of deviations from the standard flight path. These probability density functions can then be used to determine the risk of a collision between an aircraft and objects—existing or hypothetical—located in the proximity of the aircraft's path. Such analysis can then be used both to determine the level of safety at existing airports and to set risk-based standards for the design of new facilities. This paper discusses a methodology to collect data on aircraft trajectories and evaluate these deviation probability distribution functions using data collected at CYOW.

Acceptable Risk or Target Safety Level (TLS) for Aircraft Operations

The main reason for developing a safety standard is to provide an acceptable level of safety to aircraft operations. An acceptable level of safety is defined with respect to the risk for aircraft operations. According to the Civil Aviation Authority of Sri Lanka, safety risk is defined as “the assessment, expressed in terms of predicted probability and severity of the consequence(s) of a hazard taking as reference to the worst foreseeable situation” (CAASL, 2010). The worst foreseeable situation can vary with respect to the phase of the aircraft operation. For example, aircraft can collide with an object when taxiing or

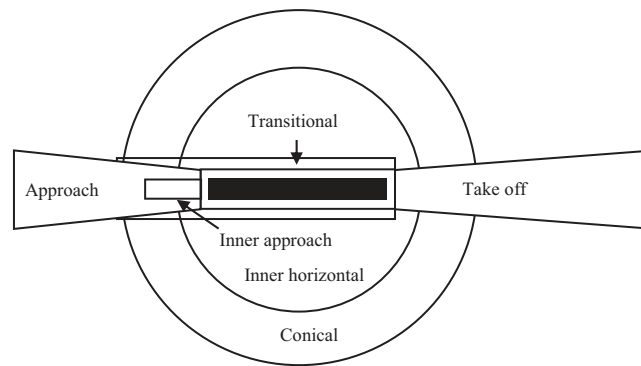


Figure 1. Obstacle limitation surfaces (OLS). Source: ICAO annex 14 (2005b).

Table 2.

Risk tolerability matrix. Source: ICAO, 2012.

Severity	Probability of Occurrence				
	Extremely Improbable	Extremely Remote	Remote	Reasonably Probable	Frequent
Catastrophic	Review	Unacceptable	Unacceptable	Unacceptable	Unacceptable
Hazardous	Review	Review	Unacceptable	Unacceptable	Unacceptable
Major	Acceptable	Review	Review	Review	Review
Minor	Acceptable	Acceptable	Acceptable	Acceptable	Review

approaching a runway. The severity and frequency of these two situations are not equivalent.

According to ICAO, the accepted probability of this kind of incident to occur during an aircraft operation is defined as the acceptable safety level (ASL). This kind of approach to safety management recognizes that it is unrealistic to expect a zero risk. Some risk may have to be tolerated to secure the benefits of an activity. Risks must therefore be balanced with the benefits, with regard to the practicability of achieving further risk reduction (Eddowes et al., 2001). Assigning an ASL value to a safety standard that protects a specific phase of an aircraft operation is a complicated process since it depends on the likelihood and severity of an incident that could occur during that phase of operation. For example, the acceptable probability of a low speed aircraft wingtip collision with an object during a taxiing operation can be higher than for a catastrophic event such as an aircraft hitting an obstacle when on final approach.

According to ICAO (2012), the consequence or severity of an incident is classified into four categories: Catastrophic, Hazard, Major, and Minor. The likelihood of occurrence is categorized into Extremely Improbable, Extremely Remote, Remote, Reasonably Probable, and Frequent. The combination of those categories creates a Risk Tolerability Matrix such as the one shown in Table 2. As can be seen in Table 2, only acceptable and review incidents are allowed to occur at airports and ASL values for those incidents should be established after a cost-benefit analysis.

In this study, the event of an aircraft hitting an object on the ground when approaching or departing from a runway

will be considered an extremely improbable, catastrophic event. The main objective of the OLS is to reduce the frequency of such an event as far as reasonably practicable. According to the risk tolerability matrix, the acceptable frequency of such an incident can be estimated by cost-benefit analysis. According to ICAO's obstacle clearance panel, a 10^{-7} probability is used for risk of collision per movement with an obstacle due to the aircraft being laterally off-path or beneath the approach path (Eddowes et al., 2001). The TLS value that should be used in aeronautical studies is set by ICAO (1980; 2005b). However, this value can change from country to country or even region to region because the results of the cost-benefit analysis depend on the investment made on safety in those countries. The estimation of the acceptable safety level for obstacle limitation surfaces is beyond the scope of this study. Therefore, we have assumed a 10^{-7} collision risk per approach as the acceptable safety value to estimate the dimensions of OLS recommended by ICAO and its obstacle clearance panel (Eddowes et al., 2001). This value was used in most recent aeronautical studies as a TLS value (Hall et al., 2008; Wong, Pitfield, Caves, & Appleyard, 2009a). However, the proposed methodology can be used to estimate the dimensions for any given value of ASL.

Deviations from Annex 14 standards can be accepted after an aeronautical study. The primary objective of an aeronautical study is to assess the adequacy of protection provided by the existing layout for the operation of the critical aircraft (ICAO, 2005a). Therefore, it depends on several factors such as weather, geographical characteristics, aircraft operational characteristics, and the flight

phase. Decision makers must consider those factors when they are conducting an aeronautical study in order to make modifications to the existing standards. In most of the previous studies (Wong et al., 2009a; Valdés, María, Comendador, Gordún, & Nieto, 2011; Wong, Pitfield, Caves, & Appleyard, 2009b), quantitative risk assessment method was used to carry out the aeronautical studies based on acceptable or target level of safety.

Quantitative risk assessment criteria were used to measure the level of safety of design standards by Eddowes and colleagues (2001) in Norwegian airports. That study identifies the need for changes in Annex 14 standards to maintain an adequate level of safety in Norwegian airports. The study also indicates that aerodrome standards can vary with respect to the geographical location of an airport. In 2010, a study was conducted by ICAO and the FAA to assess the risk level of existing OFZ standards when operating the new large aircraft (NLA) (ICAO, 2005b). OFZ is a type of OLS that provides protection for balked landings and missed approaches. The objective of that study was to verify the possibility of operating Code F aircraft in existing aerodromes that currently operate as Code E. The study used simulation flight path data to analyze the risk level of the OFZ. As a conclusion, it was shown that Code E autopilot OFZ surfaces are acceptable for autopilot operations of NLA. Furthermore, it was found

that NLA that operate using a flight director (FD) can operate at Code E Category I runways. From these findings, it can be argued that the current standards for OLS were not estimated properly. Therefore, further studies will be helpful to estimate the optimal balance between safety and cost-effectiveness for OLS standards.

Methodology

The assessment of risk associated with aircraft deviation from the standard path during airborne operations is somewhat more complex than the case with ground operations, because of the three-dimensional nature of flight paths. The analysis needs to be carried out by considering all three directions that affect the deviation probability (i.e., lateral, vertical, and longitudinal). To achieve this, the proposed methodology was divided into two major components: data processing and analysis. These two components are described in detail in following sections.

Flight Trajectory Data Collection and Treatment

Flight trajectory data were collected using NAVTRACK software. NAVTRACK is a web-based application developed by Nav Canada—the air traffic service provider in Canada—capable of collecting and saving the flight path

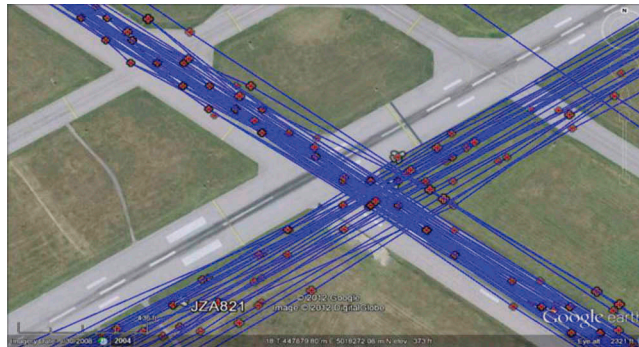


Figure 2. Observed error of flight paths.

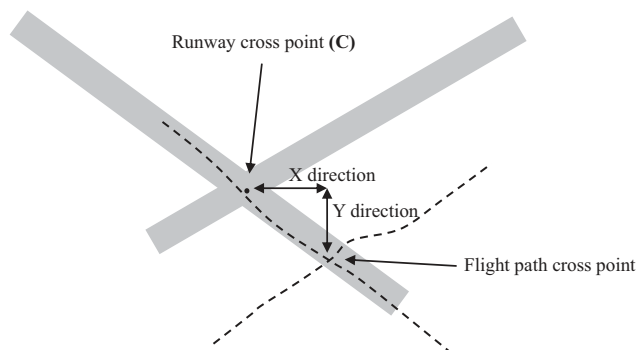


Figure 3. Runway cross point and flight path cross point.

data that is tracked by air traffic control (ATC) secondary radars in real time. However, the positional accuracy and more information on the secondary radar system were not made available to the authors. In this study, NAVTRACK was used to collect data from August 2011 to August 2012. NAVTRACK collects the aircraft location data recorded every five seconds, within a 20 km radius from an airport. This information can be used to display the airplane movements on Google Earth in real time. With this data, it is possible to plot the aircraft trajectories both on take-off and final approach.

At five-second intervals, aircraft geographical position (i.e., latitude, longitude, and altitude), speed, type, ID, and origin and destination airports are tracked and saved in KMZ format (Google Earth file). These files can be directly downloaded from the server and used to view the historical flight paths in Google Earth. This option helps the user to identify the runway that was used for an aircraft operation.

The KMZ files can only be used to work with Google Earth applications. Therefore, KMZ files were converted to KML files in order to extract required information. MATLAB is a popular tool capable of reading the data in KML files. A MATLAB program was developed in order to filter the relevant information such as coordinates and aircraft attributes from the KML files. Furthermore, a separate program was developed to convert the geographical coordinate system data to the Universal Transverse Mercator (UTM) coordinate system. This conversion will help to plot the aircraft trajectories in a three-dimensional Cartesian coordinate system. The conversion equations can be found in Synder (1987).

Truncation Error

In the data filtering process, it was observed that flight paths are shifted to a southeast direction from the runway when it was plotted on Google Earth (Figure 2). According to Nav Canada, this deviation is due to the reduced number of decimal points of tracked coordinates of aircraft. Therefore, it is a constant error in the tracked coordinates and needs to be corrected before the analysis of aircraft deviation. The following methodology was used to remove that truncation error from the data. It is mainly based on the assumption that on average, aircraft should be on the runway center line when they are moving on the runway. In other words, if an airport has crossing runways, then the aircraft movements on runways should intersect at the cross point of the two runways. Therefore, this methodology can be used only at airports that have crossing runways in order to remove that truncation error from the data.

Initially, the data samples of flight paths were collected and plotted on an XY coordinate system, and coordinates of cross section points of flight paths were calculated using Cartesian geometry (Figure 5). According to the assumption, calculated cross points should be at the intersection of the two runways if

there is no truncation error in the data. Therefore, the deviated distance of X and Y directions were calculated with respect to the point C (Figure 3). Then, the average deviation was calculated for both X and Y directions. This process was performed on the large and small aircraft samples (i.e., Code 1, 2, 3, and 4) in order to represent the all aircraft types, and average values of deviation were calculated. According to the results, it was found that X and Y directions have 64 m and -36m average errors, respectively. Therefore, 64 m was subtracted from every coordinate in the X direction and 36 m was added in the Y direction to remove the truncation error from the data. After this correction, all the aircraft paths were on the runway and their deviation can be calculated with reference to the runway center line direction.

Coordinate System

To measure the deviation of a flight from its intended path, the coordinate system was defined with reference to the runway threshold. The origin was established at one of the runway thresholds of a given runway and the line connecting the two runway thresholds taken as the Y axis. The X axis and Z axis were defined as parallel to the runway surface and perpendicular to the XY plane respectively. Figure 4 shows the diagram of the coordinate system that was used in this study.

Intended Flight Path

When aircraft is on the final approach to an airport, it needs to follow a predefined path, which in this study is referred to as the intended flight path. In instrument landing system (ILS) approaches, the intended flight path is defined by the intersection between the localizer and the glide slope planes (Figure 4). In non-precision and visual approaches, aircraft should follow the extended runway center line direction, and the descent rate which is stated in approach procedures. Therefore, in non-precision approaches and visual approaches, it is difficult to find the vertical angle of the approach path because it can change with respect to point at which it starts the final approach. Therefore, it was decided to measure the vertical deviation of aircraft with respect to the runway threshold elevation and lateral deviation with respect to the runway center line.

Categorization of Aircraft Approaches

Deviation of an aircraft from its intended path could be a result of one or multiple factors. For example, it can be due to lack of pilot experience, bad weather conditions such as high cross winds and poor visibility, calibration errors of the navigation instruments that are used for instrument approaches in airports and aircraft, and so forth. As a result, it is impossible to identify the exact reason for the deviation of an aircraft when the only data available is the actual trajectories for the analysis.

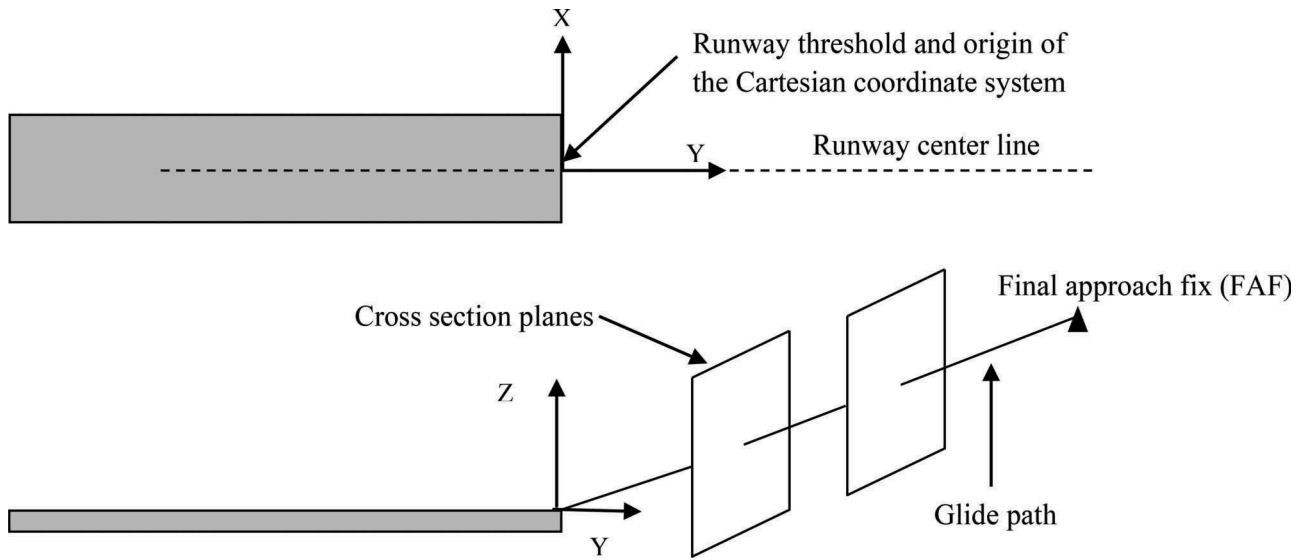


Figure 4. Runway coordinate system and intended path.

According to ICAO (1999), the effect of some of those factors on OLS dimensions is represented by categorizing the runways with respect to the approach type and code number (Table 1).

In this analysis, approach trajectory data of ICAO Code 3 aircraft on CYOW runway 07-25 were analyzed. According to the Canada air pilot (CAP) 4 document (Nav Canada, 2012), runway 07-25 has been used for both non-precision and precision approach procedures (Table 3) (Nav Canada, 2012). In precision approaches (PA), the pilot get both vertical and lateral guidance, but in non-precision approaches (NPA), they only get lateral guidance. Therefore, if we are going to estimate OLS dimensions with respect to the type of approach (i.e., precision, non-precision, visual), deviation data needs to be divided according to that. In order to do that categorization, a database that contains aircraft approach information for CYOW is required. However, during our study, we were unable to acquire such database for CYOW.

Therefore, it was decided to combine the non-precision and precision approach data and analyze the aircraft approaches with respect to the meteorological condition (i.e., instrument and visual) at the airport. Due to that categorization, the study is unable to show the effect of guidance system to deviations from the intended path. However, OLS is a permanent surface for a runway. Therefore, if a runway has been used for both types of approaches, then that runway's OLS should provide protection for both types of approaches. As a result, it can be argued that the dimensions of OLS that we get from this analysis by combining the NPA and PA will provide the adequate level of safety for both types of instrument approaches.

To distinguish the approaches under visual meteorological conditions (VMC) and instrument meteorological conditions (IMC), METAR data containing weather

information for CYOW was obtained from the Ontario Centre for Climate Impacts and Adaptation Resources. According to Horonjeff and colleagues (2010), aircraft should use instrument procedures in IMC. However, in VMC, aircraft are allowed to use instrument approach procedures. Therefore, when we categorize the data according to the meteorological condition, instrument approach data may be included in the VMC data.

Calculation of the Deviations From Intended Path

Aircraft deviation from its protected path was calculated at 500 m intervals along the runway center line (Figure 4). In this calculation, it is assumed that magnitude of deviation does not change significantly within a given 500 m interval along the intended flight path. In this study, Cartesian geometry calculations were used to estimate the deviation distances along the extended runway center line direction. As a first step, the Cartesian equation of the runway center line was calculated using the coordinates of the runway thresholds.

$$y = m_1 x + C_1 \quad (Eq.1)$$

Where

$$m_1 = \frac{Y_1 - Y_2}{X_1 - X_2};$$

$$C_1 = Y_1 - \frac{(Y_1 - Y_2) \cdot X_1}{(X_1 - X_2)}$$

The equations for the cross section lines that are perpendicular to the runway center line and at 500-m intervals are

$$y = m_2 x + C_2 \quad (Eq.2)$$

Table 3.
CYOW runway 07-25 approach types.

Instrument approach type	TDZE (ft)	FAF (km)	Minimum altitude at FAF (ft)	Visibility (SM)	Minimum descent altitude	Minimum descent height	Glide path angle	ILS CAT	Approach type
ILS	373	7.2	1500	0.5	573	200	3	I	precision
LOC	373	7.2	1500	1	760	387		-	non-precision
NDB	373	7.2	1500	1	800	427		-	non-precision

TDZE = Touchdown zone elevation; FAF = Final approach fix; SM = Statute miles; ILS CAT = Instrument approach category.

Where

$$C_2 = Y_1 - m_2 X_1; \quad m_2 = (1/m_1) \times (-1)$$

and

$$y = m_3 x + C_L \quad (Eq.3)$$

where

$$m_3 = m_2; \quad C_L = C_1 + \frac{L}{\cos \theta}; \quad \theta = \tan^{-1}(m_2)$$

Then, the equation between two tracking points of aircraft was computed as

$$y = m_p x + C_p \quad (Eq.4)$$

where

$$m_p = \frac{y_1 - y_2}{x_1 - x_2}; \quad C_p = y_1 - \frac{(y_1 - y_2) \cdot x_1}{(x_1 - x_2)}$$

In this step, we assumed that the flight path between two tracking points can be represented using a straight line. Finally, the intersection point of cross section line and flight path line was calculated.

$$y = \frac{C_L m_p - C_p m_2}{m_p - m_2} \quad (Eq.5)$$

$$x = \frac{C_L - C_p}{m_p - m_2} \quad (Eq.6)$$

$$\text{Vertical deviation} = z = z_1 - (z_1 - z_2) \frac{\{(x_1 - x_2)^2 + (y_1 - y_2)^2\}^{0.5}}{\{(x_1 - x)^2 + (y_1 - y)^2\}^{0.5}} \quad (Eq.7)$$

$$\text{Lateral deviation (D)} = [(X_c - x)^2 + (Y_c - y)^2]^{0.5} \quad (Eq.8)$$

(x_i, y_i, z_i) = Tracking point coordinates of the aircraft ($i = 1, 2$)

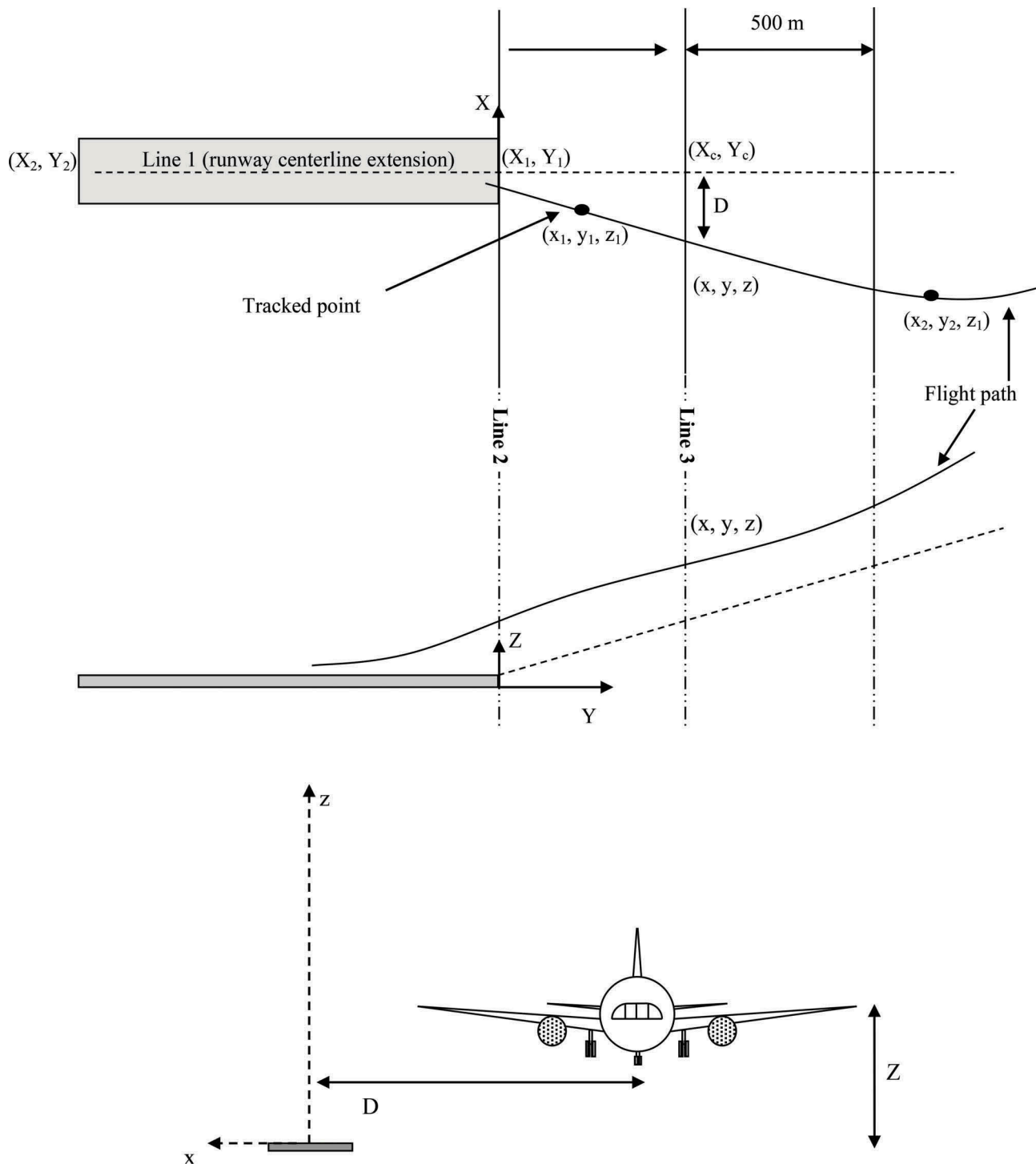
(X_i, Y_i) = Runway threshold coordinates ($i = 1, 2$)

(X_c, Y_c) = Runway center line and cross section line intersecting point coordinate ($c = 1-16$).

D = deviation distance

m_i = gradient of line; C_i = intercept of line

These were used to measure the distance between the aircraft's center of gravity and the runway center line extension. The diagram of a flight path and the deviations is shown in Figure 5. Both horizontal and vertical deviations from the intended path were measured at each cross section plane. Afterward, aircraft characteristics and weather condition were assigned to those points to filter the data according to required categories.



Estimation of Distribution Function Parameters

The deviation probabilities for approaches in a cross section can be calculated by fitting the deviation data to univariate or bivariate continuous probability density functions (PDF). As described above, maximum deviation data were used for the analysis. The type and parameters of the deviation distributions need to be estimated for each 500 m cross section

separately. Moreover, it is important to check the dependency of the lateral and vertical deviation data before estimating the distribution functions. If the data are dependent, it is necessary to estimate the joint probability functions, whereas if they are independent, two separate distribution functions can be used for the vertical and lateral deviations.

According to the above methodology, independent data were fitted to the normal mixture distribution and

dependent data were fitted to joint normal distribution (Equations 12 and 13). The main objective of using the normal mixture distribution is obtaining a good fit not only for the tail of the distribution, but also for the central part of the distribution. However, it can be argued that the results which are produced using the normal distribution is not precise when estimating the extreme probability values such as 10^{-7} . Therefore, in the future research, results needs to be compared with results obtained from using the extreme value distribution.

$$f(x) = W_1 * f(x, \mu_1, \sigma_1) + W_2 * f(x, \mu_2, \sigma_2) + W_3 * f(x, \mu_3, \sigma_3) \quad (Eq.12)$$

where

$$f(x, \mu_i, \sigma_i) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu_i)^2}{2\sigma_i^2}\right)$$

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp\left[-\frac{1}{2(1-\rho^2)}\left\{\left(\frac{x-\mu_1}{\sigma_1}\right)^2 - 2\rho\left(\frac{x-\mu_1}{\sigma_1}\right)\left(\frac{y-\mu_2}{\sigma_2}\right) + \left(\frac{y-\mu_2}{\sigma_2}\right)^2\right\}\right] \quad (Eq.13)$$

$$\sigma_1 > 0, \sigma_2 > 0, -1 \leq \rho \leq 1$$

W_i = weights
 μ_i = mean of the variable
 σ_i = variance of the variable
 ρ = correlation parameter
 x_i, y_i = aircraft deviation (lateral or vertical)

The parameters of the distributions were estimated separately for deviation data at every 500 m cross section using the "normlmix" package, which was built under R project. The package has functions to estimate parameters of the bivariate and univariate distribution parameters of normal distribution using the expectation maximization (EM) algorithm. The EM algorithm is an iterative method for finding maximum likelihood estimates of parameters in statistical models, where the model depends on unobserved latent variables (Maechler, 2013). Furthermore the Kolmogorov-Smirnov (K-S) test was used to measure the goodness of fit (GOF) of the distribution models. The K-S test does not produce good estimates for large sample sizes due to its poor assessment of fit at the tail (Eiger, Nadler, & Spiegelman, 2013). However, it is important to note here that not only do the extreme probabilities affect the calculation of location probabilities, but also the middle

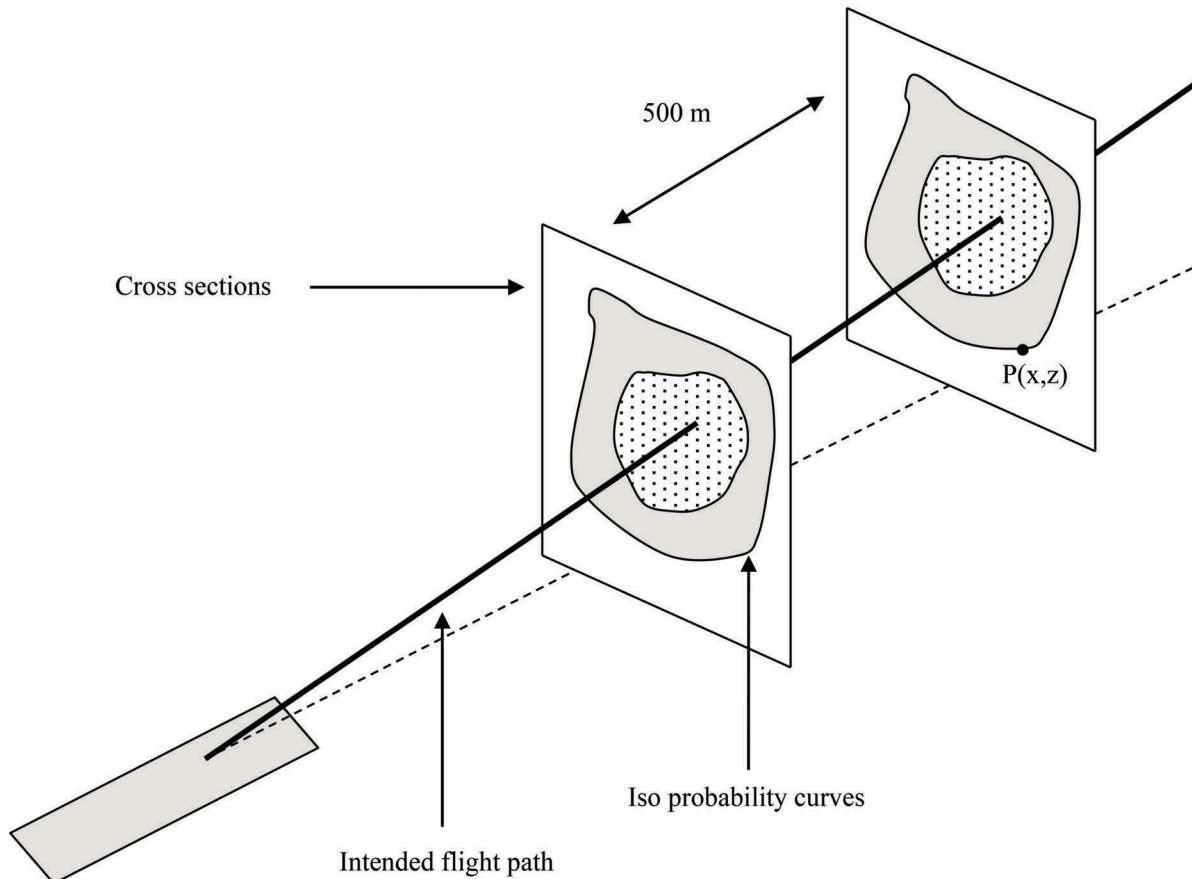


Figure 6. Iso probability curves around the intended path.

part of the distribution. Therefore, measuring the fit in the central part of the distribution curves is also essential. For this reason, the normal mixture distribution was used to estimate the overall goodness of fit for the entire data range, and the K-S test was used to assess the fit. However, in future studies, it is recommended that an extreme value distribution be used to more accurately estimate the density function's tail.

Estimation of the Required Dimensions of the Approach Surface

As described in Section 1, the main objective of the OLS is to protect airborne aircraft from obstacles on the ground in the vicinity of an airport and reduce the likelihood of collisions with such obstacles. Therefore, the dimensions of the OLS depend on the probability of an aircraft deviating from the approach path. The OLS is defined by the surface beyond which the probability of collision with an obstacle on the ground is below the acceptable safety level.

The estimated distribution functions can be used to find the inverse of the cumulative probabilities or quantile values of the probabilities that aircraft deviate beyond a given distance. In this study, those probability values are defined as the location probabilities of an aircraft. Equations 14 and 15 can be used to estimate the quantile values of the location probabilities in a given cross section. The quantile values can be estimated for 10^{-1} to 10^{-7} location probability values for each cross section. In the next step, points that have the acceptable level of safety (i.e., 10^{-7}) were identified and connected to develop iso-probability curves. This was done for each cross section, and iso-probability points were connected to develop the three-dimensional approach surface (Figure 6).

Dependent data

$$q_{x,z} = F^{-1}(1 - F_{x,z}(x,z)) \quad (Eq.14)$$

Independent data

$$q_{x,z} = \{F^{-1}(p_x)\}, \{F^{-1}(p_z)\} \quad (Eq.15)$$

Where,

$$1 - F_{x,z}(x,z) = p_x \times p_z = P$$

P = acceptable level of safety or given location probability value

F(x,z) = cumulative probability function

Results

In this study, two samples of 943 and 882 IMC and VMC Code 3 aircraft trajectories were analyzed, respectively. The categorized approach data were used to measure the aircraft deviation from its intended path and estimate deviation distribution functions. Before fitting this

deviation data to distribution functions, a Pearson correlation test was carried out to check the independency of lateral and vertical deviation data in every cross section. The null hypothesis of the test is that the correlation coefficient is equal to zero, and the alternative hypothesis is that the correlation coefficient is not equal to zero. Therefore, if the p value of the test is greater than 0.05, the null hypothesis cannot be rejected.

The results of the Pearson correlation test are shown in Table 4a-b for code 3 aircraft, which are operated under VMC and IMC. According to the analysis, no significant correlation between lateral and vertical deviation data was found. All the p values of the tests were greater than 0.05. We cannot reject the null hypothesis at 95 confidence level. Therefore, two separate distribution functions were used for vertical and lateral deviations to calculate the deviation probability on a cross section.

Table 4a.
Pearson correlation test on data for Code 3 aircraft under IMC.

Section	P-value	Correlation coefficient
500	0.3035	0.0287
100	0.8020	0.0070
1500	0.4452	-0.0213
2000	0.6139	0.0141
2500	0.5618	-0.0162
3000	0.7707	0.0081
3500	0.7782	0.0078
4000	0.5102	-0.0184
4500	0.5205	-0.0179
5000	0.3079	-0.0285
5500	0.6599	-0.0123
6000	0.1861	-0.0369
6500	0.1028	-0.0456
7000	0.7117	-0.0103
7500	0.9367	-0.0022
8000	0.4317	-0.0219

Table 4b.
Pearson correlation test on data for Code 3 under VMC.

Section	P-value	Correlation coefficient
500	0.1275	0.0652
100	0.8631	-0.0026
1500	0.0434	0.0309
2000	0.2306	-0.0183
2500	0.6747	0.0064
3000	0.2257	-0.0185
3500	0.1705	-0.0276
4000	0.0956	-0.0255
4500	0.7687	0.0045
5000	0.9432	-0.0010
5500	0.6005	0.0080
6000	0.1761	0.0207
6500	0.8800	-0.0023
7000	0.6200	-0.0075
7500	0.7262	0.0053
8000	0.9943	0.0001

Table 5a.

Lateral deviation distribution parameters for Code 3 aircraft under IMC.

Section	K-S dist	P-value	μ_1	μ_2	μ_3	σ_1	σ_2	σ_3	W1	W2	W3
500	0.0129	0.9820	-4	-0.50	-0.22	269	1.5	63	0.34	0.15	0.50
100	0.0116	0.9949	-29	-2	27	329	214	467	0.31	0.29	0.38
1500	0.0101	0.9994	-26	2	31	353	286	452	0.33	0.28	0.37
2000	0.0161	0.8939	-19	6	32	434	342	538	0.35	0.29	0.35
2500	0.0146	0.9458	-19	9	41	495	302	518	0.36	0.32	0.30
3000	0.0096	0.9997	-21	8	38	527	293	573	0.34	0.29	0.35
3500	0.0089	0.9999	-20	20	43	507	355	868	0.35	0.30	0.34
4000	0.0097	0.9997	-14	15	48	725	606	708	0.34	0.28	0.36
4500	0.0172	0.8422	-17	19	51	673	519	643	0.35	0.31	0.33
5000	0.0110	0.9977	-18	18	49	840	487	892	0.35	0.26	0.37
5500	0.0116	0.9949	-19	22	65	795	523	6256	0.39	0.32	0.27
6000	0.0113	0.9964	-23	22	63	891	515	878	0.34	0.31	0.33
6500	0.0102	0.9992	-28	23	633	948	480	1256	0.38	0.24	0.37
7000	0.0141	0.9605	-23	15	61	1446	905	1395	0.35	0.26	0.37
7500	0.0094	0.9998	-31	22	68	1170	770	1468	0.34	0.28	0.36
8000	0.0122	0.9908	-34	27	69	1315	1150	1888	0.34	0.30	0.35

Table 5b.

Vertical deviation distribution parameters Code 3 aircraft under IMC.

Section	K-S dist	P-value	μ_1	μ_2	μ_3	σ_1	σ_2	σ_3	W1	W2	W3
500	0.0109	0.9980	152	152	172	81	26	113	0.27	0.32	0.40
100	0.0129	0.9825	183	184	208	157	46	53	0.29	0.53	0.16
1500	0.0170	0.8529	204	213	235	161	50	87	0.21	0.62	0.15
2000	0.0180	0.8003	222	243	265	75	49	80	0.20	0.69	0.10
2500	0.0158	0.9060	252	274	274	74	36	246	0.27	0.42	0.30
3000	0.0096	0.9997	279	304	301	54	44	267	0.30	0.43	0.25
3500	0.0160	0.8949	307	333	329	49	45	215	0.36	0.34	0.29
4000	0.0146	0.9468	338	351	364	54	350	49	0.45	0.18	0.36
4500	0.0147	0.9433	361	367	389	136	33	117	0.21	0.28	0.50
5000	0.0119	0.9928	391	397	421	192	37	100	0.27	0.33	0.39
5500	0.0176	0.8187	400	425	445	52	66	151	0.08	0.45	0.45
6000	0.0107	0.9984	433	458	483	55	77	66	0.15	0.62	0.22
6500	0.0135	0.9731	463	486	498	76	51	142	0.23	0.36	0.39
7000	0.0120	0.9923	493	512	533	99	88	132	0.33	0.30	0.35
7500	0.0131	0.9803	528	548	556	232	47	197	0.46	0.25	0.28
8000	0.0200	0.6818	556	578	588	197	43	127	0.55	0.17	0.27

Table 5c.

Lateral deviation distribution parameters Code 3 aircraft under VMC.

Section	K-S dist	P-value	μ_1	μ_2	μ_3	σ_1	σ_2	σ_3	W1	W2	W3
500	0.0086	0.9071	-0.25	-0.35	-3.0	44	1.8	298	0.44	0.12	0.42
100	0.0088	0.8948	-26	1.0	32	351	303	380	0.36	0.28	0.34
1500	0.0080	0.9464	-21	11	34	371	418	575	0.35	0.28	0.35
2000	0.0072	0.9795	-21	12	38	352	271	521	0.35	0.29	0.34
2500	0.0068	0.9872	-17	14	40	445	379	619	0.34	0.29	0.35
3000	0.0053	0.9996	-18	13	44	464	331	593	0.34	0.28	0.36
3500	0.0079	0.9504	-16	16	49	483	336	592	0.34	0.28	0.37
4000	0.0056	0.9992	-15	23	51	647	448	808	0.35	0.29	0.34
4500	0.0078	0.9543	-16	19	57	684	406	716	0.35	0.28	0.36
5000	0.0067	0.9902	-21	19	55	721	442	866	0.34	0.27	0.37
5500	0.0087	0.9024	-23	21	61	808	516	877	0.34	0.30	0.34
6000	0.0067	0.9906	-23	23	65	905	578	1037	0.34	0.30	0.35
6500	0.0075	0.9693	-27	21	65	880	623	1168	0.32	0.30	0.37
7000	0.0074	0.9709	-28	23	69	1072	873	1474	0.33	0.30	0.35
7500	0.0078	0.9527	-32	28	65	1032	1113	1801	0.33	0.29	0.37
8000	0.0086	0.9082	-34	23	64	1390	1187	2241	0.30	0.26	0.42

Table 5d.

Vertical deviation distribution parameters Code aircraft under VMC.

Section	K-S dist	P-value	$\mu 1$	$\mu 2$	$\mu 3$	$\sigma 1$	$\sigma 2$	$\sigma 3$	W1	W2	W3
500	0.0110	0.6690	152	153	170	158	32	149	0.24	0.3	0.38
100	0.0109	0.6890	180	183	194	193	34	186	0.28	0.37	0.34
1500	0.0125	0.5158	192	213	223	74	39	220	0.14	0.57	0.27
2000	0.0124	0.5212	221	243	248	71	39	268	0.24	0.49	0.26
2500	0.0121	0.5554	248	272	276	50	51	313	0.30	0.48	0.20
3000	0.0127	0.4951	277	302	298	49	54	436	0.36	0.42	0.20
3500	0.0095	0.8339	307	322	332	58	493	56	0.43	0.25	0.31
4000	0.0238	0.0153	314	335	355	76	35	261	0.06	0.32	0.60
4500	0.0180	0.1243	344	365	383	59	42	294	0.10	0.31	0.57
5000	0.0185	0.1042	372	395	411	53	38	376	0.12	0.32	0.55
5500	0.0154	0.2632	400	425	437	50	48	441	0.13	0.30	0.56
6000	0.0116	0.6112	432	456	465	64	40	502	0.20	0.25	0.53
6500	0.0090	0.8759	461	487	493	63	67	689	0.28	0.31	0.40
7000	0.0133	0.4352	488	502	521	26	355	763	0.14	0.42	0.42
7500	0.0167	0.1827	513	543	564	210	421	1758	0.27	0.65	0.06
8000	0.0165	0.1939	547	582	588	218	346	2281	0.51	0.41	0.07

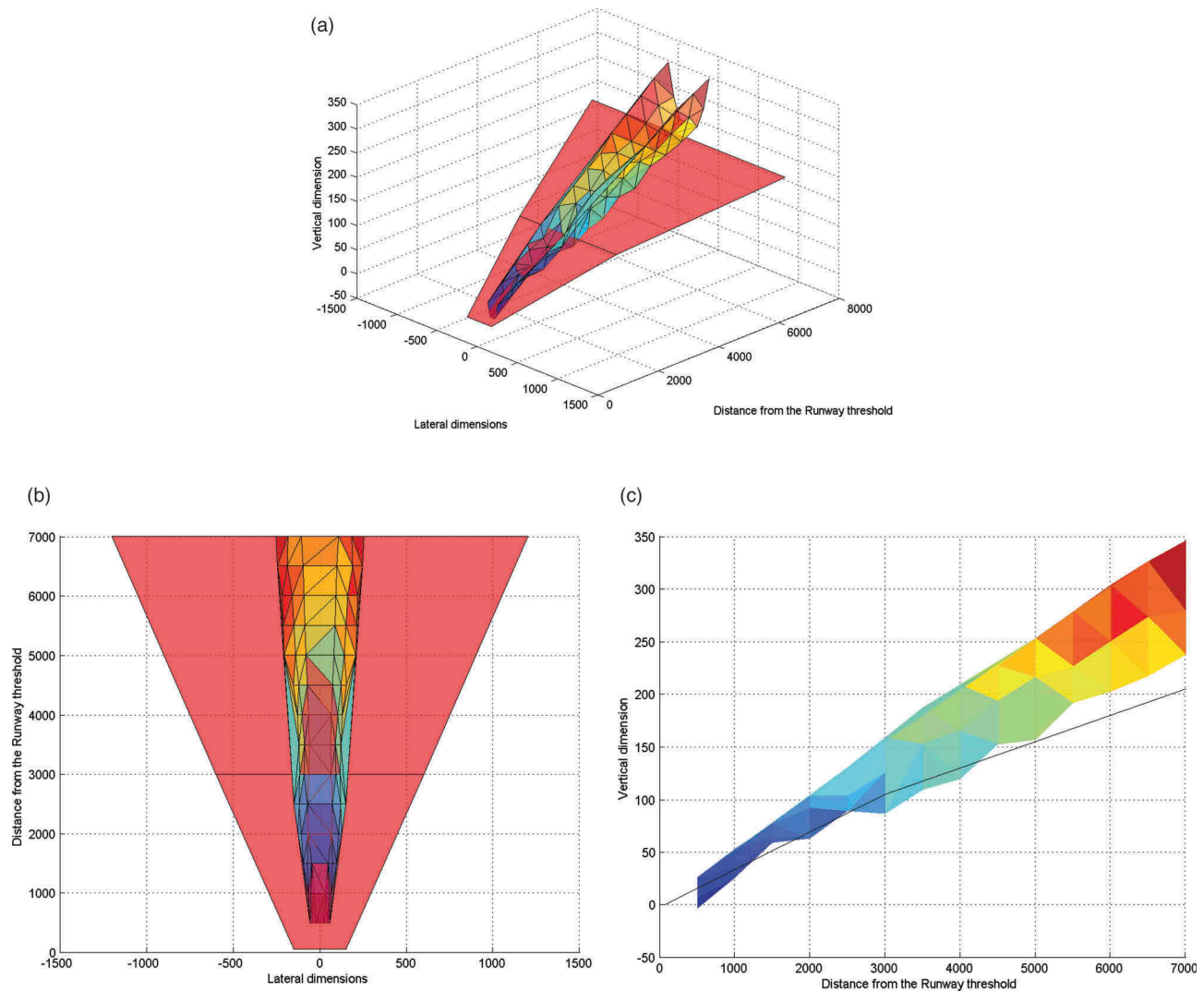


Figure 7a. 3-D view of the 10^{-7} estimated OLS surface for Code 3 IMC aircraft approaches with existing ICAO OLS surface. Figure 7b. Plan view of the 10^{-7} estimated OLS surface for Code 3 IMC aircraft approaches with existing ICAO OLS surface. Figure 7c. Profile view of the 10^{-7} estimated OLS surface for Code 3 IMC aircraft approaches with existing ICAO OLS surface.

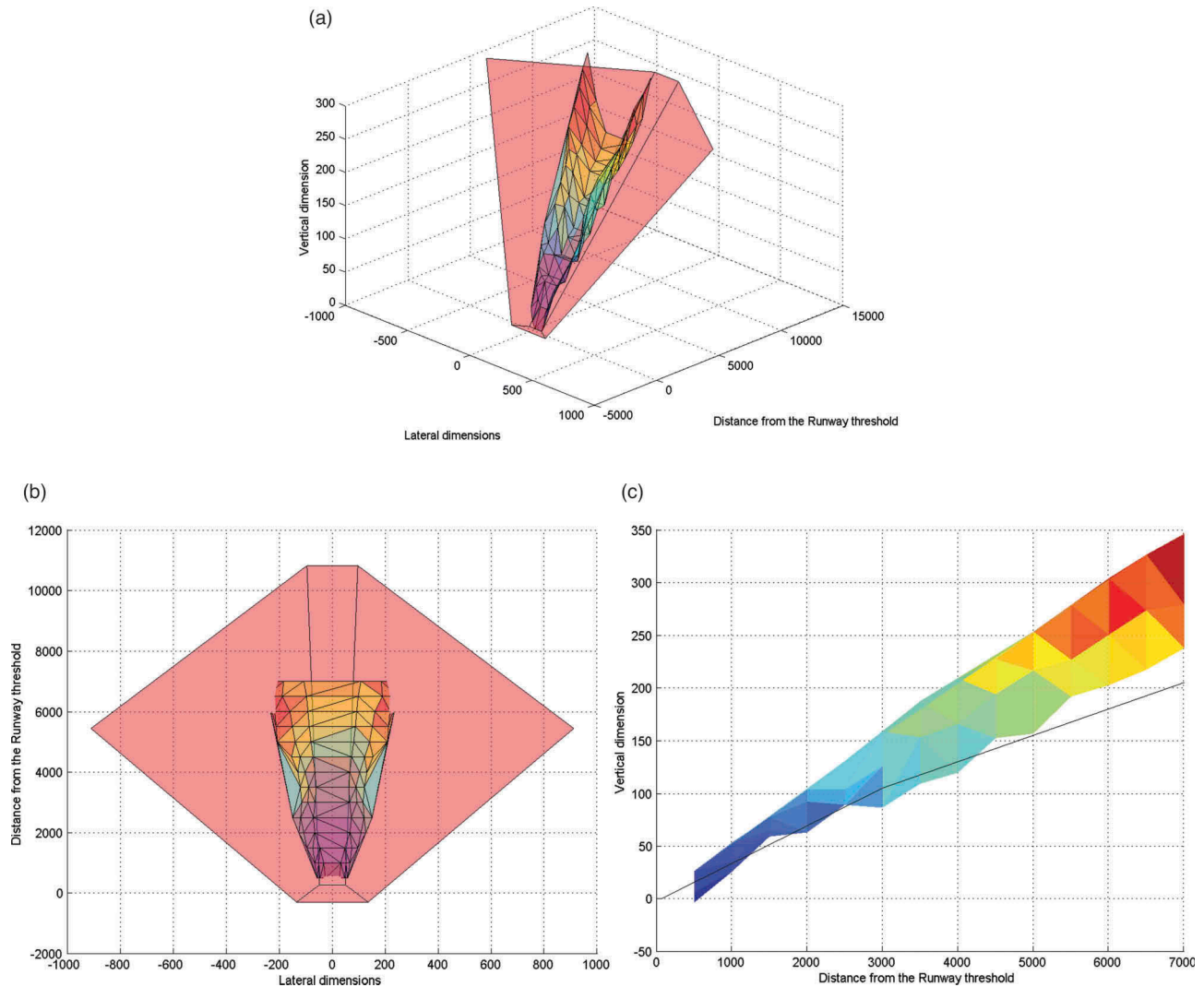


Figure 8a. 3-D view of the 10^{-7} estimated OLS surface for Code 3 IMC aircraft approaches with existing ICAO PANS-OPS surface. Figure 8b. Plan view of the 10^{-7} estimated OLS surface for Code 3 IMC aircraft approaches with existing ICAO OLS surface. Figure 8c. Profile view of the 10^{-7} estimated OLS surface for Code 3 IMC aircraft approaches with existing ICAO OLS surface.

The estimated parameters of the mixture of normal distribution and K-S goodness of fit results are shown in Table 5a-d for each meteorological condition. The estimated goodness of the fit test's p values indicates that all the models have a significant goodness of fit.

Iso-probability surfaces for IMC approaches for a 10^{-7} location probability are shown with the existing ILS and PANS-OPS surfaces in Figures 7 and 8, respectively. In this study, we assumed that IMC approaches represent instrument approaches. Therefore, the estimated surface was also compared with the PANS-OPS surface, which is specifically designed to protect instrument approaches. To estimate the dimensions of the PANS-OPS surface, it was assumed that the glide path angle is 3° , the distance between the localizer and the runway threshold is 3,000 m, and the missed approach gradient is 2.5%. The dimensions of the assumed surface were obtained from the examples

presented in the PANS-OPS standards document. Figure 9 compares the estimated surface for VMC approaches with the non-instrument surface. The plain color surfaces show the existing dimensions of the OLS/PANS-OPS, and the surfaces illustrated with multiple colors represent this study's estimated surface dimensions. The different colors of the estimated surfaces were used to show changes in the vertical dimensions and to provide a visual comparison. The estimated lateral and vertical maximum values of the surface for each cross section along the approach path are shown in Table 6a-b.

The results of the analysis show that the estimated lateral dimensions of the approach surfaces were smaller than both the Annex 14 standards and PANS-OPS standards. However, the required lateral dimensions were comparatively higher for the IMC approaches than for the VMC approaches. Moreover, the estimated surfaces indicate that

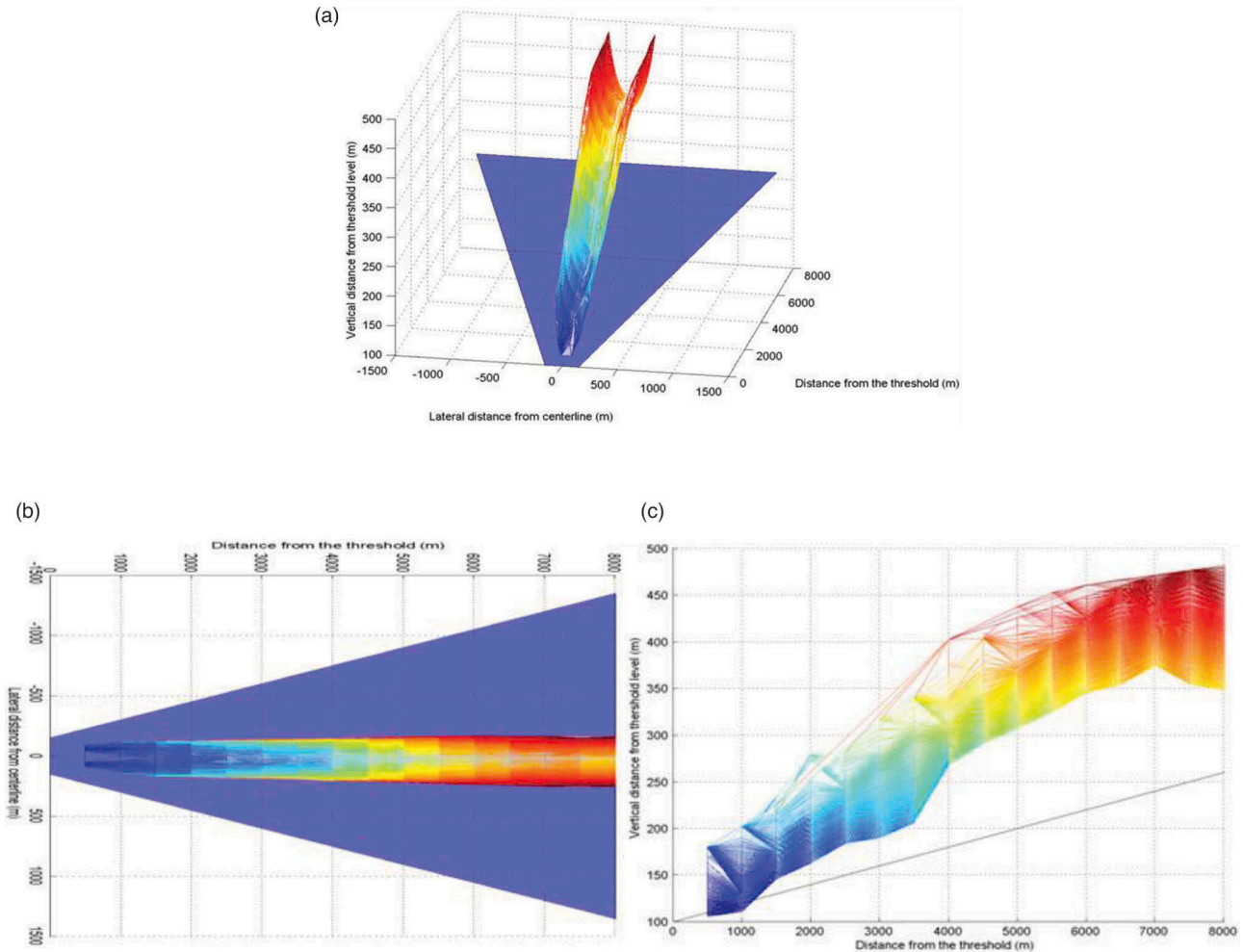


Figure 9a. 3D view of the 10^{-7} iso-probability curve for Code 3 aircraft approaches under VMC. **Figure 9b.** Plan view of the 10^{-7} iso-probability curve for Code 3 aircraft approaches under VMC. **Figure 9c.** Profile view of the 10^{-7} iso-probability curve for Code 3 aircraft approaches under VMC.

vertical dimensions of some of the approach surfaces require greater clearance than the existing surfaces in IMC operations.

It can be concluded that there has been improvement in airport navigational facilities compared with the past, which has affected the magnitude of aircraft deviation from its intended path. However, these results cannot be used to assess the effect of navigational facilities between instrument and non-instrument approaches due to the absence of approach type information. Therefore, to conduct a more detailed analysis, it is important to know the type of approach for each flight trajectory.

Furthermore the developed surface's dimensions are presented without considering the effect of aircraft geometry to its dimensions. Therefore, the wingspan length and aircraft height must be taken into account when calculating the critical OLS dimensions for an airport. As a result, aircraft types that are operated at an airport also significantly affect the OLS dimensions.

Conclusion

This paper summarizes the methodology that was used to calculate the probability of aircraft deviations from their intended path. Deviation probability functions were developed using the collected aircraft approach trajectories at CYOW. The data were extracted from the NAVTRACK software developed by Nav Canada. This study proposes a novel approach to assess the risk of OLS using actual flight path data. Most of the previous studies related to the obstacle restriction standards were developed using simulated flight paths. Those studies are not capable to represent all the factors in aircraft deviation. It is obvious that we cannot also identify all of those influence factors. However, those factors are embedded in the actual deviations measured. The same methodology can be used to develop the probability models for missed approaches and take off operations to estimate the dimensions of the take off and transitional surfaces.

Table 6a.
Comparison of estimated Code 3 IMC approach surface dimensions with ICAO ILS and PANS-OPS surface.

Section (m)	Collision probability per approach	Estimated lateral dimension (m)	Estimated vertical dimension (m)	ICAO ILS surface		ICAO PANS-OPS surface	
				Lateral dimension (m)	Vertical dimension (m)	Lateral dimension (m)	Vertical dimension (m)
500	1E-07	77.86	0	216	8.8	130	22
1000	1E-07	84.00	11.91	291	18.8	213	36.5
1500	1E-07	101.81	26.12	366	28.8	296	51
2000	1E-07	126.31	35.56	441	38.8	379	65.5
2500	1E-07	140.27	38.36	516	48.8	462	80
3000	1E-07	158.99	56.98	591	58.8	545	94.5
3500	1E-07	189.68	52.16	666	68.8	628	109
4000	1E-07	208.97	68.12	741	78.8	711	123.5
4500	1E-07	235.86	90.12	816	88.8	794	138
5000	1E-07	260.85	100.56	891	98.8	877	152.5
5500	1E-07	285.84	111.21	966	108.8	960	167
6000	1E-07	310.83	121.44	1041	118.8	1043	181.5
6500	1E-07	335.82	131.88	1116	128.8	1126	196
7000	1E-07	340.12	142.32	1191	138.8	1209	210.5

Table 6b.

Comparison of estimated Code 3 VMC approach surface dimensions with ICAO non-instrument surface.

Section (m)	Collision probability per approach	Estimated lateral dimension (m)	Estimated vertical dimension (m)	ICAO ILS surface	
				Lateral dimension (m)	Vertical dimension (m)
500	1E-07	97.81	12.15	119	14.652
1000	1E-07	99.49	50.57	169	31.302
1500	1E-07	90.33	150.36	219	47.952
2000	1E-07	95.23	160.23	269	64.602
2500	1E-07	126.18	180.63	319	81.252
3000	1E-07	135.50	185.26	369	97.902
3500	1E-07	134.90	226.23	419	114.552
4000	1E-07	142.98	270.56	469	131.202
4500	1E-07	152.78	280.12	519	147.852
5000	1E-07	162.08	312.86	569	164.502
5500	1E-07	155.03	324.23	619	181.152
6000	1E-07	160.35	338.89	669	197.802
6500	1E-07	180.17	353.55	719	214.452
7000	1E-07	199.98	368.21	769	231.102
7500	1E-07	219.80	356.19	819	247.752
8000	1E-07	239.61	350.14	869	264.402

The results of this study indicate that there is a considerable difference between dimensions of the existing ICAO ILS and PANS-OPS approach surface, and estimated surfaces that were obtained using the observed flight paths. This shows that the dimensions of existing surfaces may be overestimated as they provide higher levels of safety for aircraft operations than prescribed by ICAO. This is a desirable result at airport sites where the OLS impose no significant restrictions either to aircraft operations or to the land use in the airport's vicinity. However, if there is a restriction to aircraft operations at an airport due to obstacles that penetrate the OLS or PANS-OPS surface prescribed by the standards, this methodology can be used to check the level of safety of those operations or the risk of collisions with said obstacles. Furthermore, the goodness of fit test results indicate that models can produce statistically significant results, which is a good encouragement for future works stemming from this study. The proposed methodology will be a great help for airport expansion projects because airport owners will be able to manage their available space efficiently by assessing the level of safety of aircraft operations. Using the proposed methodology, the risk of collision with objects around the airports can be calculated. This will also be helpful for real estate developers to identify the limitations of their constructions, such as the height of the buildings. Moreover, this methodology can be used in the future to develop a computer model to estimate the risk level imposed by obstacles around the airports for both visual and instrument aircraft approaches.

The results of the study are based on the data collected from CYOW runway 07-25. For other runways and other airports, separate analyses need to be performed for different approach types to the same runway to estimate the

critical surface that should be used as the OLS. Moreover, other runways in CYOW and other airports need to be modeled to observe the effect of approach types and geographical condition on aircraft deviation from intended paths. The effect of positional error of radar tracking points in the analysis results is also acknowledged. Positional errors of tracked coordinates can impact the calculations of aircraft deviation from its intended path. According to Equations 7 and 8, the magnitude of error in deviation values (i.e., D and z) is decided by the positional accuracy of the x_i , y_i , and z_i coordinates. Therefore, it can be argued that the parameters of the deviation distributions also are dependent upon the positional accuracy of the tracked coordinates. Nevertheless, if it were possible to collect more accurate aircraft trajectories, then the effect of positional error to the analysis would be insignificant. As a result, a methodology to model the positional error would not be required.

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