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Upright Tilt Resets Dynamic Transfer Function of Baroreflex Neural Arc to Minify the Pressure Disturbance in Total Baroreflex Control

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Abstract: Maintenance of arterial pressure (AP) under orthostatic stress against gravitational fluid shift and pressure disturbance is of great importance. One of the mechanisms is that upright tilt resets steady-state baroreflex control to a higher sympathetic nerve activity (SNA). However, the dynamic feedback characteristics of the baroreflex system, a hallmark of fast-acting neural control, remain to be elucidated. In the present study, we tested the hypothesis that upright tilt resets the dynamic transfer function of the baroreflex neural arc to minify the pressure disturbance in total baroreflex control. Renal SNA and AP were recorded in ten anesthetized, vagotomized and aortic-denervated rabbits. Under baroreflex open-loop condition, isolated intracarotid sinus pressure (CSP) was changed according to a binary white noise sequence at operating pressure ± 20 mmHg, while the animal was placed supine and at 60° upright tilt. Regardless of the postures, the baroreflex neural (CSP to SNA) and peripheral (SNA to AP) arcs showed dynamic high-pass and low-pass characteristics, respectively. Upright tilt increased the transfer gain of the neural arc (resetting), decreased that of the peripheral arc, and consequently maintained the transfer characteristics of total baroreflex feedback system. A simulation study suggests that postural resetting of the neural arc would significantly increase the transfer gain of the total arc in upright position, and that in closed-loop baroreflex the resetting increases the stability of AP against pressure disturbance under orthostatic stress. In conclusion, upright tilt resets the dynamic transfer function of the baroreflex neural arc to minify the pressure disturbance in total baroreflex control.

Key words: baroreflex, blood pressure, sympathetic nervous system.

Since human beings are often under orthostatic stress, the maintenance of arterial pressure (AP) under orthostatic stress against gravitational fluid shift is of great importance. During standing, a gravitational fluid shift directed toward the lower part of the body would cause severe postural hypotension if not counteracted by compensatory mechanisms [1]. Arterial baroreflex has been considered to be the major compensatory mechanism [1–3], since denervation of baroreceptor afferents causes profound postural hypotension [4].

The baroreflex system consists of two subsystems: the neural arc that represents the input-output relationship between baroreceptor pressure and sympathetic nerve activity (SNA), and the peripheral arc that represents the relationship between SNA and systemic AP. Recently, we investigated the steady-state functional structure of these systems under orthostatic stress [5], and reported that upright tilt shifted the baroreflex peripheral arc to a lower AP for a given SNA. However, upright tilt reset the baroreflex neural arc to a higher steady state SNA. The resetting compensated for the blunted responsiveness of the peripheral arc and contributed to prevent postural hypotension [5].

In addition to the steady state characteristics [6, 7], the dynamic characteristics are other hallmark of the baroreflex system. It is because the system is a fast-acting neural control that quickly negative-feedback controls and stabilises AP against pressure disturbance in contrast to the slow-acting hormonal and humoral systems [8]. Earlier studies reported that the dynamic characteristics in supine position have a high-pass (fast) neural arc that may compensate for the low-pass (slow) peripheral arc to achieve rapid and stable AP regulation [8]. The importance of the dynamic characteristics in AP control increases under orthostatic stress that can cause postural hypotension. However, little is known about the dynamic characteristics of the baroreflex system in upright posture.

Because the gravitational body fluid shift decreases the effective circulatory blood volume [1, 9], we speculated that upright tilt may attenuate the dynamic transfer function from SNA to AP in the baroreflex peripheral arc.

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Moreover, if the upright tilt resets the dynamic characteristics of the neural arc in addition to resetting the steady state SNA reported previously [5], it would compensate for a blunted pressor response of the baroreflex peripheral arc and contribute to maintain the stability and quickness of the total baroreflex system. Accordingly, we hypothesized that upright tilt resets dynamic transfer function of baroreflex neural arc to minify the pressure disturbance in total baroreflex control.

In the present study, we identified the transfer functions of two baroreflex subsystems (the neural and peripheral arcs) separately in 60° upright posture, while opening the baroreflex negative feedback loop by vascular isolation of carotid sinus regions [8]. In addition, by connecting the subsystem transfer functions in series and closing them, we investigated the dynamic transfer characteristics and the stability against pressure disturbance of total baroreflex arc system in upright posture.

MATERIAL AND METHODS

Animals were cared for in strict accordance with the Guiding Principles for the Care and Use of Animals in the Field of Physiological Science approved by the Physiological Society of Japan. Ten Japanese white rabbits weighing 2.4–3.3 kg were initially anesthetized by intravenous injection (2 ml/kg) of a mixture of urethane (250 mg/ml) and α-chloralose (40 mg/ml). Anesthesia was maintained by continuously infusing the anaesthetics at a rate of 0.33 ml/kg/h using a syringe pump (CFV-3200, Nihon Kohden, Tokyo). The rabbits were mechanically ventilated with oxygen-enriched room air. Bilateral carotid sinuses were isolated vascularly from systemic circulation by ligating the internal and external carotid arteries and other small branches originating from the carotid sinus regions. The isolated carotid sinuses were filled with warmed physiological saline pre-equilibrated with atmospheric air, through catheters inserted via the common carotid arteries. Intra-carotid sinus pressure (CSP) was controlled by a servo-controlled piston pump (model ET-126A, Labworks; Costa Mesa, CA). Bilateral vagal and aortic depressor nerves were sectioned in the middle of the neck region to eliminate reflexes from the cardiopulmonary region and the aortic arch. Systemic AP was measured using a high-fidelity pressure transducer (Millar Instruments; Houston, TX) inserted retrograde from the right common carotid artery below the isolated carotid sinus region. Body temperature was maintained at around 38ºC with a heating pad.

The left renal sympathetic nerve was exposed retroperitoneally. A pair of stainless steel wire electrodes (Bioflex wire AS633, Cooner Wire) was attached to the nerve to record renal SNA. The nerve fibers peripheral to electrodes were ligated securely and crushed to eliminate afferent signals. The nerve and electrodes were covered with a mixture of silicone gel (Silicon Low Viscosity, KWIK-SIL, World Precision Instrument, Inc., FL) to insulate and immobilize the electrodes. The preamplified SNA signal was band-pass filtered at 150–1,000 Hz. The nerve signal was full-wave rectified and low-pass filtered with a cutoff frequency of 30 Hz to quantify the nerve activity.

Protocols. Both protocols 1 and 2 were performed on each of eight animals. After the surgical preparation, the animal was maintained supine (0°) on a tilt bed. To stabilize the posture, the head was fixed full-frontal to the bed by strings, and the body and legs were rigged up in a clothes-like bag. Before performing protocols 1 and 2, we confirmed that the nerve activity measured in supine position was SNA. CSP was decreased stepwise from 100 mmHg to 40 mmHg in decrements of 20 mmHg, and then increased stepwise to 100 mmHg in increments of 20 mmHg. Each pressure step was maintained for 60 s. In all animals, a decrease in CSP increased SNA, whereas an increase in CSP decreased SNA (Fig. 1), indicating that the nerve activity recorded was SNA.

Protocol 1: The animal was placed supine. CSP was firstly matched with systemic AP to obtain the operating AP under the baroreflex closed-loop condition. After at least 5 minutes of stabilization, the SNA and AP were recorded for 10 min to obtain closed-loop baseline values. The data were stored on the hard disk of a dedicated laboratory computer system for analysis at a sampling rate of 200 Hz using a 12-bit analog-to-digital converter. The averaged AP over 10 min was defined as the operating AP in

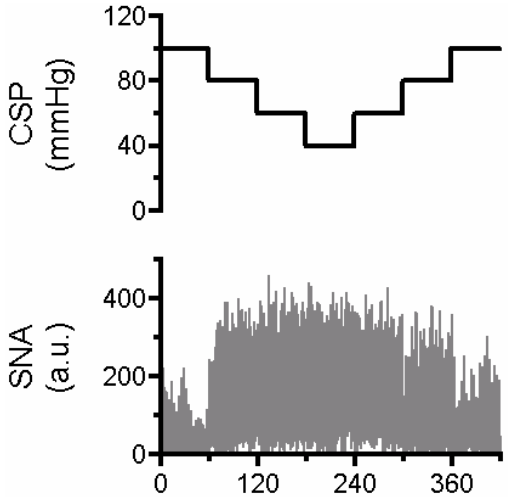

Fig. 1. Representative data of one rabbit in supine position, showing time series of carotid sinus pressure (CSP) and sympathetic nerve activity (SNA). CSP was decreased stepwise from 100 mmHg to 40 mmHg in decrements of 20 mmHg, and then increased stepwise to 100 mmHg in increments of 20 mmHg. Each pressure step was maintained for 60 s. A decrease in CSP increased SNA, whereas an increase in CSP decreased SNA, indicating that the nerve activity recorded was SNA. a.u., arbitrary unit.

supine position. Then, after at least 5 min of stabilization, CSP was randomly changed by 20 mmHg above or below the operating AP every 500 ms according to a binary white noise sequence for which the input power spectrum of CSP was reasonably flat up to 1 Hz [10]. The variables were recorded for a 10-min period and stored.

Protocol 2: CSP was firstly matched with systemic AP via a servo-controlled piston pump to obtain the actual operating pressure under baroreflex closed-loop conditions in supine and 60° upright postures. The animal was maintained supine for 10 min, and then tilted upright to 60° within 10 s by inclining the tilt bed to 60° and dropping the lower regions of the rabbit with the fulcrum set at the level of the carotid sinus. The 60° upright posture was maintained for 10 min for stabilization. Since the clothes-like bag stabilized the posture of the animal, there was no additional mechanical movement that reduced the quality of measurements. The position of the head remained almost fixed during the tilt to minimize vestibular stimulation. Thereafter, the average AP over the next 10 min was defined as the operating AP in upright tilt position. Then, after at least 5 min of stabilization, CSP was randomly changed according to a white noise sequence for 10 min as in protocol 1.

Data analysis. SNA signals were normalized by the following steps. First, the post-mortem noise level was assigned 0 arbitrary unit (a.u.). Second, SNA signals during the 10-min closed-loop baseline recording in protocol 1 (supine position) were averaged over 1 min, and assigned 100 a.u. Finally, the other SNA signals in all protocols were normalized to these values.

In both protocols 1 and 2, the transfer functions (gain and phase) and coherence function were calculated from CSP input to SNA in the baroreflex neural arc and from SNA input to AP in the baroreflex peripheral arc. The signals of CSP, SNA and AP were resampled at 10 Hz and segmented into 10 sets of 50% overlapping bins of 2^{10} data point each. The segment length was 102.4 s, which yielded the lowest frequency bound of 0.01 (0.0097) Hz. We subtracted a linear trend and applied a Hanning window for each segment. We then performed fast Fourier transform to obtain frequency spectra of the variables. We ensemble averaged the input power [$Sxx(f)$], output power [$Syy(f)$], and cross power between them [$Syx(f)$] over the 10 segments. Thereafter, we calculated the transfer function [$H(f)$] from input to output signals as follows,

$$H(f) = \frac{Syx(f)}{Sxx(f)}$$

To quantify the linear dependence between input to output signals in the frequency domain, we calculated the magnitude-squared coherence function [$Coh(f)$] as follows:

$$Coh(f) = \frac{|Syx(f)|^2}{Sxx(f)Syy(f)}$$

The coherence value ranges from zero to unity. Unity coherence indicates a perfect linear dependence between input and output signals, whereas zero coherence indicates total independence of these two signals.

Statistic analysis. All data are presented as means ± SD. Effects of upright tilt on baroreflex parameters were evaluated by repeated-measures analysis of variance. When the main effect was found to be significant, post hoc multiple comparisons were done using the Scheff's F-test to compare baroreflex controls between the supine and upright postures [11]. Differences were considered significant when $P < 0.05$.

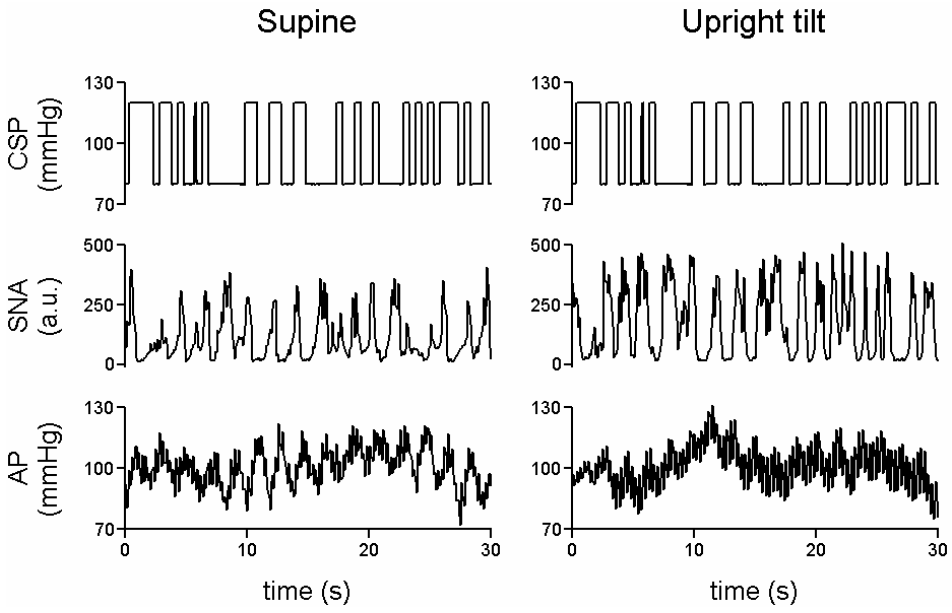

Fig. 2. Representative data of one rabbit in supine (left panels) and 60° upright tilt (right panels) positions, showing time series of carotid sinus pressure (CSP), sympathetic nerve activity (SNA) and systemic arterial pressure (AP) during CSP perturbation. CSP was changed according to a binary white noise signal with a switching interval of 500 ms. a.u., arbitrary unit.

RESULTS

Figure 2 shows the typical time series of CSP, SNA and AP derived in supine and 60° upright tilt positions in individual animal. CSP was perturbed according to a binary white noise sequence at 500-ms intervals. In both positions, SNA increased and decreased roughly in response to the decrease and increase in CSP, respectively. However, the SNA responses appeared higher in the upright tilt than in the supine position. Data from all animals (n = 8) showed that the upright tilt increased the averaged SNA (175 ± 21 a.u.) during CSP perturbation compared with the supine position (96 ± 13 a.u.). Averaged AP during CSP perturbation was similar in supine (96 ± 13 mmHg) and in upright positions (103 ± 15 mmHg).

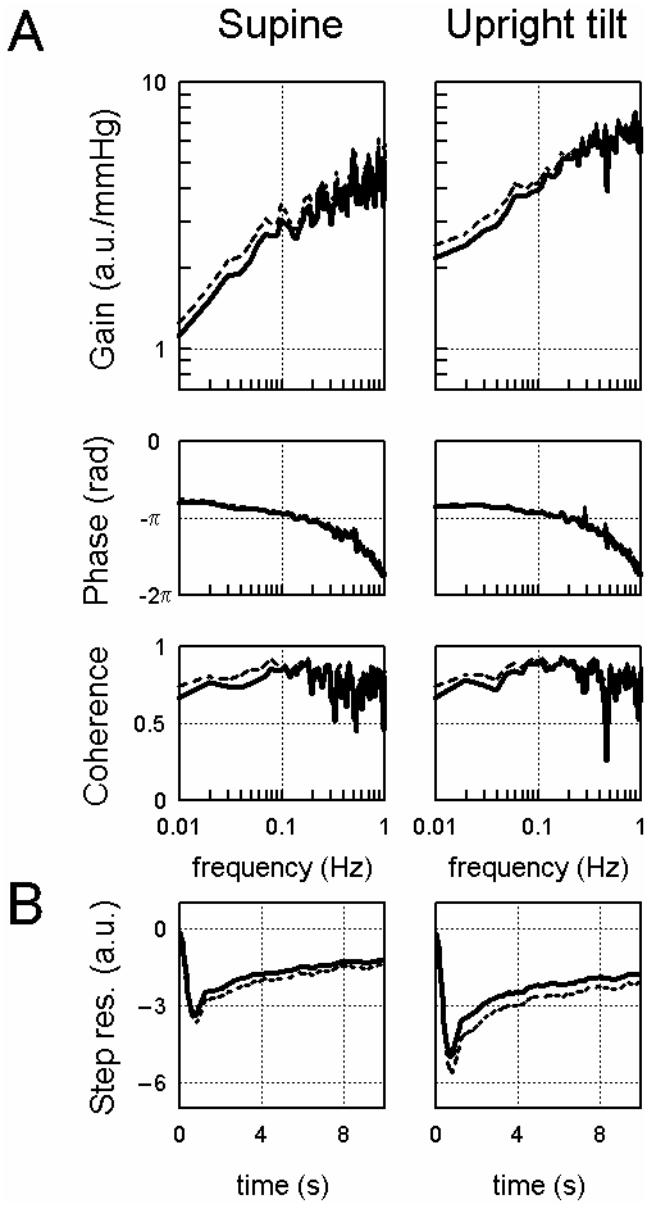

Fig. 3. A: The transfer function of the baroreflex neural arc from CSP to SNA averaged from all animals (n = 8) in supine (left panels) and 60° upright tilt (right panels) positions. The gain plots (top), phase plots (middle), and coherence function (bottom) are shown. Upright tilt increases the gain. **B**: Step responses (Step res.) derived from the transfer function corresponding to the transfer function shown in A. Upright tilt enhances the initial and steady-state responses. Solid line represents the mean values, and dashed line represents mean + SD in A and mean – SD in B. a.u., arbitrary unit.

The baroreflex neural arc

Figure 3A shows the transfer function of baroreflex neural arc from CSP to SNA averaged from all animals. In both supine and upright tilt positions, the transfer gain increased as the frequency of CSP perturbation increased for the frequency range of 0.01 to 1 Hz. This shows dynamic high-pass characteristics, indicating that more rapid change of CSP results in greater response of SNA. Note that upright tilt increased the transfer gain for the whole frequency range observed (Table 1). In addition, upright tilt decreased the slope of gain increase. In both positions, the phase approached slightly above –π radians at the lowest frequency reflecting negative feedback characters, and lagged as the frequency of CSP perturbation increased. The coherence was over 0.7 for the frequency range of 0.01 to 0.2 Hz. Upright tilt did not affect the phase or coherence. Figure 3B shows the step response of SNA corresponding to the transfer function shown in Fig. 3A. In both positions, the SNA response consisted of an initial decrease followed by partial recovery and then a steady state. Of note, upright tilt enhanced the initial decrease by 50%, and also decreased the steady-state SNA.

Table 1. Transfer function of baroreflex neural arc (from CSP to SNA) in supine and upright tilt positions.

	Supine	Upright tilt
Gain (a.u./mmHg)		
0.01 Hz	1.11 ± 0.13	2.14 ± 0.41*
0.1 Hz	2.75 ± 0.43	4.63 ± 0.52*
0.3 Hz	3.69 ± 0.30	5.08 ± 0.42*
Phase (rad)		
0.01 Hz	–2.51 ± 0.15	–2.66 ± 0.09
0.1 Hz	–2.96 ± 0.08	–2.93 ± 0.06
0.3 Hz	–3.58 ± 0.14	–3.53 ± 0.12
Coherence		
0.01 Hz	0.67 ± 0.08	0.67 ± 0.07
0.1 Hz	0.84 ± 0.04	0.89 ± 0.02
0.3 Hz	0.77 ± 0.06	0.82 ± 0.03
Slope (dB/decade)		
0.01 Hz to 0.3 Hz	7.0 ± 0.4	5.1 ± 0.5*
Step response (a.u.)		
Initial response	–3.41 ± 0.21	–4.99 ± 0.62*
Steady-state level	–1.26 ± 0.18	–1.80 ± 0.32*

Values are mean ± SD (n =10). *P < 0.05; supine position vs. upright tilt.

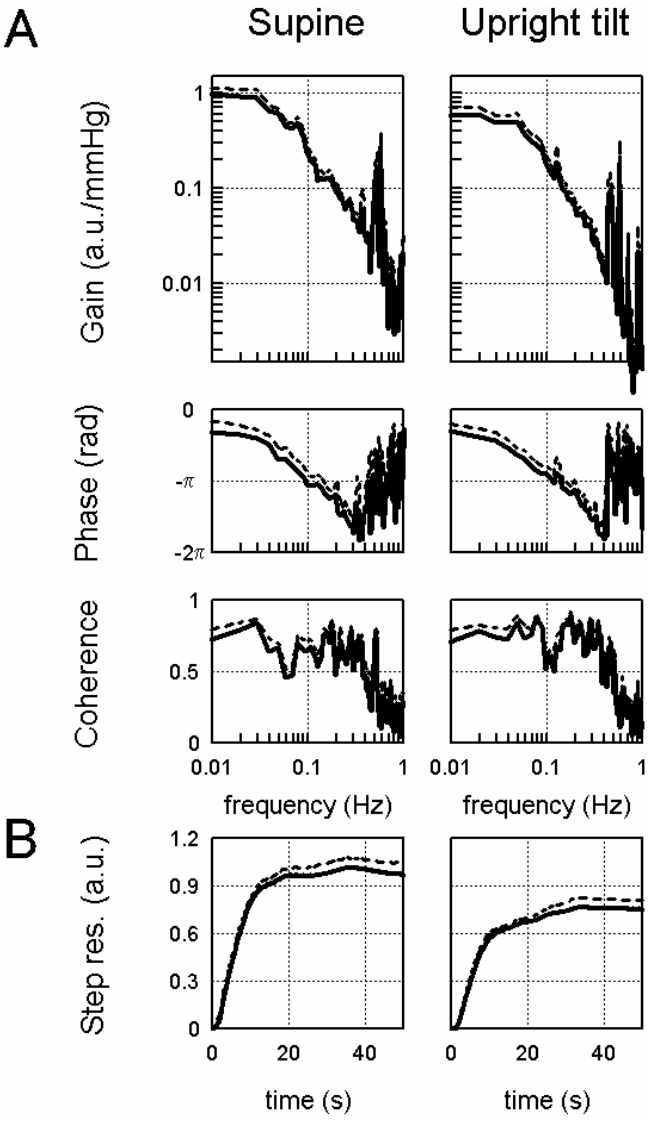

Fig. 4. A: The transfer function of the baroreflex peripheral arc from SNA to AP averaged from all animals (n = 8) in supine (left panels) and 60° upright tilt (right panels) positions. The gain plots (top), phase plots (middle), and coherence function (bottom) are shown. Upright tilt decreases the gain below the frequency of 0.1 Hz. **B**: Step responses (Step res.) derived from the transfer function corresponding to the transfer function shown in A. Upright tilt attenuates the response. Solid and dashed lines represent the mean and mean + SD values, respectively. a.u., arbitrary unit.

Table 2. Transfer function of baroreflex peripheral arc (from SNA to AP) in supine and upright tilt positions.

	Supine	Upright tilt
Gain (mmHg/au)		
0.01 Hz	0.97 ± 0.09	0.63 ± 0.06*
0.1 Hz	0.23 ± 0.03	0.15 ± 0.03*
0.3 Hz	0.04 ± 0.006	0.03 ± 0.003
Phase (rad)		
0.01 Hz	–0.79 ± 0.16	–0.69 ± 0.07
0.1 Hz	–2.83 ± 0.14	–2.58 ± 0.15
0.3 Hz	–4.74 ± 0.18	–4.63 ± 0.08
Coherence		
0.01 Hz	0.72 ± 0.07	0.71 ± 0.03
0.1 Hz	0.64 ± 0.08	0.62 ± 0.04
0.3 Hz	0.61 ± 0.08	0.68 ± 0.02
Step response (mmHg)		
Steady-state level	–0.97 ± 0.06	–0.75 ± 0.06*

Values are mean ± SD (n =10). *P < 0.05; supine position vs. upright tilt.

The baroreflex peripheral arc

Figure 4A shows the transfer function of the baroreflex peripheral arc from SNA to AP averaged from all animals. In both supine and upright tilt positions, the transfer gain decreased as the input frequency increased for the frequency range of 0.01 to 1 Hz, indicating low-pass characteristics. Upright tilt decreased the transfer gain between 0.01 and 0.1 Hz (Table 2). In both positions, the phase approached zero radian at the lowest frequency reflecting an increase in SNA with increased AP, and lagged as the input frequency increased. The coherence was over 0.5 for the frequency range of 0.01 to 1 Hz. Upright tilt did not affect the phase or coherence. Figure 4B shows the step response of AP corresponding to the transfer function shown in Fig. 4A. In both positions, the AP response increased gradually to reach a steady state. Upright tilt decreased the steady-state AP.

The total baroreflex arc

Figure 5A shows the transfer function of the total baroreflex arc from CSP to AP averaged from all animals. In both supine and upright tilt positions, the transfer gain decreased as the input frequency increased for the frequency range from 0.01 to 1 Hz, indicating low-pass characteristics. Upright tilt did not affect the transfer gain (Table 3). In both positions, the phase approached –π radians at the lowest frequency reflecting negative feedback attained by the total baroreflex loop, and lagged as the input frequency increased. The coherence was over 0.5 for the frequency range from 0.01 to 0.2 Hz. Upright tilt did not affect the phase or coherence. Figure 5B shows the step response of AP corresponding to the transfer function shown in Fig. 5A. In both positions, the AP response increased gradually to reach a steady state. Upright tilt did not affect the step response.

The right column of Table 3 shows a simulation of the total arc transfer function in the absence of resetting in the neural arc. The simulation was based on the neural arc transfer function in supine position and the peripheral arc transfer function in upright tilt position. Without the resetting, the upright tilt would decrease the transfer function gain and would attenuate the step response of AP at steady state, compared with the values in supine position and those in upright tilt position with resetting.

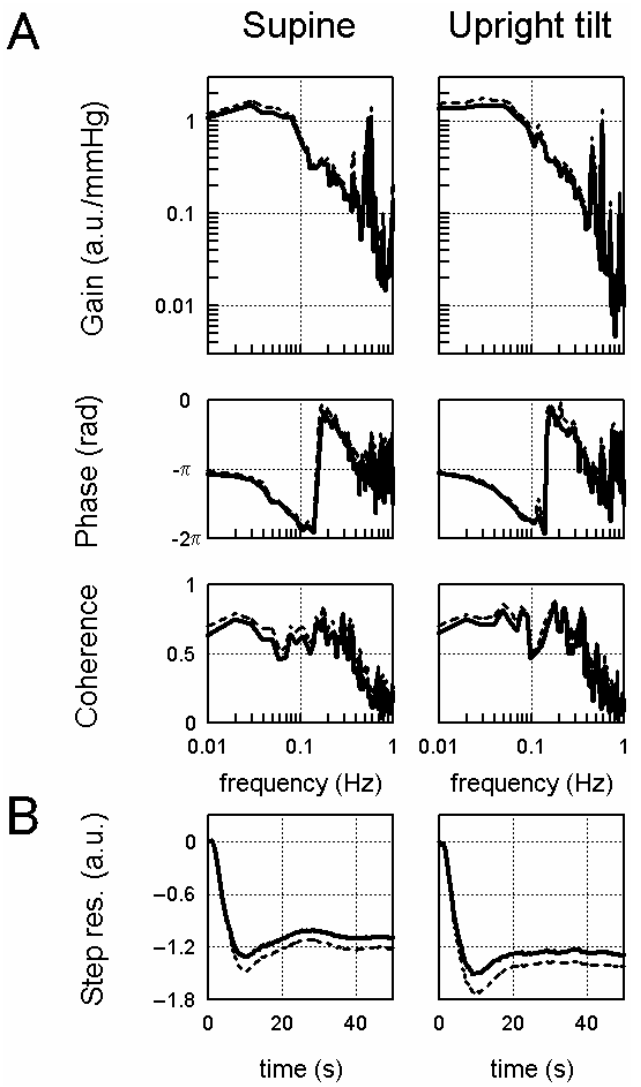

Fig. 5. A: The transfer function of the total baroreflex arc from CSP to AP averaged from all animals (n = 8) in supine (left panels) and 60° upright tilt (right panels) positions. The gain plots (top), phase plots (middle), and coherence function (bottom) are shown. **B**: Step responses (Step res.) derived from the transfer function corresponding to the transfer function shown in A. The transfer function and step response are similar in the supine and upright tilt positions. Solid and dashed lines represent the mean and mean + SD values in A and mean – SD values in B, respectively. a.u., arbitrary unit.

DISCUSSION

Arterial baroreflex is obviously a pivotal mechanism for maintaining AP under orthostatic stress against gravitational fluid shift and pressure disturbance [1, 2, 4], but the baroreflex function and its modulation in upright position are not fully understood. We previously reported that 60° upright tilt resets the steady-state characteristics of the baroreflex neural arc to a higher SNA [5]. However, the dynamic characteristics of the baroreflex system, which is a hallmark of fast-acting neural systems, in upright posture remain to be elucidated. Accordingly, in the present study, we identified the transfer function of the total baroreflex system and its two subsystems. The new major findings are that a 60° upright tilt increases the transfer gain of the baroreflex neural arc (CSP to SNA), decreases the transfer gain of the peripheral arc (SNA to AP), and as a result maintains the dynamic characteristics of the total baroreflex feedback system. These findings support our hypothesis that upright tilt resets dynamic transfer function of baroreflex neural arc to minify the pressure disturbance in total baroreflex control. These results were not affected by the order of postures, since returning the ani-

Table 3. Transfer function of total baroreflex arc (from CSP to AP) in supine, upright tilt and simulated upright tilt positions.

	Supine	Upright tilt	Simulated upright tilt without resetting of the neural arc
Gain (a.u./mmHg)			
0.01 Hz	1.10 ± 0.12	1.38 ± 0.18	0.71 ± 0.18*#
0.1 Hz	0.63 ± 0.09	0.69 ± 0.12	0.41 ± 0.13*#
0.3 Hz	0.15 ± 0.03	0.15 ± 0.03	0.11 ± 0.04*
Phase (rad)			
0.01 Hz	–3.33 ± 0.11	–3.29 ± 0.07	–3.21 ± 0.10
0.1 Hz	–5.76 ± 0.20	–5.55 ± 0.10	–5.51 ± 0.15
0.3 Hz	–1.98 ± 0.25	–1.87 ± 0.23	–1.91 ± 0.24
Coherence			
0.01 Hz	0.63 ± 0.06	0.65 ± 0.05	
0.1 Hz	0.60 ± 0.10	0.61 ± 0.06	
0.3 Hz	0.53 ± 0.07	0.55 ± 0.04	
Step response (mmHg)			
Steady-state level	–1.09 ± 0.11	–1.29 ± 0.12	–0.67 ± 0.11*#

Simulated transfer function in the absence of neural arc resetting is calculated from the neural arc transfer function in supine position and the peripheral arc transfer function in upright tilt position. Values are mean ± SD (n =10). *P < 0.05; supine vs. simulated upright tilt, #P < 0.05; upright tilt vs. simulated upright tilt.

mal posture from 60° upright tilt to horizontal supine position restored the transfer functions to the magnitudes observed in the initial supine position (data not shown).

Little is known about the arterial baroreflex feedback system under orthostatic stress. Although earlier studies investigated the gains of baroreflex control of SNA [12–14], vascular resistance [15] and R-R interval [16], these gains are parts of the total baroreflex system, and thus are insufficient to explain the dynamics of the total arc of the baroreflex feedback system. In addition, no study has examined the phase function of baroreflex in the subsystems and the total system. Moreover, while earlier studies addressed baroreflex in relation to AP regulation under orthostatic stress, most of them evaluated the baroreflex in supine, and not orthostatic posture [14]. In the present study, we identified the transfer functions of the two baroreflex subsystems (the neural and peripheral arcs) in upright posture independently using the baroreflex open-loop technique. Moreover, by connecting the subsystem transfer functions in series and closing them, we revealed the dynamic characteristics of the total baroreflex arc.

Our actual and simulation data indicated that resetting of the baroreflex neural arc in upright posture increases the transfer function gain of the total baroreflex arc. In our experiments, the 60° upright tilt reset and nearly doubled the transfer gain of the neural arc. Although the upright tilt decreased the transfer gain of the peripheral arc, resetting in the neural arc counteracted it and consequently preserved the dynamic transfer gain of the total baroreflex arc (1.4, Table 3). In a simulation of a situation where resetting in the neural arc is absent (Table 3), a 60° upright tilt would decrease the total arc transfer gain. These findings suggest that resetting of the neural arc (that is, baroreflex control of SNA) with dynamic characteristics plays an im-

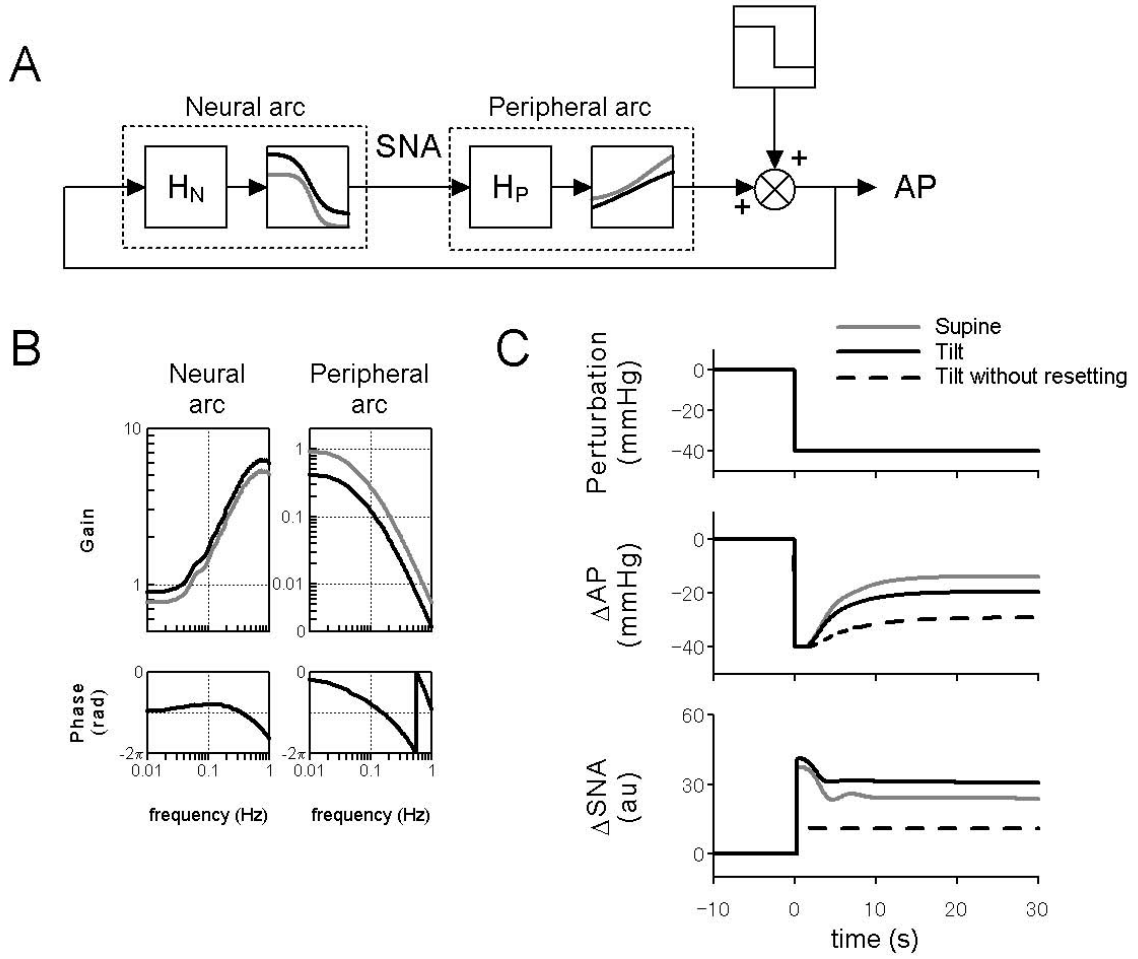

Fig. 6. A: Simulator of the baroreflex system during upright tilt. A stepwise perturbation was applied to the baroreflex negative feedback system (see APPENDIX for details). H_N, neural arc transfer function; H_P, peripheral arc transfer function. Nonlinear sigmoidal functions in the supine and upright tilt positions are shown by gray and black lines, respectively. **B**: Simulation results of integrated dynamic transfer function of linear-sigmoidal nonlinear cascade model in the neural (AP to SNA) and peripheral (SNA to AP) arcs in the supine (gray lines) and upright tilt (black lines) positions. **C**: Simulation results of a closed-loop AP and SNA responses to the stepwise pressure perturbation (–40 mmHg). The resetting during upright tilt (black line) would enhance SNA excitation as compared with the supine position (gray line) to minify a hypotension. Without the resetting in upright tilt, SNA responses would largely be attenuated to lead a hypotension.

portant role to maintain the dynamic transfer function of the total baroreflex system in upright posture.

A simulation of AP stability by baroreflex feedback control against pressure disturbance clearly suggests the importance of resetting of baroreflex neural arc in upright posture. Figure 6 shows the simulation of closed-loop baroreflex control of AP, when pressure disturbance was loaded to the peripheral cardiovascular compartment. According to an earlier study [17], we used the linear-sigmoidal nonlinear cascade model (Fig. 6A) to simulate the baroreflex dynamics. The result of simulation (Fig. 6B) was consistent with our in vivo findings that an upright tilt increased the dynamic transfer gain of the neural arc and decreased the dynamic gain of the peripheral arc. The simulation (Fig. 6C) shows that the baroreflex feedback system would minify the pressure disturbance (40 mmHg) by 50% or more in supine (14 mmHg) and upright tilt (19 mmHg) positions. However, without the resetting of the neural arc in upright tilt, the residual pressure disturbance (29 mmHg) would persist and the velocity of pressure response would become slower (Fig. 6C). These findings suggest that dynamic resetting of the neural arc increases the stability and quickness in response of orthostatic AP against pressure disturbance in closed-loop condition of the total baroreflex arc. In addition, the simulation indicates that the resetting would enhance increases in SNA in response to pressure disturbance in upright tilt compared to supine position (Fig. 6C). Without the resetting in upright tilt, the SNA response would be greatly attenuated (Fig. 6C). This suggests that resetting of the neural arc has a critical role in activating SNA appropriately to prevent hypotension by pressure disturbance during orthostatic stress.

Some explanations for the changes in baroreflex peripheral arc in upright tilt posture may be postulated. First, since the gravitational fluid shift toward the lower part of body (i.e., abdominal vascular bed, lower limbs) during upright posture decreases the preload and effective circulatory blood volume [1, 9], it may attenuate the dynamic transfer function from SNA to AP. Our actual data revealed that upright tilt decreased the transfer gain, but not the transfer phase, of the baroreflex peripheral arc (Fig. 4A). Therefore, upright tilt would blunt the magnitude of AP response to SNA without delaying the response, as shown in the calculated step response (Fig. 4B). Next, increases in humoral factors (i.e., catecholamine, angiotensin II) during upright posture could reduce the dependency of vascular resistance on neural control. However, intravenous infusion of angiotensin II did not affect the transfer function of baroreflex peripheral arc [18]. Moreover, intravenous infusion of catecholamine had no effects on the transfer function from sympathetic stimulation to heart rate [19]. These studies are consistent with the predominance of sympathetic neural control on cardiovascular pressor function [20].

Limitations

The present study has several limitations. First, we excluded the efferent effect of vagally mediated arterial and cardiopulmonary baroreflexes that may affect baroreflex control of SNA. Second, we used an anesthetic agent that may attenuate the baroreflex peripheral arc by reducing the cardiac pumping function, and may affect the neural arc gain. Third, since we sectioned the aortic depressor nerves to open the baroreflex feedback loop, the total baroreflex gain may be lower than the physiological level. Fourth, since we measured only renal SNA, our findings have limited applicability to other SNA. Although static [10, 21] and dynamic [21] regulation of the baroreflex neural arc is similar in renal, cardiac and muscle (vasoconstrictor) SNAs in supine posture, whether this holds true during orthostatic stress remains to be verified.

Lastly, we used rabbits that are quadrupeds. Since humans spend most of their time in nearly 90° upright postures whereas rabbits do not, our findings have limited applicability to humans. However, Japanese White rabbits spend most of their time in 10–40° head-up postures, and frequently stand up to nearly 70°. Since the denervation of both carotid and aortic arterial baroreflexes is known to cause severe postural hypotension at 60° upright tilt in quadrupeds [4], this suggests that even in quadrupeds, arterial baroreflex has a very important function in the maintenance of AP under orthostatic stress. Accordingly, despite the difference in species, our findings may reflect, at least, the qualitative aspects of orthostatic baroreflex physiology in humans. Indeed, recent human studies have suggested that orthostatic stress (lower body negative pressure) enhances the SNA response to AP change [22, 23] and increases baroreflex control of SNA (assessed by the relation between spontaneous changes in diastolic AP and SNA) [12] under baroreflex closed-loop condition.

In conclusion, the transfer function identified in baroreflex open-loop condition showed that 60° upright tilt increases the transfer gain of the baroreflex neural arc, decreases the transfer gain of the peripheral arc, and as a result maintains the dynamic characteristics of the total baroreflex feedback system. Simulation study suggests that resetting of the neural arc increases the transfer gain of the total baroreflex arc and also increases the stability of orthostatic AP against pressure disturbance. These findings suggest that upright tilt resets the dynamic transfer function of the baroreflex neural arc to maintain total baroreflex stability.

APPENDIX

To simulate the closed-loop AP response to stepwise pressure perturbation (Fig. 6), we used the linear-sigmoidal nonlinear cascade model [17].

We modeled the sigmoidal nonlinearity in the baroreflex neural arc by a four-parameter logistic function with

threshold according to our previous study [5] using the following equation:

$$y = \frac{P_1}{1+\exp[P_2(x-P_3)]} + P_4$$

where x and y are input (in mmHg) and output (in au) values. P_1 denotes the response range (in a.u.), P_2 is the coefficient of gain, P_3 is the midpoint of the input range (in mmHg), P_4 is the minimum output value of the symmetric sigmoid curve (in a.u.). We set $P_1 = 94$, $P_2 = 0.10$, $P_3 = 109$, $P_4 = 4$ in the supine position, and $P_1 = 112$, $P_2 = 0.09$, $P_3 = 109$, $P_4 = 29$ during upright tilt, according to our previous study [5].

The sigmoidal nonlinearity in the peripheral arc was modeled by a four-parameter logistic function using the following equation:

$$z = \frac{Q_1}{1+\exp[Q_2(y-Q_3)]} + Q_4$$

where y and z are input (in a.u.) and output (in mmHg) values. Q_1 denotes the response range (in mmHg), Q_2 is the coefficient of gain, Q_3 is the midpoint of the input range (in a.u.), and Q_4 is the minimum output value (in mmHg). We set $Q_1 = 115$, $Q_2 = -0.04$, $Q_3 = 63$, $Q_4 = 50$ in the supine position, and $Q_1 = 82$, $Q_2 = -0.05$, $Q_3 = 88$, $Q_4 = 50$ during upright tilt, according to our previous study [5].

In rabbits, the transfer function of the baroreflex neural arc (baroreceptor pressure to SNA) approximates derivative characteristics in the frequency range below 0.8 Hz, and high-cut characteristics of frequencies above 0.8 Hz [17]. Therefore, according to our previous study [17], we modeled the neural arc transfer function (H_N) using the following equation:

$$H_N(f) = -K_N \frac{1+\frac{f}{f_{c1}}j}{\left(1+\frac{f}{f_{c2}}\right)^2}\exp(-2\pi fjL)$$

where f and j represent the frequency (in Hz) and imaginary units, respectively; K_N is static gain (in a.u./mmHg); f_{c1} and f_{c2} ($fc_1 < f_{c2}$) are corner frequencies (in Hz) for derivative and high-cut characteristics, respectively; and L is a pure delay (in s) that would represent the sum of delays in the synaptic transmission through the baroreflex central pathways and the sympathetic ganglion. The dynamic gain increases in the frequency range of f_{c1} to f_{c2}, and decreases above f_{c2}. In simulations showed in Fig. 6, we matched K_N to the actual data in the supine and upright tilt positions in this study. We also set f_{c1}, f_{c2} and L at 0.05, 0.8 and 0.2, respectively, according to the present and previous studies [17].

In addition, the transfer function of the baroreflex peripheral arc (SNA to AP) approximates a second-order low-pass filter with the dead time as follows:

$$H_P(f) = K_P \frac{1}{1+2\varsigma\frac{f}{f_N}j-\left(\frac{f}{f_N}\right)^2}\exp(-2\pi fjL)$$

where f_N and ζ are the neutral frequency (in Hz) and damping ratio, respectively; and L is a pure delay (in s). In simulations showed in Fig. 6, we matched K_P to the actual data in the supine and upright tilt positions in this study. We also set f_N, ζ and L at 0.07, 1.4 and 1.0, respectively, according to the present and previous studies [17].

The input amplitude of the stepwise pressure perturbation was –40 mmHg (Fig. 5, A and C, top panel). The closed-loop AP (Fig. 5C, middle panel) and SNA (Fig. 5C, bottom panel) responses were simulated up to 30 s.

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