Numerical Modeling Studies of The Dissolution-Diffusion-Convection Process During CO2 Storage in Saline Aquifers

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Abstract

For purposes of geologic storage, CO2 would be injected into saline formations at supercritical temperature and pressure conditions, and would form a separate phase that is immiscible with the aqueous phase (brine). At typical subsurface temperature and pressure conditions, supercritical CO2 (scCO2) has lower density than the aqueous phase and would experience an upward buoyancy force. Accordingly, the CO2 is expected to accumulate beneath the caprock at the top of the permeable interval, and could escape from the storage formation wherever (sub-)vertical pathways are available, such as fractures or faults through the caprock, or improperly abandoned wells. Over time, an increasing fraction of CO2 may dissolve in the aqueous phase, and eventually some of the aqueous CO2 may react with rock minerals to form poorly soluble carbonates. Dissolution into the aqueous phase and eventual sequestration as carbonates are highly desirable processes as they would increase permanence and security of storage. Dissolution of CO2 will establish phase equilibrium locally between the overlying CO2 plume and the aqueous phase beneath. If the aqueous phase were immobile, CO2 dissolution would be limited by the rate at which molecular diffusion can remove dissolved CO2 from the interface between CO2-rich and aqueous phases. This is a slow process. However, dissolution of CO2 is accompanied by a small increase in the density of the aqueous phase, creating a negative buoyancy force that can give rise to downward convection of CO2-rich brine, which in turn can greatly accelerate CO2 dissolution. This study explores the process of dissolution-diffusion-convection (DDC), using high-resolution numerical simulation. We find that geometric features of convection patterns are very sensitive to small changes in problem specifications, reflecting self-enhancing feedbacks and the chaotic nature of the process. Total CO2 dissolution rates on the other hand are found to be quite robust against modest changes in problem parameters, and are essentially constant as long as no dissolved CO2 reaches the lower boundary of the system.

1. Introduction

CO2 injected into a saline aquifer can be stored in four different modes, (1) as a (mobile) separate supercritical phase, for simplicity here referred to as "free gas," (2) as trapped gas, (3) dissolved in the aqueous phase, and (4) as solid minerals (IPCC, 2005). At early times during a CO2 storage project, most of the injected CO2 will be present as free gas, but over time there is a continuous progression from storage mode (1) to (2), (3) and (4) (IPCC, 2005; Audigane et al., 2007). The quantitative aspects of this progression - the amounts of CO2 and the time scales involved - are of great interest, because storage security and permanence of storage increase as CO2 is first trapped, then dissolves, and eventually chemically binds to solid phases.

At typical subsurface conditions of interest, CO2 is less dense than the aqueous phase, and will therefore tend to rise to the top of the permeable formation into which it is injected. This "gravity override" may cause much of the available pore space to be bypassed, reducing storage capacity relative to what would be obtained in a uniform sweep (Nordbotten and Celia, 2006). CO2 accumulating beneath a caprock can access potential pathways for upward leakage, such as fracture zones and faults. CO2 will dissolve into the underlying aqueous phase, and will then be transported by molecular diffusion away from the interface between the two-phase (gas-aqueous) zone above into the single-phase aqueous zone below. Dissolution of CO2 will increase the density of the aqueous phase by a small amount that, depending on salinity, may range from 0.1 - 1 % (Fig. 1). The density increase is gravitationally unstable, and can give rise to downward convection of CO2-ladden water from the phase boundary. Such buoyant convection may greatly accelerate the rate at which CO2 is dissolved and removed from the overlying gas.

Because of its practical importance for CO2 storage, the process of dissolution-diffusion-convection (DDC) has been studied by many investigators. Here we make reference to selected studies that are of particular relevance to the present work. The earliest work that pointed out the significance of aqueous-phase density increase due to CO2 dissolution in the context of CO2 storage is by Weir and collaborators (Weir et al., 1995, 1996). Lindeberg and Bergmo (2003) addressed DDC and associated multi-scale resolution problems in the context of numerical simulations of the Sleipner Vest CO2 storage project in the Norwegian sector of the North Sea.
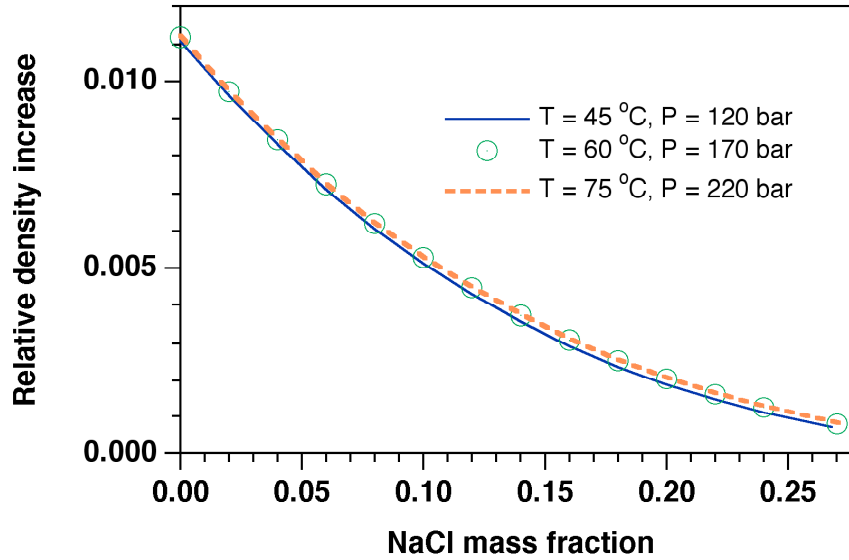
Figure 1. Relative density increase of sodium chloride brines due to dissolution of CO2, for typical temperature and pressure conditions encountered at storage depths from 1,000 - 2,000 m. The data were computed from correlations coded in the ECO2N fluid property module for the TOUGH2 simulator (Pruess and Spycher, 2007; Pruess, 2004).

Studies focusing on stability analyses for onset time for convection, preferred wavelength for growth of convective fingers, and growth rates were presented by Ennis-King et al. (2003a, b; 2005), Hesse et al. (2006), Riaz et al. (2006), Xu et al. (2006) and others. Convection induced by CO2 dissolution has similarities to thermally-buoyant convection, as driven by geothermal temperature gradients, and the extensive literature in that field (e.g. Garg and Kassoy, 1981) has helped understanding of convection induced by CO2 dissolution. There are important differences as well, the principal one being the prevalence of a constant (geothermal) temperature gradient as initial condition for thermal convection. This contrasts with the CO2 dissolution problem, in which there is no significant pre-existing gradient of dissolved aqueous CO2, making the system unconditionally unstable with respect to buoyant convection.

In the references cited above, the authors also present numerical simulations to complement and partially confirm analytical stability theory. Hesse et al. (2006) performed high-resolution simulations for extended time periods, and found that total CO2 dissolution rate is

constant during the convection-dominated period, apart from random fluctuations due to the chaotic nature of the underlying processes. Ennis-King et al. (2008) compared DDC for homogeneous media with simulations for heterogeneous media, that featured a random distribution of shale bodies in a homogeneous sand background. Recently, laboratory studies are being conducted that have confirmed qualitative and quantitative aspects of DDC (Yang and Gu, 2006; Kneafsey and Pruess, 2008).

This study explores quantitative aspects of CO2 dissolution. The DDC process begins on small spatial scales and, after convection is initiated, continually grows to eventually encompass the entire permeable interval. We employ high-resolution numerical simulation to examine the onset of convective activity, and the rate at which this process removes CO2 from the dissolution boundary. A first goal of our work is to achieve realistic numerical simulations of the DDC process, in which space and time are resolved on the actual scale of the governing diffusive and convective processes. A further goal, not addressed in this report, will be the design of sub-grid-scale discretization methods that can achieve a satisfactory representation of the processes in a field-scale modeling approach. In the context of this goal, we are primarily interested in CO2 dissolution rates for systems whose vertical thickness H is large in comparison to the thickness L_{inc} of the diffusive boundary layer at onset of instability, $H >> L_{inc}$. We focus on the earlier portion of the convective period, before convection is affected by the presence of a lower boundary. It is expected that late-stage convection, and systems with vertical thickness $H \approx L_{inc}$, can be treated adequately with the fairly coarse spatial resolutions that would be commonly employed in field-scale models.

2. Molecular Diffusion

Stability analysis has shown that, in the early stages, DDC is entirely dominated by molecular diffusion (Ennis-King and Paterson, 2003a, b). For a boundary concentration (CO2 mass fraction) X_0, applied at time t = 0 to a homogeneous domain with initial concentration X = 0, the concentration profile away from the boundary is given by the appropriate solution of the diffusion equation $\partial X / \partial t = D \partial^2 X / \partial t^2$ (Carslaw and Jaeger, 1959),

$$X(z,t) \quad = \quad X_0 \, \text{erfc}(u) \tag{1}$$

where $u = z/2\sqrt{Dt}$ is the similarity variable for the diffusion process, with z the distance from the top boundary (measured positive downward), t the time, and D the diffusivity. erfc(u) denotes the complementary error function, expressed in terms of the error function

$$\mathrm{erf}(u) \quad = \quad \frac{2}{\sqrt{\pi}} \int_{0}^{u} \exp\left(-\xi^2\right) d\xi \tag{2}$$

as erfc(u) = 1 - erf(u). The thickness of the diffusive boundary layer can be estimated as $\Delta z = \sqrt{Dt}$, although it must be kept in mind that the diffusive profile is very broad, and significant non-zero concentrations extend beyond $\sqrt{Dt}$ (see below). In some cases $2\sqrt{Dt}$ may be a better measure of the diffusive boundary layer, but for simplicity we will generally use $\sqrt{Dt}$. A finite "incubation time" t_{inc} must elapse before convection is initiated, estimated from linear stability analysis by Ennis-King and Paterson (2003a, b) as

$$t_{inc} \quad = \quad c_0 \frac{\mu^2 \phi^2 D}{(\Delta\rho)^2 g^2 k^2} \tag{3}$$

Here, μ is the fluid viscosity, $\Delta\rho$ the density increase due to CO2 dissolution, ϕ is porosity, k permeability, and g acceleration of gravity. c_0 is a numerical constant that was estimated as $c_0 \approx$ 180 based on the critical Rayleigh number for onset of convective instability, while from numerical simulations a value of c_0 = 80-100 was obtained (Ennis-King and Paterson, 2003b). Our simulations yield much larger values of $c_0 > 1,000$, see below. The thickness of the diffusive boundary layer at the onset time t_{inc} of convective activity is given by

$$L_{inc} \quad = \quad \sqrt{Dt_{inc}} \quad = \quad \sqrt{c_0} \frac{\mu\phi D}{(\Delta\rho)gk} \tag{4}$$

From the expression for diffusive flux,

$$F(z,t) = -\phi\rho D\frac{\partial X}{\partial z} = \phi\rho X_0\sqrt{\frac{D}{\pi t}}\exp\left(-\frac{z^2}{4Dt}\right) \tag{5}$$

the rate of CO2 uptake at the dissolution boundary ($z = 0$), per unit cross-sectional area, can be written as

$$F(z=0,t) = F(t) = \phi\rho X_0\sqrt{D/\pi t} \tag{6}$$

Substituting Eq. (3) into Eq. (6), we obtain the diffusive flux at the onset time of convection as

$$F(z=0,t_{inc}) = \frac{X_0\rho\,\Delta\rho g k}{\mu\sqrt{\pi c_0}} \tag{7}$$

indicating that this flux is independent of porosity and diffusivity. The total dissolved CO2 inventory accumulated after time t per unit cross-sectional area can be obtained by integrating Eq. (6) to yield

$$M(t) = 2\phi\rho X_0\sqrt{\frac{Dt}{\pi}} \tag{8}$$

Eqs. (6, 8) imply that, for a purely diffusive process, the quantity F.M will be a constant, independent of time

$$F\cdot M = F(t)\cdot M(t) = \dot{M}M = \frac{1}{2}\frac{d}{dt}(M^2) = \frac{2}{\pi}\phi^2\rho^2 X_0^2 D \tag{9}$$

As will be discussed below, F.M grows approximately linearly with time for a convective process, providing a sensitive measure for the convective onset time t_{inc}.

Of interest is the total solute inventory per unit cross-sectional area at time t in the interval (0, z). By integrating Eq. (1), the fraction of total solute inventory in the interval $0 \le u \le z/2\sqrt{Dt}$ can be written as

$$f \quad = \quad \frac{M(u)}{M(\infty)} \quad = \quad \sqrt{\pi} \int_{0}^{u} \text{erfc}(x)\, dx \tag{10}$$

where we have used $\int_{0}^{\infty} \text{erfc}(x)\, dx = 1/\sqrt{\pi}$ (Carslaw and Jaeger, 1959). From the formulas and tabulations provided by Carslaw and Jaeger (1959), Table 1 gives the relative concentrations C = X/X_0 and fractional solute inventory for two commonly employed measures of diffusive penetration.

Table 1. Relative concentrations and fractional solute inventory in a diffusive profile.

similarity variable u	distance z	relative concentration C	fractional inventory f
0.5	$\sqrt{Dt}$	0.4795	0.6461
1.0	$2\sqrt{Dt}$	0.1573	0.9109

3. Numerical Simulations

3.1 Approach

CO2 injected into a saline aquifer is buoyant, and will tend to migrate towards the top of the permeable formation, as schematically shown in Fig. 2. In the present study we do not address the full field-scale problem; instead, we focus on a vertical cross section beneath the two-phase zone. The upper boundary of the single-phase aqueous region remains at saturated CO2 concentrations, due to the overlying free supercritical CO2 phase. This is modeled by maintaining a small free gas saturation at the top boundary of the flow domain (see Fig. 3).
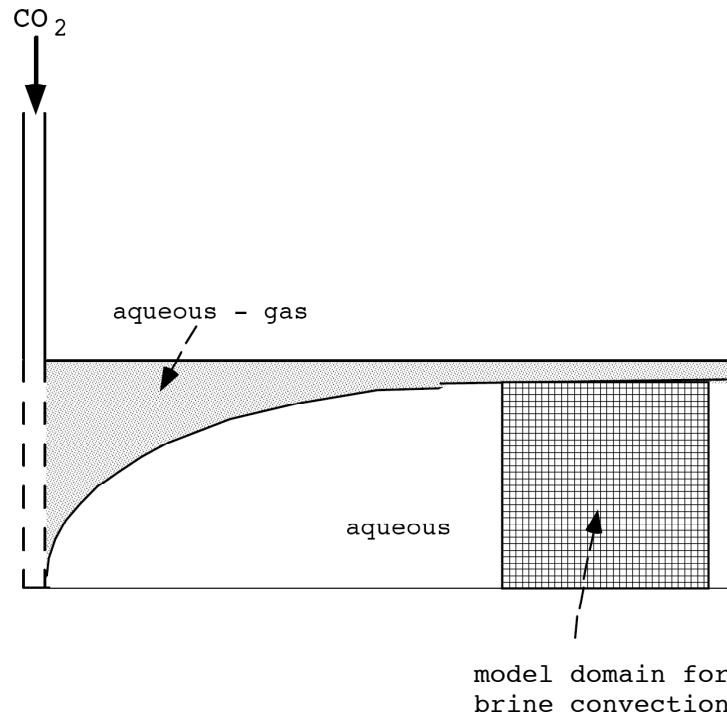
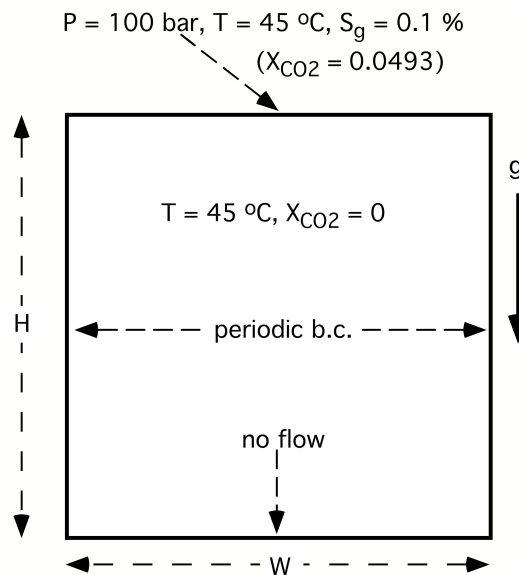Figure 2. Schematic of phase distributions around a CO2 injection well.

Figure 3. Schematic of specifications used for numerical simulations. Different heights H and widths W were employed for the simulation domain. Periodic boundary conditions on the left and right are explained in the text.

Dissolved CO2 will be removed from the interface between the two-phase zone above and single-phase aqueous conditions below by molecular diffusion at early times, and additionally by convective transport at times $t > t_{inc}$. Dissolved concentration in the interface is maintained constant due to contact with the overlying gas phase; therefore, the rate at which CO2 is transported into the single-phase aqueous region is equal to the rate at which CO2 dissolves at the phase boundary. The CO2 dissolution rate per unit "footprint area" of the reservoir is the most important quantity characterizing the DDC process, and in our simulations is computed as (space-averaged) CO2 flux across the top boundary of the model. We also employ other "integral" measures of the DDC process, including onset time of convection t_{inc}, and the growth of total dissolved CO2 inventory over time.

The flow system is initialized in gravity equilibrium (hydrostatic pressure gradient) relative to the top boundary. For the simulation of the CO2 dissolution-diffusion-convection process, we suppress advection of CO2-ladden water from the top boundary. The porous medium is assumed homogeneous, but a random variation of permeabilities with an amplitude of $\pm 1 \%$ is superimposed to seed the convective activity. The sensitivity of DDC to different random seeds is explored. Isothermal conditions are assumed throughout. In order to avoid unphysical effects from the limited size of the domain modeled, we apply "periodic" boundary conditions at the lateral edges. This is accomplished by connecting the grid blocks on the right hand side with those on the left hand side in Fig. 3, which is tantamount to "rolling up" the section about a vertical axis so that the right and left boundaries touch, in effect modeling flow on the mantle of a cylinder instead of in a rectangle. The bottom boundary is usually modeled as "no flow." The vertical extent of the domain limits the time for which the convective activity can be modeled before effects of the lower boundary will be felt. Some variations in boundary conditions, domain size, and space discretization were explored, in order to study the sensitivity of system behavior to these parameters.

We neglect chemical reactions, so that dissolved CO2 acts as a conservative solute tracer. Our initial numerical simulations were done with TOUGH2/ECO2N, which includes an accurate representation of thermophysical properties of mixtures of NaCl brine and CO2 (Pruess, 2004; Pruess and Spycher, 2007). TOUGH2/ECO2N represents the fluid as a 3-component mixture of

H2O, NaCl, and CO2. For conditions limited to a single aqueous phase, a more efficient calculation can be accomplished with TOUGH2/EOS7, in which the fluid is represented as a two-component mixture of H2O and brine; the latter being used to represent density changes in the aqueous phase from CO2 dissolution. Numerical work is approximately proportional to NEQ^2, where NEQ is the number of equations per grid block. Accordingly, a given problem can be solved with EOS7 (NEQ = 2) in less than half the time required with ECO2N (NEQ = 3). Test calculations have confirmed excellent agreement between simulations using EOS7 and ECO2N.

In order to achieve calculations with "sufficient" spatial resolution (see below) for domains of reasonable size, and over "reasonable" time scales, we use a parallelized version of TOUGH2 running on a dual-quad core PC (Wu et al., 2002; Zhang et al., 2008). In performing a parallel simulation, the TOUGH2-MP code first subdivides a simulation domain, defined by a TOUGH2 grid, into a number of subdomains by using the partitioning algorithm from the METIS software package (Karypsis and Kumar, 1998). The parallel code then relies on the MPI (Message-Passing Interface; Message Passing Forum, 1994) for its parallel implementation. Parallel simulations are run as multiple processes on several or many processors simultaneously. Each process involves calculations for one portion of the simulation domain to update thermophysical properties, assemble mass and energy balance equations, solve linear equation systems, and perform other local computations. The local linear equation systems are solved in parallel as multiple processes with the Aztec linear solver package (Tuminaro et al., 1999). When running TOUGH2-MP on multi-core PCs, or massively-parallel supercomputers, we normally would associate each processor (core or CPU) with one process. However, test calculations showed that in many cases super-linear speedup could be achieved, due to large efficiency gains for the linear equation solution when the flow domain is partitioned into a larger number of smaller subdomains (Zhang et al., 2007). This can make it advantageous to define a larger number of processes than are available as hardware processors. The simulations presented here were performed an a Dell T5400 dual quad core computer with a total of 8 cores, and in most cases 16 processes were run (two per processor), as this was found to reduce total execution time compared to running 8 processes. Depending on grid resolution and simulation time, individual runs typically took from 1/2 to 4 hours.

3.2 Space Discretization

Evolution and interaction of flow and transport over a broad range of space and time scales is an essential part of the problem studied here. We have not attempted any formal analysis of the space and time truncation errors associated with limitations in spatial and temporal resolution, because the convective behavior is subject to self-enhancing instabilities, is chaotic in nature (Kimura et al., 1986), and cannot be tackled with conventional concepts of "grid convergence" and "time truncation stability." We have followed a heuristic approach, performing numerical experiments with different grid resolution and time step controls, and comparing and contrasting observed system behavior with variability arising from variations in problem specifications (e.g., boundary conditions, and random seeding of permeability heterogeneity). Grid resolution is deemed adequate when gradients of dissolved CO2 concentrations are resolved, and "integral" measures of the CO2 transport process are stabilized. This can be judged from the outcome of our numerical simulation experiments. As will be seen below, "integral" measures of the DDC process, such as total CO2 dissolution rate at a phase boundary, tend to be rather robust, with respect to variations in both numerical discretization and overall parameter specifications of the flow system. This is an encouraging result, as it is the total CO2 dissolution rates that are of primary interest in connection with permanence and security of CO2 storage.

The early-time diffusive behavior can provide useful guidance for the spatial resolution required in space-discretized numerical models to be able to resolve the concentration gradients that drive the process. Depending primarily on formation permeability (see Eq. 3), incubation times for onset of convection in field systems may range from 10^5 to 10^9 s or more (1 day to 30 years; Ennis-King et al., 2005). For a nominal effective aqueous diffusivity of 10^{-9} m^2/s of dissolved CO2, these times correspond to a diffusive boundary layer thickness L_{inc} in the range of 0.01 - 0.3 m, necessitating mm- to cm-level space discretization near the top (dissolution) boundary. Similar arguments can be made to estimate the thickness, and associated space discretization requirements, of the diffusive halo that will evolve as convective "fingers" or "tongues" proceed downward.

Space resolution requirements can also be considered in the context of the likely practical needs for accuracy and time resolution of field-scale models of CO2 storage systems. During the active (injection) phase, which may last of the order of 30 years, "reasonable" accuracy will be demanded on a 1-year time scale, in turn requiring temporal resolution of order 1 month. For a diffusive process with diffusivity of order 10^{-9} m^2/s, the corresponding penetration depth is 5 cm. Convective processes can cover comparable or larger distance. From Darcy's law, volumetric flux associated with buoyancy flow for typical parameters applicable to CO2 storage (see Table 2) can be estimated as $u = (k/\mu)(\Delta\rho g/2) \approx 10^5 k$, corresponding to pore velocities $v = u/\phi$ in the range of 1 - 100 m/yr for permeabilities of 10^{-13} - 10^{-11} m^2. Propagation distances per month will then be 0.1 - 10 m.

The convective activity initiated after the onset time t_{inc} increases the rate at which solute is transported away from the boundary. Such an increase is possible only if the diffusive boundary layer becomes thinner on average after time t_{inc} has elapsed. In fact, while downward convection of CO2-ladden water will transport water with larger dissolved concentrations to greater depth, a concomitant upward convection of water low in CO2 will be induced, that will reduce the thickness of the diffusive boundary layer locally, and will promote increased rates of diffusive removal of solute from the upper boundary. These considerations suggest a critical role of convectively-induced concentration changes for mass transport in the diffusive boundary layer, suggesting that space discretization requirements there are likely to be more severe than estimated for a diffusion-only process. From a practical viewpoint, if grid sizes are to be limited to 10^5 grid blocks or less and relevant gradients are to be resolved properly, analysis of a high-permeability system ($k = 10^{-11}$ m^2) in 2-D is limited to a domain size of order 1 m, while for a system with a lower permeability of $k = 10^{-13}$ m^2, an order of magnitude larger scale can be modeled.

Away from the top boundary, it may not be necessary to fully resolve convective processes in order to get a reasonable approximation to field-scale behavior. Indeed, the overall rate of convective flow in a given region depends mainly on the total solute inventory in that region, and only weakly on the manner in which the solute is distributed. Accordingly, it may be possible to model overall convection rates with reasonable accuracy, even if individual

convective tongues are poorly resolved. Space resolution requirements are more stringent for solute transport, which is governed by a hyperbolic PDE, than for overall aqueous phase flow, which is governed by a PDE that is parabolic or even elliptic (if aqueous phase is assumed incompressible). Errors arising in transport simulations with coarse gridding in the main flow direction (vertical) will be subject to some self-compensation over extended time periods, with solute breakthrough curves (BTCs) at a given horizon more dispersed for coarse grids, but approaching the same cumulative solute flow at later times. The dispersion length is given by the applied grid spacing h.

We now present numerical simulations for two sets of parameters, a "high-permeability" Case 1 ($k = 10^{-11}$ m^2 $\approx$ 10 D), and a "moderate permeability" Case 2 ($k = 10^{-13}$ m^2 $\approx$ 100 mD); in both cases, permeability is assumed isotropic. In presenting results we will emphasize total CO2 flux at the top boundary of the flow domain; as had been noted above, this quantity is numerically equal to the rate at which CO2 is dissolved. Here and in the following we always refer CO2 dissolution rates and dissolved inventories to 1 m^2 of footprint area. This makes results for different-size model domains directly comparable, and allows quantities to be easily scaled for CO2 plume areas of interest.

4. Results for Case 1 (high-k, small scale)

This case uses a large formation permeability of 10^{-11} m^2 (10 Darcy), as may be appropriate for well-sorted sands, and also for typical laboratory sandpacks. Problem specifications are given in Table 2. Due to the large permeability, time scales and thickness of the diffusive boundary layer are shifted to small values, see Eqs. (3, 4). Fig. 4a shows results for CO2 flux from the top boundary, which is equal to total CO2 dissolution rate per unit area. This and subsequent simulations used a random number seed of 0.8. At early times, CO2 inventory shows the characteristic $\sqrt{t}$ dependence for diffusion (Fig. 4b). The data shown in Fig. 4 were obtained with two different levels of vertical discretization, using either a uniform grid resolution of h = 10 mm, or a grid that near the top boundary is refined to h = 1 mm. Horizontal grid resolution is 10 mm. It is seen that the coarser grid initially underestimates and later overestimates diffusive flux. Agreement with the analytically computed diffusive flux is good from about 1.1 - 1.4x10^5 s, and subsequently simulated fluxes become larger, reflecting increased

Table 2. Parameters used for Case 1 simulations.

Fluid properties	
temperature	$T = 45 \,^{\circ}C$
pressure	$P = 100$ bar
salinity	$X_s = 0$
dissolved CO2 concentration	$X = 0$
viscosity	$\mu = 0.5947 \times 10^{-3}$ Pa-s
water density	$\rho = 994.56$ kg/m^3
dissolved CO_2 mass fraction at the top boundary	$X_0 = 0.049306$
density increase of aq. phase from CO_2 dissolution	$\Delta\rho = 10.45$ kg/m^3
diffusivity	$D = 2 \times 10^{-9}$ m^2/s
Formation properties	
porosity	$\phi = 0.3$
permeability	$k = 10^{-11}$ m^2
Model domain	
height	$H = 5$ m
width	$W = 1$ m

(a)   (b)

Figure 4. CO2 flux from the top boundary (a) and CO2 inventory (b).

CO2 uptake due to convective activity. The simulation with a finer vertical grid resolution of h = 1 mm near the top boundary agrees very well with the analytical diffusive flux until about 7×10^4 s, indicating an earlier onset of convective activity than seen with the coarser grid. Dissolved CO2 inventory, being an integral quantity, does not significantly exceed the inventory for the diffusion-only case until times well in excess of $t_{inc} = 7 \times 10^4$ s, thus providing a less sensitive measure for t_{inc} than CO2 fluxes (Fig. 4b).

The good match for the diffusive behavior indicates that a grid resolution of h = 1 mm near the top boundary is adequate for the vertical direction. Horizontal resolution is an issue as well, as this places a lower limit on the wavelength of convective fingers that can be resolved. Theoretical analysis has shown that finger wavelengths favored for growth during the initial period of the convective instability are comparable to the thickness of the diffusive boundary layer at onset of convection (Ennis-King et al., 2005). For a convective onset time of $t_{inc} = 7x10^4$ s, the boundary layer thickness is $|z| = L_{inc} = \sqrt{Dt_{inc}} = 11.8$ mm. Accordingly, we chose a horizontal grid resolution of 10 mm. Corroboration of this choice comes from the numerical simulation results. Fig. 5 shows dissolved CO2 concentrations at different times, illustrating the onset and evolution of convective activity. The first frame corresponds to a time only slightly larger than the onset time of convection. The diffusive boundary layer has been distorted by numerous convective fingers; at the earliest time shown in Fig. 5 there are 25 fingers, indicating a wavelength of 40 mm, a factor 4 larger than grid spacing. Subsequently the convective fingers advance downward, and in so doing become broader and partially coalesce and merge. This process continues as time progresses (see also frames at later time in Figs. 12a and 13a), leaving only two broad fingers at the time when significant CO2 concentrations approach the bottom boundary (Fig. 13a). These simulation results suggest that a horizontal grid spacing of 10 mm is adequate for resolving the horizontal scale of the fingers.

As a further test of grid resolution, additional runs were made using the SCALE facility in TOUGH2 to change all linear dimensions of the computational grid by factors ranging from 0.2 - 3.0. This linear scaling offers a very simple and convenient way to examine grid resolution effects by means of a single input parameter, and avoids the tedium of generating new grids with different resolution. A limitation is that the SCALE factor applies equally to horizontal and vertical grid dimensions, so that effects of vertical and horizontal grid resolution cannot be separated. (Another limitation is that the flow domain itself shrinks or expands according to the SCALE factor. However, here we focus on the early-time behavior during the initial onset of convection, for which effects of distant boundaries are negligible, see below.) Fig. 6 shows CO2 dissolution rates for SCALE factors in the range from 0.2 - 3.0. It is seen that over this entire parameter range, the dissolution rates agree well with the analytically calculated diffusive flux at

early times. We conclude that vertical grid resolution in the range from 0.2 - 3.0 mm is adequate for resolving the early-time diffusive process.
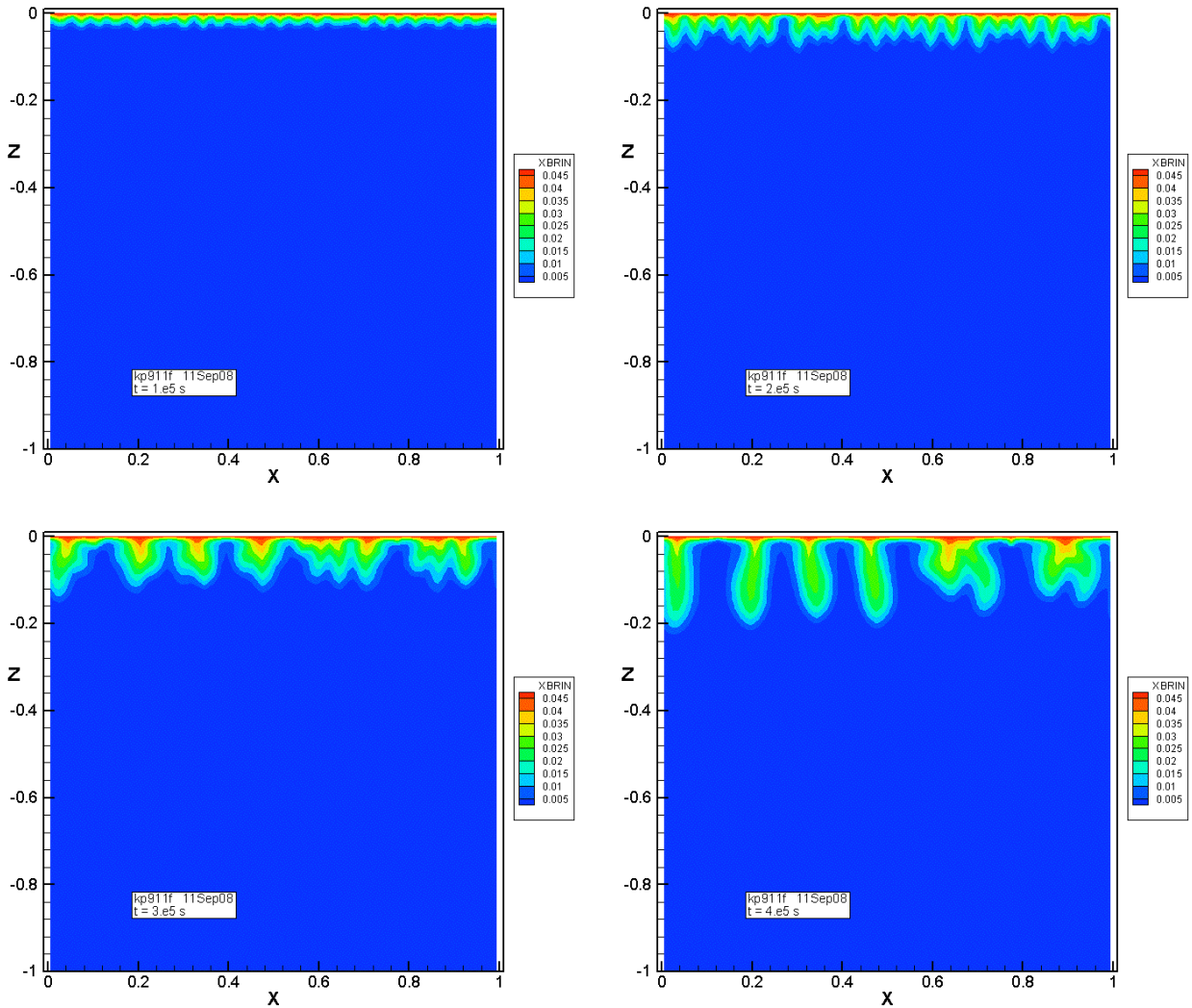

 Figure 5. Dissolved CO2 concentrations, expressed as mass fractions XBRIN, at different times for Case 1, obtained with the fine grid. Here and in subsequent frames, dimensions are in meters.
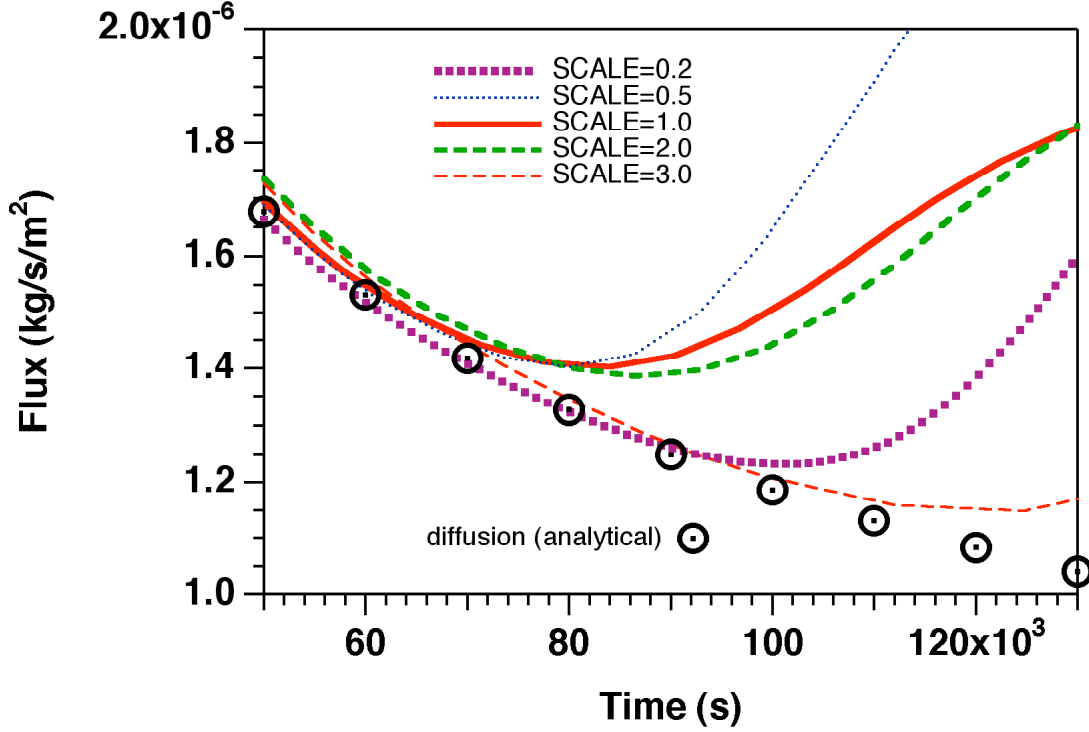
Figure 6. Simulated CO2 dissolution rates for a range of grid resolutions (see text). Dissolution rate from the analytical solution for diffusion only is also shown.

Simulated CO2 dissolution rates for $0.5 \leq SCALE \leq 2.0$, corresponding to horizontal grid resolution of 5 - 20 mm, begin to exceed diffusive flux at the same time of $t_{inc} = 7 \times 10^4$ s. The good agreement for convective onset time between the simulations for $0.5 \leq SCALE \leq 2.0$ indicates that there is little impediment for the development of the convective instability from horizontal grid resolution effects. In contrast, the coarser grid with $SCALE = 3$ (30 mm resolution) is seen to suppress convection at early times. Somewhat surprisingly, onset of convection is also delayed for the finest grid resolution ($SCALE = 0.2$, corresponding to a horizontal resolution of 2 mm). We interpret this to mean that such fine horizontal gridding impedes development of fingers with the somewhat larger wave lengths that experience larger growth rates at early times. For the inferred onset time $t_{inc} = 7 \times 10^4$ s and using the applicable problem parameters (Table 2), the coefficient in the theoretical expression Eq. (3) is calculated as $c_0 = 1155.6$.

Fig. 7 gives a more detailed view of the top of the flow domain for the case with SEED = 0.8, SCALE = 1, and also shows the computational grid with vertical discretization refined to h = 1 mm near the top boundary. It is seen that the downward convection of CO2-ladden water is fed from four roots at the top of the flow domain, the rightmost of which splits into two as it is convecting downward. The horizontal yellow line indicates the position of the diffusive front at the incubation time, $L_{inc} = 11.8$ mm, to which corresponds a dissolved CO2 mass fraction of X = 0.0236 at time t_{inc}. The interplay between diffusion and convection changes the distance from the top boundary at which a dissolved concentration of X = 0.0236 occurs; at the time t = 101.6 days for which Fig. 7 is plotted, this particular concentration corresponds to the top boundary of the dark blue region. Regions in which the diffusive boundary layer is compressed, due to upwelling water with low dissolved CO2, have increased concentration gradients, deliver larger diffusive
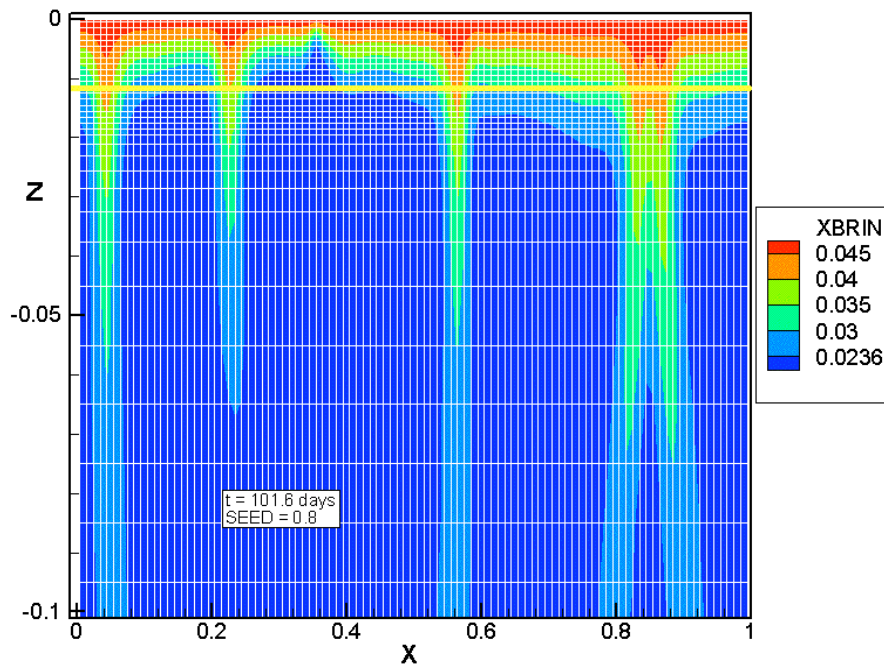

Figure 7. Dissolved CO2 mass fractions near the top of the flow domain for the Case 1 simulation with a random number SEED = 0.8 at time t = 101.6 days. Note the 10:1 vertical exaggeration. The horizontal yellow line corresponds to the diffusive boundary layer at incubation time, $|z| = L_{inc} = \sqrt{Dt_{inc}}$, with a dissolved mass fraction of X = 0.0236. Gridding is also shown. All dimensions are in m.

flux locally, and thus function as the primary sources of dissolved CO2. An extreme example of one such region occurs near x = 0.36 m. Water convecting upwards in this region is diverted sideways near the top boundary; it then picks up additional solute from laterally offset regions with smaller CO2 concentration gradients, and eventually its density increases due to increased CO2 concentration to the point where it begins to convect downward. Subsequent simulations were carried out with the finer gridding of h = 1 mm near the top and SCALE = 1. The total number of grid blocks is 52,300.

Fig. 8 gives space-averaged CO2 fluxes across horizons located at different distance from the top boundary, with data plotted on logarithmic (a) and linear time scales (b), respectively. This shows how CO2 transport progresses over time from the top boundary downward towards increasing distances. Fluxes in the top 2 cm quickly approach a quasi-steady behavior, and show only modest temporal variations of around ± 15 %. At deeper horizons fluxes continue to fluctuate more strongly, due to evolving convective activity.
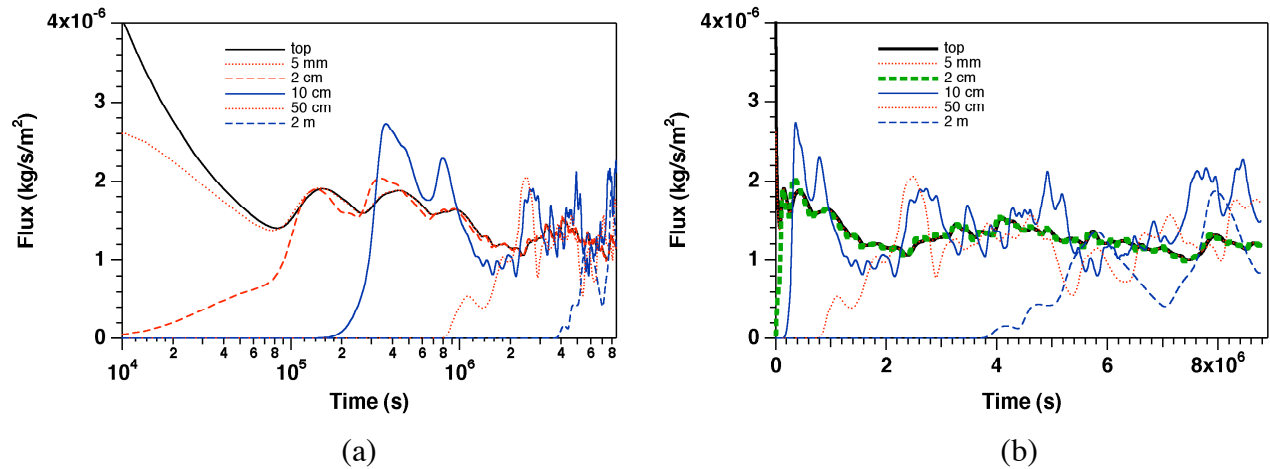

(a)   (b)

Figure 8. Total CO2 flux across horizons located at different distance from the top boundary for Case 1, showing data on logarithmic (a) and linear time scales (b), respectively.

4.1 Variations in Random Seeding

Fig. 9 shows distributions of dissolved CO2 concentrations for three different random number seeds after 101.6 days of simulation time, just before significant CO2 concentrations reach the lower boundary. It is evident that convection patterns are quite different in detail, but share similar features overall.
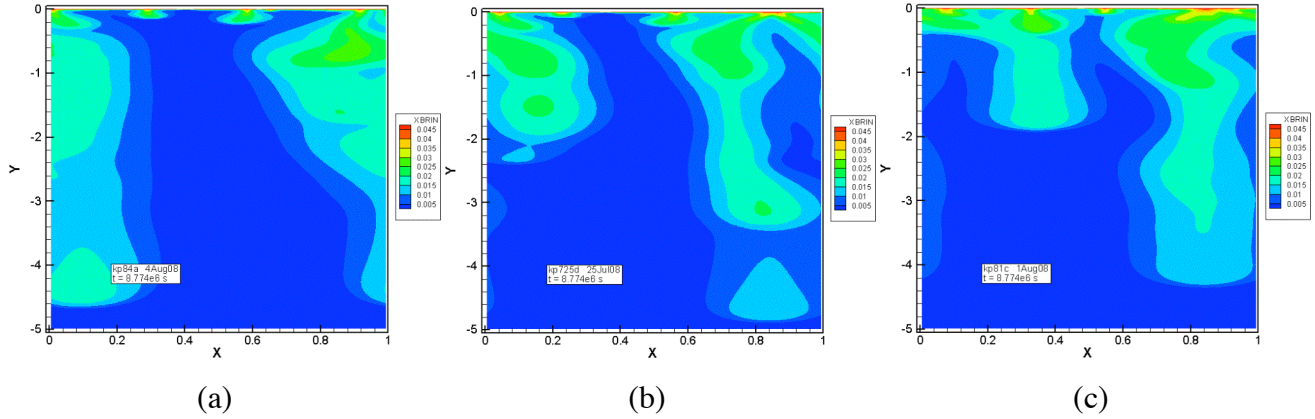

(a)   (b)   (c)

Figure 9. Simulated distribution of dissolved CO2 for Case 1 after 101.6 days for three different random number seeds to generate permeability heterogeneity (a-0.7; b-0.8; c-0.9). Note the different horizontal and vertical scales.

The CO2 mass fluxes associated with the systems shown in Fig. 9 are plotted in Fig. 10 for the time period prior to significant CO2 concentrations evolving at the lower boundary. Convection begins at $t_{inc} = 7 \times 10^4$ s, at which time CO2 dissolution rate is 1.4×10^{-6} kg/s/m^2. Some rapid quasi-periodic variations occur at early-times as convective fingers grow and partially coalesce, followed by random variations of about $\pm$ 15 % amplitude around an average flux of 1.3×10^{-6} kg/s/m^2. Apart from these variations, CO2 fluxes are seen to be essentially constant during the entire convection-dominated period, as long as no significant CO2 concentrations reach the lower boundary. This confirms earlier results by Hesse et al. (2006). We also note that differences between different random number realizations are of similar magnitude as temporal variations for a given realization.
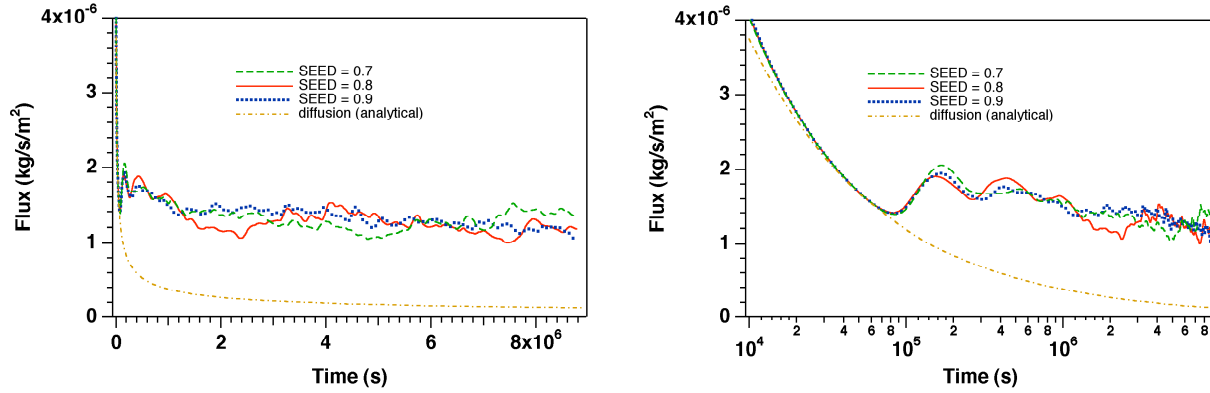
Figure 10. Simulated CO2 fluxes (dissolution rates) for Case 1 at the top boundary, for three different random number seeds, on linear (a) and logarithmic time scales (b).

Fig. 11 shows plots of the quantity F.M (Eq. 9), that remains constant for a purely diffusive process. This figure indicates that the onset time for convection is about 7×10^4 s, and is practically indistinguishable for the different realizations with different random number seeds.
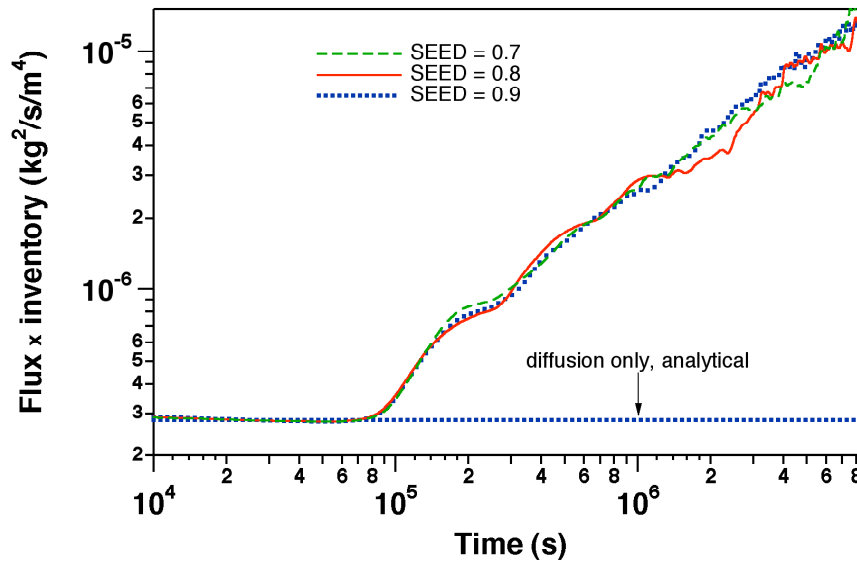

Figure 11. Parameter F.M (flux times mass inventory) for Case 1 simulations with different random number seeds. The dotted horizontal line indicates the behavior of a diffusive system without convection.

As demonstrated by the simulation results given above, the temporal evolution of CO2 dissolution rates proceeds through four distinct time periods, as follows.

1) During the early period $t < t_{inc}$, transport of CO2 away from the dissolution boundary occurs only by molecular diffusion, so that dissolution rate declines with time as $1/\sqrt{t}$, while total dissolved inventory grows as $\sqrt{t}$.

2) This is followed by a period in which convective instabilities begin and grow, leading to a general increase in dissolution rates. These are modulated by significant quasi-periodic variations, as convective fingers partially coalesce and grow.

3) The third period is characterized by a continuous downward progression of convective fingers, while total dissolution rates remain constant except for modest random fluctuations of order ± 15 %.

4) The final period begins when dissolved CO2 reaches the lower boundary. At that time, dissolved CO2 concentrations begin to increase in the upwelling limbs of the convective process, leading to diminished buoyancy force and a gradual decline in dissolution rates.

The final equilibrium state of the system consists of constant dissolved CO2 concentrations throughout, equal to those applied at the top boundary.

4.2 Variations in Boundary Conditions

Here we present a series of simulations that were obtained for a random number seed of 0.8, but employing different boundary conditions. The reference Case 1 discussed above has a no-flow boundary at the bottom of the domain (z = - 5 m). Variations of this case explored through numerical simulation experiments include (b) constant-pressure conditions at z = - 5 m, (c) use of an "unrolled" grid, in which the right hand side is not connected back to the left hand side, and (d) applying no flow boundary conditions at z = - 4 m. From the results given in Figs. 12-14, we make the following observations.

- details of convection patterns can be quite different when boundary conditions are changed;

- total dissolution rates at the top are 1.3×10^{-6} kg/s/m^2 ± 15 %, and are not sensitive to boundary conditions and associated variations in convection patterns; average dissolution rates and their random scatter are similar to what was obtained for different random number seeds;
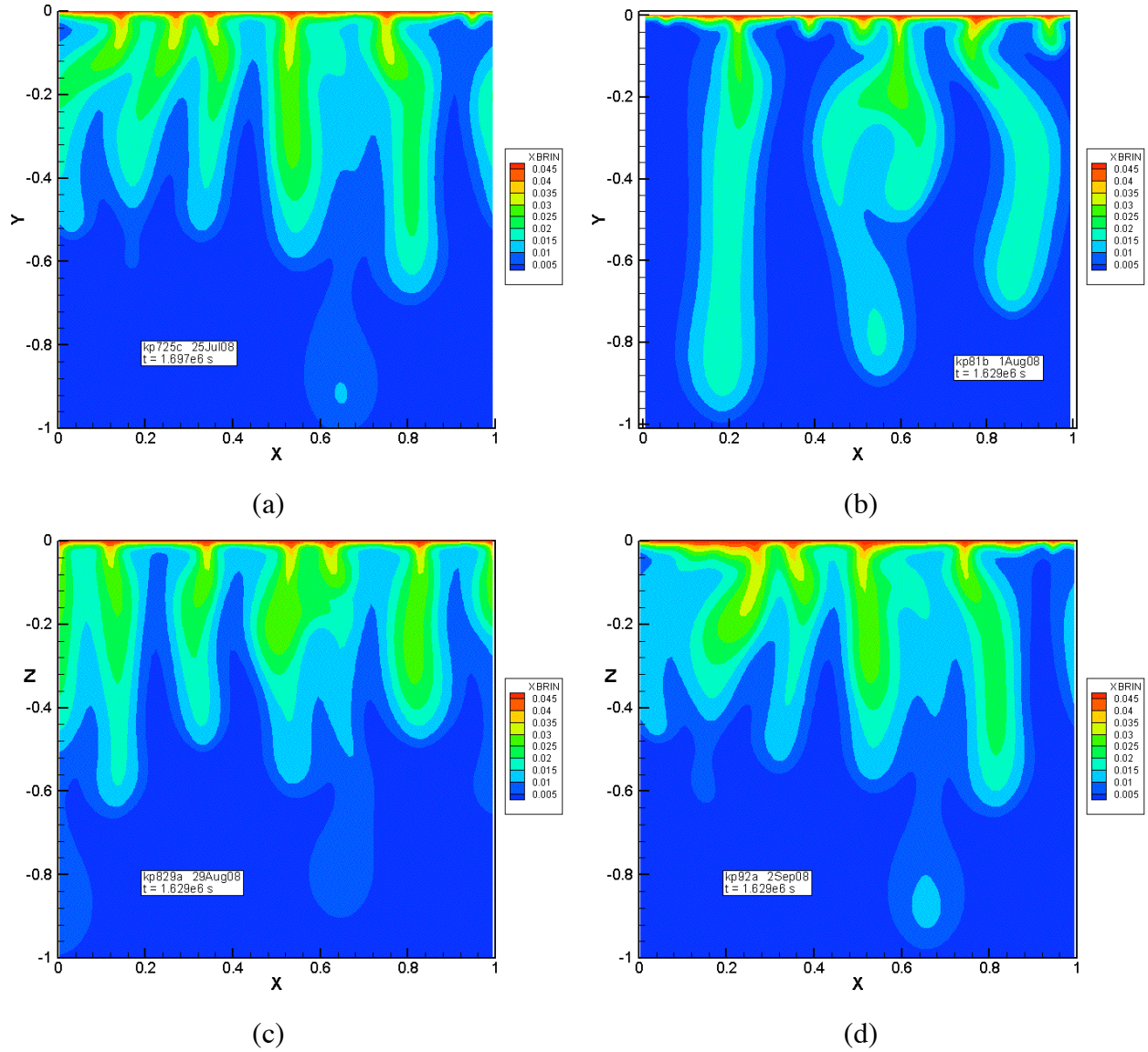
Figure 12. Simulated dissolved CO2 concentrations for Case 1 at time $t = 1.629 \times 10^6$ s for (a) reference case, (b) constant P at z = -4.995 m, (c) unrolled grid, and (d) no flow at z = -3.995 m.

- there is considerable variability in the downward advancement of convective fingers, with a spread of about a factor 1.5 between fastest and slowest, akin to longitudinal dispersion;

- there can be considerable differences in the rate of advancement of the fastest finger;

- denser CO2-ladden fluid parcels can pinch off and become disconnected from convective fingers.
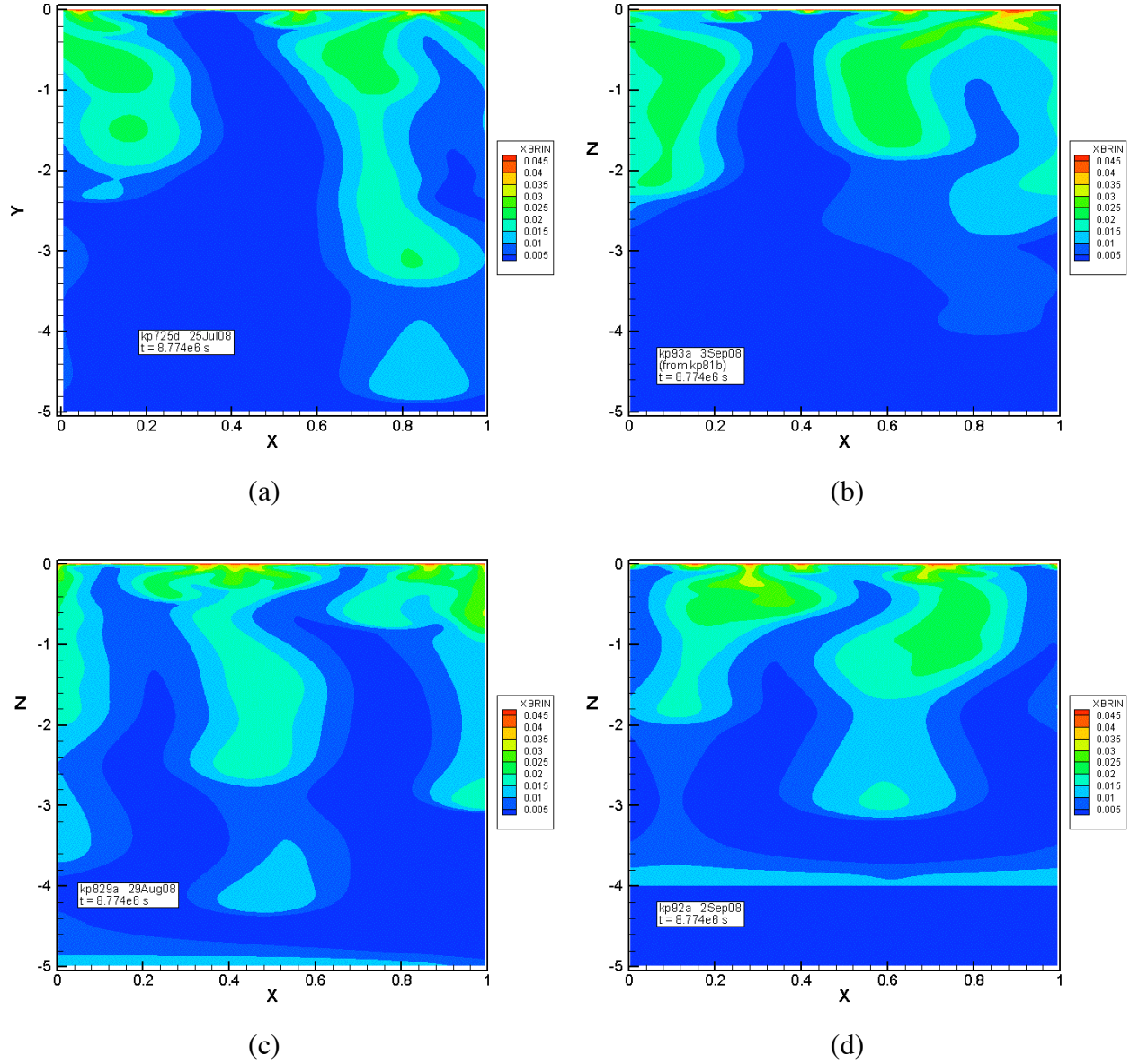
Figure 13. Simulated dissolved CO2 concentrations for Case 1 at time t = 8.774x10^6 s for (a) reference case, (b) constant P at z = -4.995 m, (c) unrolled grid, and (d) no flow at z = -3.995 m.

Overall, effects from variations in boundary conditions are similar to effects from different random number seeds. Such variations do not appear to induce any systematic changes in CO2 dissolution rates.
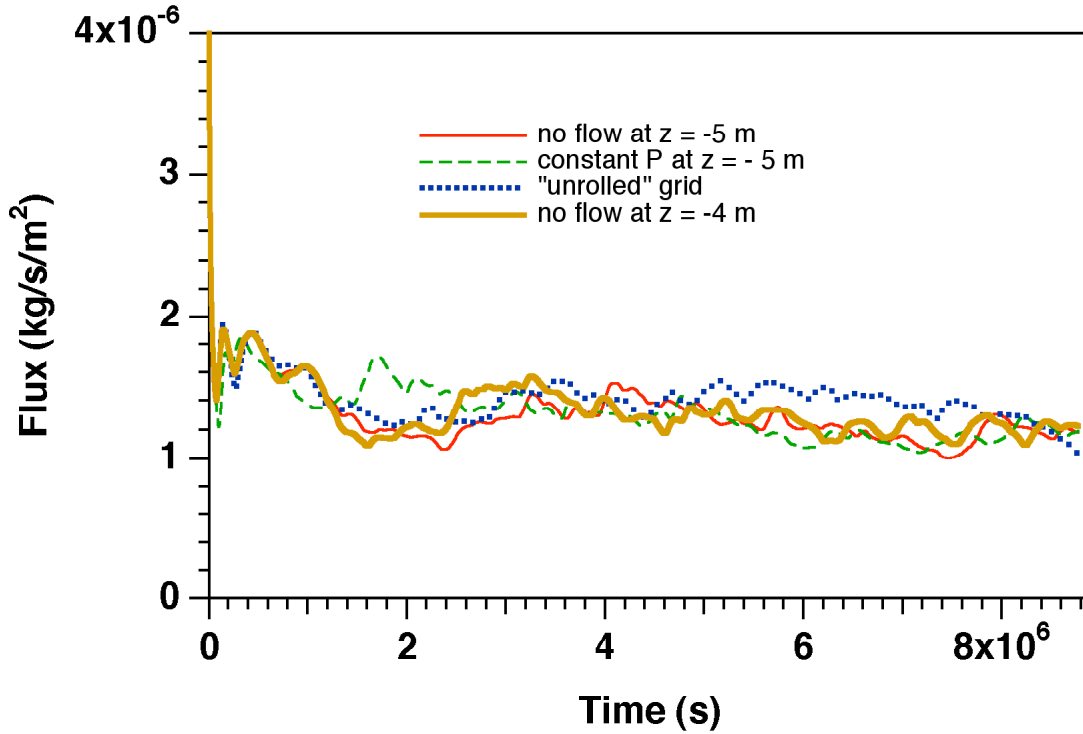
Figure 14. Simulated CO2 fluxes (dissolution rates) for Case 1 at the top boundary, for different conditions at the lateral and bottom boundaries.

5. Results for Case 2 (low-k, large scale)

Here we consider a permeability reduced by two orders of magnitude to 10^{-13} m^2, which from Eqs. (3, 4) is expected to increase the incubation time by four orders of magnitude to 7×10^8 s, and increase the thickness of the diffusive boundary layer at incubation time by two orders of magnitude to 1.18 m. Additional smaller effects arise from changes in parameters D and ϕ (see Table 3), giving an estimated value for incubation time of $t_{inc} = 1.56 \times 10^8$ s, with a corresponding thickness of the diffusive boundary layer of $L_{inc} = 0.39$ m.

This case was first run with a uniform grid spacing of h = 0.1 m in both horizontal and vertical directions. Inspection showed very steep concentration gradients near the top, that appeared to be inadequately resolved by the h = 0.1 m grid spacing. Accordingly, another run was made in which vertical grid spacing near the top was refined to h = 0.02 m. Results are given in Figs. 15-17.

Table 3. Parameter changes for Case 2 simulations.

Fluid properties	
diffusivity	$D = 2 \times 10^{-9}$ --> 10^{-9} m^2/s
Formation properties	
porosity	$\phi = 0.3$ --> 0.2
permeability	$k = 10^{-11}$ --> 10^{-13} m^2
Model domain	
height	$H = 5$ --> 10 m
width	$W = 1$ --> 20 m

Solute concentration patterns at time t = 32.2 years are shown for the coarse and refined grids, respectively, in Fig. 15. In both cases there are five regions at the top of the domain that deliver CO2-ladden fluid downward, but other than that the concentration patterns are very different. Downward convection has advanced less in the coarser grid, as expected because coarser spatial discretization acts to suppress and delay convective activity. The concentration snapshots in Fig. 15 correspond to a time just before elevated CO2 concentrations reach the bottom boundary.

CO2 fluxes at the top of the domain are shown in Fig. 16, indicating incubation times of 2.3×10^8 s for the grid with uniform spacing of h = 0.1 m, and 1.9×10^8 s for the grid with refinement to 0.02 m at the top boundary. These numbers are comparable to but somewhat larger than the incubation time of 1.56×10^8 s estimated from Equation (3) using the Case-1 value of c_0, suggesting that convective activity is somewhat suppressed and delayed due to spatial averaging from the limited grid resolution. In the finer grid, CO2 dissolution rate at onset time t_{inc} is 1.3×10^{-8} $kg/s/m^2$, two orders of magnitude smaller than in Case 1, in agreement with the scaling law Eq. (7). The coefficient in Eq. (3) for $t_{inc} = 1.9 \times 10^8$ s is $c_0 = 1411.5$. This is 22 % larger than for the high-k Case 1, and about an order of magnitude larger than values suggested by Ennis-King and Paterson (2003b). The reason for these discrepancies are unknown.

It is remarkable that, in spite of the large differences in convection patterns, CO2 fluxes for the coarse and fine grid systems are quite similar, around 1.9×10^{-8} $kg/s/m^2$ during the main convective period (Fig. 16). Alternating periods of flux overshoot and undershoot between the

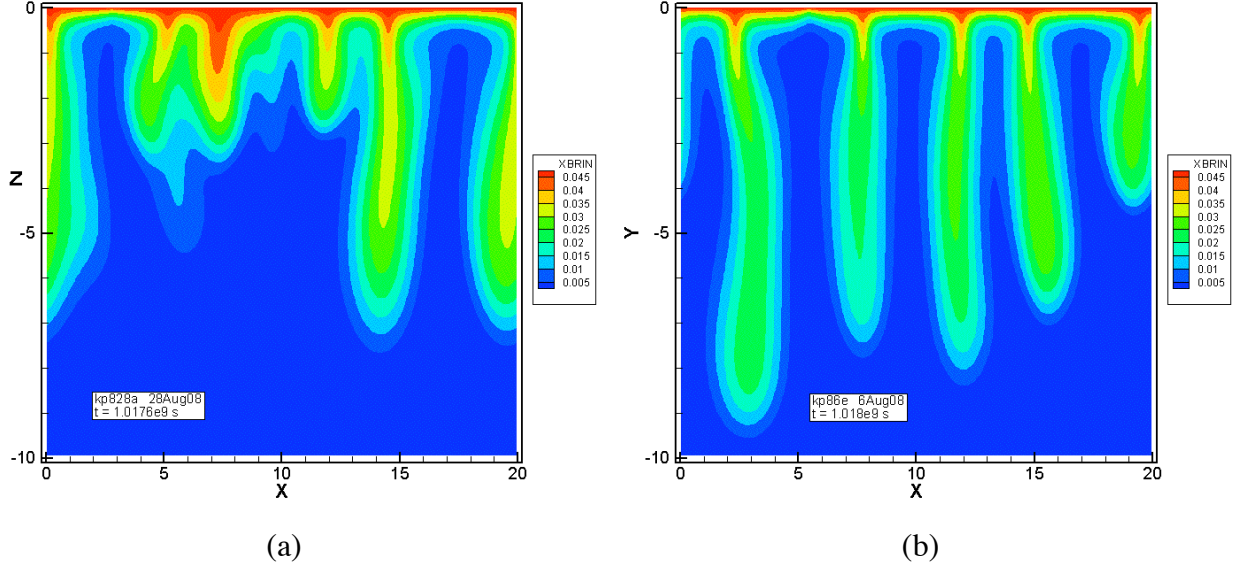(a)   (b)

Figure 15. Simulated distributions of dissolved CO2 for Case 2 after 32.2 years for the coarse (left) and refined grid (right).

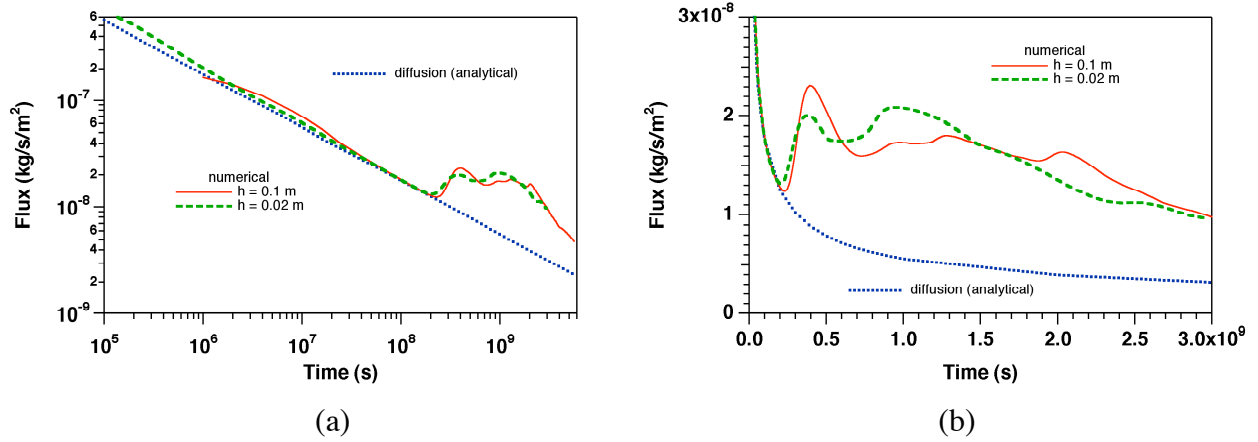(a)   (b)

Figure 16. Simulated CO2 flux (dissolution rate) from the top boundary for the low-permeability Case 2 on logarithmic (a) and linear scales (b).

two grids tend to compensate each other, leading to very small differences in the evolution of total dissolved CO2 inventory (Fig. 17). To gain some perspective on the growth of dissolved inventory shown in Fig. 17, we note that the "end state" of the system reached for t → ∞ corresponds to a uniform dissolved CO2 concentration of $X = X_0 = 0.0493$, and a dissolved inventory per unit area of $H\phi\rho X_0 = 99.1$ kg/m^2, about twice the inventory reached at $t = 3 \times 10^9$ s.
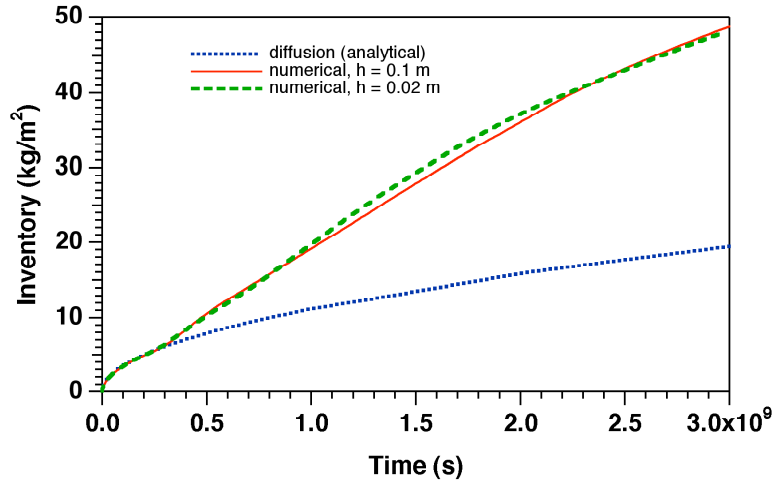
Figure 17. Simulated growth of dissolved CO2 inventory for Case 2, comparing results for different spatial resolution.

Fig. 18 shows CO2 dissolution rates for five different random number seeds to specify permeability heterogeneity. The different simulations agree very well with respect to incubation time. Significant differences occur in the subsequent period where convection is evolving, with some cases producing far greater excursions about the mean (approximately 1.9×10^{-8} kg/s/m^2) than others. Convective activity reaches the bottom boundary just after 10^9 s, and subsequently there is systematic decline, in some cases modulated by non-monotonic variations.
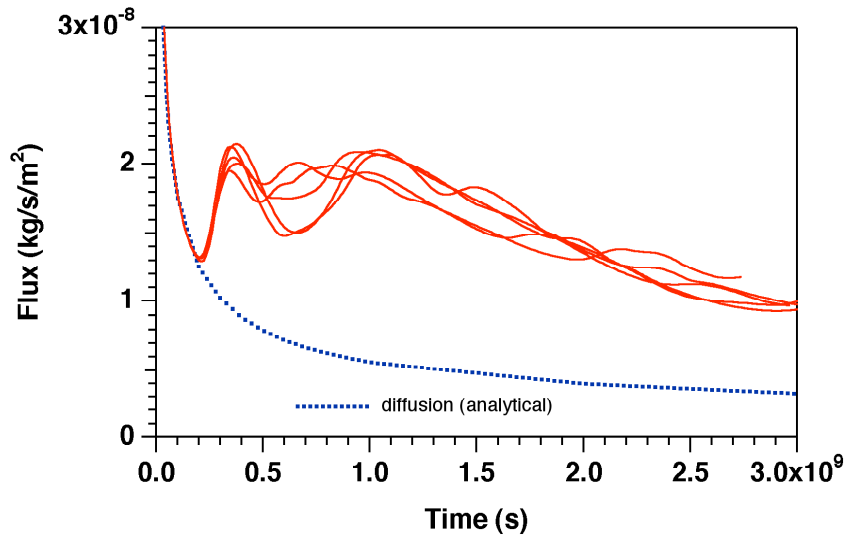

Figure 18. Simulated CO2 dissolution rates for Case 2 for 5 different choices of random seeding.

An important difference in comparison to the high-permeability Case 1 is in the relative magnitude of incubation times, and times beyond which convection is affected by dissolved CO_2 reaching the lower boundary of the flow system. Incubation times scale inversely proportional to permeability-squared (Eq. 3), while the time scale for convection to extend over a certain depth interval scales inversely proportional to permeability. The time required for convective fingers to reach the bottom of the flow domain is approximately $100 t_{inc}$ in the high-k system, while in the low-k system it is only about $6 t_{inc}$. The time scale for evolution of convection is much slower for lower permeability, and the system is still "spinning up," with large excursions from the mean, when bottom boundary effects are beginning to be felt. This difference explains why in the lower-permeability case we do not have as much of an extended period with essentially constant dissolution rate (modulated by random variations) as had been seen in the high-permeability case.

6. Discussion and Concluding Remarks

Numerical modeling of dissolution-diffusion-convection (DDC) is challenging, due to the unstable nature of the governing processes, and the broad range of relevant space and time scales. The DDC process induces large concentration variations near the dissolution boundary. Resolving the accompanying concentration gradients by fine gridding is key to accurate numerical modeling. Assessing and controlling space discretization effects is a major challenge, as the most fundamental and commonly employed approach for this purpose - systematic grid refinement - is not workable when even small changes in gridding can completely alter global convection patterns. Instead we need to look for aggregate, integral measures of the DDC process, such as total CO_2 dissolution rates, and examine their sensitivity to variations in problem parameters and numerical artifacts.

The convective activity induced by aqueous phase density increase from CO_2 dissolution presents two complementary and even contradictory aspects. On the one hand, the pattern of convection is very "fickle" and changeable; not only in response to small modifications in problem specifications, such as different random seeding, or different boundary conditions, but also for "small" changes in the simulation process, such as altered numerical roundoff for different time stepping controls, and when different domain decompositions are applied in the

linear equation solution. On the other hand, "integral" measures of the convective process, such as total solute flux across different horizons, are remarkably robust. Average solute flux across different horizons shows modest random fluctuations of typically ± 15 % over time, and is not much affected by changes in boundary conditions.

The temporal evolution of CO2 dissolution rates proceeds through four distinct time periods, as follows.

1) During the early time period, transport of CO2 away from the dissolution boundary occurs by molecular diffusion only, with diffusivity of order 10^{-9} m^2/s (Tewes and Boury, 2005), so that dissolution rate declines with time as $1/\sqrt{t}$, while total dissolved inventory grows as $\sqrt{t}$.

2) This is followed by a period in which convective instabilities begin and grow, leading to a general increase in dissolution rates. These are modulated by non-monotonic variations, as convective fingers partially coalesce and grow.

3) The third period is characterized by a continuous downward progression of convective fingers, while total dissolution rates are constant with modest random fluctuations of order ± 15 %.

4) The final period begins when dissolved CO2 reaches the lower boundary. At that time, dissolved CO2 concentrations begin to increase in the upwelling limbs of the convective process, leading to diminished buoyancy force and a gradual decline in dissolution rates.

Our simulations confirm theoretically-derived scaling relations, according to which CO2 dissolution rate at onset time of convection is proportional to permeability, and independent of diffusivity and formation porosity.

Acknowledgement

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