

RESEARCH

Open Access



# Nonoscillation for higher-order nonlinear delay dynamic equations on time scales

Chunyan Tao<sup>1</sup>, Taixiang Sun<sup>1,2\*</sup> and Qiuli He<sup>3</sup>

\*Correspondence:  
stx1963@163.com

<sup>1</sup>College of Mathematics and  
Information Science, Guangxi  
University, Nanning, Guangxi  
530004, China

<sup>2</sup>College of Information and  
Statistics, Guangxi University of  
Finance and Economics, Nanning,  
Guangxi 530003, China  
Full list of author information is  
available at the end of the article

## Abstract

In this paper, we investigate the nonoscillation of the higher-order nonlinear delay dynamic equation

$$(a_{n-1}(t)(a_{n-2}(t)(\cdots (a_1(t)x^\Delta(t))^\Delta \cdots)^\Delta)^\Delta + u(t)g(x(\delta(t))) = R(t)$$

$$\text{for } t \in [t_0, \infty)_{\mathbb{T}},$$

where  $\mathbb{T}$  is a scale with  $\sup \mathbb{T} = \infty$ ,  $t_0 \in \mathbb{T}$ , and  $[t_0, \infty)_{\mathbb{T}} = \{t \in \mathbb{T} : t \geq t_0\}$ . We obtain some sufficient conditions for all solutions of this equation to be nonoscillatory.

**MSC:** 34K11; 39A10; 39A99

**Keywords:** nonoscillation; dynamic equation; time scale

## 1 Introduction

A time scale  $\mathbb{T}$  is an arbitrary nonempty closed subset of the real numbers. Thus, the set  $\mathbb{R}$  of all real numbers, the set  $\mathbb{N}$  of all natural numbers, and the set  $\mathbb{Z}$  of all integers are examples of time scales. On a time scale  $\mathbb{T}$ , the forward jump operator, the backward jump operator, and the graininess function are defined as

$$\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}, \quad \rho(t) = \sup\{s \in \mathbb{T} : s < t\}, \quad \text{and} \quad \mu(t) = \sigma(t) - t,$$

respectively.

In this paper, we investigate the nonoscillation of the higher-order nonlinear delay dynamic equation

$$(a_{n-1}(t)(a_{n-2}(t)(\cdots (a_1(t)x^\Delta(t))^\Delta \cdots)^\Delta)^\Delta + u(t)g(x(\delta(t))) = R(t)$$

$$\text{for } t \in [t_0, \infty)_{\mathbb{T}}, \tag{1.1}$$

where  $t_0 \in \mathbb{T}$ , the time scale interval  $[t_0, \infty)_{\mathbb{T}} \equiv \{t \in \mathbb{T} : t \geq t_0\}$ ,  $a_i \in C_{rd}([t_0, \infty)_{\mathbb{T}}, (0, \infty))$  ( $1 \leq i \leq n-1$ ),  $u, R \in C_{rd}([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$ ,  $\delta \in C_{rd}([t_0, \infty)_{\mathbb{T}}, \mathbb{T})$  is surjective with  $\delta(t) \leq t$  and  $\delta(t) \rightarrow \infty$  as  $t \rightarrow \infty$ , and  $g \in C([t_0, \infty)_{\mathbb{T}} \times \mathbb{R}, \mathbb{R})$ . Our goal is to obtain sufficient conditions for all solutions of (1.1) to be nonoscillatory.

We define

$$R_i(t, x(t)) = \begin{cases} x(t) & \text{if } i = 0, \\ a_i(t)R_{i-1}^\Delta(t, x(t)) & \text{if } 1 \leq i \leq n-1. \end{cases} \quad (1.2)$$

Then (1.1) reduces to the equation

$$R_{n-1}^\Delta(t, x(t)) + u(t)g(x(\delta(t))) = R(t). \quad (1.3)$$

We can suppose the  $\sup \mathbb{T} = \infty$  since we are interested in the oscillatory behavior of solutions near infinity. By a solution of (1.1) we mean a nontrivial real-valued function  $x \in C_{rd}([T_x, \infty)_{\mathbb{T}}, \mathbb{R})$ ,  $T_x \geq t_0$ , such that  $R_{n-1}(t, x(t)) \in C_{rd}^1([T_x, \infty)_{\mathbb{T}}, \mathbb{R})$  and satisfies (1.1) on  $[T_x, \infty)$ . Since we are working on a time scale, the notion of oscillation takes the form of what is known as a *generalized zero* of a function. We say that  $x(t)$  has a generalized zero at a point  $T$  if  $x(T)x(\sigma(T)) \leq 0$ . A function is said to be *oscillatory* if it has arbitrarily large generalized zeros and *nonoscillatory* otherwise.

In order to create a theory that can unify discrete and continuous analysis, the theory of time scale was initiated by Hilger's landmark paper [1], which has received a lot of attention. There exist a variety of interesting time scales, and they give rise to many applications (see [2]). We refer the reader to [3, 4] for further results on time-scale calculus. In the thousands of papers in the literature, finding sufficient conditions for all solutions of an equation to be oscillatory have been a major focus of study (see [5–28]), but finding necessary and sufficient conditions for the existence of a nonoscillatory bounded solution of an equation are more rare (see [29]).

Zhu and Wang [21] studied the existence of nonoscillatory solutions to neutral dynamic equation

$$[x(t) + p(t)x(g(t))]^\Delta + f(t, x(h(t))) = 0.$$

Karpuz and Öcalan [22] studied the asymptotic behavior of delay dynamic equations of the form

$$[x(t) + A(t)x(\alpha(t))]^\Delta + B(t)F(x(\beta(t))) - C(t)G(x(\gamma(t))) = \varphi(t).$$

Wu *et al.* [25] investigated the oscillation of the higher-order dynamic equation

$$\{r_n(t)[(r_{n-1}(t)(\cdots(r_1(t)x(t)^\Delta)^\Delta \cdots)^\Delta)^\Delta]^\gamma\}^\Delta + F(t, x(\tau(t))) = 0.$$

Sun *et al.* [26] obtained some necessary and sufficient conditions for the existence of nonoscillatory solution for the higher-order equation

$$\{a(t)[(x(t) - p(t)x(\tau(t)))^{\Delta^m}]^\alpha\}^\Delta + f(t, x(\delta(t))) = 0.$$

## 2 Auxiliary results

We state the following conditions, which are needed in the sequel.

(H<sub>1</sub>) There exist constants  $\alpha, \beta \geq 0$  and  $\gamma \geq 0$  such that  $|g(u)| \leq \alpha|u|^\gamma + \beta$ .

(H<sub>2</sub>)  $\int_{t_0}^\infty \frac{\Delta s_1}{a_1(s_1)} \int_{t_0}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{t_0}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{t_0}^{s_{n-1}} |R(s_n)| \Delta s_n < \infty$ .

$$(H_3) \int_{t_0}^{\infty} \frac{\Delta s_1}{a_1(s_1)} \int_{t_0}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{t_0}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{t_0}^{s_{n-1}} |u(s_n)| \Delta s_n < \infty.$$

We shall employ the following lemma.

**Lemma 2.1** *Let  $\mathbb{R}_+ \equiv [0, \infty)$  and  $H = \{(t, s_1, s_2, \dots, s_{n-1}) : 0 \leq s_{n-1} \leq s_{n-2} \leq \cdots \leq s_1 \leq t < \infty\}$ . Suppose that  $r \in C_{rd}([t_0, \infty)_{\mathbb{T}}, \mathbb{R}_+)$ ,  $h \in C_{rd}(H, \mathbb{R}_+)$ , and that  $p \in C(\mathbb{R}_+, \mathbb{R}_+)$  is nondecreasing with  $p(r) > 0$  for  $r > 0$ . If there exists a constant  $c > 0$  such that*

$$r(t) \leq c + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) p(r(s_n)) \Delta s_n, \quad (2.1)$$

then

$$r(t) \leq P^{-1} \left( P(c) + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n \right),$$

where

$$P(w) = \int_{w_0}^w \frac{ds}{p(s)}, \quad w_0, w > 0,$$

$P^{-1}$  is the inverse function of  $P$ , and

$$P(c) + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n \in \text{Dom}(P^{-1}). \quad (2.2)$$

*Proof* Let  $z(t)$  denote the right side of inequality (2.1). Then  $z(t_0) = c$ ,  $r(t) \leq z(t)$ , and

$$\begin{aligned} z^\Delta(t) &= \int_{t_0}^t \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(t, s_2, \dots, s_n) p(r(s_n)) \Delta s_n \\ &\leq p(z(t)) \int_{t_0}^t \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(t, s_2, \dots, s_n) \Delta s_n. \end{aligned}$$

Since  $z^\Delta(t) \geq 0$  and  $p$  is nondecreasing, we obtain

$$\frac{z^\Delta(t)}{p(z(t))} \leq \int_{t_0}^t \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(t, s_2, \dots, s_n) \Delta s_n. \quad (2.3)$$

Noting that

$$P^\Delta(z(t)) = z^\Delta(t) \int_0^1 \frac{dh}{p[hz(\sigma(t)) + (1-h)z(t)]} \leq \frac{z^\Delta(t)}{p(z(t))},$$

we have

$$P(z(t)) \leq P(z(t_0)) + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n.$$

Since  $P(w)$  is increasing, we have

$$z(t) \leq P^{-1} \left( P(c) + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n \right).$$

The proof is complete.  $\square$

Notice that taking  $p(v) = v^\xi$  and  $\xi > 1$  in Lemma 2.1, we have

$$P(z(t)) - P(z(t_0)) = \frac{1}{1-\xi} [z^{1-\xi}(t) - z^{1-\xi}(t_0)].$$

So

$$\frac{1}{1-\xi} z^{1-\xi}(t) \leq \frac{1}{1-\xi} z^{1-\xi}(t_0) + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n,$$

that is,

$$z^{1-\xi}(t) \geq z^{1-\xi}(t_0) + (1-\xi) \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n.$$

We have

$$r(t) \leq \left[ c^{1-\xi} - (\xi-1) \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n \right]^{\frac{-1}{\xi-1}},$$

provided that

$$\int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n < \frac{c^{1-\xi}}{\xi-1}. \quad (2.4)$$

### 3 Main results

Now, we state and prove our main results.

**Theorem 3.1** Assume that conditions (H<sub>1</sub>)-(H<sub>3</sub>) hold and for some  $k \geq 0$ ,

$$\int_{t_0}^{\infty} \frac{\Delta s_1}{a_1(s_1)} \int_{t_0}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{t_0}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{t_0}^{s_{n-1}} |u(s_n)| \delta^{k\gamma}(s_n) \Delta s_n < \infty. \quad (3.1)$$

If  $x(t)$  is an oscillatory solution of (1.1) such that

$$|x(t)| = O(t^k), \quad t \rightarrow \infty, \quad (3.2)$$

then  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ .

*Proof* We will show  $\limsup_{t \rightarrow \infty} x(t) = 0$  and  $\liminf_{t \rightarrow \infty} x(t) = 0$ . Suppose that  $\limsup_{t \rightarrow \infty} x(t) = L > 0$ . Then for any  $t_1 \geq t_0$ , there exists  $t_2 \geq t_1$  such that  $x(t_2) > \frac{L}{2}$ . In view of conditions (H<sub>2</sub>), (H<sub>3</sub>), (3.1), and (3.2), there exist  $T_0 \geq t_0$  and  $K > 0$  such that  $|x(t)| \leq Kt^k$  ( $t \geq T_0$ ) and

$$\begin{aligned} & \int_{T_0}^{\infty} \frac{\Delta s_1}{a_1(s_1)} \int_{T_0}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T_0}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \\ & \times \int_{T_0}^{s_{n-1}} \{ |R(s_n)| + |u(s_n)| [\alpha K^\gamma \delta^{k\gamma}(s_n) + \beta] \} \Delta s_n < \frac{L}{4}. \end{aligned} \quad (3.3)$$

Since  $x(t)$  is an oscillatory solution of (1.1), every  $R_i(t, x(t))$  is oscillatory for  $i = 1, 2, \dots, n-1$ . Choose  $T_0 < T_1 \leq T_2 \leq \dots \leq T_{n-1}$  such that

$$R_{n-i}(T_i, x(T_i))R_{n-i}(\sigma(T_i), x(\sigma(T_i))) \leq 0, \quad i = 1, 2, \dots, n-1, \quad (3.4)$$

and

$$R_{n-i}(T_i, x(T_i)) \leq 0, \quad i = 1, 2, \dots, n-1. \quad (3.5)$$

Integrating (1.1) from  $T_i$  to  $t$ ,  $i = 1, 2, \dots, n-1$ , successively  $n-1$  times with  $t > T_{n-1}$ , we obtain

$$\begin{aligned} a_1 x^\Delta(t) &= a_1(T_{n-1})x^\Delta(T_{n-1}) + \int_{T_{n-1}}^t \frac{R_2(T_{n-2}, x(T_{n-2}))}{a_2(s_{n-2})} \Delta s_{n-2} \\ &\quad + \int_{T_{n-1}}^t \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \int_{T_{n-2}}^{s_{n-2}} \frac{R_3(T_{n-3}, x(T_{n-3}))}{a_3(s_{n-3})} \Delta s_{n-3} \\ &\quad + \dots \\ &\quad + \int_{T_{n-1}}^t \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \int_{T_{n-2}}^{s_{n-2}} \frac{\Delta s_{n-3}}{a_3(s_{n-3})} \dots \int_{T_2}^{s_2} \frac{R_{n-1}(T_1, x(T_1))}{a_{n-1}(s_1)} \Delta s_1 \\ &\quad + \int_{T_{n-1}}^t \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \int_{T_{n-2}}^{s_{n-2}} \frac{\Delta s_{n-3}}{a_3(s_{n-3})} \dots \int_{T_1}^{s_1} [R(s) - u(s)g(x(\delta(s)))] \Delta s \\ &\leq \int_{T_{n-1}}^t \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \int_{T_{n-2}}^{s_{n-2}} \frac{\Delta s_{n-3}}{a_3(s_{n-3})} \dots \int_{T_1}^{s_1} [R(s) - u(s)g(x(\delta(s)))] \Delta s. \end{aligned} \quad (3.6)$$

Choose  $T_n > T_{n-1}$  so that

$$x(T_n)x(\sigma(T_n)) \leq 0 \quad \text{and} \quad x(T_n) \leq 0.$$

Take  $T_{n+1} \geq T_n$  such that

$$x(T_{n+1}) \geq \frac{L}{2} \quad \text{and} \quad x(t) > 0, \quad t \in (T_n, T_{n+1}).$$

Note that such  $T_{n+1}$  exists since  $\limsup_{t \rightarrow \infty} x(t) > \frac{L}{2}$ . Dividing (3.6) by  $a_1(t)$  and integrating once more from  $T_n$  to  $T_{n+1}$ , we have

$$\begin{aligned} \frac{L}{2} \leq x(T_{n+1}) &\leq \int_{T_n}^{T_{n+1}} \frac{\Delta s_{n-1}}{a_1(s_{n-1})} \int_{T_{n-1}}^{s_{n-1}} \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \int_{T_{n-2}}^{s_{n-2}} \frac{\Delta s_{n-3}}{a_3(s_{n-3})} \\ &\quad \dots \int_{T_1}^{s_1} [R(s) - u(s)g(x(\delta(s)))] \Delta s. \end{aligned} \quad (3.7)$$

It follows from  $(H_1)$  that

$$\begin{aligned} \frac{L}{2} &\leq \int_{T_n}^{T_{n+1}} \frac{\Delta s_{n-1}}{a_1(s_{n-1})} \int_{T_{n-1}}^{s_{n-1}} \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \dots \int_{T_1}^{s_1} [|R(s)| + |u(s)| |g(x(\delta(s)))|] \Delta s \\ &\leq \int_{T_n}^{T_{n+1}} \frac{\Delta s_{n-1}}{a_1(s_{n-1})} \int_{T_{n-1}}^{s_{n-1}} \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \end{aligned}$$

$$\begin{aligned} & \cdots \int_{T_1}^{s_1} \{ |R(s)| + |u(s)| [\alpha |x(\delta(s))|^\gamma + \beta] \} \Delta s \\ & \leq \int_{T_n}^{T_{n+1}} \frac{\Delta s_{n-1}}{a_1(s_{n-1})} \int_{T_{n-1}}^{s_{n-1}} \frac{\Delta s_{n-2}}{a_2(s_{n-2})} \cdots \int_{T_1}^{s_1} \{ |R(s)| + |u(s)| [\alpha K^\gamma \delta^{k\gamma}(s) + \beta] \} \Delta s. \end{aligned}$$

In view of (3.3), we have a contradiction.

In a similar fashion, we can show that  $\liminf_{t \rightarrow \infty} x(t) = 0$ . The proof is complete.  $\square$

**Theorem 3.2** Assume that conditions  $(H_1)$ – $(H_3)$  hold with  $\gamma \geq 1$ . Then every oscillatory solution of (1.1) is bounded.

*Proof* Let  $x(t)$  be an oscillatory solution of (1.1), and  $d > 0$  be a constant.

If  $\gamma > 1$ , then it follows from conditions  $(H_2)$  and  $(H_3)$  that there exists  $T^* \geq t_0$  such that

$$\int_{T^*}^{\infty} \frac{\Delta s_1}{a_1(s_1)} \int_{T^*}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T^*}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T^*}^{s_{n-1}} [|R(s_n)| + \beta |u(s_n)|] \Delta s_n < d \quad (3.8)$$

and

$$\int_{T^*}^{\infty} \frac{\Delta s_1}{a_1(s_1)} \int_{T^*}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T^*}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T^*}^{s_{n-1}} \alpha |u(s_n)| \Delta s_n < \frac{d^{1-\gamma}}{2(\gamma-1)}. \quad (3.9)$$

We will show that eventually for any interval on which  $x(t)$  is positive, we have that  $x(t)$  is bounded by a constant independent of  $x(t)$ . Choose  $T^* < T_1 \leq T_2 \leq \cdots \leq T_{n-1} \leq T_n$  so that (3.4)–(3.5) are satisfied,  $\delta(t) > T_{n-1}$  for  $t \geq T_n$ , and  $x(\delta(T_n))x(\delta(\sigma(T_n))) \leq 0$  with  $x(\delta(T_n)) \leq 0$ . As in the proof of Theorem 3.1, using (3.8), we have

$$\begin{aligned} x(\delta(t)) & \leq \int_{T_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \\ & \quad \cdots \int_{T_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T_1}^{s_{n-1}} \{ |R(s_n)| + |u(s_n)| [\alpha |x(\delta(s_n))|^\gamma + \beta] \} \Delta s_n \\ & = \int_{T_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T_1}^{s_{n-1}} [|R(s_n)| + \beta |u(s_n)|] \Delta s_n \\ & \quad + \int_{T_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T_1}^{s_{n-1}} |u(s_n)| \alpha |x(\delta(s_n))|^\gamma \Delta s_n \\ & \leq d + \int_{T_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \\ & \quad \cdots \int_{T_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T_1}^{s_{n-1}} |u(s_n)| \alpha |x(\delta(s_n))|^\gamma \Delta s_n. \end{aligned} \quad (3.10)$$

We can apply Lemma 2.1 with  $c = d$ ,  $h(s_1, s_2, \dots, s_n) = \frac{\alpha |u(s_n)|}{a_1(s_1)a_2(s_2)\cdots a_{n-1}(s_{n-1})}$ ,  $\xi = \gamma$ , and  $p(s) = s^\gamma$ . From condition (3.9) we have

$$\begin{aligned} & d^{1-\gamma} - (\gamma-1)\alpha \int_{T_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T_1}^{s_{n-1}} |u(s_n)| \Delta s_n \\ & > d^{1-\gamma} - (\gamma-1) \frac{d^{1-\gamma}}{2(\gamma-1)} = \frac{d^{1-\gamma}}{2} > 0. \end{aligned}$$

Thus, (2.4) holds. It follows from Lemma 2.1 that

$$\begin{aligned} x(\delta(t)) &\leq \left[ d^{1-\gamma} - (\gamma-1)\alpha \int_{T_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T_1}^{s_{n-1}} |u(s_n)| \Delta s_n \right]^{\frac{-1}{\gamma-1}} \\ &\leq \frac{2^{\frac{1}{\gamma-1}}}{d}. \end{aligned}$$

So  $x(\delta(t))$  is bounded. A similar argument holds for intervals where  $x(t)$  is negative.

If  $\gamma = 1$ , then choose  $\hat{T} \geq t_0$  so that (3.8) holds with  $T^*$  replaced by  $\hat{T}$  and

$$\int_{\hat{T}}^{\infty} \frac{\Delta s_1}{a_1(s_1)} \int_{\hat{T}}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{\hat{T}}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{\hat{T}}^{s_{n-1}} |u(s_n)| \Delta s_n < \frac{1}{\alpha+1}.$$

Choose  $T^* < T'_1 \leq T'_2 \leq \cdots \leq T'_{n-1} \leq T'_n$  so that  $R_{n-i}(T'_i, x(T'_i))R_{n-i}(\sigma(T'_i), x(\sigma(T'_i))) \leq 0$  with  $R_{n-i}(T'_i, x(T'_i)) \geq 0$  for  $1 \leq i \leq n$  and  $\delta(t) > T'_{n-1}$  for  $t \geq T'_n$ . As in the proof of Theorem 3.1, using (3.8), we have

$$x(\delta(t)) \geq -d - \int_{T'_1}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{T'_1}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_{T'_1}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{T'_1}^{s_{n-1}} |u(s_n)| \alpha |x(\delta(s_n))| \Delta s_n.$$

Combining (3.10) with this inequality, we obtain

$$\begin{aligned} |x(\delta(t))| &\leq d + \int_L^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_L^{s_1} \frac{\Delta s_2}{a_2(s_2)} \\ &\quad \cdots \int_L^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_L^{s_{n-1}} |u(s_n)| \alpha |x(\delta(s_n))| \Delta s_n, \end{aligned} \quad (3.11)$$

where  $L = \min\{T_1, T'_1\}$ . Denoting by  $z(t)$  the right side of inequality (3.11), we see that  $|x(\delta(t))| \leq z(t)$ ,  $z(\delta(t)) \leq z(t)$ , and

$$\begin{aligned} z(t) &= d + \int_L^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_L^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_L^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_L^{s_{n-1}} |u(s_n)| \alpha |x(\delta(s_n))| \Delta s_n \\ &\leq d + \int_L^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_L^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_L^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_L^{s_{n-1}} |u(s_n)| \alpha z(s_n) \Delta s_n \\ &\leq d + z(t) \int_L^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_L^{s_1} \frac{\Delta s_2}{a_2(s_2)} \cdots \int_L^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_L^{s_{n-1}} |u(s_n)| \alpha \Delta s_n \\ &\leq d + \frac{\alpha}{\alpha+1} z(t), \end{aligned}$$

which implies  $x(\delta(t)) \leq d(\alpha+1)$ . The proof is complete.  $\square$

After seeing the proof of Theorem 3.2, the proof of the following Theorem 3.3 becomes obvious.

**Theorem 3.3** Assume that conditions  $(H_1)$ – $(H_3)$  hold with  $\gamma \geq 1$ . If (3.1) holds, then every oscillatory solution of (1.1) converges to zero as  $t \rightarrow \infty$ .

In a similar fashion as before, we can show the following theorem.

**Theorem 3.4** *Assume that conditions  $(H_1)$ – $(H_3)$  hold with  $0 < \gamma < 1$ . If (3.1) holds, then every oscillatory solution of (1.1) is bounded and converges to zero as  $t \rightarrow \infty$ .*

*Proof* Notice that taking  $p(v) = v^\xi$  and  $0 < \xi < 1$  in Lemma 2.1, we have

$$P(z(t)) - P(z(t_0)) = \frac{1}{1-\xi} [z^{1-\xi}(t) - z^{1-\xi}(t_0)].$$

So

$$\frac{1}{1-\xi} z^{1-\xi}(t) \leq \frac{1}{1-\xi} z^{1-\xi}(t_0) + \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n,$$

that is,

$$z(t) \leq \left[ z^{1-\xi}(t_0) + (1-\xi) \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n \right]^{\frac{1}{1-\xi}}.$$

We have

$$r(t) \leq \left[ z^{1-\xi}(t_0) + (1-\xi) \int_{t_0}^t \Delta s_1 \int_{t_0}^{s_1} \Delta s_2 \int_{t_0}^{s_2} \cdots \int_{t_0}^{s_{n-1}} h(s_1, s_2, \dots, s_n) \Delta s_n \right]^{\frac{1}{1-\xi}}.$$

Further, the proof is similar to that of Theorem 3.2, so we have

$$\begin{aligned} x(\delta(t)) &\leq \left[ d^{1-\gamma} + (1-\gamma)\alpha \int_{t_0}^{\delta(t)} \frac{\Delta s_1}{a_1(s_1)} \int_{t_0}^{s_1} \frac{\Delta s_2}{a_2(s_2)} \right. \\ &\quad \left. \cdots \int_{t_0}^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_{t_0}^{s_{n-1}} |u(s_n)| \Delta s_n \right]^{\frac{1}{1-\gamma}}. \end{aligned}$$

So we can conclude that every oscillatory solution of (1.1) is bounded, and by Theorem 3.1  $x(t)$  converges to zero as  $t \rightarrow \infty$ . The proof is complete.  $\square$

**Theorem 3.5** *Assume that conditions  $(H_1)$ – $(H_3)$  hold with  $g(0) = 0$ . If there exists  $N > 0$  such that for all large  $T$ , either*

$$\liminf_{t \rightarrow \infty} \int_T^t [R(s) - N|u(s)|] \Delta s > 0 \quad (3.12)$$

or

$$\limsup_{t \rightarrow \infty} \int_T^t [R(s) + N|u(s)|] \Delta s < 0, \quad (3.13)$$

*then all solutions of (1.1) are nonoscillatory.*

*Proof* For contradiction, let  $x(t)$  be an oscillatory solution of (1.1). By Theorem 3.3 and Theorem 3.4,  $x(t)$  converges to 0 as  $t \rightarrow \infty$ . Hence, there exists  $T_0 \geq t_0$  such that



$|g(x(\delta(t)))| \leq N$  for  $t \geq T_0$ . From (1.3) we have

$$R(t) - N|u(t)| \leq R_{n-1}^\Delta(t, x(t)) \leq R(t) + N|u(t)|. \quad (3.14)$$

If (3.12) holds, then we choose  $T \geq T_0$  such that  $\delta(t) \geq T_0$  for  $t \geq T$ ,

$$R_{n-2}(T, x(T))R_{n-2}(\sigma(T), x(\sigma(T))) \leq 0, \quad R_{n-2}(T, x(T)) \geq 0, \quad (3.15)$$

and integrating the left inequality in (3.14) from  $T$  to  $t$ , we obtain

$$R_{n-2}(T, x(T)) + \int_T^t [R(s) - N|u(s)|] \Delta s \leq R_{n-2}(t, x(t)).$$

This is a contradiction since if  $x(t)$  is oscillatory, then  $R_{n-2}(t, x(t))$  is also oscillatory.

If (3.13) holds, then we choose  $T$  so that the second inequality in (3.15) is reversed. This completes the proof of the theorem.  $\square$

#### 4 Example

In this section, we give an example to illustrate our main results.

**Lemma 4.1** [23, 24] Assume that  $s, t \in \mathbb{T}$  and  $g \in C_{rd}(\mathbb{T} \times \mathbb{T}, \mathbb{R})$ . Then

$$\int_s^t \left[ \int_\eta^t g(\eta, \zeta) \Delta \zeta \right] \Delta \eta = \int_s^t \left[ \int_s^{\sigma(\zeta)} g(\eta, \zeta) \Delta \eta \right] \Delta \zeta.$$

**Example 4.1** Let  $\mathbb{T} = \{q^n : n \in \mathbb{Z}\} \cup \{0\}$  with  $q > 1$ . Consider the higher-order dynamic equation

$$(t(t(\dots(t^{2+\frac{1}{\gamma}}x^\Delta)\dots)^\Delta)^\Delta)^\Delta + \frac{1}{t^{1+k\gamma+\frac{1}{\gamma}}} \left| x\left(\frac{t}{q}\right) \right|^\gamma \operatorname{sgn} x\left(\frac{t}{q}\right) = \frac{1}{t^{1+\frac{1}{\gamma}}}, \quad (4.1)$$

where  $t \in [q, \infty)_{\mathbb{T}}$ ,  $\gamma > 0$ ,  $k \geq 0$ ,  $a_1(t) = t^{2+\frac{1}{\gamma}}$ ,  $a_i(t) = t$  ( $2 \leq i \leq n-1$ ),  $u(t) = \frac{1}{t^{1+k\gamma+\frac{1}{\gamma}}}$ ,  $\delta(t) = \frac{t}{q}$ ,  $R(t) = \frac{1}{t^{1+\frac{1}{\gamma}}}$ , and  $g(u) = |u|^\gamma \operatorname{sgn}(u)$ .

It is easy to verify that  $R(t)$  and  $u(t)$  satisfy the condition (3.12). We will use the following inequality: if  $s > t \geq q$ , then

$$\begin{aligned} \int_t^s \frac{1}{\tau} \Delta \tau &= \int_t^{qt} \frac{1}{\tau} \Delta \tau + \int_{qt}^{q^2t} \frac{1}{\tau} \Delta \tau + \dots + \int_{q^{n-1}t}^{q^nt=s} \frac{1}{\tau} \Delta \tau \\ &= \frac{qt-t}{t} + \frac{q^2t-qt}{qt} + \dots + \frac{q^nt-q^{n-1}t}{q^{n-1}t} \\ &= n(q-1) \leq q^{n+1} \leq q^nt = s. \end{aligned}$$

Applying Lemma 4.1 and the last inequality, we have

$$\begin{aligned} &\int_q^\infty \frac{\Delta s_1}{a_1(s_1)} \int_q^{s_1} \frac{\Delta s_2}{a_2(s_2)} \dots \int_q^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_q^{s_{n-1}} |u(s_n)| \Delta s_n \\ &\leq \int_q^\infty \frac{\Delta s_1}{a_1(s_1)} \int_q^{s_1} \frac{\Delta s_2}{a_2(s_2)} \dots \int_q^{s_{n-2}} \frac{\Delta s_{n-1}}{a_{n-1}(s_{n-1})} \int_q^{s_{n-1}} |R(s_n)| \Delta s_n \end{aligned}$$

$$\begin{aligned}
&= \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-2}} \frac{\Delta s_{n-1}}{s_{n-1}} \int_q^{s_{n-1}} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&= \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-3}} \frac{\Delta s_{n-2}}{s_{n-2}} \int_q^{s_{n-2}} \Delta s_{n-1} \int_q^{s_{n-1}} \frac{1}{s_{n-1}} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&\leq \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-3}} \frac{\Delta s_{n-2}}{s_{n-2}} \int_q^{s_{n-2}} \Delta s_{n-1} \int_q^{\sigma(s_{n-1})} \frac{1}{s_{n-1}} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&= \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-3}} \frac{\Delta s_{n-2}}{s_{n-2}} \int_q^{s_{n-2}} \frac{\Delta s_n}{s_n^{1+\frac{1}{\gamma}}} \int_{s_n}^{s_{n-2}} \frac{1}{s_{n-1}} \Delta s_{n-1} \\
&\leq \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-3}} \frac{\Delta s_{n-2}}{s_{n-2}} \int_q^{s_{n-2}} \frac{s_{n-2}}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&= \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-4}} \frac{\Delta s_{n-3}}{s_{n-3}} \int_q^{s_{n-3}} \Delta s_{n-2} \int_q^{s_{n-2}} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&\leq \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-4}} \frac{\Delta s_{n-3}}{s_{n-3}} \int_q^{s_{n-3}} \Delta s_{n-2} \int_q^{\sigma(s_{n-2})} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&= \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-4}} \frac{\Delta s_{n-3}}{s_{n-3}} \int_q^{s_{n-3}} \Delta s_n \int_{s_n}^{s_{n-3}} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_{n-2} \\
&\leq \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{\Delta s_2}{s_2} \cdots \int_q^{s_{n-3}} \frac{s_{n-3}}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&\dots \\
&\leq \int_q^\infty \frac{\Delta s_1}{s_1^{2+\frac{1}{\gamma}}} \int_q^{s_1} \frac{s_1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \leq \int_q^\infty \frac{\Delta s_1}{s_1^{1+\frac{1}{\gamma}}} \int_q^{\sigma(s_1)} \frac{1}{s_n^{1+\frac{1}{\gamma}}} \Delta s_n \\
&= \int_q^\infty \frac{\Delta s_n}{s_n^{1+\frac{1}{\gamma}}} \int_{s_n}^\infty \frac{1}{s_1^{1+\frac{1}{\gamma}}} \Delta s_1 \\
&\leq \int_q^\infty \frac{\Delta s_n}{s_n^{1+\frac{1}{\gamma}}} \int_q^\infty \frac{1}{s_1^{1+\frac{1}{\gamma}}} \Delta s_1 = \left( \frac{q-1}{q^{\frac{1}{\gamma}}-1} \right)^2 < \infty.
\end{aligned}$$

Thus, conditions  $(H_1)$ – $(H_3)$  and (3.1) hold. Then it follows from Theorem 3.5 that every solution  $x(t)$  of (4.1) is nonoscillatory.

#### Competing interests

The authors declare that they have no competing interests.

#### Authors' contributions

All authors contributed equally and significantly in writing this article. All authors read and approved the final manuscript.

#### Author details

<sup>1</sup>College of Mathematics and Information Science, Guangxi University, Nanning, Guangxi 530004, China. <sup>2</sup>College of Information and Statistics, Guangxi University of Finance and Economics, Nanning, Guangxi 530003, China. <sup>3</sup>College of Electrical Engineering, Guangxi University, Nanning, Guangxi 530004, China.

#### Acknowledgements

This project is supported by NNSF of China (11461003).

Received: 26 November 2015 Accepted: 21 February 2016 Published online: 27 February 2016

## References

- Hilger, S: Analysis on measure chains - a unified approach to continuous and discrete calculus. *Results Math.* **18**, 18-56 (1990)
- Kac, V, Chueng, P: *Quantum Calculus*. Universitext (2002)
- Bohner, M, Peterson, A: *Dynamic Equations on Time Scales: An Introduction with Applications*. Birkhäuser, Boston (2001)
- Bohner, M, Peterson, A: *Advances in Dynamic Equations on Time Scales*. Birkhäuser, Boston (2003)
- Bohner, M, Li, T: Kamenev-type criteria for nonlinear damped dynamic equations. *Sci. China Math.* **58**, 1445-1452 (2015)
- Zhang, C, Agarwal, RP, Bohner, M, Li, T: Oscillation of fourth-order delay dynamic equations. *Sci. China Math.* **58**, 143-160 (2015)
- Zhang, C, Li, T: Some oscillation results for second-order nonlinear delay dynamic equations. *Appl. Math. Lett.* **26**, 1114-1119 (2013)
- Agarwal, RP, Bohner, M, Saker, SH: Oscillation of second order delay dynamic equations. *Can. Appl. Math. Q.* **13**, 1-17 (2005)
- Bohner, M, Karpuz, B, Öcalan, Ö: Iterated oscillation criteria for delay dynamic equations of first order. *Adv. Differ. Equ.* **2008**, 458687 (2008)
- Erbe, L, Peterson, A, Saker, SH: Oscillation criteria for second-order nonlinear delay dynamic equations. *J. Math. Anal. Appl.* **333**, 505-522 (2007)
- Han, Z, Shi, B, Sun, S: Oscillation criteria for second-order delay dynamic equations on time scales. *Adv. Differ. Equ.* **2007**, 070730 (2007)
- Han, Z, Sun, S, Shi, B: Oscillation criteria for a class of second-order Emden-Fowler delay dynamic equations on time scales. *J. Math. Anal. Appl.* **334**, 847-858 (2007)
- Şahiner, Y: Oscillation of second-order delay differential equations on time scales. *Nonlinear Anal.* **63**, e1073-e1080 (2005)
- Şahiner, Y: Oscillation of second-order neutral delay and mixed-type dynamic equations on time scales. *Adv. Differ. Equ.* **2006**, 065626 (2006)
- Zhang, B, Zhu, S: Oscillation of second-order nonlinear delay dynamic equations on time scales. *Comput. Math. Appl.* **49**, 599-609 (2005)
- Grace, SR, Agarwal, RP, Kaymakçalan, B, Sae-jie, W: On the oscillation of certain second order nonlinear dynamic equations. *Math. Comput. Model.* **50**, 273-286 (2009)
- Erbe, L, Peterson, A, Saker, SH: Asymptotic behavior of solutions of a third-order nonlinear dynamic equation on time scales. *J. Comput. Appl. Math.* **181**, 92-102 (2005)
- Erbe, L, Peterson, A, Saker, SH: Hille and Nehari type criteria for third order dynamic equations. *J. Math. Anal. Appl.* **329**, 112-131 (2007)
- Erbe, L, Peterson, A, Saker, SH: Oscillation and asymptotic behavior a third-order nonlinear dynamic equation. *Can. Appl. Math. Q.* **14**, 129-147 (2006)
- Karpuz, B, Öcalan, Ö, Rath, RN: Necessary and sufficient conditions on the oscillatory and asymptotic behaviour of solutions to neutral delay dynamic equation. *Electron. J. Differ. Equ.* **2009**, 64 (2009)
- Zhu, Z, Wang, Q: Existence of nonoscillatory solutions to neutral dynamic equations on time scales. *J. Math. Anal. Appl.* **335**, 751-762 (2007)
- Karpuz, B, Öcalan, Ö: Necessary and sufficient conditions on the asymptotic behaviour of solutions of forced neutral delay dynamic equations. *Nonlinear Anal.* **71**, 3063-3071 (2009)
- Karpuz, B: Asymptotic behaviour of bounded solutions of a class of higher-order neutral dynamic equations. *Appl. Math. Comput.* **215**, 2174-2183 (2009)
- Karpuz, B: Unbounded oscillation of higher-order nonlinear delay dynamic equations of neutral type with oscillating coefficients. *Electron. J. Qual. Theory Differ. Equ.* **2009**, 34 (2009)
- Wu, X, Sun, T, Xi, H, Cheng, C: Kamenev-type oscillation criteria for higher-order nonlinear dynamic equations on time scales. *Adv. Differ. Equ.* **2013**, 248 (2013)
- Sun, T, Xi, H, Peng, X, Yu, W: Nonoscillatory solutions for higher-order neutral dynamic equations on time scales. *Abstr. Appl. Anal.* **2010**, 428963 (2010)
- Zhang, Z, Dong, W, Li, Q, Liang, H: Positive solutions for higher order nonlinear neutral dynamic equations on time scales. *Appl. Math. Model.* **33**, 2455-2463 (2009)
- Agarwal, RP, Bohner, M: Basic calculus on time scales and some of its applications. *Results Math.* **35**, 3-22 (1999)
- Graef, JR, Hill, M: Nonoscillation of all solutions of a higher order nonlinear delay dynamic equation on time scales. *J. Math. Anal. Appl.* **423**, 1693-1703 (2015)