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# Existence of solutions for fractional stochastic impulsive neutral functional differential equations with infinite delay

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## Abstract

This paper addresses a class of fractional stochastic impulsive neutral functional differential equations with infinite delay which arise from many practical applications such as viscoelasticity and electrochemistry. Using fractional calculations, fixed point theorems and the stochastic analysis technique, sufficient conditions are derived to ensure the existence of solutions. An example is provided to prove the main result.

**Keywords:** fractional stochastic functional differential equations; existence; neutral; impulsive; infinite delay; fixed point theorem

## 1 Introduction

It is commonly believed that fractional calculus dates back to 1695. Fractional derivatives supply a powerful tool in describing the memory and hereditary properties of many materials and processes [1, 2]. Many researchers have focused their attention on fractional differential equations. For example, robust stability and stabilization of fractional-order interval systems were investigated in [3]. Li et al. presented a stability theorem for fractional-order nonlinear dynamic systems [4].

Dynamical behaviors such as existence and stability are basic problems of fractional differential equations [5–10]. Shen and Lam proved that for fractional-order nonlinear system described by Caputo's or Riemann-Liouville's definition, any equilibrium cannot be finite-time stable as long as the continuous solution corresponding to the initial value problem globally exists [5]. Song and Cao gave some sufficient conditions ensuring the existence and uniqueness of the nontrivial solution [6]. In recent years, scholars have paid more attention to impulsive differential equations. This is mainly because of many processes in which their state is changed suddenly at some instants. These phenomena can be described by impulsive differential equations. So far, there have been several interesting results that studied the existence of solutions for fractional impulsive differential equations, see [11–20] and the references therein.

It is well known that time delays exist in different technical systems which may cause unpredictable system behaviors. There are some results about integer-order and fractional-order functional differential equations with infinite delay [11, 12, 21–24]. Sakthivel et al. studied the existence of solutions for a class of nonlinear fractional differential equations

with infinite delays by utilizing fractional calculations and a fixed point technique [11]. Another kind of time-delay, called neutral-type time-delay, has received considerable attention [25–27]. Actually, many real delayed systems can be described as neutral differential equations. The differential expression includes the derivative terms of current state and past state. In [12], Liao et al. gave the existence theorem of solutions for fractional impulsive neutral functional differential equations with infinite delay by using the Caputo fractional derivative, Hausdorff's measure of noncompactness and the theory of Mönch.

Since the real environment is influenced by noise inevitably, it is significant to consider the dynamical properties for a fractional stochastic impulsive neutral functional differential equation with infinite delay, especially for the existence of solutions. To the best of our knowledge, few results have studied this problem, and the aim of this paper is to shorten this gap.

Motivated by the above discussions, in this paper we aim to study the existence of solutions for fractional stochastic impulsive neutral functional differential equations with infinite delays. In the established model, the stochastic disturbances are described in terms of a Brownian motion. By using fixed point theorems, we derive sufficient criteria to ensure the existence of solutions. Moreover, our results take some well-studied models, such as integer-order functional differential equations with infinite delay, as special cases.

This paper is organized as follows. In Section 2, we introduce some useful preliminaries. In Section 3, we prove the existence of solutions for the fractional-order system under investigation. In Section 4, an example is given to demonstrate the correctness of the main theorems. Conclusions are made in Section 5.

## 2 Preliminaries

In this paper, we adopt the symbols as follows:  $K_1$  and  $K_2$  are separable Hilbert spaces.  $\mathcal{L}(K_2, K_1)$  is the space which contains all the bounded linear operators from  $K_2$  into  $K_1$ .  $\|\cdot\|$  and  $(\cdot, \cdot)$  denote the norm and inner product in  $K_1$  and  $K_2$ .  $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, P)$  is a complete filtered probability space satisfying the fact that  $\mathcal{F}_0$  contains all  $P$ -null sets of  $\mathcal{F}$ .  $W = \{W(t)\}_{t \geq 0}$  is a  $Q$ -Wiener process defined on  $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, P)$  with the covariance operator  $Q$  such that  $\text{Tr}Q < \infty$ .  $E\{\cdot\}$  denotes the expectation. It is assumed that  $Q\delta_k = \gamma_k\delta_k$ ,  $k = 1, 2, \dots$ , and  $(w(u), \delta)_{K_2} = \sum_{k=1}^{\infty} \sqrt{\gamma_k}(\delta_k, \delta)_{K_2} \beta_k(u)$ ,  $\delta \in K_2$ ,  $e \geq 0$ , where  $\{\delta_k\}_{k \geq 1}$  in  $K_2$  is a complete orthonormal system,  $\gamma_k$  is a bounded sequence of nonnegative real numbers,  $\{\beta_k\}_{k \geq 1}$  are independent Brownian motions.

We discuss the following fractional functional differential equations:

$$\begin{cases} {}^c D_u^\alpha [x(u) + g(u, x_u)] = f(u, x_u) + \sigma(u, x_u) \frac{dW(u)}{du}, & u \in H = [0, T], u \neq u_k, \\ \Delta x(u_k) = I_k(x(u_k)), & u = u_k, k = 1, 2, \dots, m, \\ x(u) = \xi(u) \in \mathcal{B}_h, & u \in (-\infty, 0], \end{cases} \quad (2.1)$$

where  ${}^c D_u^\alpha$  denotes  $\alpha$ -order Caputo fractional derivative,  $\alpha > \frac{1}{2}$ ;  $x(\cdot) \in K_1$ . The history  $x_u : (-\infty, 0] \rightarrow K_1$ ,  $x_u(v) = x(u+v) \in \mathcal{B}_h$ ,  $v \leq 0$ .  $f : H \times \mathcal{B}_h \rightarrow K_1$ ,  $g : H \times \mathcal{B}_h \rightarrow K_1$ ,  $\sigma : H \times \mathcal{B}_h \rightarrow \mathcal{L}_2^0$ ,  $I_k : \mathcal{B}_h \rightarrow K_1$  ( $k = 1, 2, \dots, m$ ) are appropriate functions. Here  $0 = u_0 \leq u_1 \leq \dots \leq u_m \leq u_{m+1} = T$ ,  $\Delta x(u_k) = x(u_k^+) - x(u_k^-)$ ,  $x(u_k^+) = \lim_{\epsilon \rightarrow 0^+} x(u_k + \epsilon)$  and  $x(u_k^-) = \lim_{\epsilon \rightarrow 0^+} x(u_k - \epsilon)$ .  $\xi = \{\xi(u), u \in (-\infty, 0]\}$  denotes the initial condition, and it is an  $\mathcal{F}_0$ -measurable  $\mathcal{B}_h$ -values random variable which is independent of  $\omega$ .

We adopt the following symbols in [22].

Suppose  $h : (-\infty, 0] \rightarrow (0, \infty)$  is a continuous function satisfying  $l = \int_{-\infty}^0 h(u) du < \infty$ . Define the space  $\mathcal{B}_h$  by

$$\mathcal{B}_h = \left\{ \xi : (-\infty, 0] \rightarrow K_1, \text{ for any } a > 0, (E|\xi(\theta)|^2)^{\frac{1}{2}} \text{ is a bounded and measurable function on } [-a, 0] \text{ with } \xi(0) = 0 \text{ and } \int_{-\infty}^0 h(v) \sup_{v \leq \theta \leq 0} (E|\xi(\theta)|^2)^{\frac{1}{2}} dv < \infty \right\}.$$

Let  $\|\xi\|_{\mathcal{B}_h} = \int_{-\infty}^0 h(v) \sup_{v \leq \theta \leq 0} (E|\xi(\theta)|^2)^{\frac{1}{2}} dv$ ,  $\xi \in \mathcal{B}_h$ , then  $(\mathcal{B}_h, \|\cdot\|_{\mathcal{B}_h})$  is a Banach space. Define the space

$$\mathcal{B}_b = \{x : (-\infty, T] \rightarrow K_1 \text{ such that } x|_{H_k} \in C(H_k, K_1) \text{ and there exist } x(u_k^+), x(u_k^-), x(u_k) = x(u_k^-), x_0 = \xi \in \mathcal{B}_h, k = 1, 2, \dots, m\},$$

where  $x|_{H_k}$  is the restriction of  $x$  to  $H_k = (u_k, u_{k+1}]$ ,  $k = 0, 1, 2, \dots, m$ . Define  $\|x\|_{\mathcal{B}_b} = \|\xi\|_{\mathcal{B}_h} + \sup_{v \in [0, T]} (E\|x(v)\|_{K_1}^2)^{\frac{1}{2}}$ ,  $x \in \mathcal{B}_b$ , then  $\|\cdot\|_{\mathcal{B}_b}$  is a seminorm in  $\mathcal{B}_b$ .

The following definitions and lemmas are needed to ensure the existence of solutions of (2.1).

**Definition 2.1** ([1, 2]) The fractional integral of order  $\alpha$  for a function  $f$  is defined as

$$I^\alpha f(u) = \frac{1}{\Gamma(\alpha)} \int_{u_0}^u (u-v)^{\alpha-1} f(v) dv,$$

where  $u \geq u_0$  and  $\alpha > 0$ .

**Definition 2.2** ([1, 2]) Caputo's derivative of order  $\alpha$  for a function  $f \in C^n([u_0, +\infty), R)$  is defined by

$${}^c D_\alpha^u f(u) = \frac{1}{\Gamma(n-\alpha)} \int_{u_0}^u (u-v)^{n-\alpha-1} f^{(n)}(v) dv,$$

where  $u \geq u_0$  and  $n$  is a positive integer such that  $n-1 < \alpha < n$ .

Particularly, when  $0 < \alpha < 1$ ,  ${}^c D_\alpha^u f(u) = \frac{1}{\Gamma(1-\alpha)} \int_{u_0}^u (u-v)^{-\alpha} f'(v) dv$ .

**Definition 2.3** An  $\mathcal{F}_t$ -adapted stochastic process  $x : (-\infty, T] \rightarrow K_1$  is called a solution of (2.1) if  $x_0 = \xi \in \mathcal{B}_h$  satisfying  $x_0 \in \mathcal{L}_2^0(\Omega, K_1)$  and the following conditions hold:

- (i)  $x(u)$  is  $\mathcal{B}_h$ -valued and the restriction of  $x(\cdot)$  to the interval  $(u_k, u_{k+1}]$  ( $k = 1, 2, \dots, m$ ) is continuous.
- (ii)

$$x(u) = \begin{cases} \xi(u), & u \in (-\infty, 0], \\ \xi(0) + g(0, \xi(0)) - g(u, x_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, x_v) dv + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, x_v) dW(v), & u \in (0, u_1], \\ \xi(0) + g(0, \xi(0)) - g(u, x_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, x_v) dv + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, x_v) dW(v) + \sum_{i=1}^k I_i(x(u_i)), & u \in (u_k, u_{k+1}], k = 1, 2, \dots, m. \end{cases} \quad (2.2)$$

- (iii)  $\Delta x|_{u=u_k} = I_k(x(u_k))$ ,  $k = 1, 2, \dots, m$ , the restriction of  $x(\cdot)$  to the interval  $[0, T] \setminus \{u_1, \dots, u_m\}$  is continuous.

**Lemma 2.4** Assume, for all  $u \in H = [0, T]$ ,  $x_u \in \mathcal{B}_h$ ,  $x_0 = \xi \in \mathcal{B}_h$ , then

$$\|x_u\|_{\mathcal{B}_h} \leq l \sup_{u \in [0, T]} (E\|x(u)\|_{K_1}^2)^{\frac{1}{2}} + \|x_0\|_{\mathcal{B}_h}.$$

*Proof* For all  $u \in [0, T]$ ,

$$\begin{aligned} \sup_{v \leq \theta \leq 0} (E\|x(u + \theta)\|^2)^{\frac{1}{2}} &\leq \max \left\{ \sup_{v \leq \theta \leq -u} (E\|x(u + \theta)\|^2)^{\frac{1}{2}}, \sup_{-u \leq \theta \leq 0} (E\|x(u + \theta)\|^2)^{\frac{1}{2}} \right\} \\ &\leq \sup_{v \leq \theta \leq -u} (E\|x(u + \theta)\|^2)^{\frac{1}{2}} + \sup_{-u \leq \theta \leq 0} (E\|x(u + \theta)\|^2)^{\frac{1}{2}} \\ &= \sup_{v+u \leq \theta \leq 0} (E\|x(\theta)\|^2)^{\frac{1}{2}} + \sup_{0 \leq v \leq u} (E\|x(v)\|^2)^{\frac{1}{2}} \\ &\leq \sup_{v \leq \theta \leq 0} (E\|x(\theta)\|^2)^{\frac{1}{2}} + \sup_{0 \leq u \leq T} (E\|x(u)\|^2)^{\frac{1}{2}}. \end{aligned}$$

So

$$\begin{aligned} \|x_u\|_{\mathcal{B}_h} &= \int_{-\infty}^0 h(v) \sup_{v \leq \theta \leq 0} (E|x_u(\theta)|^2)^{\frac{1}{2}} dv \\ &= \int_{-\infty}^0 h(v) \sup_{v \leq \theta \leq 0} (E|x(u + \theta)|^2)^{\frac{1}{2}} dv \\ &\leq \int_{-\infty}^0 h(v) \left( \sup_{v \leq \theta \leq 0} (E\|x(\theta)\|^2)^{\frac{1}{2}} + \sup_{0 \leq u \leq T} (E\|x(u)\|^2)^{\frac{1}{2}} \right) dv \\ &= \int_{-\infty}^0 h(v) \sup_{v \leq \theta \leq 0} (E\|x(\theta)\|^2)^{\frac{1}{2}} dv + \int_{-\infty}^0 h(v) \sup_{0 \leq u \leq T} (E\|x(u)\|^2)^{\frac{1}{2}} dv \\ &= \int_{-\infty}^0 h(v) dv \sup_{0 \leq u \leq T} (E\|x(u)\|^2)^{\frac{1}{2}} + \|x_0\|_{\mathcal{B}_h} \\ &= l \sup_{0 \leq u \leq T} (E\|x(u)\|^2)^{\frac{1}{2}} + \|x_0\|_{\mathcal{B}_h}. \end{aligned}$$

This completes the proof.  $\square$

**Lemma 2.5** (Krasnoselskii's fixed point theorem [19]) Let  $B$  be a nonempty closed convex set of a Banach space  $(X, \|\cdot\|)$ . Suppose that  $P$  and  $Q$  map  $B$  into  $X$  such that

- (i)  $Px + Qy \in B$  whenever  $x, y \in B$ ;
- (ii)  $P$  is compact and continuous;
- (iii)  $Q$  is a contraction mapping;

then there exists  $z \in B$  such that  $z = Pz + Qz$ .

### 3 Main results

To obtain the existence of solutions of (2.1), we need the following assumptions:

(H1) There exists  $L_1 > 0$  such that

$$E\|f(u, x) - f(u, y)\|_{K_1}^2 \leq L_1 \|x - y\|_{\mathcal{B}_h}^2, \quad \forall x, y \in \mathcal{B}_h.$$

(H2) There exists  $L_2 > 0$  such that

$$E \|g(u, x) - g(u, y)\|_{K_1}^2 \leq L_2 \|x - y\|_{\mathcal{B}_h}^2, \quad \forall x, y \in \mathcal{B}_h.$$

(H3) There exists  $L_3 > 0$  such that

$$E \|\sigma(u, x) - \sigma(u, y)\|_{\mathcal{L}_2^0}^2 \leq L_3 \|x - y\|_{\mathcal{B}_h}^2, \quad \forall x, y \in \mathcal{B}_h.$$

(H4) There exists  $L_4 > 0$  such that

$$E \|I_k(x) - I_k(y)\|_{K_1}^2 \leq L_4 \|x - y\|_{\mathcal{B}_h}^2, \quad \forall x, y \in \mathcal{B}_h \text{ and } k = 1, 2, \dots, m.$$

Now we will use the Banach fixed point theorem to prove the existence theorem for (2.1).

**Theorem 3.1** *Assume that conditions (H1)-(H4) hold, then (2.1) has a unique solution if the following condition holds:*

$$4l^2 \left( L_2 + \frac{1}{\Gamma(\alpha)} L_1 \frac{T^{2\alpha}}{\alpha^2} + \frac{1}{\Gamma(\alpha)} L_3 \frac{T^{2\alpha-1}}{2\alpha-1} + m^2 L_4 \right) < 1. \quad (3.1)$$

*Proof* Define the operator  $\Pi : \mathcal{B}_b \rightarrow \mathcal{B}_b$  by

$$\Pi x(t) = \begin{cases} \xi(u), & u \in (-\infty, 0], \\ \xi(0) + g(0, \phi(0)) - g(u, x_u) \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, x_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, x_v) dW(v), & u \in (0, u_1], \\ \xi(0) + g(0, \phi(0)) - g(u, x_u) \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, x_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, x_v) dW(v) \\ \quad + \sum_{i=1}^k I_i(x(u_i)), & u \in (u_k, u_{k+1}], k = 1, 2, \dots, m. \end{cases} \quad (3.2)$$

For  $\xi \in \mathcal{B}_b$ , define

$$\bar{\xi}(t) = \begin{cases} \xi(u), & u \in (-\infty, 0], \\ 0, & u \in H, \end{cases}$$

then  $\bar{\xi}_0 = \xi$ . Next, define the function

$$\bar{\eta}(t) = \begin{cases} 0, & u \in (-\infty, 0], \\ \eta(u), & u \in H, \end{cases}$$

for each  $\eta \in C(H, R)$ , with  $\eta(0) = 0$ .

If  $x(\cdot)$  satisfies (2.2), then  $x(u) = \bar{\xi}(u) + \bar{\eta}(u)$  for  $u \in H$ , which implies  $x_u = \bar{\xi}_u + \bar{\eta}_u$  for  $u \in H$ , and the function  $\eta(\cdot)$  satisfies

$$\eta(u) = \begin{cases} g(0, \xi(0)) - g(u, x_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, x_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, x_v) dW(v), & u \in (0, u_1], \\ g(0, \xi(0)) - g(u, x_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, x_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, x_v) dW(v) \\ \quad + \sum_{i=1}^k I_i(x(u_i)), & u \in (u_k, u_{k+1}], \\ & k = 1, 2, \dots, m \end{cases}$$

$$= \begin{cases} g(0, \xi(0)) - g(u, \bar{\xi}_u + \bar{\eta}_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, \bar{\xi}_v + \bar{\eta}_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, \bar{\xi}_v + \bar{\eta}_v) dW(v), & u \in (0, u_1], \\ g(0, \xi(0)) - g(u, \bar{\xi}_u + \bar{\eta}_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, \bar{\xi}_v + \bar{\eta}_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, \bar{\xi}_v + \bar{\eta}_v) dW(v) \\ \quad + \sum_{i=1}^k I_i(\bar{\xi}(u_i) + \bar{\eta}(u_i)), & u \in (u_k, u_{k+1}], \\ & k = 1, 2, \dots, m. \end{cases}$$

Set  $\mathcal{B}_b^0 = \{\eta \in \mathcal{B}_b, \text{ such that } \eta_0 = 0\}$  and for any  $\eta \in \mathcal{B}_b^0$ , one has

$$\|\eta\|_{\mathcal{B}_b^0} = \|\eta_0\|_{\mathcal{B}_h} + \sup_{u \in H} (E\|\eta(u)\|_{K_1}^2)^{\frac{1}{2}} = \sup_{u \in H} (E\|\eta(u)\|_{K_1}^2)^{\frac{1}{2}},$$

thus  $(\mathcal{B}_b^0, \|\cdot\|_{\mathcal{B}_b^0})$  is a Banach space.

Define the operator  $\Psi : \mathcal{B}_b^0 \rightarrow \mathcal{B}_b^0$  by

$$(\Psi\eta)(u) = \begin{cases} g(0, \xi(0)) - g(u, \bar{\xi}_u + \bar{\eta}_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, \bar{\xi}_v + \bar{\eta}_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, \bar{\xi}_v + \bar{\eta}_v) dW(v), & u \in (0, u_1], \\ g(0, \xi(0)) - g(u, \bar{\xi}_u + \bar{\eta}_u) + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, \bar{\xi}_v + \bar{\eta}_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, \bar{\xi}_v + \bar{\eta}_v) dW(v) \\ \quad + \sum_{i=1}^k I_i(\bar{\xi}(u_i) + \bar{\eta}(u_i)), & u \in (u_k, u_{k+1}], \\ & k = 1, 2, \dots, m. \end{cases}$$

In order to prove the existence result, it is enough to show that  $\Psi$  has a unique fixed point.

Let  $\eta, \eta^* \in \mathcal{B}_b^0$ , then for all  $u \in (0, u_1]$ , we have

$$\begin{aligned} & E\|(\Psi\eta)(u) - (\Psi\eta^*)(u)\|_{K_1}^2 \\ & \leq 3E\|g(u, \bar{\xi}_u + \bar{\eta}_u) - g(u, \bar{\xi}_u + \bar{\eta}_u^*)\|_{K_1}^2 \\ & \quad + 3E\left\|\frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} [f(v, \bar{\xi}_v + \bar{\eta}_v) - f(v, \bar{\xi}_v + \bar{\eta}_v^*)] dv\right\|_{K_1}^2 \\ & \quad + 3E\left\|\frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} [\sigma(v, \bar{\xi}_v + \bar{\eta}_v) - \sigma(v, \bar{\xi}_v + \bar{\eta}_v^*)] dW(v)\right\|_{K_1}^2 \\ & \leq 3L_2\|\bar{\eta}_u - \bar{\eta}_u^*\|_{\mathcal{B}_h}^2 + 3\left(\frac{1}{\Gamma(\alpha)}\right)^2 \int_0^u (u-v)^{\alpha-1} dv \int_0^u (u-v)^{\alpha-1} \\ & \quad \times E\|f(v, \bar{\xi}_v + \bar{\eta}_v) - f(v, \bar{\xi}_v + \bar{\eta}_v^*)\|_{K_1}^2 dv \\ & \quad + 3\left(\frac{1}{\Gamma(\alpha)}\right)^2 \int_0^u (u-v)^{2(\alpha-1)} E\|\sigma(v, \bar{\xi}_v + \bar{\eta}_v) - \sigma(v, \bar{\xi}_v + \bar{\eta}_v^*)\|_{\mathcal{L}_2^0}^2 dv \\ & \leq 3L_2\|\bar{\eta}_u - \bar{\eta}_u^*\|_{\mathcal{B}_h}^2 + 3\left(\frac{1}{\Gamma(\alpha)}\right)^2 \frac{T^\alpha}{\alpha} \int_0^u (u-v)^{\alpha-1} L_1\|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 dv \\ & \quad + 3\left(\frac{1}{\Gamma(\alpha)}\right)^2 \int_0^u (u-v)^{2(\alpha-1)} L_3\|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 dv \\ & \leq 3L_2t^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 \\ & \quad + 3\left(\frac{1}{\Gamma(\alpha)}\right)^2 \frac{T^\alpha}{\alpha} L_1 \int_0^u (u-v)^{\alpha-1} t^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 dv \end{aligned}$$

$$\begin{aligned}
 & + 3 \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_3 \int_0^u (u-v)^{2(\alpha-1)} l^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 dv \\
 & \leq 3L_2 l^2 \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2 + 3 \left( \frac{1}{\Gamma(\alpha)} \right)^2 l^2 \frac{T^{2\alpha}}{\alpha^2} L_1 \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2 \\
 & \quad + 3 \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_3 \frac{T^{2\alpha-1}}{2\alpha-1} l^2 \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2 \\
 & = 3l^2 \left[ L_2 + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} L_1 + \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_3 \frac{T^{2\alpha-1}}{2\alpha-1} \right] \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2.
 \end{aligned}$$

For  $u \in (u_k, u_{k+1}]$ ,  $k = 1, 2, \dots, m$ , one can obtain

$$\begin{aligned}
 & E \|\Psi\eta(u) - (\Psi\eta^*)(u)\|_{K_1}^2 \\
 & \leq 4E \|g(u, \bar{\xi}_u + \bar{\eta}_u) - g(u, \bar{\xi}_u + \bar{\eta}_u^*)\|_{K_1}^2 \\
 & \quad + 4E \left\| \sum_{i=1}^k (I_i(\bar{\eta}(u_1) + \bar{\xi}(u_1)) - I_i(\bar{\eta}^*(u_1) + \bar{\xi}(u_1))) \right\|_{K_1}^2 \\
 & \quad + 4E \left\| \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} [f(v, \bar{\xi}_v + \bar{\eta}_v) - f(v, \bar{\xi}_v + \bar{\eta}_v^*)] dv \right\|_{K_1}^2 \\
 & \quad + 4E \left\| \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} [\sigma(v, \bar{\xi}_v + \bar{\eta}_v) - \sigma(v, \bar{\xi}_v + \bar{\eta}_v^*)] dW(v) \right\|_{K_1}^2 \\
 & \leq 4L_2 \|\bar{\eta}_u - \bar{\eta}_u^*\|_{\mathcal{B}_h}^2 + 4m^2 l^2 L_4 E \|\bar{\eta}(u_1) - \bar{\eta}^*(u_1)\|_{K_1}^2 \\
 & \quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^\alpha}{\alpha} \int_0^u (u-v)^{\alpha-1} L_1 \|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 dv \\
 & \quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_0^u (u-v)^{2(\alpha-1)} L_3 \|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 dv \\
 & \leq 4L_2 l^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 + 4m^2 l^2 L_4 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 \\
 & \quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^\alpha}{\alpha} L_1 \int_0^u (u-v)^{\alpha-1} l^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 dv \\
 & \quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_3 \int_0^u (u-v)^{2(\alpha-1)} l^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 dv \\
 & \leq \left( 4l^2 \left[ L_2 + \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_1 \frac{T^{2\alpha}}{\alpha^2} + \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_3 \frac{T^{2\alpha-1}}{2\alpha-1} \right] + 4m^2 l^2 L_4 \right) \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2.
 \end{aligned}$$

Therefore, for all  $u \in [0, T]$ ,

$$\begin{aligned}
 & E \|\Psi\eta(u) - (\Psi\eta^*)(u)\|_{K_1}^2 \\
 & \leq 4l^2 \left( L_2 + \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_1 \frac{T^{2\alpha}}{\alpha^2} + \left( \frac{1}{\Gamma(\alpha)} \right)^2 L_3 \frac{T^{2\alpha-1}}{2\alpha-1} + m^2 L_4 \right) \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2.
 \end{aligned}$$

From (3.1), we conclude that  $\Psi$  is a contraction mapping. This implies that (2.1) has a unique solution on  $(-\infty, T]$ . The proof is complete.  $\square$

The next result is established by using Krasnoselskii's fixed point theorem. We need the following assumptions.

(H5)  $f : H \times \mathcal{B}_h \rightarrow K_1$  is continuous, and there exists a continuous function  $\mu_1 : H \rightarrow (0, +\infty)$  such that

$$E \|f(u, x)\|_{K_1}^2 \leq \mu_1(u) \|x\|_{\mathcal{B}_h}^2, \quad \forall (u, x) \in H \times \mathcal{B}_h,$$

where  $\mu_1^* = \sup_{0 \leq v \leq u} \mu_1(v)$ .

(H6)  $g : H \times \mathcal{B}_h \rightarrow K_1$  is continuous, and there exists a continuous function  $\mu_2 : H \rightarrow (0, +\infty)$  such that

$$E \|g(u, x)\|_{K_1}^2 \leq \mu_2(u) \|x\|_{\mathcal{B}_h}^2, \quad \forall (u, x) \in H \times \mathcal{B}_h,$$

where  $\mu_2^* = \sup_{0 \leq v \leq u} \mu_2(v)$ .

(H7)  $\sigma : H \times \mathcal{B}_h \rightarrow \mathcal{L}_2^0$  is continuous, and there exists a continuous function  $\mu_3 : H \rightarrow (0, +\infty)$  such that

$$E \|\sigma(u, x)\|_{\mathcal{L}_2^0}^2 \leq \mu_3(u) \|x\|_{\mathcal{B}_h}^2, \quad \forall (u, x) \in H \times \mathcal{B}_h,$$

where  $\mu_3^* = \sup_{0 \leq v \leq u} \mu_3(v)$ .

(H8) There exists  $K > 0$  such that  $I_k : \mathcal{B}_h \rightarrow K_1$ ,  $k = 1, 2, \dots, m$ ,  $E \|I_k(x)\|_{K_1}^2 \leq K$ .

Let  $B_q = \{y \in \mathcal{B}_b^0, \|y\|_{\mathcal{B}_b^0}^2 \leq q, q > 0\}$ , then  $B_q$  is a bounded closed convex set in  $\mathcal{B}_b^0$ ,  $\forall y \in B_q$ .

From Lemma 2.4, we get

$$\begin{aligned} \|y_u + \bar{\eta}_u\|_{\mathcal{B}_h}^2 &\leq 2(\|y_u\|_{\mathcal{B}_h}^2 + \|\bar{\eta}_u\|_{\mathcal{B}_h}^2) \\ &\leq 4\left(l^2 \sup_{v \in [0, u]} E \|y(v)\|_{K_1}^2 + \|y_0\|_{\mathcal{B}_h}^2\right) + 4\left(l^2 \sup_{v \in [0, u]} E \|\bar{\eta}(v)\|_{K_1}^2 + \|\bar{\eta}_0\|_{\mathcal{B}_h}^2\right) \\ &\leq 8(\|\xi\|_{\mathcal{B}_h}^2 + l^2 q) \triangleq M. \end{aligned}$$

**Theorem 3.2** Assume that conditions (H1)-(H8) hold, then (2.1) has at least one solution if the following conditions hold:

$$40l^2 \left[ \mu_2^* + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_1^* \frac{T^{2\alpha}}{\alpha^2} + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* \frac{T^{2\alpha-1}}{2\alpha-1} \right] < 1, \quad (3.3)$$

and

$$2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \left( \frac{T^{2\alpha}}{\alpha^2} L_1 + \frac{T^{2\alpha-1}}{2\alpha-1} L_3 \right) l^2 < 1. \quad (3.4)$$

*Proof* See Appendix. □

#### 4 Example

The existence, uniqueness and stability of integer-order Volterra integro-differential equation have been investigated for its wide and important application in the fields of financial mathematics, physics, biology, medicine, automatic control, demography, dynamics etc.



But there are few results about fractional stochastic Volterra integro-differential equations. In this section, we provide an example for which there is at least one solution due to the fact that the conditions in Theorem 3.2 are satisfied.

**Example 4.1** Consider the following fractional stochastic impulsive neural functional differential equations with infinite delay:

$$\begin{cases} {}^c D_u^{\frac{3}{2}} [x(u) - \frac{1}{8} \int_{-\infty}^0 e^{2v} x(u+v) dv] \\ \quad = \frac{1}{8} \int_{-\infty}^0 e^{2v} x(u+v) dv + \frac{1}{8} \int_{-\infty}^0 e^{2v} x(u+v) dv \frac{dW(v)}{dv}, & u \in (0, \frac{1}{2}) \cup (\frac{1}{2}, 1], \\ \Delta x(\frac{1}{2}) = \frac{1}{4}, \\ x(u) = 0, & u \in (-\infty, 0], \end{cases} \quad (4.1)$$

where  $g(u, x_u) = -\frac{1}{8} \int_{-\infty}^0 e^{2v} x(u+v) dv$ ,  $f(u, x_u) = \frac{1}{8} \int_{-\infty}^0 e^{2v} x(u+v) dv$ ,  $\sigma(u, x_u) = \frac{1}{8} \int_{-\infty}^0 e^{2v} \times x(u+v) dv$ ,  $H = [0, \frac{1}{2}) \cup (\frac{1}{2}, 1]$ ,  $T = 1$ ,  $m = 1$ .

For  $\xi \in \mathcal{B}_h$ , define  $\|\xi\|_{\mathcal{B}_h} = \int_{-\infty}^0 h(v) \sup_{v \leq \theta \leq 0} (E|\xi(\theta)|^2)^{\frac{1}{2}} dv$ ,  $h(v) = e^{2v}$ ,  $l = \frac{1}{2}$ , then  $\xi \in \mathcal{B}_h$ , and  $(\mathcal{B}_h, \|\cdot\|_{\mathcal{B}_h})$  is a Banach space which has the following properties.

A1. If  $x(u) : (-\infty, T] \rightarrow R$  is continuous on  $H$ , and  $x_0 \in \mathcal{B}_h$ , then  $x_u \in \mathcal{B}_h$ , and  $x_u$  is continuous on  $H$ .

A2.  $\mathcal{B}_h$  is a Banach space.

A3.  $\|x_u\|_{\mathcal{B}_h} \leq \frac{1}{2} \sup_{u \in [0, T]} (E\|x(u)\|_{K_1}^2)^{\frac{1}{2}} + \|x_0\|_{\mathcal{B}_h}$ .

In addition, let  $\mu_1(u) = \frac{1}{64}$ ,  $\mu_2(u) = \frac{1}{64}$ ,  $\mu_3(u) = \frac{1}{64}$ ,  $\mu_1^* = \frac{1}{64}$ ,  $\mu_2^* = \frac{1}{64}$ ,  $\mu_3^* = \frac{1}{64}$ .  $L_1 = \frac{1}{64}$ ,  $L_2 = \frac{1}{64}$ ,  $L_3 = \frac{1}{64}$ ,  $K = \frac{1}{16}$ ,  $L_4 = 0$ , we have that conditions (H1)-(H8) are satisfied and (3.3), (3.4) hold, i.e.,

$$\begin{aligned} & 40l^2 \left[ \mu_2^* + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_1^* \frac{T^{2\alpha}}{\alpha^2} + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* \frac{T^{2\alpha-1}}{2\alpha-1} \right] \\ & \approx 40 * \frac{1}{4} * \left[ \frac{1}{64} + \frac{1}{1.3541^2} * \frac{1}{64} * \frac{9}{4} + \frac{1}{64} * \frac{1}{1.3541^2} * 3 \right] = 0.6036 < 1, \end{aligned}$$

and

$$\begin{aligned} & 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \left( \frac{T^{2\alpha}}{\alpha^2} L_1 + \frac{T^{2\alpha-1}}{2\alpha-1} L_3 \right) l^2 \\ & \approx 2 * \frac{1}{1.3541^2} \left( \frac{1}{64} * \frac{9}{4} + \frac{1}{64} * 3 \right) * \left( \frac{1}{2} \right)^2 = 0.0224 < 1, \end{aligned}$$

then (4.1) has at least one solution by Theorem 3.2.

## 5 Conclusions

Fractional stochastic impulsive neutral functional differential equations are very useful in viscoelasticity, electrochemistry, automatic control etc. In this paper, based on fractional calculation, fixed point theorems and the stochastic analysis technique, new existence theorems of solutions for these equations are given. Moreover, our results take some well-studied models, such as integer-order functional differential equations with infinite delay, as special cases. The main result is verified by an example.

# Appendix

*Proof of Theorem 3.2* Define the operator  $\Pi_1 : B_q \rightarrow B_q$  and  $\Pi_2 : B_q \rightarrow B_q$ , where

$$(\Pi_1 \eta)(u) = \begin{cases} 0, & u \in (-\infty, 0], \\ g(0, \xi(0)) - g(u, \bar{\xi}_u + \bar{\eta}_u), & u \in (0, u_1], \\ g(0, \xi(0)) - g(u, \bar{\xi}_u + \bar{\eta}_u) + \sum_{i=1}^k I_i(\bar{\xi}(u_i) + \bar{\eta}(u_i)), & u \in (u_k, u_{k+1}], \\ & k = 1, 2, \dots, m, \end{cases} \quad (\text{A.1})$$

$$(\Pi_2 \eta)(u) = \begin{cases} 0, & u \in (-\infty, 0], \\ \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, \bar{\xi}_v + \bar{\eta}_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, \bar{\xi}_v + \bar{\eta}_v) dW(v), & u \in (0, u_1], \\ \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} f(v, \bar{\xi}_v + \bar{\eta}_v) dv \\ \quad + \frac{1}{\Gamma(\alpha)} \int_0^u (u-v)^{\alpha-1} \sigma(v, \bar{\xi}_v + \bar{\eta}_v) dW(v), & u \in (u_k, u_{k+1}], \\ & k = 1, 2, \dots, m. \end{cases} \quad (\text{A.2})$$

If  $\Pi_1$  is compact and continuous and  $\Pi_2$  is a contraction operator, from Lemma 2.5, (2.1) has at least one solution. We will prove them according to the following five steps.

*Step 1:* We use contradiction to prove that there is  $q^* \in N$  such that  $\Pi_1 \eta + \Pi_2 \eta^* \in B_{q^*}$  for  $\eta, \eta^* \in B_{q^*}$ . Otherwise, for each  $q \in N$ , there would exist  $\eta^q \in B_q$ ,  $\eta^{*q} \in B_q$  and  $u_q \in [0, T]$  such that

$$E \|\Pi_1 \eta^q + \Pi_2 \eta^{*q}\|_{K_1}^2 > q. \quad (\text{A.3})$$

Without losing generality, we assume  $\lim_{q \rightarrow \infty} u_q = T$ .

For  $u_q \in (0, u_1]$ , we have

$$\begin{aligned} q &< E \left\| (\Pi_1 \eta^q)(u_q) + (\Pi_2 \eta^{*q})(u_q) \right\|_{K_1}^2 \\ &\leq 4E \|g(0, \xi(0))\|_{K_1}^2 + 4E \|g(u_q, \bar{\eta}_{u_q}^q + \bar{\xi}_{u_q}^q)\|_{K_1}^2 \\ &\quad + 4E \left\| \frac{1}{\Gamma(\alpha)} \int_0^{u_q} (u_q - v)^{\alpha-1} f(v, \bar{\eta}_v^* + \bar{\xi}_v) dv \right\|_{K_1}^2 \\ &\quad + 4E \left\| \frac{1}{\Gamma(\alpha)} \int_0^{u_q} (u_q - v)^{\alpha-1} \sigma(v, \bar{\eta}_v^* + \bar{\xi}_v) dW(v) \right\|_{K_1}^2 \\ &\leq 4E \|g(0, \xi(0))\|_{K_1}^2 + 4\mu_2^* \|\bar{\eta}_{u_q}^q + \bar{\xi}_{u_q}^q\|_{\mathcal{B}_h}^2 \\ &\quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_0^{u_q} (u_q - v)^{\alpha-1} dv \int_0^{u_q} (u_q - v)^{\alpha-1} E \|f(v, \bar{\eta}_v^* + \bar{\xi}_v)\|_{K_1}^2 dv \\ &\quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_0^{u_q} (u_q - v)^{2(\alpha-1)} E \|\sigma(v, \bar{\eta}_v^* + \bar{\xi}_v)\|_{\mathcal{L}_2^0}^2 dv \\ &\leq 4E \|g(0, \xi(0))\|_{K_1}^2 + 4\mu_2^* M + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{u_q^\alpha}{\alpha} \int_0^{u_q} (u_q - v)^{\alpha-1} \mu_1^* M dv \\ &\quad + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_0^{u_q} (u_q - s)^{2(\alpha-1)} \mu_3^* M dv \\ &\leq 4E \|g(0, \xi(0))\|_{K_1}^2 + 4\mu_2^* M + 4\mu_1^* M \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} + 4 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* M \frac{T^{2\alpha-1}}{2\alpha-1}. \end{aligned}$$

Similarly, for  $u_q \in (u_k, u_{k+1}]$ ,  $k = 1, \dots, m$ , we can obtain

$$\begin{aligned}
 q &< E \left\| (\Pi_1 \eta^q)(u_q) + (\Pi_2 \eta^{*q})(u_q) \right\|_{K_1}^2 \\
 &\leq 5E \|g(0, \xi(0))\|_{K_1}^2 + 5E \|g(u_q, \bar{\eta}_{u_q}^q + \bar{\xi}_{u_q}^q)\|_{K_1}^2 + 5E \left\| \sum_{i=1}^k I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i)) \right\|_{K_1}^2 \\
 &\quad + 5E \left\| \frac{1}{\Gamma(\alpha)} \int_0^{u_q} (u_q - v)^{\alpha-1} f(v, \bar{\eta}_v^* + \bar{\xi}_v) dv \right\|_{K_1}^2 \\
 &\quad + 5E \left\| \frac{1}{\Gamma(\alpha)} \int_0^{u_q} (u_q - v)^{\alpha-1} \sigma(v, \bar{\eta}_v^* + \bar{\xi}_v) dW(v) \right\|_{K_1}^2 \\
 &\leq 5E \|g(0, \xi(0))\|_{K_1}^2 + 5\mu_2^* \|\bar{\eta}_{u_q}^q + \bar{\xi}_{u_q}^q\|_{B_h}^2 + 5m \sum_{i=1}^m E \|I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i))\|_{K_1}^2 \\
 &\quad + 5 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_0^{u_q} (u_q - v)^{\alpha-1} dv \int_0^{u_q} (u_q - v)^{\alpha-1} E \|f(v, \bar{\eta}_v^* + \bar{\xi}_v)\|_{K_1}^2 dv \\
 &\quad + 5 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_0^{u_q} (u_q - v)^{2(\alpha-1)} E \|\sigma(v, \bar{\eta}_v^* + \bar{\xi}_v)\|_{\mathcal{L}_2^0}^2 dv \\
 &\leq 5E \|g(0, \xi(0))\|_{K_1}^2 + 5\mu_2^* M + 5\mu_1^* M \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} + 5 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* M \frac{T^{2\alpha-1}}{2\alpha-1} \\
 &\quad + 5m \sum_{i=1}^m E \|I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i))\|_{K_1}^2 \\
 &\leq 5E \|g(0, \xi(0))\|_{K_1}^2 + 5\mu_2^* M + 5\mu_1^* M \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} \\
 &\quad + 5 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* M \frac{T^{2\alpha-1}}{2\alpha-1} + 5m^2 K.
 \end{aligned}$$

So, we obtain

$$\begin{aligned}
 q &< 5E \|g(0, \xi(0))\|_H^2 + 5\mu_2^* M + 5\mu_1^* M \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} \\
 &\quad + 5 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* M \frac{T^{2\alpha-1}}{2\alpha-1} + 5m^2 K.
 \end{aligned} \tag{A.4}$$

Dividing by  $q$  and taking the lower limit on both sides of inequality (A.4), one can get

$$1 \leq \left( \liminf_{q \rightarrow +\infty} \frac{M}{q} \right) 5 \left( \mu_2^* M + \mu_1^* \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* \frac{T^{2\alpha-1}}{2\alpha-1} \right). \tag{A.5}$$

On the other hand, according to  $\lim_{q \rightarrow +\infty} \inf \frac{M}{q} = 8l^2$  and inequality (A.5),

$$1 \leq 40l^2 \left[ \mu_2^* + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_1^* \frac{T^{2\alpha}}{\alpha^2} + \left( \frac{1}{\Gamma(\alpha)} \right)^2 \mu_3^* \frac{T^{2\alpha-1}}{2\alpha-1} \right]$$

are easily obtained. This is a contradiction with inequality (3.3). Therefore, there exists  $q^* \in N$  such that  $\Pi_1 \eta + \Pi_2 \eta^* \in B_{q^*}$  for  $\eta, \eta^* \in B_{q^*}$ .

*Step 2:* We need to prove  $\Pi_1$  is continuous on  $B_{q^*}$ .

Suppose  $\{\eta^n\}_{n=1}^\infty$  is a sequence in  $B_{q^*}$  with  $\lim_{n \rightarrow \infty} \eta^n = \eta \in B_{q^*}$ . Then, for  $u \in (0, u_1]$ , we have

$$\begin{aligned} E\|(\Pi_1 \eta^n)(u) - (\Pi_1 \eta)(u)\|_{K_1}^2 &\leq E\|g(u, \bar{\eta}_u^n + \bar{\xi}_u) - g(u, \bar{\eta}_u + \bar{\xi}_u)\|_{K_1}^2 \\ &\leq L_2 \|\eta_u^n - \eta_u\|_{\mathcal{B}_h}^2 \leq L_2 l^2 \|\eta^n - \eta\|_{\mathcal{B}_b^0}^2. \end{aligned}$$

Similarly, for  $u \in (u_k, u_{k+1}]$ ,  $k = 1, 2, \dots, m$ ,

$$\begin{aligned} E\|(\Pi_1 \eta^n)(u) - (\Pi_1 \eta)(u)\|_{K_1}^2 &\leq 2E\|g(u, \bar{\eta}_u^n + \bar{\xi}_u) - g(u, \bar{\eta}_u + \bar{\xi}_u)\|_{K_1}^2 \\ &\quad + 2E\left\|\sum_{i=1}^k I_i(\bar{\eta}^n(u_i) + \bar{\xi}(u_i)) - \sum_{i=1}^k I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i))\right\|_{K_1}^2 \\ &\leq 2L_2 \|\eta_u^n - \eta_u\|_{\mathcal{B}_h}^2 + 2m^2 L_4 \|\eta_u^n - \eta_u\|_{\mathcal{B}_h}^2 \\ &\leq 2(L_2 + m^2 L_4) l^2 \|\eta^n - \eta\|_{\mathcal{B}_b^0}^2. \end{aligned}$$

So,  $\lim_{n \rightarrow \infty} E\|\Pi_1 \eta^n - \Pi_1 \eta\|_{K_1}^2 = 0$ , which implies that the mapping  $\Pi_1$  is continuous on  $B_{q^*}$ .

*Step 3:* We prove that  $\Pi_1$  maps bounded sets into bounded sets in  $B_{q^*}$ .

For  $u \in (0, u_1]$ , we have

$$\begin{aligned} E\|(\Pi_1 \eta)(t)\|_{K_1}^2 &\leq 2E\|g(0, \xi(0))\|_{K_1}^2 + 2E\|g(u, \bar{\eta}_u + \bar{\xi}_u)\|_{K_1}^2 \\ &\leq 2E\|g(0, \xi(0))\|_{\eta}^2 + 2\mu_2^* \|\bar{\eta}_u + \bar{\xi}_u\|_{\mathcal{B}_h}^2 \\ &\leq 2E\|g(0, \xi(0))\|_{K_1}^2 + 2\mu_2^* M. \end{aligned}$$

If  $u \in (u_k, u_{k+1}]$ ,  $k = 1, 2, \dots, m$ ,

$$\begin{aligned} E\|(\Pi_1 \eta)(u)\|_{K_1}^2 &\leq 3E\|g(0, \xi(0))\|_{K_1}^2 + 3E\|g(u, \bar{\eta}_u + \bar{\xi}_u)\|_{K_1}^2 \\ &\quad + 3E\left\|\sum_{i=1}^k I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i))\right\|_{K_1}^2 \\ &\leq 3E\|g(0, \xi(0))\|_{K_1}^2 + 3\mu_2^* M + 3m^2 K \triangleq \hat{r}. \end{aligned}$$

Hence, for  $q^* > 0$ , there exists  $\hat{r} > 0$  such that  $E\|(\Pi_1 \eta)(u)\|_{K_1}^2 \leq \hat{r}$ ,  $\forall \eta \in B_{q^*}$ ,  $u \in (u_i, u_{i+1}]$ ,  $i = 0, 1, \dots, m$ .

*Step 4:* The map  $\Pi_1$  is equicontinuous.

Let  $0 < t < s \leq u_1$ ,  $\eta \in B_{q^*}$ , we obtain

$$E\|(\Pi_1 \eta)(t) - (\Pi_1 \eta)(s)\|_{K_1}^2 = E\|g(t, \bar{\eta}_t + \bar{\xi}_t) - g(s, \bar{\eta}_s + \bar{\xi}_s)\|_{K_1}^2,$$

for  $u_k < t < s \leq u_{k+1}$ ,  $k = 1, \dots, m$ ,

$$\begin{aligned} & E \left\| (\Pi_1 \eta)(t) - (\Pi_1 \eta)(s) \right\|_{K_1}^2 \\ &= E \left\| g(t, \bar{\eta}_t + \bar{\xi}_t) - g(s, \bar{\eta}_s + \bar{\xi}_s) + \sum_{i=1}^k I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i)) - \sum_{i=1}^k I_i(\bar{\eta}(u_i) + \bar{\xi}(u_i)) \right\|_{K_1}^2 \\ &= E \left\| g(t, \bar{\eta}_t + \bar{\xi}_t) - g(s, \bar{\eta}_s + \bar{\xi}_s) \right\|_{K_1}^2. \end{aligned}$$

Combining  $g$  is continuous and the definition of  $\bar{\eta}, \bar{\xi}$ , we conclude that  $\lim_{t \rightarrow s} \|g(t, \bar{\eta}_t + \bar{\xi}_t) - g(s, \bar{\eta}_s + \bar{\xi}_s)\|_{K_1}^2 = 0$ , so  $\Pi_1(B_{q^*})$  is equicontinuous. From Steps 1-4 and Ascoli's theorem,  $\Pi_1$  is compact.

*Step 5:*  $\Pi_2$  is a contraction mapping.

Let  $\eta, \eta^* \in B_{q^*}$  and  $u \in (u_k, u_{k+1}]$ ,  $k = 0, 1, \dots, m$ ,

$$\begin{aligned} & E \left\| (\Pi_2 \eta)(u) - (\Pi_2 \eta^*)(u) \right\|_{K_1}^2 \\ & \leq 2E \left\| \frac{1}{\Gamma(\alpha)} \int_{u_i}^u (u-v)^{\alpha-1} [f(v, \bar{\eta}_v + \bar{\xi}_v) - f(v, \bar{\eta}_v^* + \bar{\xi}_v)] dv \right\|_{K_1}^2 \\ & \quad + 2E \left\| \frac{1}{\Gamma(\alpha)} \int_{u_i}^u (u-v)^{\alpha-1} [\sigma(v, \bar{\eta}_v + \bar{\xi}_v) - \sigma(v, \bar{\eta}_v^* + \bar{\xi}_v)] dW(v) \right\|_{K_1}^2 \\ & \leq 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_{u_i}^u (u-v)^{\alpha-1} dv \int_{u_i}^u (u-v)^{\alpha-1} E \|f(v, \bar{\eta}_v + \bar{\xi}_v) - f(v, \bar{\eta}_v^* + \bar{\xi}_v)\|_{K_1}^2 du \\ & \quad + 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_{u_i}^u (u-v)^{2(\alpha-1)} E \|\sigma(v, \bar{\eta}_v + \bar{\xi}_v) - \sigma(v, \bar{\eta}_v^* + \bar{\xi}_v)\|_{\mathcal{L}_2^0}^2 dv \\ & \leq 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{(u-u_i)^\alpha}{\alpha} \int_{u_i}^u (u-v)^{\alpha-1} L_1 \|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 dv \\ & \quad + 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \int_{u_i}^u (u-v)^{2(\alpha-1)} L_3 \|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 dv \\ & \leq 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha}}{\alpha^2} L_1 \|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 + 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \frac{T^{2\alpha-1}}{2\alpha-1} L_3 \|\bar{\eta}_v - \bar{\eta}_v^*\|_{\mathcal{B}_h}^2 \\ & \leq 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \left( \frac{T^{2\alpha}}{\alpha^2} L_1 + \frac{T^{2\alpha-1}}{2\alpha-1} L_3 \right) l^2 \sup_{v \in [0, T]} \|\eta(v) - \eta^*(v)\|_{K_1}^2 \\ & \leq 2 \left( \frac{1}{\Gamma(\alpha)} \right)^2 \left( \frac{T^{2\alpha}}{\alpha^2} L_1 + \frac{T^{2\alpha-1}}{2\alpha-1} L_3 \right) l^2 \|\eta - \eta^*\|_{\mathcal{B}_b^0}^2. \end{aligned}$$

From (3.4),  $\Pi_2$  is a contraction mapping. Therefore, according to Krasnoselskii's fixed point theorem, (2.1) has at least one solution on  $(-\infty, T]$ . The proof is complete.  $\square$

#### Competing interests

The authors declare that they have no competing interests.

#### Authors' contributions

HB carried out the main results of this paper and drafted the manuscript. JC directed the study and helped to inspect the manuscript. All authors read and approved the final manuscript.

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