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Existence and β -Ulam-Hyers stability for a class of fractional differential equations with non-instantaneous impulses

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Abstract

In this paper, we investigate a new class of fractional differential equations with non-instantaneous impulses. We give a suitable formula of piecewise continuous solutions and present the concept of β -Ulam-Hyers stability. We present existence and β -Ulam-Hyers stability results on a compact interval.

Keywords: fractional differential equations; non-instantaneous impulses; existence; β -Ulam-Hyers stability

1 Introduction

Impulsive fractional differential equations are used to describe many practical dynamical systems in many evolutionary processes models. There are many recent contributions [1–4] on fractional differential equations with instantaneous impulses of the form

$$\begin{cases} {}^c D_{0,t}^\alpha x(t) = f(t, x(t)), & t \in [0, T] \setminus \{\tau_1, \dots, \tau_m\}, \\ \Delta x(\tau_k) = I_k(x(\tau_k^-)), & k = 1, 2, \dots, m, \end{cases}$$

where ${}^c D_{0,t}^\alpha$ is the Caputo fractional derivative of the order $\alpha \in (n-1, n)$, $n \in \mathbb{N}$, $f: J \times \mathbb{R} \rightarrow \mathbb{R}$ and $I_k: \mathbb{R} \rightarrow \mathbb{R}$ and τ_k satisfies $0 = \tau_0 < \tau_1 < \dots < \tau_m < \tau_{m+1} = T$, $x(\tau_k^+) = \lim_{\epsilon \rightarrow 0^+} x(\tau_k + \epsilon)$ and $x(\tau_k^-) = \lim_{\epsilon \rightarrow 0^-} x(\tau_k - \epsilon)$ represent the right and left limits of $x(t)$ at $t = \tau_k$, respectively. Here, I_k is a sequence of instantaneous impulse operators and it has been used to describe abrupt changes such as shocks, harvesting, and natural disasters.

In general, the classical instantaneous impulses cannot describe some certain dynamics of evolution processes. For example, when we consider the hemodynamic equilibrium of a person, the introduction of the drugs in the bloodstream and the consequent absorption for the body are gradual and continuous process. In fact, the above situation can be characterized by a new case of impulsive action, which starts at an arbitrary fixed point and stays active on a finite time interval. From the viewpoint of general theories, Hernández and O'Regan [5] initially offered a study of a new class of abstract cases of semilinear impulsive differential modeling with no instantaneous impulses and Pierri *et al.* [6] continued the work and extended the previous results.

However, we note that the absorption of drugs has a memory effect. In fact, fractional calculus provides a powerful tool for hereditary properties on various materials and mem-

ory processes [7, 8]. Motivated by [5–8], we investigate the following new class of impulsive differential equations:

$$\begin{cases} {}^c D_{s_i, t}^\alpha x(t) = -\lambda x(t) + f(t, x(t)), & t \in (s_i, t_{i+1}], i = 0, 1, 2, \dots, m, \alpha \in (0, 1), \lambda \geq 0, \\ x(t) = q + I_{t_i, t}^\gamma g_i(t, x(t)) - I_{0, s_i}^\alpha f(s_i, x(s_i)), & t \in (t_i, s_i], i = 1, 2, \dots, m, \gamma \in (0, 1), \gamma \neq \alpha, \end{cases} \quad (1)$$

where ${}^c D_{s_i, t}^\alpha$ is the Caputo fractional derivative of the order $\alpha \in (0, 1)$ with the lower limit s_i , $0 = s_0 < t_1 \leq s_1 \leq t_2 < \dots < t_m \leq s_m \leq t_{m+1} = T$ are pre-fixed numbers, $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous and $g_i : [t_i, s_i] \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous for all $i = 1, 2, \dots, m$ and $q \in \mathbb{R}$. $I_{t_i, t}^\gamma g_i$ and $I_{0, s_i}^\alpha f$ are given by

$$I_{t_i, t}^\gamma g_i(t, x(t)) = \frac{1}{\Gamma(\gamma)} \int_{t_i}^t (t-s)^{\gamma-1} g_i(s, x(s)) ds,$$

$$I_{0, s_i}^\alpha f(s_i, x(s_i)) = \frac{1}{\Gamma(\alpha)} \int_0^{s_i} (s_i-s)^{\alpha-1} f(s, x(s)) ds.$$

The Ulam stability problem [9] has attracted many famous researchers. For more details, the readers can refer to good monographs of Hyers *et al.* [10], Rassias [11], Jung [12], Cădariu [13] and other recent contributions [14–20] in standard normed spaces and [21, 22] in β -normed spaces. As far as we known, neither the existence of a solution nor the Ulam type stability of (1) in β -normed spaces has been studied. Here, we shall apply the usual methods of analysis and novel techniques in β -Banach spaces to deal with our problem.

2 Preliminaries

To begin with, we present the concept of β -Banach space.

Definition 2.1 ([14]) Suppose E is a vector space over \mathbb{K} . A function $\|\cdot\|_\beta$ ($0 < \beta \leq 1$): $E \rightarrow [0, \infty)$ is called a β -norm if and only if it satisfies (i) $\|x\|_\beta = 0$ if and only if $x = 0$; (ii) $\|\lambda x\|_\beta = |\lambda|^\beta \|x\|_\beta$ for all $\lambda \in \mathbb{K}$ and all $x \in E$; (iii) $\|x + y\|_\beta \leq \|x\|_\beta + \|y\|_\beta$. The pair $(E, \|\cdot\|_\beta)$ is called a β -normed space. A β -Banach space is a complete β -normed space.

Let $J = [0, T]$ and $C(J, \mathbb{R})$ be the β -Banach space of all continuous functions from J into \mathbb{R} with the β -norm $\|x\|_\beta := \max\{|x(t)|^\beta : t \in J, 0 < \beta < 1\}$ for $x \in C(J, \mathbb{R})$. We also need the piecewise continuous β -Banach space $PC(J, \mathbb{R}) := \{x : J \rightarrow \mathbb{R} : x \in C((t_k, t_{k+1}], \mathbb{R}), k = 0, 1, \dots, m, \text{ and there exist } x(t_k^-) \text{ and } x(t_k^+), k = 1, \dots, m, \text{ with } x(t_k^-) = x(t_k^+)\}$ with the $P\beta$ -norm $\|x\|_{P\beta} := \sup\{|x(t)|^\beta : t \in J, 0 < \beta < 1\}$.

Next, we recall some basic concepts of the fractional integral and derivative, and some results as regards fractional differential equations [23].

Definition 2.2 The fractional integral of order γ with the lower limit a for a function f is defined as

$$I_{a, t}^\gamma f(t) = \frac{1}{\Gamma(\gamma)} \int_a^t \frac{f(s)}{(t-s)^{1-\gamma}} ds, \quad t > a, \gamma > 0,$$

provided the right side is point-wise defined on $[a, \infty)$, where $\Gamma(\cdot)$ is the gamma function.

Definition 2.3 The Riemann-Liouville derivative of order γ with the lower limit a for a function $f : [a, \infty) \rightarrow \mathbb{R}$ can be written as

$${}^L D_{a,t}^\gamma f(t) = \frac{1}{\Gamma(n-\gamma)} \frac{d^n}{dt^n} \int_a^t \frac{f(s)}{(t-s)^{\gamma+1-n}} ds, \quad t > a, n-1 < \gamma < n.$$

Definition 2.4 The Caputo derivative of order γ for a function $f : [a, \infty) \rightarrow \mathbb{R}$ can be written as

$${}^C D_{a,t}^\gamma f(t) = {}^L D_{a,t}^\gamma \left[f(t) - \sum_{k=0}^{n-1} \frac{t^k}{k!} f^{(k)}(a) \right], \quad t > a, n-1 < \gamma < n.$$

Denote $\mathbb{E}_\alpha(z) := \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k + 1)}$ and $\mathbb{E}_{\alpha,\alpha}(z) := \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k + \alpha)}$. By [24], Lemma 2, for any $\lambda \geq 0$ and $t \in J$, $\mathbb{E}_\alpha(0) = 1$, $\mathbb{E}_\alpha(-t^\alpha \lambda) \leq 1$, $\mathbb{E}_{\alpha,\alpha}(-t^\alpha \lambda) \leq \frac{1}{\Gamma(\alpha)}$.

Lemma 2.5 Let $h : J \rightarrow \mathbb{R}$ be a continuous function. A function $x \in PC(J, \mathbb{R})$ is a solution of the fractional integral equations

$$\begin{aligned} x(0) &= x_0; \\ x(t) &= \mathbb{E}_\alpha(-t^\alpha \lambda) x_0 + \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) h(s) ds, \quad t \in (0, t_1]; \\ x(t) &= q + I_{t_i,t}^\gamma g_i(t) - I_{0,s_i}^\alpha h(s_i), \quad t \in (t_i, s_i], i = 1, 2, \dots, m; \\ x(t) &= \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) \left(q + I_{t_i,s_i}^\gamma g_i(s_i) - I_{0,s_i}^\alpha h(s_i) \right) \\ &\quad + \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) h(s) ds, \quad t \in (s_i, t_{i+1}], i = 1, \dots, m, \end{aligned}$$

if and only if x is a solution of the equation

$$\begin{cases} {}^C D_{s_i,t}^\alpha x(t) = -\lambda x(t) + h(t), & t \in (s_i, t_{i+1}], i = 0, 1, 2, \dots, m, \alpha \in (0, 1), \\ x(t) = q + I_{t_i,t}^\gamma g_i(t) - I_{0,s_i}^\alpha h(s_i), & t \in (t_i, s_i], i = 1, 2, \dots, m, \gamma \in (0, 1), \\ x(0) = x_0 \in \mathbb{R}. \end{cases} \quad (2)$$

Proof Suppose that x satisfies (2).

For $t \in [0, t_1]$, we consider

$${}^C D_{0,t}^\alpha x(t) = -\lambda x(t) + h(t), \quad \text{with } x(0) = x_0.$$

Integrating from 0 to t by virtue of Definition 2.2, one can obtain

$$x(t) = \mathbb{E}_\alpha(-t^\alpha \lambda) x_0 + \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) h(s) ds, \quad t \in [0, t_1].$$

For $t \in (t_1, s_1]$, $x(t) = q + I_{t_1,t}^\gamma g_1(t) - I_{0,s_1}^\alpha h(s_1)$.

For $t \in (s_1, t_2]$, we consider

$${}^C D_{s_1,t}^\alpha x(t) = -\lambda x(t) + h(t), \quad \text{with } x(s_1) = q + I_{t_1,s_1}^\gamma g_1(s_1) - I_{0,s_1}^\alpha h(s_1).$$

Then

$$\begin{aligned} x(t) &= \int_{s_1}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) h(s) ds \\ &\quad + \mathbb{E}_\alpha(-(t-s_1)^\alpha \lambda) (q + I_{t_1,s_1}^\gamma g_1(s_1) - I_{0,s_1}^\alpha h(s_1)). \end{aligned}$$

For $t \in (t_2, s_2]$, $x(t) = q + I_{t_2,t}^\gamma g_2(t) - I_{0,s_2}^\alpha h(s_2)$.

For $t \in (s_2, t_3]$, we consider

$${}^c D_{s_2,t}^\alpha x(t) = -\lambda x(t) + h(t), \quad \text{with } x(s_2) = q + I_{t_2,s_2}^\gamma g_2(s_2) - I_{0,s_2}^\alpha h(s_2).$$

So we get

$$\begin{aligned} x(t) &= \int_{s_2}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) h(s) ds \\ &\quad + \mathbb{E}_\alpha(-(t-s_2)^\alpha \lambda) (q + I_{t_2,s_2}^\gamma g_2(s_2) - I_{0,s_2}^\alpha h(s_2)). \end{aligned}$$

Finally, for any $t \in (s_i, t_{i+1}]$, we consider

$${}^c D_{s_i,t}^\alpha x(t) = -\lambda x(t) + h(t), \quad \text{with } x(s_i) = q + I_{t_i,s_i}^\gamma g_i(s_i) - I_{0,s_i}^\alpha h(s_i).$$

Thus,

$$\begin{aligned} x(t) &= \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) h(s) ds \\ &\quad + \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i,s_i}^\gamma g_i(s_i) - I_{0,s_i}^\alpha h(s_i)). \end{aligned}$$

Conversely, one can verify the fact by proceeding the standard steps to complete the rest of proof. \square

3 β -Ulam-Hyers stability concept and auxiliary facts

Let $0 < \beta < 1$, $\epsilon > 0$. We consider the following inequality:

$$\begin{cases} |{}^c D_{s_i,t}^\alpha y(t) + \lambda y(t) - f(t, y(t))| \leq \epsilon, & t \in (s_i, t_{i+1}], i = 0, 1, 2, \dots, m, \\ |y(t) - q - I_{t_i,t}^\gamma g_i(t, y(t)) + I_{0,s_i}^\alpha f(s_i, y(s_i))| \leq \epsilon, & t \in (t_i, s_i], i = 1, 2, \dots, m. \end{cases} \quad (3)$$

Then our goal is to find a solution $y(\cdot)$ close to the measured output $x(\cdot)$ and this closeness is defined in the sense of β -Ulam's type stability as follows.

Definition 3.1 Equation (1) is β -Ulam-Hyers stable if there exists a real number $c_{f,\alpha,\gamma,\beta,g_i} > 0$ such that for each $\epsilon > 0$ and for each solution $y \in PC^1(J, \mathbb{R})$ of the inequality (3) there exists a solution $x \in PC^1(J, \mathbb{R})$ of (1) with

$$|y(t) - x(t)|^\beta \leq c_{f,\alpha,\gamma,\beta,g_i} \epsilon^\beta, \quad t \in J.$$

Remark 3.2 A function $y \in PC^1(J, \mathbb{R})$ is a solution of the inequality (3) if and only if there is a number G such that

- (i) $|G| \leq \epsilon$;
- (ii) ${}^c D_{s_i, t}^\alpha y(t) = -\lambda y(t) + f(t, y(t)) + G, \quad t \in (s_i, t_{i+1}], \quad i = 0, 1, 2, \dots, m$;
- (iii) $y(t) = q + I_{t_i, t}^\gamma g_i(t, y(t)) - I_{0, s_i}^\alpha f(s_i, y(s_i)) + G, \quad t \in (t_i, s_i], \quad i = 1, 2, \dots, m$.

Remark 3.3 If $y \in PC^1(J, \mathbb{R})$ is a solution of the inequality (3) then y is a solution of the following integral inequality:

$$\begin{cases} |y(t) - q - I_{t_i, t}^\gamma g_i(t, y(t)) - I_{0, s_i}^\alpha f(s_i, y(s_i))| \leq \epsilon, & t \in (t_i, s_i], \quad i = 1, 2, \dots, m; \\ |y(t) - \mathbb{E}_\alpha(-t^\alpha \lambda) y(0) - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds| \\ \leq \frac{t_1^\alpha}{\Gamma(\alpha+1)} \epsilon, & t \in [0, t_1]; \\ |y(t) - \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \\ - \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i, s_i}^\gamma g_i(s_i, y(s_i)) - I_{0, s_i}^\alpha f(s_i, y(s_i)))| \\ \leq \epsilon + \frac{(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \epsilon, & t \in (s_i, t_{i+1}], \quad i = 1, 2, \dots, m. \end{cases} \quad (4)$$

In fact, by Remark 3.2 we get

$$\begin{cases} {}^c D_{s_i, t}^\alpha y(t) = -\lambda y(t) + f(t, y(t)) + G, & t \in (s_i, t_{i+1}], \quad i = 0, 1, 2, \dots, m, \\ y(t) = q + I_{t_i, t}^\gamma g_i(t, y(t)) - I_{0, s_i}^\alpha f(s_i, y(s_i)) + G, & t \in (t_i, s_i], \quad i = 1, 2, \dots, m. \end{cases} \quad (5)$$

Clearly, the solution of (5) is given by

$$\begin{aligned} y(t) &= q + I_{t_i, t}^\gamma g_i(t, y(t)) - I_{0, s_i}^\alpha f(s_i, y(s_i)) + G, \quad t \in (t_i, s_i], \quad i = 1, 2, \dots, m; \\ y(t) &= \mathbb{E}_\alpha(-t^\alpha \lambda) y(0) + \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) [f(s, y(s)) + G] ds, \quad t \in [0, t_1]; \\ y(t) &= \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) [f(s, y(s)) + G] ds \\ &\quad + \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i, s_i}^\gamma g_i(s_i, y(s_i)) - I_{0, s_i}^\alpha f(s_i, y(s_i)) + G), \\ &\quad t \in (s_i, t_{i+1}], \quad i = 1, 2, \dots, m. \end{aligned}$$

For $t \in (s_i, t_{i+1}], \quad i = 1, 2, \dots, m$, we get

$$\begin{aligned} &\left| y(t) - \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right. \\ &\quad \left. - \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i, s_i}^\gamma g_i(s_i, y(s_i)) - I_{0, s_i}^\alpha f(s_i, y(s_i))) \right| \\ &\leq |G| + \left| \frac{1}{\Gamma(\alpha)} \int_{s_i}^t (t-s)^{\alpha-1} G ds \right| \\ &\leq \epsilon + \frac{1}{\Gamma(\alpha)} \int_{s_i}^t (t-s)^{\alpha-1} \epsilon ds \\ &\leq \epsilon + \frac{(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \epsilon. \end{aligned}$$

Proceeding as above, we derive that

$$|y(t) - q - I_{t_i, t}^\gamma g_i(t, y(t)) - I_{0, s_i}^\alpha f(s_i, y(s_i))| \leq |G| \leq \epsilon, \quad t \in (t_i, s_i], \quad i = 1, 2, \dots, m$$

and

$$\begin{aligned} & \left| y(t) - \mathbb{E}_\alpha(-t^\alpha \lambda) y(0) - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right| \\ & \leq \left| \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} G ds \right| \leq \frac{t_1^\alpha}{\Gamma(\alpha+1)} \epsilon, \quad t \in [0, t_1]. \end{aligned}$$

4 Existence and β -Ulam-Hyers stability results

We impose the following assumptions:

(A₁): $f \in C(J \times \mathbb{R}, \mathbb{R})$.

(A₂): There exists a positive constant L_f such that

$$|f(t, u_1) - f(t, u_2)| \leq L_f |u_1 - u_2|, \quad \text{for each } t \in J \text{ and all } u_1, u_2 \in \mathbb{R}.$$

(A₃): $g_i \in C([t_i, s_i] \times \mathbb{R}, \mathbb{R})$ and there are positive constants L_{g_i} , $i = 1, 2, \dots, m$ such that

$$|g_i(t, u_1) - g_i(t, u_2)| \leq L_{g_i} |u_1 - u_2|, \quad \text{for each } t \in [t_i, s_i] \text{ and all } u_1, u_2 \in \mathbb{R}.$$

We begin by giving the existence and uniqueness result for the solutions to (1).

Theorem 4.1 *Assume that (A₁), (A₂), (A₃) are satisfied. Then (1) has a unique solution provided that*

$$\begin{aligned} \varrho := \max & \left\{ \left(\frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \right)^\beta + \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma+1)} \right)^\beta + \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta, \right. \\ & \left. \left(\frac{L_f t_1^\alpha}{\Gamma(\alpha+1)} \right)^\beta : i = 1, 2, \dots, m \right\} < 1. \end{aligned} \quad (6)$$

Proof Consider an operator $\Lambda : PC(J, \mathbb{R}) \rightarrow PC(J, \mathbb{R})$ defined by

$$\begin{aligned} (\Lambda x)(0) &= x_0; \\ (\Lambda x)(t) &= q + I_{t_i, t_i}^\gamma g_i(t, x(t)) - I_{0, s_i}^\alpha f(s_i, x(s_i)), \quad t \in (t_i, s_i], i = 1, 2, \dots, m; \\ (\Lambda x)(t) &= \mathbb{E}_\alpha(-t^\alpha \lambda) x_0 + \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, x(s)) ds, \quad t \in [0, t_1]; \\ (\Lambda x)(t) &= \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, x(s)) ds \\ &\quad + \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i, s_i}^\gamma g_i(s_i, x(s_i)) - I_{0, s_i}^\alpha f(s_i, x(s_i))), \\ &\quad t \in (s_i, t_{i+1}], i = 1, 2, \dots, m. \end{aligned}$$

It is easy to see that Λ is well defined. Next, we show that Λ is a contraction mapping.

Case 1: For $u_1, u_2 \in PC(J, \mathbb{R})$ and for each $t \in [0, t_1]$, we have

$$\begin{aligned} & |(\Lambda u_1)(t) - (\Lambda u_2)(t)| \\ &= \left| \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, u_1(s)) ds \right. \end{aligned}$$

$$\begin{aligned}
& \left| - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, u_2(s)) ds \right| \\
& \leq \frac{L_f}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |u_1(s) - u_2(s)| ds \\
& \leq \frac{L_f}{\Gamma(\alpha)} \|u_1 - u_2\|_{PC} \int_0^t (t-s)^{\alpha-1} ds \\
& \leq \frac{L_f t_1^\alpha}{\Gamma(\alpha+1)} \|u_1 - u_2\|_{PC},
\end{aligned}$$

which implies that

$$|(\Lambda u_1)(t) - (\Lambda u_2)(t)|^\beta \leq \left(\frac{L_f t_1^\alpha}{\Gamma(\alpha+1)} \right)^\beta \|u_1 - u_2\|_{P\beta}.$$

This reduces to

$$\|\Lambda u_1 - \Lambda u_2\|_{P\beta} \leq \left(\frac{L_f t_1^\alpha}{\Gamma(\alpha+1)} \right)^\beta \|u_1 - u_2\|_{P\beta}.$$

Case 2: For $u_1, u_2 \in PC(J, \mathbb{R})$ and for each $t \in (t_i, s_i]$, $i = 1, 2, \dots, m$, we have

$$\begin{aligned}
& |(\Lambda u_1)(t) - (\Lambda u_2)(t)| \\
& \leq \frac{1}{\Gamma(\gamma)} \int_{t_i}^t (t-s)^{\gamma-1} |g_i(s, u_1(s)) - g_i(s, u_2(s))| ds \\
& \quad + \frac{1}{\Gamma(\alpha)} \int_0^{s_i} (s_i-s)^{\alpha-1} |f(s, u_1(s)) - f(s, u_2(s))| ds \\
& \leq \frac{L_{g_i}}{\Gamma(\gamma)} \int_{t_i}^t (t-s)^{\gamma-1} |u_1(s) - u_2(s)| ds + \frac{L_f}{\Gamma(\alpha)} \int_0^{s_i} (s_i-s)^{\alpha-1} |u_1(s) - u_2(s)| ds \\
& \leq \frac{L_{g_i}}{\Gamma(\gamma)} \|u_1 - u_2\|_{PC} \int_{t_i}^t (t-s)^{\gamma-1} ds + \frac{L_f}{\Gamma(\alpha)} \|u_1 - u_2\|_{PC} \int_0^{s_i} (s_i-s)^{\alpha-1} ds \\
& \leq \left(\frac{L_{g_i} (s_i - t_i)^\gamma}{\Gamma(\gamma+1)} + \frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right) \|u_1 - u_2\|_{PC},
\end{aligned}$$

which implies that

$$|(\Lambda u_1)(t) - (\Lambda u_2)(t)|^\beta \leq \left(\frac{L_{g_i} (s_i - t_i)^\gamma}{\Gamma(\gamma+1)} + \frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta \|u_1 - u_2\|_{P\beta}.$$

This reduces to

$$\|\Lambda u_1 - \Lambda u_2\|_{P\beta} \leq \left[\left(\frac{L_{g_i} (s_i - t_i)^\gamma}{\Gamma(\gamma+1)} \right)^\beta + \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta \right] \|u_1 - u_2\|_{P\beta}.$$

Case 3: For $u_1, u_2 \in PC(J, \mathbb{R})$ and for each $t \in (s_i, t_{i+1}]$, $i = 1, 2, \dots, m$, we have

$$\begin{aligned}
& |(\Lambda u_1)(t) - (\Lambda u_2)(t)| \\
& \leq \frac{L_f}{\Gamma(\alpha)} \int_{s_i}^t (t-s)^{\alpha-1} |u_1(s) - u_2(s)| ds + \frac{L_{g_i}}{\Gamma(\gamma)} \int_{t_i}^{s_i} (s_i-s)^{\gamma-1} |u_1(s_i) - u_2(s_i)| ds
\end{aligned}$$

$$\begin{aligned}
& + \frac{L_f}{\Gamma(\alpha)} \int_0^{s_i} (s_i - s)^{\alpha-1} |u_1(s) - u_2(s)| ds \\
& \leq \frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha + 1)} \|u_1 - u_2\|_{PC} + \frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma + 1)} \|u_1 - u_2\|_{PC} \\
& \quad + \frac{L_f s_i^\alpha}{\Gamma(\alpha + 1)} \|u_1 - u_2\|_{PC} \\
& \leq \left(\frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha + 1)} + \frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma + 1)} + \frac{L_f s_i^\alpha}{\Gamma(\alpha + 1)} \right) \|u_1 - u_2\|_{PC},
\end{aligned}$$

which implies that

$$|(\Lambda u_1)(t) - (\Lambda u_2)(t)|^\beta \leq \left(\frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha + 1)} + \frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma + 1)} + \frac{L_f s_i^\alpha}{\Gamma(\alpha + 1)} \right)^\beta \|u_1 - u_2\|_{P\beta}.$$

This reduces to

$$\begin{aligned}
& \|\Lambda u_1 - \Lambda u_2\|_{P\beta} \\
& \leq \left[\left(\frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha + 1)} \right)^\beta + \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma + 1)} \right)^\beta + \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha + 1)} \right)^\beta \right] \|u_1 - u_2\|_{P\beta}.
\end{aligned}$$

From the above cases, we obtain

$$\|\Lambda u_1 - \Lambda u_2\|_{P\beta} \leq \varrho \|u_1 - u_2\|_{P\beta},$$

where ϱ is given in (6). Finally, we can deduce that Λ is a contraction mapping. Then one can derive the result immediately. \square

In what follows, we discuss the stability of (1) by using the concept of β -Ulam-Hyers in the above section.

Theorem 4.2 *With the same assumptions in Theorem 4.1. Then (1) is β -Ulam-Hyers stable with respect to ϵ .*

Proof Denote by x the unique solution of

$$\begin{cases} {}^c D_{0,t}^\alpha x(t) = -\lambda x(t) + f(t, x(t)), & t \in (s_i, t_{i+1}], i = 0, 1, 2, \dots, m, \alpha \in (0, 1), \\ x(t) = q + I_{t_i,t}^\gamma g_i(t, x(t)) - I_{0,s_i}^\alpha f(s_i, x(s_i)), & t \in (t_i, s_i], i = 1, 2, \dots, m, \\ x(0) = y(0). \end{cases} \quad (7)$$

Then we get

$$x(t) = \begin{cases} q + I_{t_i,t}^\gamma g_i(t, x(t)) - I_{0,s_i}^\alpha f(s_i, x(s_i)), & t \in (t_i, s_i], i = 1, 2, \dots, m; \\ \mathbb{E}_\alpha(-t^\alpha \lambda) y(0) + \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, x(s)) ds, & t \in (0, t_1]; \\ \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, x(s)) ds \\ \quad + \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i,s_i}^\gamma g_i(s_i, x(s_i)) - I_{0,s_i}^\alpha f(s_i, x(s_i))), & t \in (s_i, t_{i+1}], i = 1, \dots, m. \end{cases}$$

Let $y \in PC^1(J, \mathbb{R})$ be a solution of the inequality (3). According to (4), for each $t \in (s_i, t_{i+1}]$, $i = 1, 2, \dots, m$, we have

$$\begin{aligned} & \left| y(t) - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right. \\ & \quad \left. - \mathbb{E}_\alpha(-(t-s_i)^\alpha \lambda) (q + I_{t_i, s_i}^\gamma g_i(s_i, y(s_i)) - I_{0, s_i}^\alpha f(s_i, y(s_i))) \right| \\ & \leq \epsilon + \frac{(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha + 1)} \epsilon, \end{aligned}$$

and for $t \in (t_i, s_i]$, $i = 1, 2, \dots, m$, we have

$$|y(t) - q - I_{t_i, t}^\alpha g_i(t, y(t)) + I_{0, s_i}^\alpha f(s_i, y(s_i))| \leq \epsilon,$$

and for $t \in [0, t_1]$, we have

$$\left| y(t) - \mathbb{E}_\alpha(-t^\alpha \lambda) y(0) - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right| \leq \frac{t_1^\alpha}{\Gamma(\alpha + 1)} \epsilon.$$

Case 1: For each $t \in [0, t_1]$, we get

$$\begin{aligned} |y(t) - x(t)| & \leq \left| y(t) - \mathbb{E}_\alpha(-t^\alpha \lambda) y(0) - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right. \\ & \quad \left. + \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right. \\ & \quad \left. - \int_0^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha, \alpha}(-(t-s)^\alpha \lambda) f(s, x(s)) ds \right| \\ & \leq \frac{t_1^\alpha}{\Gamma(\alpha + 1)} \epsilon + \frac{L_f}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |y(s) - x(s)| ds \\ & \leq \frac{t_1^\alpha}{\Gamma(\alpha + 1)} \epsilon + \frac{L_f t_1^\alpha}{\Gamma(\alpha + 1)} \|y - x\|_{PC}, \end{aligned}$$

where

$$\begin{aligned} |y(t) - x(t)|^\beta & \leq \left(\frac{t_1^\alpha}{\Gamma(\alpha + 1)} \epsilon + \frac{L_f t_1^\alpha}{\Gamma(\alpha + 1)} \|y - x\|_{PC} \right)^\beta \\ & \leq \left(\frac{t_1^\alpha}{\Gamma(\alpha + 1)} \epsilon \right)^\beta + \left(\frac{L_f t_1^\alpha}{\Gamma(\alpha + 1)} \right)^\beta \|y - x\|_{P\beta}^\beta, \end{aligned}$$

which implies that

$$\left[1 - \left(\frac{L_f t_1^\alpha}{\Gamma(\alpha + 1)} \right)^\beta \right] \|y - x\|_{P\beta} \leq \left(\frac{t_1^\alpha}{\Gamma(\alpha + 1)} \epsilon \right)^\beta.$$

Thus,

$$|y(t) - x(t)|^\beta \leq c_{f, \alpha, \gamma, \beta, g_i} \epsilon^\beta, \quad t \in [0, t_1], \quad (8)$$

where

$$c_{f,\alpha,\gamma,\beta,g_i} := \frac{\left(\frac{t_1^\alpha}{\Gamma(\alpha+1)}\right)^\beta}{1 - \left(\frac{L_f t_1^\alpha}{\Gamma(\alpha+1)}\right)^\beta}.$$

Case 2: For $t \in (t_i, s_i]$, $i = 1, 2, \dots, m$, we have

$$\begin{aligned} |y(t) - x(t)|^\beta &\leq |y(t) - q - I_{t_i,t}^\gamma g_i(t, y(t)) - I_{0,s_i}^\alpha f(s_i, y(s_i))|^\beta \\ &\quad + |I_{0,s_i}^\alpha f(s_i, y(s_i)) - I_{0,s_i}^\alpha f(s_i, x(s_i))|^\beta \\ &\quad + |I_{t_i,t}^\gamma g_i(t, y(t)) - I_{t_i,t}^\gamma g_i(t, x(t))|^\beta \\ &\leq \epsilon^\beta + \left[\left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta + \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma+1)} \right)^\beta \right] \|y - x\|_{P\beta}, \end{aligned}$$

which implies that

$$\left[1 - \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta - \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma+1)} \right)^\beta \right] \|y - x\|_{P\beta} \leq \epsilon^\beta.$$

Thus,

$$|y(t) - x(t)|^\beta \leq c_{f,\alpha,\gamma,\beta,g_i} \epsilon^\beta, \quad t \in (t_i, s_i], i = 1, 2, \dots, m, \quad (9)$$

where

$$c_{f,\alpha,\gamma,\beta,g_i} := \frac{1}{1 - \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)}\right)^\beta - \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma+1)}\right)^\beta}.$$

Case 3: For $t \in (s_i, t_{i+1}]$, $i = 1, 2, \dots, m$, we have

$$\begin{aligned} |y(t) - x(t)|^\beta &\leq \left| y(t) - \int_{s_i}^t (t-s)^{\alpha-1} \mathbb{E}_{\alpha,\alpha}(-(t-s)^\alpha \lambda) f(s, y(s)) ds \right. \\ &\quad \left. - \mathbb{E}_{\alpha,\alpha}(-(t-s_i)^\alpha \lambda) (q + I_{t_i,s_i}^\gamma g_i(s_i, y(s_i)) - I_{0,s_i}^\alpha f(s_i, y(s_i))) \right|^\beta \\ &\quad + \left[\frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |f(s, y(s)) - f(s, x(s))| ds \right]^\beta \\ &\quad + |I_{t_i,s_i}^\gamma g_i(s_i, y(s_i)) - I_{t_i,s_i}^\gamma g_i(s_i, x(s_i))|^\beta + |I_{0,s_i}^\alpha f(s_i, y(s_i)) - I_{0,s_i}^\alpha f(s_i, x(s_i))|^\beta \\ &\leq \left(\epsilon + \frac{(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \epsilon \right)^\beta \\ &\quad + \left[\left(\frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \right)^\beta + \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma+1)} \right)^\beta + \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta \right] \|y - x\|_{P\beta}, \end{aligned}$$

which yields

$$\begin{aligned} &\left\{ 1 - \left[\left(\frac{L_f(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \right)^\beta + \left(\frac{L_{g_i}(s_i - t_i)^\gamma}{\Gamma(\gamma+1)} \right)^\beta + \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)} \right)^\beta \right] \right\} \|y - x\|_{P\beta} \\ &\leq \left(\epsilon + \frac{(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \epsilon \right)^\beta \leq \left[1 + \left(\frac{(t_{i+1} - s_i)^\alpha}{\Gamma(\alpha+1)} \right)^\beta \right] \epsilon^\beta. \end{aligned}$$

Thus,

$$|y(t) - x(t)|^\beta \leq c_{f,\alpha,\gamma,\beta,g_i} \epsilon^\beta, \quad t \in (s_i, t_{i+1}], i = 1, 2, \dots, m, \quad (10)$$

where

$$c_{f,\alpha,\gamma,\beta,g_i} := \frac{1 + \left(\frac{(t_{i+1}-s_i)^\alpha}{\Gamma(\alpha+1)}\right)^\beta}{1 - \left[\left(\frac{L_f(t_{i+1}-s_i)^\alpha}{\Gamma(\alpha+1)}\right)^\beta + \left(\frac{L_{g_i}(s_i-t_i)^\gamma}{\Gamma(\gamma+1)}\right)^\beta + \left(\frac{L_f s_i^\alpha}{\Gamma(\alpha+1)}\right)^\beta\right]}.$$

Summarizing, (8), (9), and (10) imply that (1) is β -Ulam-Hyers stable with respect to ϵ . The proof is completed. \square

5 Example

Let us consider

$$\begin{cases} {}^c D_{0,t}^{\frac{3}{5}} x(t) = -x(t) + \frac{1}{8+e^t+t^2} \arctan(t^2 + x(t)), & t \in (0, 1], \\ x(t) = q + \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|x(s)|}{16(1+|x(s)|)} ds \\ \quad - \frac{1}{\Gamma(\frac{3}{5})} \int_0^2 (2-s)^{-\frac{2}{5}} \frac{1}{8+e^s+s^2} \arctan(s^2 + x(s)) ds, & t \in (1, 2] \end{cases} \quad (11)$$

and

$$\begin{cases} |{}^c D_{0,t}^{\frac{3}{5}} y(t) + y(t) - \frac{1}{8+e^t+t^2} \arctan(t^2 + y(t))| \leq 1, & t \in (0, 1], \\ |y(t) - q - \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|y(s)|}{16(1+|y(s)|)} ds \\ \quad + \frac{1}{\Gamma(\frac{3}{5})} \int_0^2 (2-s)^{-\frac{2}{5}} \frac{1}{8+e^s+s^2} \arctan(s^2 + y(s)) ds| \leq 1, & t \in (1, 2]. \end{cases} \quad (12)$$

Set $\lambda = 1$, $\alpha = \frac{3}{5}$, $\gamma = \frac{2}{3}$, $J = [0, 2]$, $0 = t_0 = s_0 < t_1 = 1 < s_1 = 2$, and $\beta = \frac{1}{2}$. Denote $f(t, x(t)) = \frac{1}{8+e^t+t^2} \arctan(t^2 + x(t))$ with $L_f = \frac{1}{9}$ for $t \in (0, 1]$ and $L_{1,t}^{\frac{2}{3}} g_1(t, x(t)) = \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|x(s)|}{16(1+|x(s)|)} ds$ with $L_{g_1} = \frac{1}{16}$ for $t \in (1, 2]$. Moreover, we put $\epsilon = 1$.

Let $y \in PC^1([0, 2], \mathbb{R})$ be a solution of the inequality (12). Then there exists $G \in \mathbb{R}$ such that $|G| \leq 1$ and

$$\begin{aligned} {}^c D_{0,t}^{\frac{3}{5}} y(t) &= -y(t) + \frac{1}{8+e^t+t^2} \arctan(t^2 + y(t)) + G, \quad t \in (0, 1], \\ y(t) &= q + \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|y(s)|}{16(1+|y(s)|)} ds \\ &\quad - \frac{1}{\Gamma(\frac{3}{5})} \int_0^2 (2-s)^{-\frac{2}{5}} \frac{1}{8+e^s+s^2} \arctan(s^2 + y(s)) ds + G, \quad t \in (1, 2]. \end{aligned} \quad (13)$$

For $t \in (0, 1]$, integrating (13) from 0 to t , we have

$$\begin{aligned} y(t) &= \mathbb{E}_{\frac{3}{5}}(-t^{\frac{3}{5}}) y(0) \\ &\quad + \int_0^t (t-s)^{\frac{3}{5}-1} \mathbb{E}_{\frac{3}{5}, \frac{3}{5}}(-(t-s)^{\frac{3}{5}}) \left(\frac{1}{8+e^s+s^2} \arctan(s^2 + y(s)) + G \right) ds. \end{aligned}$$

For $t \in (1, 2]$, we have

$$y(t) = q + \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|y(s)|}{16(1+|y(s)|)} ds \\ - \frac{1}{\Gamma(\frac{3}{5})} \int_0^2 (2-s)^{-\frac{2}{5}} \frac{1}{8+e^s+s^2} \arctan(s^2+y(s)) ds + G.$$

After checking the conditions in Theorem 4.1, we find that

$$\begin{cases} {}^c D_{0,t}^{\frac{3}{5}} x(t) = -x(t) + \frac{1}{8+e^t+t^2} \arctan(t^2+x(t)), & t \in (0, 1], \\ x(t) = q_1 + \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|x(s)|}{16(1+|x(s)|)} ds \\ \quad - \frac{1}{\Gamma(\frac{3}{5})} \int_0^2 (2-s)^{-\frac{2}{5}} \frac{1}{8+e^s+s^2} \arctan(s^2+x(s)) ds, & t \in (1, 2], \\ x(0) = y(0), \end{cases} \quad (14)$$

has a unique solution, where

$$\varrho := \max \left\{ \frac{1}{3\sqrt{\Gamma(\frac{8}{5})}}, \frac{1}{4\sqrt{\Gamma(\frac{5}{3})}} + \frac{2^{\frac{3}{10}}}{3\sqrt{\Gamma(\frac{8}{5})}} \right\} \approx \max\{0.3526, 0.6972\} < 1.$$

Next, let us take the solution x of the problem (14) given by

$$x(t) = \mathbb{E}_{\frac{3}{5}}(-t^{\frac{3}{5}})y(0) \\ + \int_0^t (t-s)^{-\frac{2}{5}} \mathbb{E}_{\frac{3}{5}, \frac{3}{5}}(-(t-s)^{\frac{3}{5}}) \left(\frac{1}{8+e^s+s^2} \arctan(s^2+x(s)) \right) ds, \quad t \in (0, 1], \\ x(t) = q + \frac{1}{\Gamma(\frac{2}{3})} \int_1^t (t-s)^{-\frac{1}{3}} \frac{|x(s)|}{16(1+|x(s)|)} ds \\ - \frac{1}{\Gamma(\frac{3}{5})} \int_0^2 (2-s)^{-\frac{2}{5}} \frac{1}{8+e^s+s^2} \arctan(s^2+x(s)) ds, \quad t \in (1, 2].$$

For $t \in (0, 1]$, we have

$$|y(t) - x(t)|^{\frac{1}{2}} \leq \frac{\frac{1}{\sqrt{\Gamma(\frac{8}{5})}}}{1 - \frac{1}{3\sqrt{\Gamma(\frac{8}{5})}}} \epsilon^{\frac{1}{2}} \leq 1.64.$$

For $t \in (1, 2]$, we have

$$|y(t) - x(t)|^{\frac{1}{2}} \leq \frac{1}{1 - \frac{2^{\frac{3}{10}}}{3\sqrt{\Gamma(\frac{8}{5})}} - \frac{1}{4\sqrt{\Gamma(\frac{5}{3})}}} \leq 3.3.$$

Summarizing, we have

$$|y(t) - x(t)|^{\frac{1}{2}} \leq 3.3 = 3.3 \cdot 1^{\frac{1}{2}}, \quad t \in J,$$

which shows that (11) is $\frac{1}{2}$ -Ulam-Hyers stable with respect to $\epsilon = 1$.

6 Conclusions

This paper has investigated a new class of fractional differential equations with instantaneous impulses. In particular, the existence and β -Ulam-Hyers stability for such a new class of impulsive equations on a compact interval are obtained.

Competing interests

The author declares to have no competing interests.

Author's contributions

YXL proved the theorems, interpreted the results, wrote the article, and defined the research theme, and read and approved the manuscript.

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