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Sign-changing solutions to discrete fourth-order Neumann boundary value problems

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Abstract

By using topological degree theory and fixed point index theory, we consider a discrete fourth-order Neumann boundary value problem. We provide sufficient conditions for the existence of sign-changing solutions, positive solutions, and negative solutions.

Keywords: topological degree theory; fixed point index theory; sign-changing solutions; positive solutions; negative solutions

1 Introduction

In this paper, we consider the existence of sign-changing solutions to the following discrete nonlinear fourth-order boundary value problem (BVP):

$$\Delta^4 u(t-2) - \alpha \Delta^2 u(t-1) + \beta u(t) = f(t, u(t)), \quad t \in [2, T]_{\mathbb{Z}}, \quad (1.1)$$

$$\Delta u(1) = \Delta u(T) = \Delta^3 u(0) = \Delta^3 u(T-1) = 0, \quad (1.2)$$

where Δ denotes the forward difference operator defined by $\Delta u(t) = u(t+1) - u(t)$, $T > 2$ is an integer, $f : [2, T]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous, and α, β are real parameters and satisfy

$$\alpha^2 \geq 4\beta, \quad \text{and} \quad \alpha - \sqrt{\alpha^2 - 4\beta} > -8 \sin^2 \frac{\pi}{2(T-1)}.$$

Let a, b be two integers with $a < b$. We employ $[a, b]_{\mathbb{Z}}$ to denote the discrete interval given by $\{a, a+1, \dots, b\}$.

The theory of nonlinear difference equations has been widely used to study discrete models in many fields such as computer science, economics, neural network, ecology, cybernetics, *etc.* In recent years, a great deal of work has been done in the study of the existence and multiplicity of solutions for a discrete boundary value problem. For the background and recent results, we refer the reader to [1–5] and the references therein.

We may think of BVP (1.1), (1.2) as a discrete analogue of the fourth-order boundary value problem

$$u^{(4)}(t) - \alpha u^{(2)}(t) + \beta u(t) = \lambda f(t, u(t)), \quad t \in (0, 1), \quad (1.3)$$

$$u'(0) = u'(1) = u^3(0) = u^3(1) = 0. \quad (1.4)$$

The special case of BVP (1.3), (1.4) has been studied by many authors using various approaches; for example, see [6, 7].

However, it seems that there is no similar result in the literature on the existence of sign-changing solutions, positive solutions, and negative solutions for BVP (1.1), (1.2). Motivated by [8], our purpose is to apply some basic theorems in topological degree theory and fixed point index theory to establish some conditions for the nonlinear function f , which are able to guarantee the existence of sign-changing solutions, positive solutions, and negative solutions for the above discrete boundary value problem.

The organization of this paper is as follows. In Section 2, we state some notations and preliminary knowledge about the topological degree theory and fixed point index theory. In Section 3, we present the spectrum of second-order eigenvalue problems. In Section 4, we give the expression of Green's function of second-order Neumann problems and consider the eigenvalue problem of fourth-order BVPs. In Section 5, by computing the topological degree and the fixed point index, we discuss the existence of multiple sign-changing solutions to BVP (1.1), (1.2).

2 Preliminaries

As we have mentioned, we will use the theory of the Leray-Schauder degree and the fixed point index in a cone to prove our main existence results. Let us collect some results that will be used below. One can refer to [9–12] for more details.

Lemma 2.1 (see [9, 10]) *Let E be a Banach space and $X \subset E$ be a cone in E . Assume that Ω is a bounded open subset of E . Suppose that $A : X \cap \overline{\Omega} \rightarrow X$ is a completely continuous operator. If there exists $x_0 \in X \setminus \{\theta\}$ such that*

$$x - Ax \neq \mu x_0, \quad \forall x \in X \cap \partial\Omega, \mu \geq 0, \tag{2.1}$$

then the fixed point index $i(A, X \cap \Omega, X) = 0$.

Lemma 2.2 (see [9, 10]) *Let E be a Banach space and let $X \subset E$ be a cone in E . Assume that Ω is a bounded open subset of E , $\theta \in \Omega$. Suppose that $A : X \cap \overline{\Omega} \rightarrow X$ is a completely continuous operator. If*

$$Ax \neq \mu x, \quad \forall x \in X \cap \partial\Omega, \mu \geq 1, \tag{2.2}$$

then the fixed point index $i(A, X \cap \Omega, X) = 1$.

Lemma 2.3 (see [11]) *Let E be a Banach space, let Ω be a bounded open subset of E , $\theta \in \Omega$, and $A : \overline{\Omega} \rightarrow E$ be completely continuous. Suppose that*

$$\|Ax\| \leq \|x\|, \quad Ax \neq x, \forall x \in \partial\Omega. \tag{2.3}$$

Then $\deg(I - A, \Omega, \theta) = 1$.

Lemma 2.4 (see [12]) *Let A be a completely continuous operator which is defined on a Banach space E . Let $x_0 \in E$ be a fixed point of A and assume that A is defined in a neighborhood of x_0 and Fréchet differentiable at x_0 . If 1 is not an eigenvalue of the linear operator*

$A'(x_0)$, then x_0 is an isolated singular point of the completely continuous vector field $I - A$, and for small enough $r > 0$,

$$\deg(I - A, B(x_0, r), \theta) = (-1)^k, \tag{2.4}$$

where k is the sum of algebraic multiplicities of real eigenvalues of $A'(x_0)$ in $(1, +\infty)$.

Lemma 2.5 (see [12]) *Let A be a completely continuous operator which is defined on a Banach space E . Assume that 1 is not an eigenvalue of the asymptotic derivative. Then the completely continuous vector field $I - A$ is nonsingular on spheres $S_\rho = \{x \in E : \|x\| = \rho\}$ of sufficiently large radius ρ and*

$$\deg(I - A, B(\theta, \rho), \theta) = (-1)^k, \tag{2.5}$$

where k is the sum of algebraic multiplicities of real eigenvalues of $A'(\infty)$ in $(1, +\infty)$.

Lemma 2.6 (see [12]) *Let X be a solid cone of a Banach space E (X° is nonempty), let Ω be a relatively bounded open subset of X , and let $A : X \rightarrow X$ be a completely continuous operator. If any fixed point of A in Ω is an interior point of X , there exists an open subset O of E ($O \subset \Omega$) such that*

$$\deg(I - A, O, \theta) = i(A, \Omega, X). \tag{2.6}$$

Now, we will consider the space

$$E = \{u : [2, T]_{\mathbb{Z}} \rightarrow \mathbb{R}, \Delta u(1) = \Delta u(T) = \Delta^3 u(0) = \Delta^3 u(T - 1) = 0\} \tag{2.7}$$

equipped with the norm $\|u\| = \max_{t \in [2, T]_{\mathbb{Z}}} |u(t)|$. Clearly, E is a $(T - 1)$ -dimensional Banach space. Choose the cone $P \subset E$ defined by

$$P = \{u \in E \mid u(t) \geq 0, t \in [2, T]_{\mathbb{Z}}\}. \tag{2.8}$$

Obviously, the interior of P is $P^\circ = \{u \in E \mid u(t) > 0, t \in [2, T]_{\mathbb{Z}}\}$. For each $u, v \in E$, we write $u \geq v$ if $u(t) \geq v(t)$ for $t \in [2, T]_{\mathbb{Z}}$. A solution u of BVP (1.1), (1.2) is said to be a positive solution (a negative solution, resp.) if $u \in P \setminus \{\theta\}$ ($u \in (-P) \setminus \{\theta\}$, resp.). A solution u of BVP (1.1), (1.2) is said to be a sign-changing solution if $u \notin P \cup (-P)$.

3 Spectrum of second-order eigenvalue problems

Consider the second-order discrete linear eigenvalue problems

$$-\Delta^2 y(t - 1) + \lambda y(t) = 0, \quad t \in [1, T]_{\mathbb{Z}}, \tag{3.1}$$

$$\Delta y(1) = \Delta y(T) = 0. \tag{3.2}$$

Lemma 3.1 (see [13] Theorem 1) *The eigenvalues of (3.1), (3.2) can be given by*

$$\lambda_k = 2 \cos \frac{k\pi}{T + 1} - 2,$$

and the corresponding eigenfunction is if $k = 0$, then $\varphi_0(t) = 1$. If $k \in \{1, 2, \dots, T - 2\}$, we have

- (i) if $k \neq \frac{T-1}{3}$, then $\varphi_k(t) = \frac{1}{\cos \frac{3k\pi}{2(T-1)}} \cos \frac{k\pi}{2(T-1)}(2t - 3)$,
- (ii) if $k = \frac{T-1}{3}$, then $\varphi_k(t) = \sin \frac{\pi t}{3}$.

4 Green's function and eigenvalue problems to fourth-order BVPs

In this section, we construct Green's function associated with BVP (1.1), (1.2).

Let r_1, r_2 be roots of the polynomial $P(r) = r^2 - \alpha r + \beta$, namely,

$$r_1 = \frac{\alpha + \sqrt{\alpha^2 - 4\beta}}{2}, \quad r_2 = \frac{\alpha - \sqrt{\alpha^2 - 4\beta}}{2}.$$

Then we have

$$\begin{aligned} \Delta^4 u(t - 2) - \alpha \Delta^2 u(t - 1) + \beta u(t) &= (-\Delta^2 L + r_1)(-\Delta^2 L + r_2)u(t) \\ &= (-\Delta^2 L + r_2)(-\Delta^2 L + r_1)u(t), \end{aligned}$$

where $u = (u(0), u(1), \dots, u(T + 2))$, $Lu = u(t - 1)$, $t \in [2, T]_{\mathbb{Z}}$. Under the basic assumption on α, β , it is easy to see that $r_1 \geq r_2 > -4 \sin^2 \frac{\pi}{2(T-1)}$.

Consider the two initial value problems:

$$\begin{cases} -\Delta^2 u(t - 1) + r_i u(t) = 0, & t \in [2, T]_{\mathbb{Z}}, \\ \Delta u(1) = 0, & u(1) = 1, \end{cases} \quad (4.1)$$

$$\begin{cases} -\Delta^2 v(t - 1) + r_i v(t) = 0, & t \in [2, T]_{\mathbb{Z}}, \\ \Delta v(T) = 0, & v(T) = 1. \end{cases} \quad (4.2)$$

By the direct computing, we get (4.1) has a unique solution

$$u(t) = \frac{r_2 - 1}{r_1(r_2 - r_1)} r_1^t + \frac{1 - r_1}{r_2(r_2 - r_1)} r_2^t,$$

and (4.2) has a unique solution

$$v(t) = \frac{r_2 - 1}{r_1^T(r_2 - r_1)} r_1^t + \frac{1 - r_1}{r_2^T(r_2 - r_1)} r_2^t.$$

Let

$$\rho := \frac{(r_1 - 1)(r_2 - 1)(r_2^{T-1} - r_1^{T-1})}{r_1^{T-1} r_2^{T-1}}.$$

Lemma 4.1 Let $h : [1, T]_{\mathbb{Z}} \rightarrow \mathbb{R}$ and $i \in \{1, 2\}$ be fixed. Then the problem

$$\begin{cases} -\Delta^2 u(t - 1) + r_i u(t) = h(t), & t \in [2, T]_{\mathbb{Z}}, \\ \Delta u(1) = \Delta u(T) = 0 \end{cases} \quad (4.3)$$

has a unique solution

$$u(t) = \sum_{s=2}^T G_i(t, s)h(s), \quad t \in [1, T + 1]_{\mathbb{Z}},$$

where $G_i(t, s)$ is given by

$$G_i(t, s) = \frac{1}{\rho} \begin{cases} u(t)v(s), & 1 \leq s \leq t \leq T + 1, \\ u(s)v(t), & 1 \leq t \leq s \leq T + 1. \end{cases}$$

Remark 4.1 Green's function $G_i(t, s)$ defined by Lemma 4.1 is positive on $[1, T]_{\mathbb{Z}} \times [1, T]_{\mathbb{Z}}$.

Define operators $K, f, A : E \rightarrow E$, respectively, by

$$(Ku)(t) = \sum_{s=2}^T \sum_{k=2}^T G_2(t, k)G_1(k, s)u(s), \quad u \in E, t \in [1, T]_{\mathbb{Z}}; \tag{4.4}$$

$$(fu)(t) = f(t, u(t)), \quad u \in E, t \in [1, T]_{\mathbb{Z}};$$

$$A = Kf. \tag{4.5}$$

Now, from Lemma 4.1, it is easy to see that BVP (1.1), (1.2) has a solution $u = u(t)$ if and only if u is a fixed point of the operator A . It follows from the continuity of f that $A : E \rightarrow E$ is completely continuous.

Lemma 4.2 Let $h : [2, T]_{\mathbb{Z}} \rightarrow \mathbb{R}$. Then the linear discrete fourth-order boundary value problem

$$\begin{cases} \Delta^4 u(t - 2) - \alpha \Delta^2 u(t - 1) + \beta u(t) = h(t), & t \in [2, T]_{\mathbb{Z}}, \\ \Delta u(1) = \Delta u(T) = \Delta^3 u(0) = \Delta^3 u(T - 1) = 0 \end{cases} \tag{4.6}$$

has a unique solution

$$\begin{aligned} u(t) &= \sum_{s=2}^T \left(\sum_{k=2}^T G_1(t, k)G_2(k, s)h(s) \right) \\ &= \sum_{s=2}^T \left(\sum_{k=2}^T G_2(t, k)G_1(k, s)h(s) \right), \quad t \in [2, T]_{\mathbb{Z}}, \end{aligned}$$

and

$$u(0) = u(3), \quad u(1) = u(2), \quad u(T) = u(T + 1), \quad u(T - 1) = u(T + 2).$$

Proof The conclusion is obvious, so we omit it. □

We will use the following assumptions.

(H1) α, β are real parameters and satisfy

$$\alpha^2 \geq 4\beta, \quad \text{and} \quad \alpha - \sqrt{\alpha^2 - 4\beta} > -8 \sin^2 \frac{\pi}{2(T - 1)}.$$

(H2) $f : [2, T]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous, for any $t \in [2, T]_{\mathbb{Z}}, f(t, 0) = 0$; for any $t \in [2, T]_{\mathbb{Z}}$ and $x \in \mathbb{R}, xf(t, x) \geq 0$.

(H3) There exists an even number $k_0 \in [0, T - 2]_{\mathbb{Z}}$ such that

$$\frac{1}{\lambda_{k_0}^2} < \beta_0 < \frac{1}{\lambda_{k_0+1}^2}, \tag{4.7}$$

where $\lim_{x \rightarrow 0} \frac{f(t,x)}{x} = \beta_0$ uniformly for $t \in [2, T]_{\mathbb{Z}}$, λ_k is defined in Lemma 3.1 and $\lambda_{T-1} \triangleq \infty$.

(H4) There exists an even number $k_1 \in [0, T - 2]_{\mathbb{Z}}$ such that

$$\frac{1}{\lambda_{k_1}^2} < \beta_{\infty} < \frac{1}{\lambda_{k_1+1}^2}, \tag{4.8}$$

where $\lim_{x \rightarrow \infty} \frac{f(t,x)}{x} = \beta_{\infty}$ uniformly for $t \in [2, T]_{\mathbb{Z}}$, and $\lambda_0, \lambda_1, \dots, \lambda_{T-1}$ are given in the condition (H3).

(H5) There exists a constant $M > 0$ such that for any $(t, x) \in [2, T]_{\mathbb{Z}} \times [-M, M]$,

$$|f(t, x)| < \omega^{-1}M, \tag{4.9}$$

where $\omega = \max_{t \in [2, T]_{\mathbb{Z}}} \sum_{s=2}^T \sum_{k=2}^T G_2(t, k)G_1(k, s)$.

Lemma 4.3 *Suppose that (H2) holds and $u \in P \setminus \{\theta\}$ is a solution of BVP (1.1), (1.2). Then $u \in P^{\circ}$.*

Proof According to (H2) and the positivity of Green's function defined in Lemma 4.1, we can easily get the desired conclusion. □

Remark 4.2 Similarly to Lemma 4.3, we also know that if (H2) holds and $u \in (-P) \setminus \{\theta\}$ is a solution of BVP (1.1), (1.2), then $u \in (-P)^{\circ}$.

Lemma 4.4 *Suppose that (H2)-(H4) hold. Then the operator A is Fréchet differentiable at θ and ∞ , where the operator A is defined by (4.5). Moreover, $A'(\theta) = \beta_0 K$ and $A'(\infty) = \beta_{\infty} K$.*

Proof By (H3), for any $\epsilon > 0$, there exists $\delta > 0$ such that $|f(t, x) - \beta_0 x| < \epsilon|x|$ for any $0 < |x| < \delta$, $t \in [2, T]_{\mathbb{Z}}$. Hence, noticing that $f(t, 0) = 0$ for any $t \in [2, T]_{\mathbb{Z}}$, we have

$$\begin{aligned} \|Au - A\theta - \beta_0 Ku\| &= \|K(fu - \beta_0 u)\| \\ &\leq \|K\| \max_{t \in [2, T]_{\mathbb{Z}}} |f(t, u(t)) - \beta_0 u(t)| < \epsilon \|K\| \|u\| \end{aligned} \tag{4.10}$$

for any $u \in E$ with $0 < |u| < \delta$, where $\|K\| = \max_{t \in [2, T]_{\mathbb{Z}}} \sum_{s=2}^T \sum_{k=2}^T |G_2(t, k)| |G_1(k, s)|$. Consequently,

$$\lim_{\|u\| \rightarrow 0} \frac{\|Au - A\theta - \beta_0 Ku\|}{\|u\|} = 0. \tag{4.11}$$

This means that the nonlinear operator A is Fréchet differentiable at θ and $A'(\theta) = \beta_0 K$.

By (H4), for any $\epsilon > 0$, there exists $W > 0$ such that $|f(t, x) - \beta_{\infty} x| < \epsilon|x|$ for any $|x| > W$, $t \in [2, T]_{\mathbb{Z}}$. Let $c = \max_{(t,x) \in [2, T]_{\mathbb{Z}} \times [-W, W]} |f(t, x) - \beta_{\infty} x|$. By the continuity of $f(t, x)$ with

respect to x , we have $c < +\infty$. Then, for any $(t, x) \in [2, T]_{\mathbb{Z}} \times \mathbb{R}$, $|f(t, x) - \beta_{\infty}x| < \epsilon|x| + c$. Thus

$$\|Au - \beta_{\infty}Ku\| \leq \|K\| \cdot \max_{t \in [2, T]_{\mathbb{Z}}} |f(t, u) - \beta_{\infty}u(t)| < \|K\|(\epsilon\|u\| + c) \tag{4.12}$$

for any $u \in E$. Consequently,

$$\lim_{\|u\| \rightarrow \infty} \frac{\|Au - A\theta - \beta_{\infty}Ku\|}{\|u\|} = 0, \tag{4.13}$$

which implies that operator A is Fréchet differentiable at ∞ and $A'(\infty) = \beta_{\infty}K$. The proof is completed. \square

Lemma 4.5 *Let M be given in the condition (H5). Suppose that (H1)-(H4) hold. Then $A(P) \subset P$, $A(-P) \subset (-P)$. Moreover, one has the following.*

(i) *There exists an $r_0 \in (0, M)$ such that for any $0 < r \leq r_0$,*

$$i(A, P \cap B(\theta, r), P) = 0, \quad i(A, (-P) \cap B(\theta, r), -P) = 0. \tag{4.14}$$

(ii) *There exists an $R_0 > M$ such that for any $R \geq R_0$,*

$$i(A, P \cap B(\theta, R), P) = 0, \quad i(A, (-P) \cap B(\theta, R), -P) = 0. \tag{4.15}$$

Proof By (H2) and the fact that $G_i(t, s)$ is positive on $[2, T]_{\mathbb{Z}} \times [2, T]_{\mathbb{Z}}$, we get that for any $t \in [2, T]_{\mathbb{Z}}$, $f(t, P) \subset P$, $f(t, -P) \subset -P$, and $K(P) \subset P$, $K(-P) \subset -P$. Then $A(P) \subset P$ and $A(-P) \subset -P$.

We only need to prove conclusion (i). The proof of conclusion (ii) is similar and will be omitted here. Let $\gamma_0 = \inf_{\|u\|=1} \|u - \beta_0Ku\|$. The condition (H3) yields $\gamma_0 > 0$. It follows from (4.12) that there exists $r_0 \in [0, M]$ such that

$$\|Au - \beta_{\infty}Ku\| < \frac{1}{2}\gamma_0\|u\|, \tag{4.16}$$

where $0 < u \leq r_0$. Setting $H(s, u) = sAu + (1 - s)\beta_0Ku$, then $H : [0, 1] \times E \rightarrow E$ is completely continuous. For any $s \in [0, 1]$ and $0 < u \leq r_0$, we obtain that

$$\|u - H(s, u)\| \geq \|u - \beta_0Ku\| - s\|Au - \beta_0Ku\| \geq \gamma_0\|u\| - \frac{1}{2}\gamma_0\|u\| > 0. \tag{4.17}$$

According to the homotopy invariance of the fixed point index, for any $0 < r \leq r_0$, we have

$$i(A, P \cap B(\theta, r), P) = i(\beta_0K, P \cap B(\theta, r), P), \tag{4.18}$$

$$i(A, -P \cap B(\theta, r), -P) = i(\beta_0K, -P \cap B(\theta, r), -P). \tag{4.19}$$

Let $\varphi_0(t) = 1$. Then $K\varphi_0 = \lambda_0^2\varphi_0$ and $\varphi_0 \in P$ (see Lemma 3.1 and the proof of Lemma 4.2). We claim

$$u - \beta_0Ku \neq \sigma\varphi_0, \quad \forall u \in P \cap \partial B(\theta, r), \sigma \geq 0. \tag{4.20}$$

Indeed, we assume that there exist $u_1 \in P \cap \partial B(\theta, r)$ and $\sigma_1 \geq 0$ such that $u_1 - \beta_0 K u_1 = \sigma_1 \varphi_0$. Obviously, $u_1 = \beta_0 K u_1 + \sigma_1 \varphi_0 \geq \sigma_1 \varphi_0$. Since $\beta_0 \neq \lambda_k^{-2}$, $k = 1, 2, \dots, T - 2$, then $\sigma_1 > 0$. Set $\sigma_{\max} = \sup\{\sigma : u_1 \geq \sigma \varphi_0\}$. It is clear that $\sigma_1 \leq \sigma_{\max} < \infty$ and $u_1 \geq \sigma_{\max} \varphi_0$. Then

$$u_1 = \beta_0 K u_1 + \sigma_1 \varphi_0 \geq \beta_0 K \sigma_{\max} \varphi_0 + \varphi_0 \sigma_1 = (\beta_0 \lambda_0^2 \sigma_{\max} + \sigma_1) \varphi_0. \tag{4.21}$$

Since $\beta_0 \lambda_0^2 > 1$, then $\beta_0 \lambda_0^2 \sigma_{\max} + \sigma_1 > \sigma_{\max}$, which contradicts the definition of σ_{\max} . This proves (4.21).

It follows from Lemma 2.1 and (4.20) that

$$i(\beta_0 K, P \cap B(\theta, r), P) = 0. \tag{4.22}$$

Similarly to (4.22), we know also that

$$i(\beta_0 K, -P \cap B(\theta, r), -P) = 0. \tag{4.23}$$

By (4.18), (4.19), (4.22), and (4.23), we conclude

$$i(A, P \cap B(\theta, r), P) = 0, \quad i(A, -P \cap B(\theta, r), -P) = 0. \tag{4.24}$$

□

5 Main results

Now, with the aid of the lemmas in Section 2, we are in a position to state and prove our main results.

Theorem 5.1 *Assume that the conditions (H1)-(H5) hold. Then BVP (1.1), (1.2) has at least two sign-changing solutions. Moreover, BVP (1.1), (1.2) has at least two positive solutions and two negative solutions.*

Proof Since $G(t, s)$ is positive on $[2, T]_{\mathbb{Z}} \times [1, T]_{\mathbb{Z}}$, by (H5), we have for any $u \in E$ with $\|u\| = M$,

$$\begin{aligned} |Au(t)| &= \left| \sum_{s=2}^T \sum_{k=2}^T G_2(t, k) G_1(k, s) f(t, u(t)) \right| \leq \sum_{s=2}^T \sum_{k=2}^T G_2(t, k) G_1(k, s) |f(t, u(t))| \\ &< \omega^{-1} M \cdot \sum_{s=2}^T \sum_{k=2}^T G_2(t, k) G_1(k, s) \leq M, \quad \forall t \in [2, T]_{\mathbb{Z}}. \end{aligned} \tag{5.1}$$

This gives

$$\|Au\| < M = \|u\|. \tag{5.2}$$

By (5.2) and Lemmas 2.2 and 2.3, we have

$$\deg(I - A, B(\theta, M), \theta) = 1, \tag{5.3}$$

$$i(A, P \cap B(\theta, M), P) = 1, \tag{5.4}$$

$$i(A, -P \cap B(\theta, M), P) = 1. \tag{5.5}$$

From (H3) and Lemma 3.1, one has that the eigenvalues of the operator $A'(\theta) = \beta_0 K$ which are larger than 1 are

$$\beta_0 \lambda_0^2, \beta_0 \lambda_1^2, \dots, \beta_0 \lambda_{k_0}^2. \tag{5.6}$$

From (H4) and Lemma 3.1, one has that the eigenvalues of the operator $A'(\infty) = \beta_\infty K$ which are larger than 1 are

$$\beta_\infty \lambda_0^1, \beta_\infty \lambda_1^2, \dots, \beta_\infty \lambda_{k_1}^2. \tag{5.7}$$

It follows from Lemmas 2.4 and 2.5 that there exist $0 < r_1 < r_0$ and $R_1 > R_0$ such that

$$\deg(I - A, B(\theta, r_1), \theta) = (-1)^{k_0} = 1, \tag{5.8}$$

$$\deg(I - A, B(\theta, R_1), \theta) = (-1)^{k_1} = 1, \tag{5.9}$$

where r_0 and R_0 are given in Lemma 4.5. Owing to Lemma 4.3, one has

$$i(A, P \cap B(\theta, r_1), P) = 0, \tag{5.10}$$

$$i(A, -P \cap B(\theta, r_1), -P) = 0, \tag{5.11}$$

$$i(A, P \cap B(\theta, R_1), P) = 0, \tag{5.12}$$

$$i(A, -P \cap B(\theta, R_1), -P) = 0. \tag{5.13}$$

According to the additivity of the fixed point index, by (5.4), (5.10), and (5.12), we have

$$\begin{aligned} i(A, P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)}), P) &= i(A, P \cap B(\theta, M), P) - i(A, P \cap B(\theta, r_1), P) \\ &= 1 - 0 = 1, \end{aligned} \tag{5.14}$$

$$\begin{aligned} i(A, P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)}), P) &= i(A, P \cap B(\theta, R_1), P) - i(A, P \cap B(\theta, M), P) \\ &= 0 - 1 = -1. \end{aligned} \tag{5.15}$$

Hence, the nonlinear operator A has at least two fixed points $u_1 \in P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)})$ and $u_2 \in P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)})$, respectively. Then, u_1 and u_2 are positive solutions of BVP (1.1), (1.2). Using again the additivity of the fixed point index, by (5.5), (5.11), and (5.13), we get

$$i(A, -P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)}), -P) = 1 - 0 = 1, \tag{5.16}$$

$$i(A, -P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)}), -P) = 0 - 1 = -1. \tag{5.17}$$

Hence, the nonlinear operator A has at least two fixed points $u_3 \in -P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)})$ and $u_4 \in -P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)})$, respectively. Then, u_3 and u_4 are negative solutions of BVP (1.1), (1.2).

Let

$$\Gamma_1 = \{u \in P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)}) : Au = u\},$$

$$\Gamma_2 = \{u \in P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)}) : Au = u\},$$

$$\Gamma_3 = \{u \in -P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)}) : Au = u\},$$

$$\Gamma_4 = \{u \in -P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)}) : Au = u\}.$$

It follows from Lemmas 2.6, 4.3, Remark 4.2, and (5.14)-(5.17) that there exist open subsets $O_1, O_2, O_3,$ and O_4 of E such that

$$\Gamma_1 \subset O_1 \subset P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)}), \quad \Gamma_1 \subset O_1 \subset P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)}), \quad (5.18)$$

$$\Gamma_3 \subset O_3 \subset -P \cap (B(\theta, M) \setminus \overline{B(\theta, r_1)}), \quad \Gamma_4 \subset O_4 \subset -P \cap (B(\theta, R_1) \setminus \overline{B(\theta, M)}), \quad (5.19)$$

$$\deg(I - A, O_1, \theta) = 1, \quad (5.20)$$

$$\deg(I - A, O_2, \theta) = -1, \quad (5.21)$$

$$\deg(I - A, O_3, \theta) = 1, \quad (5.22)$$

$$\deg(I - A, O_4, \theta) = -1. \quad (5.23)$$

By (5.3), (5.20), (5.22), (5.8), and the additivity of the Leray-Schauder degree, we get

$$\deg(I - A, B(\theta, M) \setminus (\overline{O_1} \cup \overline{O_3} \cup \overline{B(\theta, r_1)}), \theta) = 1 - 1 - 1 - 1 = -2, \quad (5.24)$$

which implies that the nonlinear operator A has at least one fixed point $u_5 \in B(\theta, M) \setminus (\overline{O_1} \cup \overline{O_3} \cup \overline{B(\theta, r_1)})$.

Similarly, by (5.9), (5.21), (5.23), and (5.3), we get

$$\deg(I - A, B(\theta, R_1) \setminus (\overline{O_2} \cup \overline{O_4} \cup \overline{B(\theta, M)}), \theta) = 1 + 1 + 1 - 1 = 2, \quad (5.25)$$

which implies that the nonlinear operator A has at least one fixed point $u_6 \in B(\theta, R_1) \setminus (\overline{O_2} \cup \overline{O_4} \cup \overline{B(\theta, M)})$. Then, u_5 and u_6 are two distinct sign-changing solutions of BVP (1.1), (1.2). Thus, the proof of Theorem 5.1 is finished. \square

Theorem 5.2 *Assume that the conditions (H1)-(H5) hold, and that $f(t, x) = -f(t, -x)$ for $t \in [2, T]_{\mathbb{Z}}$ and $x \in \mathbb{R}$. Then BVP (1.1), (1.2) has at least four sign-changing solutions. Moreover, BVP (1.1), (1.2) has at least two positive solutions and two negative solutions.*

Proof It follows from the proof of Theorem 5.1 that BVP (1.1), (1.2) has at least six different nontrivial solutions u_i ($i = 1, 2, \dots, 6$) satisfying

$$u_1, u_2 \in P^\circ, \quad u_3, u_4 \in -P^\circ, \quad u_5, u_6 \notin P \cup (-P), \quad (5.26)$$

$$r_1 < \|u_5\| < |M| < \|u_6\| < R_1.$$

By the condition that $f(t, x) = -f(t, -x)$ for $t \in [2, T]_{\mathbb{Z}}$ and $x \in \mathbb{R}$, we know that $-u_5$ and $-u_6$ are also solutions of BVP (1.1), (1.2). Let $u_7 = -u_5, u_8 = -u_6$, then u_i ($i = 1, 2, \dots, 8$) are different nontrivial solutions of BVP (1.1), (1.2). The proof is completed. \square

By the method used in the proof of Theorems 5.1 and 5.2, we can prove the following corollaries.

Corollary 5.3 *Assume that the conditions (H1)-(H3) and (H5) or (H1), (H2), (H4), and (H5) hold. Then BVP (1.1), (1.2) has at least one sign-changing solution. Moreover, BVP (1.1), (1.2) has at least one positive solution and one negative solution.*

Corollary 5.4 *Assume that the conditions (H1)-(H3) and (H5) or (H1), (H2), (H4), and (H5) hold, and that $f(t, x) = -f(t, -x)$ for $t \in [2, T]_{\mathbb{Z}}$ and $x \in \mathbb{R}$. Then BVP (1.1), (1.2) has at least two sign-changing solutions. Moreover, BVP (1.1), (1.2) has at least one positive solution and one negative solution.*

Competing interests

The author declares that they have no competing interests.

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